A

SYSTEM

OF

MECHANICS,

BEING THE

SUBSTANCE OF LECTURES UPON THAT BRANCH OF NATURAL PHILOSOPHY,

By the Rev. T. PARKINSON, M.A.

FELLOW OF CHRIST'S COLLEGE, CAMBRIDGE.

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MASSACHUSETTS INSTITUTE OF TECHNOLOGY

FELLOW OF CHRIST'S COLLEGE, CAMBRIDGE.

BY THE REV. J. PLAYFAIR, M.A.

SUBSTANCE OF LECTURES UPON THAT BRANCH OF

NATURAL PHILOSOPHY,

BEING THE

MECHANICS,

TO

WHICH IS PREFIXED,

A

TO THE

TUTORS, AND OTHER MEMBERS OF THE UNIVERSITY,

INTERESTED IN THE

ADVANCEMENT OF PHILOSOPHICAL KNOWLEDGE,

THE FOLLOWING WORK,

FOR THE USE OF THE ACADEMIC STUDENT,

IS,

WITH GREAT DEFERENCE AND RESPECT,

INSCRIBED

BY THEIR VERY HUMBLE SERVANT,

THOMAS PARKINSON.

CHRIST'S COLLEGE,
NOV. 25, 1784.

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BY THEIR LATE HUMBLE SERVANT,

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DEDICATED.

CHRIST'S COLLEGE.
NOV. 25, 1824.

PREFACE.

THE want of ſyſtematic treatiſes on mechanics and hydroſtatics hath long been conſidered as equally troubleſome to the tutor, and diſcouraging to his pupils, and firſt induced a deſire to facilitate the attainment of theſe branches of ſcience by a collection, and methodical arrangement, of their ſcattered parts. The preſent coincides, very nearly, with the propoſitions, or heads of lectures, upon this ſubject, adopted by the generality of tutors in the univerſity, and is recommended by an obvious connexion and regular order of dependancy. In all natural ſcience, the analytic method of reaſoning neceſſarily precedes the ſynthetic, and the converſe of this order would terminate in uncertainty and chimera. The exiſtence and delineation of thoſe properties of matter, which are conceived to generate the phenomena of preſſure and motion, are therefore conciſely and generally premiſed in the firſt ſix chapters, and ſupply data, derived from experience and uncontroverted facts, for ſynthetic demonſtrations. The general properties of motion are deſcribed in the chapter upon ſolidity, becauſe the cleareſt conceptions of motion are derived from impulſe, which ariſes from ſolidity; and the laws of motion are introduced in the chapter upon the inertia of matter, becauſe they are inſeparably connected

with

with it. The compoſition and reſolution of forces are immediately ſubſequent; becauſe every propoſition upon this ſubject is deducible from the ſecond law of motion, and may be eſteemed a corollary to it. The connection of the other parts of the treatiſe is, I truſt, equally natural and obvious. To have diveſted this elementary branch of philoſophy of that dry, uninviting aſpect, ſo frequently and feelingly lamented by the young pupil, was certainly moſt deſirable; but the ſame complaint is applicable to the elements of all ſcience, and could not, I believe, be removed without an entire change of the formality of preciſe definitions and propoſitions into a more undefined and leſs ſcientific form of compoſition, nor conſequently without ſacrificing real advantage to leſs material amuſement. The following performance, therefore, claims little more than the inferior merit of facilitating the progreſs of the ſtudent by a ſelection, from the works of others, which may ſuperſede the neceſſity of applying to a multitude of books, and an arrangement coinciding with his lectures. The whole is written in the ſame language for the ſake of uniformity; demonſtrations are dilated or contracted as was deemed expedient; and ſometimes, though as ſeldom as poſſible, new proofs are given. It is no eaſy taſk to compoſe a ſyſtem equally accommodated to every deſcription of underſtandings, and I dare not hope to have accompliſhed it: for the benefit of thoſe, who may be diſſatisfied with the diſcuſſion of any ſubject here, accurate references to the page or chapter of the beſt writers where it is treated, are always inſerted. To be of ſervice to the ignorant and uninformed was the chief motive for undertaking this work, and the ſole object of attention in the execution of it: this laſt conſideration may ſerve to obviate ſome objections, which naturally will occur to more enlightened readers already converſant with the ſubject. Leſt I appear to preſume upon the experience that may be ſuppoſed to attend my ſituation, I beg leave to explain my-

myself. When ſeveral demonſtrations of the ſame propoſition are exhibited, let it not be inferred that one was deemed inſufficient to eſtabliſh its truth and required an auxiliary: when any important ſubject is treated with prolixity, and extended beyond the limits uſually preſcribed to an elementary treatiſe, let it not be attributed to negligence or inadvertency: they are both the effects of deſign, and I am warranted, by my own experience at leaſt, to aſſert their utility. It muſt be remembered, that clear and adequate ideas upon a new ſubject are not communicated by a tranſient impreſſion, and that the capacity and comprehenſion of an uninformed mind are only expanded and improved by repeated exertions and aſſiduity. Science implies ſomething more than a mere ability to go through a demonſtration; and a clear comprehenſive knowledge of a queſtion, which may be competent for the ſolution of problems and diſſipation of doubts and objections, is perhaps only to be attained by long reflection, and ſtudiouſly contemplating it on every ſide; and theſe are certainly much aſſiſted by different demonſtrations, which place the ſubject in different points of view, and by tracing its affinity with other truths ſimilar to, or deducible from, it. A ſingle demonſtration may eaſily be too long, and too anxious a deſire to be perſpicuous may occaſion perplexity and confuſion; but it is not eaſy to give too many demonſtrations of a fundamental propoſition, or too many problems and corollaries reſulting from it. This ſpecies of prolixity appears to me to be extremely uſeful, as it may, at leaſt, teach a young ſtudent the art of thinking, an art which can only be acquired, and is found indeed to be no eaſy acquiſition. For theſe reaſons, the reader will obſerve ſome leading ſubjects extended beyond the bounds abſolutely neceſſary, and ſome parts will apparently be ſuperfluous: I ſhall hold him juſtified in thinking ſo, when he ſhall be ſo informed on the ſubject as to pronounce them uſeleſs to him.

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PREFACE.

I cannot conclude this preface without expreſſing my ſincere thanks to Mr. Fiſher and Mr. Vince, of Caius College; to the firſt for his general theorem of the wedge; to the latter for his friendly reviſion of the whole work. Had I conſulted theſe friends more frequently, many errors and imperfections, for I believe there are many, might poſſibly have been avoided. My thanks are alſo juſtly due to thoſe gentlemen who have kindly honoured this undertaking with their approbation and ſupport, and I willingly embrace this public opportunity of acknowledging my obligation.

INTRO-

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INTRODUCTION

TO THE STUDY OF

NATURAL PHILOSOPHY.

1. NATURAL phenomena, in the wideſt acceptation of the terms, denote any effects in the material part of the creation addreſſed to one or more of the ſenſes; and natural philoſophy is the hiſtory of theſe phenomena, and an inveſtigation of the cauſes employed in their production. A phenomenon may itſelf be a natural cauſe productive of numberleſs effects, and each of theſe may alſo be a cauſe of others, &c.; for, of that infinite variety of events obſervable in the material world, none are induced per ſaltum, but effect is dependent upon effect in contiguous ſucceſſion. As matter is totally inactive, and incapable of communicating motion to itſelf, all its motions, and powers of producing a change of motion, in the various operations of nature, are derivative: but the inſtruments immediately directing the movements of the ſeveral parts of the ſyſtem elude the inquiſition of human ability, and whether any inexplicable effect be owing to the Creator's immediate fiat, or ſome ſecondary material power, cannot be known; for the action of a pure ſpirit upon matter cannot be comprehended: but many ſubordinate inſtruments in the government of nature are conſpicuous, matter being impreſſed by its great Creator with ſeveral attributes, which appear, and are conceived by ſome philoſophers, to reſide in it, miniſterial to the continuance of exiſtence and preſervation. The rules by which theſe attributes are directed in their operations, are called natural principles or laws, becauſe in ſimilar circumſtances, they are invariably the ſame; and the attributes themſelves are generally called powers or forces,

from the ſimilitude of their effects to thoſe produced by animal exertions: ſuch are gravity, coheſion, elaſticity, magnetiſm, electricity. The uniform and regular action and utility of ſome of theſe natural powers are very obſervable; but the laſt powers ſeem to be ſtill in a ſtate of analyſis, and the laws, by which their influence is directed, very imperfectly aſcertained. The attraction of coheſion, or of that power by whoſe influence the minute particles of matter tend to each other at ſmall diſtances, is the cement which prevents the diſperſion of the component parts of matter, and, as far as we are competent to decide, adminiſters to the growth of bodies in the animal, vegetable, and foſſil kingdoms. The figures and motions of the great bodies compoſing the ſolar ſyſtem are preſerved by an uninterrupted exertion of the attraction of gravity. Nor is the oppoſite quality of elaſticity or repulſion leſs regular or important. The particles of air are endued with this repulſive power which is eſſential to the preſervation of all bodies contiguous to it, and a diminution of it would proportionably diminiſh its ſalutary influence, rendering it noxious to animal and vegetable life; and many hard bodies are obviouſly poſſeſſed of this quality probably to preſerve their ſpecific nature by protecting their conſtituent particles from the effects of attrition, &c. The operations of other attributes of matter, however deſultory and accidental apparently, are, upon the fulleſt information, diſcovered to be reſtrained within preſcribed limits, whoſe obſervance is productive of harmony, and violation of diſorder. Plants and animals are always produced from their proper ſeed; the reflection and refraction of light are effected according to inviolate laws; matter, by its vis inertiæ, reſiſts the action of any material power, and when in motion moves, according to determinate rules, &c. To deſcribe the various phenomena exhibited in the production and change of motion in the material world, whether explicable or not, promiſcuouſly, is the buſineſs of the natural hiſtorian; and to ſelect thoſe which are explicable, and inveſtigate the ſecondary powers, or qualities, conceived to be reſident in matter, by whoſe inſtrumentality they appear to be effected, is the province and proper occupation of the natural philoſopher.

2. The

2. The hiſtorical part of philoſophy, or deſcription of natural phenomena, is immediately tranſcribed from the works of nature; and, from the inadequacy of our ideas of matter, an inveſtigation of the ſecondary material powers producing them muſt be derived from the ſame ſource. Some phenomena being obſerved to be invariably coexiſtent or ſucceſſive, a connexion is underſtood, or preſumed, to obtain between them; and, the object of philoſophy being an evolution of this connexion, the works of nature where only it is diſcoverable, muſt be attentively explored, the relation noted, and extended, by a cautious ſelection of all the circumſtances of ſimilitude in other phenomena, to a common principle or law of nature. The following proceſs is therefore adopted by the beſt philoſophers, and is the only certain method of philoſophizing.

Firſt, By repeated and accurate obſervations upon matter, or upon ſome general ſimilar phenomena in the material world, the exiſtence and qualities of any individual cauſe are demonſtrated from the phenomena evidently and invariably attached to it; the cauſe of this cauſe, and the cauſe of this laſt, &c. and the effects ſucceſſively more ſubordinate and particular reſulting from the phenomena, conſidered as mechanical cauſes, are then inveſtigated by again exploring the works of nature, and this proceſs is repeated to the limit of human ability. How far the chain of theſe ſecondary material powers, either progreſſive or regreſſive, from thoſe that are more general to their ſubordinate effects, and vice verſa, is extended, is undiſcoverable; but the philoſopher's reſearches are ſoon limited by the occurrence of bodies inconceivably minute, or removed to immeaſurable diſtances. An examination of the few powers that are known is, however, a rational and not unprofitable employment; for they exhibit proofs of unbounded power, conſummate wiſdom, and paternal benevolence in the great Creator; and by their connexion with many uſeful arts, are made ſubſervient to the wants and infirmities of his creatures. *Secondly*, The intenſity at a given diſtance, and law of variation at different diſtances, of any material power being aſcertained by the menſuration of its effects, it is aſſumed as a principle, and from its influence, all ſimilar phenomena are demonſtrated to reſult by

mathematical or other ſcientific methods of reaſoning. For many effects are, upon examination, found to bear ſtrong marks of ſimilitude, which to a negligent obſerver exhibit no likeneſs; and, theſe being diveſted of all adventitious particularities, and ranged under the ſame cauſe, a few principles are diſcovered to pervade the whole ſyſtem of matter, producing innumerable phenomena. The firſt of theſe is called the analytic, and the ſecond the ſynthetic method of philoſophizing.

3. Examples illuſtrating the analytic method of reaſoning.

EXAMP. I. The ſpherical figure of the earth proved analytically.

PHENOMENA.

PHENOM. I. The altitude of either pole of the equator is always equal to the latitude of the obſerver.

PHENOM. II. In an eclipſe of the moon a ſection of the earth's ſhadow is always terminated by a circular arc.

Many other phenomena might be adduced in proof of the globular figure of the earth, but it is eſtabliſhed by theſe, becauſe no other afford a ſolution of them. This figure was impreſſed at the original formation of the earth, and is preſerved by an unremitted exertion of the attraction of gravity; and here the analyſis terminates, the cauſe of gravity being undiſcovered.

4. EXAMP. II. The diurnal revolution of the earth proved analytically.

PHENOMENA.

PHENOM. I. The ſun and moſt of the planets revolve round their axes, and a ſimilar motion of the earth is analogous to theſe.

PHENOM. II. The ſun, planets and fixed ſtars appear to revolve uniformly in circles, whoſe planes are perpendicular to, and centers in, a line paſſing through the center of the earth, and perform one revolution in twenty-four hours nearly.

PHE-

PHENOM. III. The gravity of bodies is leaſt under the equator, and increaſes as they recede from it.

If this motion of the heavenly bodies were real, they would be retained in their orbits by forces tending to their correſponding centers in the axis of the world (Newt. ſect. 2. prop. 2.), which are imaginary points in which no attractive powers reſide; and ſome of theſe motions could not be effected without the influence of forces infinitely greater than any mechanical powers yet diſcovered. They are therefore apparent only, and reſult from the rotation of the earth round an axis; and this is confirmed by phenom. 2. which is eaſily explicable by, and inexplicable without, ſuch rotation.

5. EXAMP. III. The properties of light inveſtigated analytically.

PHENOMENA.

PHENOM. I. If the ſun's rays be admitted, through a ſmall aperture, into a dark room, and refracted through a glaſs priſm, an oblong image conſiſting of ſeveral colours will be formed upon a ſheet of paper placed at a proper diſtance.

PHENOM. II. If another priſm be placed behind the former, ſo that their axes be perpendicular, the image will be refracted on one ſide, of the ſame length and breadth as before.

PHENOM. III. Any one colour refracted through any number of priſms, always exhibits a circular image of that colour.

If the ſun's rays were equally refrangible, its image would be circular, and, if differently refrangible, oblong; and conſequently (phenom. 1ſt and 2d) light is compoſed of heterogeneous parts differently refrangible. If the ſun's rays ſplitted or dilated by refraction, the image would be circular and increaſed by every refraction, therefore (phenom. 2d) they do not ſplit or dilate; and (phenom. 3d) the properties of homogeneous rays are innate and unalterable by refraction.

6. The

6. The concluſions thus derived by analyſis are analogical, as they reſult from a compariſon between preſent and paſt phenomena, and will be juſt only when theſe compariſons are repeatedly made, and the ſimilitude of the phenomena perfectly eſtabliſhed. In example the 1ſt. the altitude of the pole being found equal to the latitude of the obſerver, and a ſection of the earth's ſhadow to be a circular arc, and theſe phenomena being invariably the ſame in innumerable trials, an aſſurance that they reſult from ſome fixed cauſes and will never vary, ariſes and commands our aſſent.

Philoſophy therefore, when real and not fantaſtical, has for its baſis uniform and uncontroverted experience; and hence appears the neceſſity of adhering to the firſt rule of philoſophizing.

RULE I.

No more cauſes of natural events ought to be admitted than are real, and ſufficient to explain the phenomena.

7. Of thoſe bodies which are neither concealed by their minuteneſs, nor remote diſtance, few can undergo an analytical diſcuſſion; and philoſophy would be very limited, were it confined to thoſe only which have actually been the objects of experiments; but it is rendered univerſal by obſerving the following rules.

RULE II.

Effects of the ſame kind are to be aſcribed to the ſame cauſe.

The ſame cauſe occaſions the deſcent of bodies in different places of the earth, reſpiration in different animals, the ſenſation of heat from a culinary fire and the ſun, ſolutions of bodies in different menſtruums, and of water in air, &c.

RULE III.

8. *Thoſe qualities of matter which do not vary, and are found in all bodies that admit of experimental examination, ought to be conſidered as qualities of all bodies in general.*

Thus

Thus the attraction of gravity is diſcovered, by experiments and aſtronomical obſervations, to pervade all matter with which we are acquainted: all bodies near the earth's ſurface, and the moon, gravitate towards the earth; the waters of the ſea gravitate towards the moon; the ſun, planets, and comets, gravitate towards each other mutually; and of this principle no bodies acceſſible to experiments can be diveſted, and therefore, from this rule, it is inferred to be an univerſal attribute of matter.

9. As much falſe philoſophy hath been diſſeminated by fanciful hypotheſes and mere metaphyſical conſiderations, unſupported by the reality of facts, the only ſources of natural ſcience, the utility of the following rule is apparent.

RULE IV.

In experimental philoſophy, propoſitions collected from phenomena by induction are to be deemed, notwithſtanding contrary hypotheſes, either accurately true or very nearly ſo; until other phenomena occur by which they may be rendered either more accurate, or liable to exception.

10. The exiſtence, quantity at a given diſtance, and law of variation at different diſtances, of any natural power being demonſtrated by the analytic method of reaſoning, the only way by which they can be known; they are aſſumed as eſtabliſhed general principles, and their adequacy to the production of other phenomena, ſimilar to thoſe uſed in the analyſis, is proved ſynthetically.

Examples illuſtrating the ſynthetic method of reaſoning.

EXAMP. I. The influence of the attraction of gravity, its quantity and law of variation, being aſcertained analytically, it is aſſumed as an eſtabliſhed general principle, and demonſtrated geometrically to be an adequate cauſe of the motions of pendulums, projectiles, preceſſion of the equinoxes, irregularities of the moon's motion, riſing and ebbing of the ſea, and innumerable other phenomena.

EXAMP. II. The weight of the air being aſcertained by experiments, it is ſuppoſed to be allowed, and affords an eaſy ſolution of the phenomena of pumps, ſyringes, barometers, &c.

EXAMP. III. The equality of the angles of incidence and reflection of light, of the conſtant ratio obtaining between the ſines of incidence and refraction, and the unequal refrangibility of different colours, are diſcovered by experiments; and, being ſuppoſed to be univerſally true, they afford eaſy explanations of the figure and magnitude of images formed by reflection and refraction, of the rainbow, &c.

EXAMP. IV. The ſpherical figure of the earth, its diurnal motion, and obliquity of the ecliptic are diſcovered by repeated obſervation, and, being aſſumed as known principles, they afford an eaſy ſolution of the doctrine of the ſphere, of the art of dialling, of day and night and their inequalities, of heat and cold, and many other phenomena.

11. Of theſe two methods of reaſoning, the latter may ſtrictly be denominated ſcience; for the exiſtence of any natural power, its magnitude and variation being preſuppoſed, it is demonſtrated geometrically to be competent to the production of various effects, and, were this power changed or annihilated, the truth of this reaſoning would remain unaltered. Whether this ſcience be chimerical, or accord with actual exiſtence, depends upon the truth of the preſuppoſed data, or analytic concluſions, which admit of various degrees of conviction from bare preſumption to certainty. The exiſtence of ſome undiſcovered and ſtill unknown quality of matter, collected only from a few experiments, amounts only to a preſumption; but the degree of probability increaſes with their number, and, by repeated and uniformly concurring trials, eſtabliſhes at length an evidence as unqueſtioned as the exiſtence of matter or the ſenſes. That the qualities of matter will remain unchanged and continue always to produce the ſame effects, depends upon the will of that divine Agent, who ordained that the various

various events in the material world ſhould be effected by the intervention of ſimple and general material cauſes, acting with invariable conſtancy and uſefulneſs, and only ſuffered to tranſgreſs their preſcribed bounds according to the dictates of infinite wiſdom, power and goodneſs. Preſuming therefore upon the identity of the ſenſes and the uniformity of natural operations, the ſtudy of philoſophy may be deemed ſcientific; for, being founded upon the baſis of uniform and uncontroverted experience, and geometric demonſtration, its certainty will continue with them, and conſequently can only be affected or ſubverted by a change or ſubverſion of the conſtitution of nature.

12. Of all magnitudes, numbers are the moſt ſimple, and their minute differences moſt eaſily diſcriminated, and therefore more ſuſceptible of clear ideas than any other magnitudes; and the relations ſubſiſting between powers or forces, and the changes or velocities produced by their exertions, are ſaid to be known, when reduced to numeral expreſſions, though the mode of producing theſe effects be unknown, and perhaps undiſcoverable. The next, in degree of ſimplicity and clearneſs of comprehenſion, are lines, ſurfaces and ſolids, being permanent and eaſily compared by juxta-poſition. The conception of other magnitudes is more remote and difficult. Forces, velocities, and times, having no permanent repreſentatives like numbers and geometric magnitudes, and diſappearing when not actually ſubſiſting, are beſt underſtood from their effects; and this ſtudy is therefore much ſimplified by finding magnitudes of eaſier conception, and more eaſily meaſurable and permanent, as numbers, lines and ſurfaces, whoſe relation is the ſame with that of times and velocities, and natural powers. Philoſophy may conſequently be reduced to an inveſtigation of the relation ſubſiſting between lines, ſurfaces, &c. which vary as, and may be denominated the repreſentatives of, natural powers and their effects; and a knowledge of ratios, or of the rules by which theſe relations are increaſed and diminiſhed, is a neceſſary lemma to this ſtudy and here premiſed.

RATIOS.

13. DEF. *WHATEVER is capable of increaſe or decreaſe, is called magnitude or quantity, as numbers, lines, velocities, forces, &c.*

14. DEF. *Ratio is the mutual relation of two magnitudes of the ſame kind in reſpect of their greatneſs or ſmallneſs; the firſt is called the antecedent and the ſecond the conſequent of the ratio.*

15. Ratio is therefore a compariſon, which always implies a ſimilitude, and is limited by the definition to the relative greatneſs or ſmallneſs of the quantities compared. The magnitude of the ratio of equal quantities is equal to nothing; for the exiſtence of ratios reſults from the inequality of the quantities compared, though not meaſured by it; and it is evident, that the magnitude of a ratio may increaſe or decreaſe through every ſtage of aſſignable quantity.

EXAMPLES.

FIG. I. EXAMP. I. If the diſtance of E from B be equal to nothing, the diameter QB, and chord QE coincide, and their ratio is a ratio of equality, and its magnitude equal to nothing; but as the arc BE increaſes from nothing to a ſemicircle, the magnitude of this ratio increaſes from nothing through every ſtage of aſſignable magnitude, and, when E and Q coincide, is unaſſignably great.

EXAMP. II. The ratio of the tangent TA to the ſine SN of an arc SA, or of the ſecant CT to the radius CS, is a ratio of equality, and its magnitude equal to nothing, when the arc vaniſhes, and S and A coincide. But as the arc SA increaſes from nothing to a quadrant, the magnitude of this ratio increaſes from nothing through

through every ſtage of aſſignable magnitude, and, when S and Q coincide, is unaſſignably great. If the magnitude of this ratio (when e. g. $SA = 30°$) be expounded by any finite line L, and twice this ratio by twice this line, &c. when S and A coincide, L is equal to nothing; and as S recedes from A, L increaſes and becomes infinitely great when S arrives at Q.

Ratios therefore are magnitudes, and like all other magnitudes the object of ratios, and capable of addition, ſubtraction, multiplication and diviſion. They are poſitive or negative, according to their different effects in addition. The ſum of two poſitive, or of two negative ratios, will conſtitute a poſitive, or negative ratio, greater than either of them; and, according as a poſitive ratio is greater or leſs than a negative one, their ſum will be poſitive or negative; and, if they be equal, their ſum is nothing. The magnitudes of the ratio of $L : M$ and of $M : L$, or of $3 : 2$ and of $2 : 3$, are clearly equal, but of different denominations; and any third ratio, of the ſame denomination with the ratio of $L : M$, will be equally encreaſed by the addition of the ratio of $L : M$ and ſubtraction of the ratio of $M : L$. If the ratio obtaining between L and M, of which L is the greateſt, be called poſitive, and repreſented by any line or number a, twice this ratio will be repreſented by twice a, and n times this ratio by $n \times a$. The ratio alſo of $M : L$ will be repreſented by $-a$, and $n \times$ the ratio of $M : L$ by $n \times -a$; and a line or number, repreſenting any third affirmative ratio, will be equally encreaſed by the addition of $n \times a$ and ſubtraction of $n \times -a$. As magnitudes are only meaſurable by magnitudes, ſui generis, a line by a line, a ſurface by a ſurface, and a ratio by a ratio: to aſcertain the quantity of any ratio, ſome more ſimple ratio may be uſed as a criterion. Thus logarithms are a ſeries of numbers expreſſing the relation which ſubſiſts between any given ratio, conſidered as a criterion, and all other ratios with which it is compared.

16. DEF. *In a ſeries of magnitudes of the ſame kind, either increaſing or decreaſing, the ratio of the extremes is ſaid to be compounded of the ratios of the intermediate terms.*

In the ſeries of magnitudes A, B, C, D, &c. the ratio of the firſt to the laſt, or of $A : D$, is ſaid to be compounded of the ratios of $A : B$, $B : C$, $C : D$; and any ratio, as that of $PQ : PR$, is ſaid to
FIG. II. be reſolvable into, and equal to, the ratios of $PQ : Pa$, $Pa : Pb$, $Pb : Pc \ldots . PL : PR$; for the ratio of $PQ : PR$ is a real magnitude, and like other magnitudes diviſible into its component parts, which are the ratios of $PQ : Pa$, $Pa : Pb$, $Pb : Pc$, &c.: therefore the ſum of any number of continued ratios, where the antecedent of any ratio is the conſequent of the preceding, is equal to the ratio of the firſt and laſt terms.

FIG. II. 17. Cor. When any ratio, as that of $PQ : PR$, is to be divided into any other ratios by an arbitrary inſertion of other quantities Pa, Pb, &c.; theſe are not neceſſarily intermediate, or contained between PQ and PR, the ratio of $PQ : PR$ being equal to the ratios of $PQ : Pv$ and of $Pv : PR$. For the ratio of $PQ : Pv$ is equal to the ratios of $PQ : PR$ and of $PR : Pv$ (16), and conſequently the ratio of $PQ : PR$ is equal to the ratio of $PQ : Pv$ diminiſhed by the ratio of $PR : Pv$, or added to the ratio of $Pv : PR$ (15).

ADDITION OF RATIOS.

18. PROP. *To add the ratios of* A : B, C : D, E : F, *&c. together.*

When the two ratios of $A : B$ and $C : D$ are to be added, let A
FIG. III. and C, B and D be reſpectively the ſides of two rectangular parallelograms X and Z; and (Euclid. VI. 23.) the ratios of $A : B$ and $C : D$, when compounded, are equal to the ratio of $X : Z$, or of $A \times C : B \times D$, theſe quantities being reſpectively equal to X and Z. When the ratios of $A : B$, $C : D$, $E : F$ are to be added, the ſum of the two firſt is equal to the ratio of $AC : BD$ by the proceſs above; and, by making $A \times C$ and E, $B \times D$ and F, reſpectively the ſides of two rectangles, it appears, by the ſame proceſs, that the ſum of the ratios of $AC : BD$ and of $E : F$ is equal to

the

the ratio of $ACE : BDF$. Whatever be the number of ratios to be added the proceſs is ſimilar, and gives the following

RULE.

Multiply the antecedents together for a new antecedent, and the conſequents for a new conſequent.

19. EXAMP. I. The ſum of the ratios of $1:2$, $3:4$, $5:6$, $7:8$ is equal to the ratio of $1\times3\times5\times7 : 2\times4\times6\times8$, or of $105 : 384$. This alſo appears from the following analogies and article (16); for (38)

$$1 : 2 :: 105 : 210$$
$$3 : 4 :: 210 : 280$$
$$5 : 6 :: 280 : 336$$
$$7 : 8 :: 336 : 384.$$

The ſum of the ratios of $1:2$, $3:4$, $5:6$, $7:8$, is equal to the ſum of the ratios of $105:210$, $210:280$, $280:336$, $336:384$, or (16) to the ratio of $105:384$, as above.

20. EXAMP. II. When two bodies move with uniform motions, philoſophical writers ſay, that the ſpaces deſcribed S and s are to each other in a ratio compounded of the velocities and times; the meaning of which is, that the ratio of the ſpaces is equal to the ſum of the ratio of the velocities when changed, and the ratio of the times when changed, or that the ratio of $S:s$ is equal to the two ratios of $V:v$ and of $T:t$, or to the ratio of $V\times T : v\times t$, ſuppoſing v and t to repreſent any correſponding values of the velocity and time.

21. Cor. 1. If there be any number of quantities A, B, C, D, &c. of which $A:B :: R:r$ and $B:C :: S:s$ and $C:D :: T:t$, A will be to D as $RST:rst$; for $A:D$ in a ratio compounded of the ratios of $A:B$, $B:C$, $C:D$ (16), or their equals $R:r$, $S:s$, $T:t$, or as $RST:rst$ (18).

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SCHOLIUM.

22. When the terms of any ratios are forces, times, velocities, &c. lines or numbers are ſuppoſed to be taken whoſe ratios are the ſame with them, and rectangular parallelograms whoſe ſides are theſe lines, or the products of theſe numbers actually multiplied together, are always implied in the multiplication of ſuch magnitudes. The ſum of the ratios of $L:M$ (denoting forces), of $N:P$ (denoting velocities), of $\mathcal{Q}:R$ (denoting ſpaces), and of $S:T$ (denoting times), is equal to the ratio of $L\times N\times \mathcal{Q}\times S : M\times P\times R\times T$, which ſignify two products of numbers whoſe factors are as $L:M$, $N:P$, $\mathcal{Q}:R$, $S:T$.

SUBTRACTION OF RATIOS.

23. PROP. *To ſubtract the ratio of* C:D *from that of* A:B.

Let the ratio of $A:B$ be equal to the ratios of $C:D$ and $x:y$; and (18) $A:B :: xC:yD$, and $x:y :: \frac{A}{C} : \frac{B}{D}$ (Euc. v. 4.) $:: AD:BC$ (Euc. v. 10.); from hence we have the following

RULES.

RULE I. *Divide the antecedent of the ſubtrahend by the antecedent of the ratio to be ſubtracted for a new antecedent, and the conſequent by the conſequent for a new conſequent.*

Or, II. *Invert the terms of the ratio to be ſubtracted, and proceed as in addition.*

24. EXAMP. I. The ratio of 6 : 5 ſubtracted from the ratio of 3 : 2 is equal to the ratio of $\frac{3}{6} : \frac{2}{5}$ or of 15 : 12, which is thus confirmed. The ratio of 3 : 2 is equal to the ratio of 6 : 4, which is equal to the ratio of 6 : 5 and of 5 : 4 (16); and if the ratio of

6 : 5

6 : 5 be taken away, the remainder is the ratio of 5 : 4 or of 15 : 12 (Euc. v. 15.).

25. EXAMP. II. The ratio of 2 : 3 diminiſhed by the ratio of 4 : 5 is equal to the ratio of $\frac{2}{4} : \frac{3}{5}$ or of 10 : 12, which is thus confirmed. The ratio of 2 : 3 is equal to the ratio of 4 : 6 (Euc. v. 15.), that is, of 4 : 5 and 5 : 6 (16); and, if the ratio of 4 : 5 be taken away, the remainder is the ratio of 5 : 6 or of 10 : 12 (Euc. v. 15.).

MULTIPLICATION OF RATIOS.

26. PROP. *To multiply the ratio of* A : B *by any number* m.

The ratio of $A : B$ added to itſelf is equal to the ratio of $A^2 : B^2$, and this added to the ratio of $A : B$ is equal to the ratio of $A^3 : B^3$, and this repeated m times will clearly give the ratio of $A^m : B^m$ (18), and we have this rule.

RULE.

Involve the terms of the ratio to a dimenſion equal to the multiplier.

27. EXAMP. I. Four times the ratio of $A : B$ is equal to the ratio of $A^4 : B^4$, which is confirmed by the following proceſs; for (38)

$$A : B :: A^4 : A^3B$$
$$A : B :: A^3B : A^2B^2$$
$$A : B :: A^2B^2 : A^2B^2$$
$$A : B :: AB^3 : B^4.$$

Therefore four times the ratio of $A : B$ is equal to the ratios of $A^4 : A^3B$, $A^3B : A^2B^2$, $A^2B^2 : AB^3$, $AB^3 : B^4$, or the ratio of $A^4 : B^4$ (16).

28. EXAMP.

28. EXAMP. II. Five times the ratio of 2:3 is equal to the ratio of 25:35 or 32:243, which alſo appears from the proceſs above and (16). For (38)

2 : 3 :: 32 : 48
2 : 3 :: 48 : 72
2 : 3 :: 72 : 108
2 : 3 :: 108 : 162
2 : 3 :: 162 : 243.

Therefore the ratio of 2:3 multiplied into five is equal to the ratios of 32:48, 48:72, 72:108, 108:162, 162:243; or to the ratio of 32:243 (16).

DIVISION OF RATIOS.

29. PROP. *To divide the ratio of* A:B *by any number* m.

Let $A = x^m$ and $B = y^m$; and the ratio of $A:B$ is equal to the ratio of $x^m : y^m$ or to m times the ratio of $x:y$ (18), which is therefore $\frac{1}{m}$ part of the ratio of $A:B$, and equal to the ratio of $A^{\frac{1}{m}} : B^{\frac{1}{m}}$; becauſe $x = A^{\frac{1}{m}}$ and $y = B^{\frac{1}{m}}$. Whence we have the following

RULE.

Extract that root of the terms of the ratio which is expreſſed by the diviſor.

30. EXAMP. The ratio of 32:162 divided by four is equal to the ratio of $\overline{32}^{\frac{1}{4}} : \overline{162}^{\frac{1}{4}}$ or of 2:3. And this is confirmed by the proceſs uſed in example (28), where the ratio of 32:162 is equal to the ratio of $\overline{2:3} \times 4$, and conſequently the ratio of 2:3 is $\frac{1}{4}$th of the ratio of 32:162.

31. PROP. *When the difference of two magnitudes is very ſmall compared with the magnitudes themſelves, their ratio is multiplied or divided*

divided by any number m, *by increaſing or diminiſhing their difference* m *times.*

DEM. Let the two magnitudes be A and $A \pm y$, whoſe difference y is very ſmall compared with A; and m times the ratio of $A : A \pm y$ is equal to the ratio of $A^m : \overline{A \pm y}^m$, or of $A^m : A^m \pm mA^{m-1}y + m \cdot \frac{m-1}{2} A^{m-2}y^2$, &c. or (dividing the antecedent and conſequent by A^{m-1}) to the ratio of $A : A \pm my$; becauſe the terms involving $\frac{y^2}{A}$, $\frac{y^3}{A^2}$, &c. are evaneſcent compared with the two firſt, and may be neglected.

By a ſimilar proceſs $\frac{1}{m}$th part of the ratio of $A : A \pm y$ appears to be equal to the ratio of $A : A \pm \frac{y}{m}$. Q. E. D.

32. EXAMP. Twice the ratio of 11 : 10 is equal to the ratio of $\overline{11}^2 : \overline{10}^2$ or of 121 : 100; and, according to this propoſition, it is the ratio of 11 : 9, or of 121 : 99.

Twice the ratio of 101 : 100 is equal to the ratio of $\overline{101}^2 : \overline{100}^2$ or of 10201 : 10000; and according to this propoſition it is equal to the ratio of 101 : 99 or of 10201 : 9999, which is nearly equal to the former.

33. EXAMP. II. A half of the ratio of 101 : 100 is equal to the ratio of $\overline{101}^{\frac{1}{2}} : \overline{100}^{\frac{1}{2}}$, or of 10.049 : 10 nearly; and by this propoſition it is equal to the ratio of $100\frac{1}{2} : 100$, or of 201 : 200, or of 10.05 : 10.

METHODS OF COMPARING RATIOS.

34. DEF. *Proportion is an equality of ratios. When the ratios of* A : B *and* C : D *are equal, they are ſaid to be proportional, and uſually written thus* A : B :: C : D, *or* A *is to* B *as* C *to* D.

35. Cor. If A, B, C, D be proportional, and $A = \frac{1}{4}B$, or $\frac{m}{n} \times B$, C will be equal to $\frac{1}{4}D$, or to $\frac{m}{n} \times D$; or if theſe magnitudes be incommenſurate, and A be greater, or leſs, than any part or parts of B, C will be greater, or leſs, than the ſame part or parts of D. If A be contained between $\frac{m}{n} \times B$ and $\frac{m+1}{n} \times B$, (m and n being any numbers whatever,) C will alſo be contained between $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$. This is evident from the definitions of ratios and proportion; for if A were contained between $\frac{18}{17} \times B$ and $\frac{19}{17} \times B$, or $\frac{m}{n} \times B$ and $\frac{m+1}{n} \times B$, and C were not contained between $\frac{18}{17} \times D$ and $\frac{19}{17} \times D$, or $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$, A's magnitude compared with B's, would not be equal to C's magnitude compared with D's, or the ratios of $A : B$ and $C : D$ would not be equal, and they would not be proportional.

36. PROP. *If* A *cannot be greater than, equal to, or leſs than, any part or parts of* B, *but at the ſame time* C *is greater than, equal to, or leſs than, the ſame part or parts of* D, *they will be proportional, or* A : B :: C : D.

DEM. Let $A : B :: E : D$, and if $A = \frac{m}{n} \times B$, $E = \frac{m}{n} \times D$ (35), and, from the hypotheſis, $C = \frac{m}{n} \times D$: therefore $E = C$ and $A : B :: C : D$. Let theſe magnitudes be incommenſurate, and if A be contained between $\frac{m}{n} \times B$ and $\frac{m+1}{n} \times B$, E will be contained between $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$ (35), and, from the ſuppoſition, C will

C will be contained between $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$. The difference therefore between C and E is between $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$, and consequently is not greater than $\frac{D}{n}$; and because this is true whatever be the magnitnde of the number n, which may be unassignably great and $\frac{D}{n} = 0$, C will be equal to E, and $A : B :: C : D$. Q. E. D.

37. Cor. 1. If four magnitudes A, B, C, D be proportional, the products of the extreme, and middle, terms are equal, or $A \times D = B \times C$. For let $A = \frac{m}{n} \times B$, and therefore $C = \frac{m}{n} \times D$ (35): consequently $A \times D = \frac{m}{n} \times B \times D$, and $B \times C = B \times \frac{m}{n} \times D = A \times D$. If they be incommensurate, let A be greater than $\frac{m}{n} \times B$, and less than $\frac{m+1}{n} \times B$, and C will be contained between $\frac{m}{n} \times D$ and $\frac{m+1}{n} \times D$ (35); therefore $A \times D$ is contained between $D \times \frac{m}{n} \times B$ and $D \times \frac{m+1}{n} \times B$, and $C \times B$ is contained between $B \times \frac{m}{n} \times D$, and $B \times \frac{m+1}{n} \times D$. The difference of these products is therefore not greater than $\frac{DB}{n}$, which, because n may be taken unassignably great, $= 0$; and consequently $A \times D = B \times C$.

38. Cor. 2. If two products be equal, their factors are proportional. Let $A \times D = B \times C$; and if $A = \frac{m}{n} \times B$, then $C = \frac{A \times D}{B} =$ (by

$=$ (by ſubſtituting A's value) $\frac{m}{n} \times D$; or if A be leſs than $\frac{\overline{m+1}}{n}$ $\times B$, but greater than $\frac{m}{n} \times B$; then C, being equal to $\frac{A \times D}{B}$, will be leſs than $\frac{\overline{m+1}}{n} \times D$, and greater than $\frac{m}{n} \times B$; conſequently (36) $A : B :: C : D$. In the ſame manner it may be proved, that $A : C :: B : D$, if they be ſimilar; or that $A : BC :: 1 : D$, and $B : A :: D : C$, or $B : A \times D :: 1 : C$, or $A : B :: C : \frac{BC}{A}$. Any equation is therefore reſolvable into a proportion by ſo arranging the terms, that the rectangle of the extreme terms may be one ſide of the equation, and that of the mean terms the other.

39. Cor. 3. Ratios, which are equal to any ratio, are equal to each other. Let $A : B :: C : D$ and $C : D :: E : F$; and if A be equal to $\frac{m}{n} \times B$, or contained between $\frac{m}{n} \times B$ and $\frac{\overline{m+1}}{n} \times B$, C will be equal to $\frac{m}{n} \times D$, or contained between $\frac{m}{n} \times D$ and $\frac{\overline{m+1}}{n} \times D$ (35), and alſo E will be equal to $\frac{m}{n} \times F$, or contained between $\frac{m}{n} \times F$ and $\frac{\overline{m+1}}{n} \times F$ (35); therefore A and E are either equal to, or contained between, the ſame parts of B and F reſpectively, and $A : B :: E : F$ (36).

40. Cor. 4. If $A : B :: C : D$ they will be proportional inverſely, or $B : A :: D : C$. Let A be equal to $\frac{m}{n} \times B$ or contained between $\frac{m}{n} \times B$ and $\frac{\overline{m+1}}{n} \times B$, and C will be equal to $\frac{m}{n} \times D$, or contained between $\frac{m}{n} \times D$ and $\frac{\overline{m+1}}{n} \times D$ (35); therefore $\frac{n}{m} \times A$ is equal to

or

or greater than, and $\frac{n}{m+1} \times A$ is leſs, than B, or B is contained between $\frac{n}{m+1} \times A$ and $\frac{n}{m} \times A$, or equal to $\frac{n}{m} \times A$; and for the ſame reaſon D is contained between $\frac{n}{m+1} \times D$ and $\frac{n}{m} \times D$, or equal to $\frac{n}{m} \times C$; therefore (36) $B : A :: D : C$.

41. Cor. 5. Magnitudes are proportional to their equimultiples or equal parts. Let $A = \frac{m}{n} \times B$, and $2A$ will be equal to $\frac{m}{n} \times 2B$, and $\frac{1}{2}A = \frac{m}{n} \times \frac{1}{2}B$; therefore (36) $A : B :: 2A : 2B :: \frac{1}{2}A : \frac{1}{2}B$; or let A be contained between $\frac{m}{n} \times B$ and $\frac{\overline{m+1}}{n} \times B$, and $2A$ will be contained between $\frac{m}{n} \times 2B$ and $\frac{\overline{m+1}}{n} \times 2B$; and $\frac{1}{2}A$ between $\frac{m}{n} \times \frac{1}{2}B$ and $\frac{\overline{m+1}}{n} \times \frac{1}{2}B$; therefore (36) $A : B :: 2A : 2B :: \frac{1}{2}A : \frac{1}{2}B$, &c.

42. Cor. 6. If $A : B :: C : D$, $A^m : B^m :: C^m : D^m$ and $A^{\frac{1}{m}} : B^{\frac{1}{m}} :: C^{\frac{1}{m}} : D^{\frac{1}{m}}$. For m times, or an mth part of, the ratio of $A : B$ is equal to m times, or an mth part of, that of $C : D$, becauſe theſe ratios are equal to each other; therefore (34) $A^m : B^m :: C^m : D^m$; and $A^{\frac{1}{m}} : B^{\frac{1}{m}} :: C^{\frac{1}{m}} : D^{\frac{1}{m}}$.

43. Cor. 7. If $A : B :: C : D$; then $A+B : B :: C+D : D$. Let A be equal to $\frac{m}{n} \times B$, or contained between $\frac{m}{n} \times B$ and $\frac{\overline{m+1}}{n} \times B$, and (35) C will be equal to $\frac{m}{n} \times D$, or contained between $\frac{m}{n} \times D$ and

and $\overline{\frac{m+1}{n}} \times D$; therefore adding B to both, $A+B$ will be equal to $\overline{\frac{m+n}{n}} \times B$, or greater than $\overline{\frac{m+n}{n}} \times B$ and leſs than $\frac{m+1+n}{n} \times B$; and $C+D$ will be equal to $\frac{m+n}{n} \times D$, or greater than this, and leſs than $\overline{\frac{m+1+n}{n}} \times D$; and conſequently (36) $A+B : B :: C+D : D$. In the ſame manner it may be proved, that $A-B : B :: C-D : D$; and $A : B :: A \pm C : B \pm D$.

44. DEF. *That ratio is ſaid to be greater or leſs than another, whoſe antecedent has a greater proportion to its conſequent than the antecedent of the other to its conſequent.*

Two ratios, whoſe antecedents, or conſequents, are the ſame, are eaſily compared: for it is evident that the ratio of 6 : 3 is greater, and the ratio of 4 : 3 leſs, than the ratio of 5 : 3; and the negative ratio of 3 : 6 is greater, and of 3 : 4 leſs, than the ratio of 3 : 5.

45. *The firſt method of comparing unequal ratios is to reduce them to other ratios equal to them with a common antecedent, or conſequent.*

EXAMP. To compare the ratios of $A : B$ and of $C : D$. Find a ratio equal to either of them, whoſe antecedent or conſequent is the antecedent or conſequent of the other; thus, $A : B :: C : \frac{BC}{A}$ (38), and conſequently the ratio of $A : B$ being equal to that of $C : \frac{B \times C}{A}$, is greater or leſs than the ratio of $C : D$, according as $\frac{BC}{A}$ is leſs or greater than D.

Let

Let the ratios of 3 : 5 and of 6 : 9 be compared; and 3 : 5 :: 6 : $\frac{30}{3}$ (10), therefore the ratio of 3 : 5, being the same with that of 6 : 10, is a greater negative ratio than that of 6 : 9.

46. *The second method of comparing ratios, is to divide the antecedents by their respective consequents, and that ratio will be the greatest, the quotient of whose terms is the greatest.*

EXAMP. The ratio of $A : B$, being equal to that of $C : \frac{BC}{A}$ (38), is greater than, equal to, or less than the ratio of $C : D$, according as $\frac{B \times C}{A}$ is less than, equal to, or greater than D, or $\frac{C}{A}$ less than, equal to, or greater than $\frac{D}{B}$, or $\frac{A}{C}$ greater than, equal to, or less than $\frac{B}{D}$. This method is expeditious and true, but let it be remembered that $\frac{A}{B}$ is a number as every quotient is, and does not measure the ratio of $A : B$, nor is the relative magnitude or ratio of the ratios of $A : B$ and $C : D$ equal to the ratio of $\frac{A}{B} : \frac{C}{D}$.

47. *The third method of comparing ratios. If* A *be contained between* $\frac{m}{n} \times$ B *and* $\frac{m+1}{n} \times$ B, *and* C *be contained between* $\frac{m}{n} \times$ D *and* $\frac{m+1}{n} \times$ D, *the ratios of* A : B *and* C : D *are equal: if therefore* A *be greater than* $\frac{m}{n} \times$ B *and* C *be not greater than* $\frac{m}{n} \times$ D, *or if* n A *be greater than* m B, *but* n C *not greater than* m D, *the ratio of* A : B *is greater than that of* C : D.

EXAMP.

EXAMP. Let the ratios to be compared be 7 : 5 and 4 : 3. Multiply the first and third by 3, and the second and fourth by 4, and the resulting numbers are 21, 20, 12, 12; and the first multiple being greater than the second, but the third not greater than the fourth, 7 has to 5 a greater ratio than 4 : 3.

48. DEF. *Any magnitude* A *is said to be, or vary, directly as another* B, *when* A *is to any new value of* A *as* B *to a corresponding new value of* B, *that is, when* A : a :: B : b, a *and* b *being corresponding new values of* A *and* B.

FIG. IV. EXAMP. I. If the line mn move parallel to itself, and its extremities m and n be always in the lines LP, LQ; Lm varies as mn. For $LA : La$ (a new value of Lm) :: $mn : AB$ (a corresponding new value of mn).

EXAMP. II. The area Lmn varies directly as the square of Lm or mn; for $Lmn : LAB$ (a new value of Lmn) :: $mn^2 : AB^2$ (the square of a new value of mn).

49. DEF. *Any magnitude* A *is said to be, or vary, inversely as another* B, *when* A *is to a new value of* A, *as a cotemporary new value of* B *is to* B, *or when* A : a :: b : B.

EXAMP. I. In the lever the power is inversely as the perpendicular let fall from the center of motion upon its direction; for let F and f be two powers in equilibrio, P and p the perpendiculars let fall from the center of motion upon their directions; and $F : f$ (a new value of the power) :: p (the perpendicular let fall upon f's direction) : P.

EXAMP.

EXAMP. II. If a given ſpace be deſcribed in different times T and t, with unequal uniform velocities V and v, the velocities and times are inverſely as each other; for $V : v$ (a new value of the velocity) $:: t$ (a new value of the time correſponding to v) $: T$.

EXAMP. III. If two variable right lines AB, AC form the equal rectangles AD, EF, they are inverſely as each other; for (Euc. VI. 14.) $AB : CF$ (a new value of AB) $:: CE$ (a new value of AC) $: AC$. FIG. V.

SCHOLIUM.

50. When any quantity A varies directly, or inverſely as any other B, an analogy is always implied, and A and B are not neceſſarily homogeneous.

51. Cor. 1. If A be directly as B, and B directly as C, A will be directly as C; for (48) $A : a :: B : b$ and $B : b :: C : c$, therefore (39) $A : a :: C : c$, and A is directly as C (48).

52. Cor. 2. If A be as B and B as C, A will be as $B \pm C$, or as $\sqrt{BC}$; for $A : a :: B : b :: C : c$, and (43) $B : b :: B \pm C : b \pm c$; therefore (39) $A : a :: B \pm C : b \pm c$, and A is as $B \pm C$ (48): and becauſe the ratios of $B : b$ and $C : c$ are equal, $B^2 : b^2 :: BC : bc$ and $B : b :: \sqrt{BC} : \sqrt{bc}$. B therefore, and conſequently A (51), is as $\sqrt{BC}$.

53. Cor. 3. A varies as $m \times A$, or as $\frac{A}{m}$; for $A : a :: m \times A : m \times a$, or as $\frac{A}{m} : \frac{a}{m}$ (41); therefore (48) A is as $m \times A$, or as $\frac{A}{m}$.

54. Cor. 4. If A be as B, A^2 will be as B^2, and A^m as B^m, and $A^{\frac{1}{m}}$ as $B^{\frac{1}{m}}$; for ſince $A:a::B:b$ (48) $A^m:a^m::B^m:b^m$, or $A^{\frac{1}{m}}:a^{\frac{1}{m}}::B^{\frac{1}{m}}:b^{\frac{1}{m}}$ (42); therefore A^m is as B^m and $A^{\frac{1}{m}}$ as $B^{\frac{1}{m}}$ (48).

55. Cor. 5. If S be as $V \times T$, $\frac{S}{T}$ will be as V, $\frac{S}{V}$ as T, and $\frac{S}{V \times T}$ a given quantity: for (48) $S:s::VT:vt$ and $\frac{S}{V}:\frac{s}{v}::T:t$ and $\frac{S}{T}:\frac{s}{t}::V:v$, and $\frac{V}{VT}:\frac{s}{vt}::1:1$ (41); therefore $\frac{S}{V}$ is as T, $\frac{S}{T}$ as V, and $\frac{S}{VT}$ does not vary (48).

56. Cor. 6. If A be as B, and C as D, $A \times C$ will be as $B \times D$; for $A:a::B:b$ and $C:c::D:d$; therefore the ratios of $A:a$ and $C:c$ are equal to the ratios of $B:b$ and $D:d$, and the ſums of theſe ratios are equal, or the ratio of $AC:ac$ is equal to that of $BD:bd$ (18), and $AC:ac::BD:bd$ (34), and AC is as BD (48).

57. Cor. 7. If A be inverſely as B, then B will be inverſely as A; for $A:a::B:b$ (49) and $b:B::a:A$; and if B be to b as 4:5, $A:a::5:4$.

58. Cor. 8. If A be directly as B, and B inverſely as C, A will be inverſely as C; for $A:a::B:b$ (48) and $B:b::c:C$; therefore $A:a::c:C$ (39), and A is inverſely as C (49).

59. Cor. 9. If A be inverſely as B, and B inverſely as C, A will be directly as C: for $A:a::b:B$ and $b:B::C:c$, therefore $A:a::C:c$ and A is as C.

60. Cor.

60. Cor. 10. If $A \times B$ be always the ſame, A is inverſely as B; for $A \times B : a \times b :: 1 : 1$ and $A : a :: b : B$; or otherwiſe, ſince $A \times B = a \times b$, $A : a :: b : B$ (38).

61. Cor. 11. If A be inverſely as B, it will be as $\frac{1}{B}$ and $v . v$; for $A : a :: b : B$ (49) $:: \frac{1}{B} : \frac{1}{b}$ (41), therefore A is as $\frac{1}{B}$ (48). If A be as $\frac{1}{B}$, $A : a :: \frac{1}{B} : \frac{1}{b}$ (48) $:: b : B$ (41); and A is inverſely as B (49).

62. Cor. 12. If A be as $\frac{L}{M}$, A will be inverſely as $\frac{M}{L}$; for $A : a :: \frac{L}{M} : \frac{l}{m}$ (48) $:: \frac{m}{l} : \frac{M}{L}$ (41); and A is inverſely as $\frac{M}{L}$ (49).

63. DEF. *If any quantity* A *be dependent upon ſeveral others* P, Q, R, S, T, *all independent of each other, ſo that none of the quantities* P, Q, R *can vary, but* A *varies in the ſame ratio, nor either* S *or* T *can vary, but* A *varies in a contrary ratio;* A *is ſaid to be as* P *and* Q *and* R *directly, and* S *and* T *inverſely.*

Thus, the fraction $\frac{LMN}{XZ}$ varies as L and M and N directly and X and Z inverſely; becauſe none of the factors in the numerator can vary, but the value of the fraction varies in the ſame ratio; and none of the factors in the denominator can vary, but the value of the fraction varies in a contrary ratio. If any one of the factors in the numerator be multiplied by 2, 3, &c. the value of the fraction is 2, 3, &c. times its former value; and if any of the factors in the denominator be multiplied by 2, 3, &c. the value of the fraction becomes $\frac{1}{2}$, $\frac{1}{3}$, &c. of its former value.

64. Cor. 1. If any magnitude A vary as P and Q and R directly, and as X and Z inverſely, theſe magnitudes being independent of each other, and any one may vary without affecting the reſt, A will vary as $\frac{P \times Q \times R}{X \times Z}$. For let any new cotemporary values of P, Q, R, X, Z, be reſpectively equal to p, q, r, x, z, and let A, when changed in the ratios of $P : p$, $Q : q$, $R : r$, $\frac{1}{X} : \frac{1}{x}$, and $\frac{1}{Z} : \frac{1}{z}$, become a; that is,

Let $P : p :: A : B =$ A's value after the change of P.
$Q : q :: B : C =$ A's value after the change of P, Q.
$R : r :: C : D =$ A's value after the change of P, Q, R.
$\frac{1}{X} : \frac{1}{x} :: D : E =$ A's value after the change of P, Q, R, X.
$\frac{1}{Z} : \frac{1}{z} :: E : a =$ A's value after the change of P, Q, R, X, Z.

The ſum of the ratios of $A : B$, $B : C$, $C : D$, $D : E$, $E : a$, or the ratio of $A : a$ (16) is equal to the ſum of the ratios of $P : p$, $Q : q$, $R : r$, $\frac{1}{X} : \frac{1}{x}$, $\frac{1}{Z} : \frac{1}{z}$, or to the ratios of $\frac{PQR}{XZ} : \frac{pqr}{xz}$ (18); and A varies as $\frac{PQR}{XZ}$ (48).

65. Cor. 2. If any of the quantities P, Q, R, X, Z be given or remain invariable, they are to be rejected, and A will vary as the reſt. Let P be given or $P = p$, and, becauſe $P : p :: A : B$, $A = B$ (38), and the ratios of $B : C$, $C : D$, $D : E$, $E : a$, or the ratio of $B = A : a$, is equal to the ratio of $\frac{QR}{XZ} : \frac{qr}{xz}$ (18), and A is as $\frac{QR}{XZ}$ (48). Let Q be alſo given or $Q = q$, and $A (= B = C) : a :: \frac{R}{XZ} : \frac{r}{xz}$, or A is as $\frac{R}{XZ}$ (48). Hence may be underſtood what is meant by philoſophical writers, when they ſay the velocity (V) varies

varies as the ſpace (S) directly, and the time (T) inverſely, or as $\frac{S}{T}$; and, if T be given, V is as S, and, if S be given, V varies as $\frac{1}{T}$.

66. EXAMP. I. The number of feet (S) deſcribed in any time (T), with an uniform velocity (V), encreaſes or decreaſes directly with V and T, both of which are independent of each other, and therefore varies as $V \times T$. If V be doubled or encreaſed in the ratio of 2 : 1, and T be encreaſed in the ratio of 3 : 1, S will be encreaſed in the ratios of 2 : 1 and 3 : 1, or of 6 : 1.

67. EXAMP. II. The quantity of matter (Q) in different bodies varies as the magnitude (M) multiplied into the denſity (D). For if the magnitude vary in the ratio of $M : m$, and the denſity or cloſeneſs of the conſtituent parts, in the ratio of $D : d$, the quantity of matter will be changed according to both theſe ratios, or $Q : q :: M : m$ and $D : d :: M \times D : m \times d$, or Q varies as $M \times D$ (48).

68. EXAMP. III. The velocity (V) of a body moving uniformly in the peripheries of different circles, varies as the radius (R) directly, and periodic time (P) inverſely. For, if P remain conſtant whilſt the ſpace deſcribed or periphery varies, the velocity will encreaſe or decreaſe directly as the ſpace, or as R, becauſe the peripheries of circles are as their diameters; and if the periodic time be encreaſed in the ratio of 2 or 3 : 1, or univerſally in the ratio of $P : p$, the velocity will be changed in the ratio of 1 : 2 or 3, or of $p : P$. If therefore the radius be changed in the ratio of $R : r$, and periodic time in the ratio of $P : p$, and V become v, $V : v$ as $R : r$, and $\frac{1}{P} : \frac{1}{p}$, or as $\frac{R}{P} : \frac{r}{p}$, and the velocity is as $\frac{R}{P}$ (48).

69. Ex-

69. EXAMP. IV. If V be the velocity communicated, by the action of a force F, to a quantity of matter repreſented by $\mathcal{Q}$, and theſe quantities be ſuppoſed to vary, V will be as $\frac{F}{\mathcal{Q}}$; for if the force become $2F$, $3F$, &c. the velocity will become $2V$, $3V$, &c. and if a quantity of matter become $2\mathcal{Q}$, $3\mathcal{Q}$, &c. the velocity communicated will be $\frac{V}{2}$, $\frac{v}{3}$, &c. and V therefore is as $\frac{F}{\mathcal{Q}}$ (64).

A SYSTEM

A SYSTEM OF NATURAL PHILOSOPHY.

MECHANICS.

MECHANICAL philoſophy acquired the name from its utility in the conſtruction of machines; but it is now, in a more general ſenſe, underſtood to comprehend two branches of ſcience, cultivated at different periods of time, denominated Statics, or the ſcience of the equilibrium and relation of powers, and Dynamics, or the ſcience of actual motion. The firſt profeſſes to deſcribe the conſtruction, properties, and mechanical advantages of machines, and their various combinations, calculated to ſuſtain the preſſure of heavy bodies and facilitate their motion; and to inveſtigate the equilibrium of powers acting upon them, or their relative magnitudes, when by oppoſite exertions they deſtroy each other's effect or remain quieſcent. This branch comprehends that part called the mechanical powers, and is ſometimes called practical mechanics. The object of dynamics is the nature, geneſis, and change of actual motion, or an inveſtigation of the direction,

rection, quantity, and law of variation, of a force or power capable of generating any motion or change of motion; and vice versâ. This comprehends the laws by which all motions are regulated, the motions resulting from colliſions, the theory of oſcillations, projectiles, and centripetal forces, and is ſometimes called rational mechanics. The principles of ſtatics were calculated and eſtabliſhed by Archimedes, and have, ſince that period, been almoſt exhauſted by the labours of ſucceeding writers. Galileo demonſtrated the laws of deſcent of heavy bodies, and from him originated the ſcience of dynamics, which has ſince been proſecuted to an amazing extent in Euler's Mechanica, and Newton's Principia. As the objects of mechanical philoſophy are the equilibrium and motions of bodies; a deſcription of the different qualities, or mechanical affections of matter, producing preſſure, motion, and other phenomena, ought to be premiſed. Mechanics therefore might with great propriety be divided into two parts; of which the firſt would contain the properties of matter, or the exiſtence, intenſity at a given diſtance, and laws of variation at different diſtances, of thoſe general principles which are the apparent origin of motion, and the continuation of motion in the material world, inveſtigated by analyſis: and the ſecond would be an application of theſe principles, containing ſynthetic demonſtrations of their effects upon machines, commonly called the mechanical powers, when in equilibrio, and their relation to actual motions, rectilineal and curvilineal, uniform and variable. This is the moſt obvious diviſion of the ſubject, and every deviation from it muſt be attributed to the deſign of this ſelection, which is ſolely the utility of the academic ſtudent.

CHAP.

MATTER, AND ITS PROPERTIES.

CHAP. I.

OF MATTER.

70. MATTER is the ſubſtance employed in the formation of that part of the creation, whoſe exiſtence is evidenced by the teſtimony of the ſenſes; and the moſt characteriſtic and prominent marks of it ſeem to be extenſion and ſolidity. Indeed ſolidity is the moſt diſcriminating mark of matter, as it diſtinguiſhes it from every thing elſe; but taſtes, ſmells, ſounds equally indicate the exiſtence, though whatever is ſolid and extended is the common and moſt general deſcription, of matter. Many other qualities invariably adhere to all matter with which we are acquainted, whether hard, ſoft, or fluid; and from our ignorance of its internal conſtitution, or that latent principle, by whoſe influence its qualities are connected, and from which they neceſſarily derive their origin, theſe, and many others inacceſſible to the ſenſes, may be ingredients in its eſſence. All our knowledge of matter, as far as it is related to the preſent ſubject, is either geometrical, or philoſophical: the firſt conſiders matter as being of ſome magnitude, or circumſcribing ſpace and having ſome figure, then called body, and is uſually denominated ſtereometry, or the menſuration of magnitudes of three dimenſions, length, breadth, and thickneſs; and the ſecond comprehends all the properties of matter addreſſed to the ſenſes, which may be ſtiled phyſical or philoſophical, becauſe all the phenomena of nature are conceived to reſult imme-

diately from them; as extenſion, ſolidity, inertia, and thoſe apparently more active qualities, gravity, magnetiſm, electricity, coheſion, elaſticity. Theſe laſt are called mechanical affections of matter, or mechanical cauſes, becauſe they are conceived to reſide in matter, and all mechanical phenomena, or changes of motion obſervable in the material world, appear to be directed by their neceſſary and uniform agency. The philoſophical properties of matter are diſtinguiſhable into two kinds, general, and ſpecific: the firſt are ſuch as univerſally adhere to every ſpecies of matter, and of which no art hath been able to diveſt them, as *extenſion*, *ſolidity*, *mobility*, *quieſcibility*, *inertia*, *figure*, *attractions and repulſions*, and probably many more which are too ſubtle for the obſervation of ſenſe, or have yet eluded the inquiſition of the philoſopher; and the ſecond are ſuch as are attached only to particular ſpecies of matter, as opacity, tranſparency, hardneſs, fluidity, colour, magnetiſm, elaſticity, &c. Another diſcrimination of theſe qualities is, that ſome are incapable of intenſion or remiſſion, as extenſion, ſolidity, inertia, mobility, figure, which are inſeparable from a body and its component parts; and others are relative and capable of encreaſe and decreaſe, as attractions and repulſions, whoſe intenſity depends upon the magnitude and diſtance of the attracting or repelling bodies, and as that magnitude and diſtance may vary without limit, the influence of theſe powers may, by remoteneſs, decreaſe without limit, and become evaneſcent. A knowledge of the exiſtence, and diſcrimination of theſe qualities, is entirely derived from experiment and obſervation, and conſtitutes the ſum of all that is known concerning matter. The internal conſtitution of it is unknown, and its effects cannot be inveſtigated without the aſſiſtance of experience; and whether any more, beſides thoſe eight general properties enumerated, belong to it, and what, or whether any, connection ſubſiſt between thoſe already diſcovered, and to what particular conſtitution ſpecific qualities are owing, muſt be derived from the ſame ſource, experiment, and if ever diſcovered, will probably reſult from the labour of the chymiſt.

CHAP.

CHAP. II.

Of EXTENSION.

71.* THERE are three kinds of extenſion, lineal, as the line *AB*; ſuperficial, having length and breadth, as *ABCD*; and ſolid, having length, breadth and thickneſs, as *AH*. Ideas of theſe three kinds of extenſion are undefinable, and only to be acquired by the ſenſes of ſeeing and feeling. The perceptions introduced to the mind by ſeeing or feeling two diſtant parts of the line *AB*, a ſurface *ABCD*, and material body *AH*, convey reſpectively the meaning of lineal, ſuperficial and ſolid extenſion; which are diſſimilar magnitudes, and incapable of compariſon with each other. A line, having no breadth, cannot, however repeated, conſtitute a ſurface; and a ſurface, having no thickneſs, cannot conſtitute a ſolid. The parts of a line, though divided without limit, are ſtill lineal extenſion, and the parts of a ſurface, or ſolid, though divided into a number of parts unaſſignably great, are ſtill ſuperficial and ſolid extenſion. This quality is ſo far eſſential to matter that it cannot be diveſted of it, or conceived to exiſt without it. FIG. VIII.

72. DEF. *A magnitude is ſaid to be finite when an equal to it can be aſſigned, or when its encreaſe and decreaſe are limited within aſſignable bounds.*

73. DEF. *A magnitude is ſaid to be infinitely great or ſmall, when no finite ratio obtains between it and a finite magnitude, or when its encreaſe or decreaſe is not limited by any aſſignable boundary.*

74. PROP.

* Keil's Phyſics. Muſchenbroek.

FIG. VI. 74. PROP. *A finite right line* EX *is divisible in infinitum.*

DEM. A mathematical point *A* may be taken between *X* and *E*, and another *B* between *A* and *E*, and this process may be continued without limit, because the intermediate points *A*, *B*, &c. having no length, can never coincide with *X* or *E*, or with each other. Q. E. D.

FIG. VII. Otherwise: Through *E* and *X* draw *EP*, *XC* parallel to each other, and, because they never meet, a number of points *a*, *b*, *c*, *d*, &c. greater than any assignable number may be taken in *XC*; and if right lines be drawn from them to any point *P* on the other side of *EX*, they will divide it into a number of parts equal to the number of points *a*, *b*, *c*, &c.: for if they did not, two lines must pass through the same part, that is, either intersect each other in *EX*, or coincide till they arrive at it, and then diverge, both of which are impossible. There is therefore no assignable limit to the divisibility of *EX*. Q. E. D.

FIG. VIII. 75. Cor. 1. The finite surface *ABCD* is infinitely divisible; for it is equally divided with *AB*, by drawing mathematical right lines *pf*, *qg*, *rh*, &c. from the points *p*, *q*, *r*, &c. parallel to *AD*, which having no breadth cannot coincide. If *ABCD* be a boundary of the solid *AH*, and mathematical planes be drawn through *pf*, *qg*, *rh*, &c. parallel to *AF*, they cannot coincide, having no thickness, and consequently will divide the solid into the same number of parts with the surface *ABCD*, or line *AB*.

76. Cor. 2. Every finite line, surface and solid, is therefore composed of an unlimited number of parts; and each of these parts
FIG. IX. is composed of an unlimited number, &c. For let *LM* be infinitely greater than *Ln*, and take *LM* : *Ln* :: *Ln* : *Lo* :: *Lo* : *Lp*, &c.; and drawing any finite line *MA*, making an angle with *LM*, and

and nB, oC, pD, &c. parallel to MA and terminated by LA; MA is infinitely greater than nB; nB than oC; oC than pD, &c. But MA is infinitely divisible, and right lines, drawn from L to the points of division, will cut nB, oC, &c. into the same number of parts with it.

77. Cor. 3. Matter is therefore infinitely divisible, because extended. And this proposition and corollaries are applicable to magnitudes of every kind, as velocities, forces, times, &c.

SCHOLIUM.

78. The terms infinitely great and small are relative, and imply a comparison with an assignable magnitude, and compared with it, all infinitely great or small magnitudes are to each other in a ratio of equality; but, compared with each other, they admit of the same inequality of ratios with finite magnitudes. The line AM is infinitely divisible, and if the points of division be equidistant, any one part xy, multiplied into their number, is equal to AM; and $xy : AM ::$ unity: a number unassignably great, or xy is an infinitesimal of the first order. The infinitesimal xy is infinitely greater than wt, and wt than rs; for $xy : wt :: wt : xs :: LM : Ln$. But infinitesimals of the same order may be to each other in any assignable ratio; for, let LM be to LF as 3, 4, 5, or or $m : 1$, and FG, being drawn parallel to MA, will be equally divided with it, and the infinitesimal $vz : xy :: LM : LF :: 1 : 3, 4, 5,$ or any number m. This is called the mathematical divisibility of matter, and is equally applicable to space and all other magnitudes, which may be represented by extension; but that an actual divisibility, or actual separation of the parts of matter, is limited by certain inviolate bounds, is inferred from the identity of natural substances.

PHENOM. I. Salt dissolved in a menstruum, becomes the same salt when the menstruum is supposed to dry gradually. Salt converted

verted, by a chymical proceſs, to an acid ſpirit, is, by reverſing the proceſs, regenerated into the ſame ſalt. Metals liquidated by fire, are reſtored to their priſtine ſtate by the attraction of coheſion. But were the decompounded particles of the ſalt, or metal, attenuated by the action of the menſtruum or fire, and again to coaleſce by their coheſive force, ſubſtances of a different texture and appearance, and of different ſpecific gravities, would reſult. The moſt powerful natural agent, with which we are acquainted, is fire; which, whether artificial or collected in the focus of a burning glaſs, only attenuates bodies to a limited degree by converting them into a thick ſmoke, glaſs, &c. Every ſpecies of matter fluctuates and decays by the ſeparation of its component parts, and is renovated by their acceſſion; but were the nutritious particles, adminiſtering to the encreaſe of natural ſubſtances, capable of diviſibility or diminution by attrition, &c. new ſpecies of ſubſtances would reſult with new properties and characters. Water and earth, compoſed of old particles, and fragments of particles produced by attrition, would have a different ſpecific gravity, from water and earth compoſed of entire and unbroken particles; and the nature and textures of theſe and all other ſubſtances would by repeated attritions, be perpetually changing, which is contrary to experience. Bodies therefore break, not in the midſt of ſolid particles, but where thoſe particles cohere in a few points; and the diviſibility of matter is only a ſeparation of its conſtituent parts, effected by a diſſolution of that coheſive force which unites them, and is limited by ultimate elementary particles which are a perfect repletion of ſpace, without pores and indiviſible.

CHAP.

CHAP. III.

OF SOLIDITY.

79. THE ſecond philoſophical quality of matter is that by which it occupies ſpace to the excluſion of all other matter, and is called its ſolidity; but the meaning of it cannot be conveyed by words, being undefinable and only to be acquired by the ſenſe of touching. The perception introduced to the mind by the inſuperable reſiſtance felt in a body is an idea of ſolidity. This reſiſtance, and total excluſion of matter from ſpace already occupied, is inſeparable from all matter with which we are acquainted, whether hard, ſoft, or fluid; and the little reſiſtance experienced in ſome bodies, is not owing to a want of ſolidity, but to their fluidity and ſoftneſs, by which qualities their component parts are eaſily diſplaced. That hard and ſoft bodies are ſolid, and cannot occupy the ſame part of ſpace, appears from uncontroverted experience; for the oppoſite ſides of the ſubſtance compreſſing them are never found to meet, but by removing the intervening parts. And the ſame is diſcovered to obtain in all fluids within the reach of obſervation; for no portion of water, air, mercury, &c. can occupy the ſame place, becauſe they afford an inſuperable reſiſtance preventing the coincidence of the oppoſite ſides of the ſubſtance compreſſing them; and their dimenſions are never found to be diminiſhed by preſſure without an adequate cauſe, viz. compreſſibility, and tranſmiſſion through the vacuities of the veſſel containing them. Numberleſs facts demonſtrate electric and magnetic effluvia, whoſe parts are immeaſurably minute, to be capable of impulſe and reſiſtance like other fluids; and it is inferred from analogy, that theſe fluids, circumſcribed and compreſſed by plane ſurfaces, would invariably oppoſe their junction, were the vacuities in thoſe ſurfaces leſs than the particles of

the fluids. Solidity therefore is an univerſal attribute of matter, but its cauſe is unknown and probably undiſcoverable by human faculties. The approach of one body to another is apparently limited by the actual contact of their neareſt parts, which abſolutely fill the ſpaces occupied by them, and conſequently a nearer acceſs and greater ſurfaces of contact, only reſult from their diſlocation; but this is not allowed without controverſion. Compreſſibility, contraction by cold, elaſticity, &c. prove that the minute parts of ſome bodies are not in mathematical contact, and their reſiſtance is an indication of repulſion; and the nearer acceſs therefore of two bodies is imagined to be impeded by a ſtrong repulſive power, which being overcome, a mutual penetration of parts enſues, and the bodies occupy the ſame part of ſpace. But this doctrine is ſtill only hypothetical; and though the minute parts of ſome bodies do exert an influence at a diſtance, and a repulſive power be confeſſed to obtain between them, it cannot be concluded, generally, to be the only cauſe preventing their nearer approach, nor admitted as a general principle in nature, contrary to the common apprehenſion of mankind, till eſtabliſhed by ſatisfactory and uncontroverted experiments. The tranſmiſſion of one body through another, and apparent penetration of parts, ſeem, and may be conceived, to reſult from empty unoccupied ſpace between thoſe parts; and the quantity of theſe vacuities is collected from the following phenomena.

80. PHENOM. Many vacuities or pores are actually viſible, through a microſcope, in every ſpecies of animals, vegetables and foſſils. The bottom of the ſea is viſible at a greater depth than ſixty feet. A man's finger, placed before the aperture of a dark chamber, is tranſparent by the paſſage of light through its pores: and light is tranſmitted in almoſt every direction through glaſs and water, and when condenſed three thouſand times in the focus of a burning glaſs, it ſeems to be admitted into water and glaſs without obſtruction. Electric effluvia paſs through gold with a velocity unaſſignably great, and the magnetic power is tranſmitted through every ſpecies of matter, except iron, without diminution.

The

The volatile ſpirit of ſulphur tinges, with a brown colour, ſilver ſurrounded with repeated coverings of cloth or paper; the ſcents of muſk, civet, &c. paſs through wood. Air and water imbibe each other; oils penetrate the vacuities of ſulphur and ſome ſtones; mercury penetrates the pores of gold, braſs, and is tranſmitted through human ſkin, leather, &c.; water is tranſmitted through the membranes of animals, and the fine tubes of vegetables, and may, by compreſſion, be forced through gold, ſilver, &c.* From numberleſs chymical experiments it appears, that all animals, vegetables, and foſſils, yield water plentifully by the force of heat; and all bodies, whether hard or fluid, admit the particles of fire into their pores, through which it paſſes and is diſſipated.

81. DEF. *The magnitude of a body is the magnitude of ſolid extenſion, that is, length, breadth and thickneſs, or the number of cubical inches contained in it.*

82. DEF. *The quantity of matter in a body is the number of equal particles contained in it. If the matter compoſing different bodies be reduced to equal particles without pores, the quantity of matter in each will be equal to one particle multiplied reſpectively into their number.*

83. DEF. *Denſity of a body is the contiguity, or cloſe adheſion, of its particles; but this term uſually implies the ratio obtaining between the number of equal particles, or quantities of matter, in bodies of the ſame magnitude.*

84. DEF. *Homogeneous bodies are thoſe which have the ſame denſity in every part; heterogeneous are thoſe which have not.*

85. DEF.

* In the celebrated Florentine experiment, a quantity of water was encloſed in a hollow ſphere of ſilver, and then forcibly compreſſed by ſcrews, till the fluid was ſeen to ooze through the pores of the metal and cover its ſurface like a dew.

85. DEF. *The porosity of a body is the remoteness of its elementary particles, or the ratio of the quantities of vacuity in different bodies of equal bulk.*

86. PROP. *If* Q, D, B *represent respectively the quantity of matter, density, and magnitude, of a body, and be supposed to vary;* Q *will vary as* D × B.

DEM. If D, or B, be encreased or diminished in the ratio of 2, 3, &c. to 1, $\mathcal{Q}$ will evidently be encreased or diminished in the same ratio, and D and B are unconnected; therefore (64) $\mathcal{Q}$ is as $D \times B$. Q.E.D.

87. Cor. 1. Since $\mathcal{Q}$ is as $D \times B$, if q, d, b be cotemporary new values of $\mathcal{Q}, D, B$; $\mathcal{Q} : q :: DB : db$, and $\frac{\mathcal{Q}}{D} : \frac{q}{d} :: B : b$, & $\frac{\mathcal{Q}}{B} : \frac{q}{b} :: D : d$ (41); or if D be given, $\mathcal{Q}$ is as B; and if B be given, $\mathcal{Q}$ is as D; and if $\mathcal{Q}$ be given, D is $\frac{1}{B}$ and B as $\frac{1}{D}$. This cor. follows also from (65).

88. Cor. 2. If numbers, or lines, whose ratio is the same with that of D and B, be substituted for them, $\mathcal{Q}$ is properly expressed by the product of these numbers, or a rectangle whose sides are these lines.

89. Cor. 3. If the density of a body be encreased in the ratio of 2, 3, &c. to 1, the porosity (P) will be diminished in the ratio of 1 to 2, 3, &c.; and consequently P is as $\frac{1}{D}$, or (87) as $\frac{B}{\mathcal{Q}}$. If B be given, P is as $\frac{1}{\mathcal{Q}}$; and if $\mathcal{Q}$ be given, P is as B; and P being given, B is as $\mathcal{Q}$.

EXAMP.

EXAMP. I. The denſity of gold is to that of water as $19\frac{1}{2} : 1$, and conſequently the relative quantity of pores in gold and water is as $1 : 19\frac{1}{2}$. The relative denſities of gold and cork are as $81\frac{1}{3} : 1$, and their quantities of pores therefore as $1 : 81\frac{1}{3}$. If one half of the magnitude of gold were vacuous, the relative quantities of pore and ſolid parts in the water and cork, would be reſpectively as 39 : 1 and 163 : 1.

EXAMP. II. If a body whoſe magnitude is A were conſtructed of particles cohering in ſuch a manner as to have $\frac{1}{2}$ of its magnitude vacuous, and theſe particles were ſimilarly conſtructed of other leſs particles having $\frac{1}{4}$ of their magnitude vacuous, and the third order of particles were elementary, and a perfect repletion of ſpace, the quantity of vacuity would be equal to $A \times \frac{1}{2} + A \times \frac{1}{2} \times \frac{1}{4} + A \times \frac{1}{2} \times \frac{1}{2} \times \frac{1}{8} = A \times \overline{\frac{1}{2} + \frac{1}{4} + \frac{1}{8}} = A \times \frac{7}{8}$. And the magnitude of vacuity is to the magnitude of matter as 7 : 1.

SCHOLIUM.

90. What the figure and magnitude of the elementary particles of matter are, cannot be known from the ſenſes, which, with every microſcopical aſſiſtance, are unable to diſcern them. An elementary particle of matter hath probably never yet been ſeen. A number of elementary particles, uniting by the power of coheſion, form greater particles; and theſe, uniting again by the ſame power, form greater ſtill; and, this proceſs being made repeatedly, a corpuſcle is at length formed of a ſenſible bulk. All bodies ſeem to be compoſed of theſe derivative corpuſcles, which, formed of more or fewer repeated unions, compoſe bodies more or leſs denſe. Theſe derivative corpuſcles ſeem ſometimes to be ſimilar: if a beam of light be ſeparated by a priſm into ſmall coloured rays, and any ſlender ray of the ſame colour be minutely examined, its component parts ſeem to be ſimilar, becauſe they affect the ſight exactly in the ſame manner. Pure mercury ſqueezed through the pores of leather, or raiſed into fume, and received upon clean glaſs,

exhibit globules ſimilar and undiſtinguiſhable. This is alſo obſervable of the vapours of pure water. And, in other ſpecies of matter, the derivative particles are combined from others exactly ſimilar to them; a red globe of blood is obſerved, through a microſcope, to be compoſed of ſix yellowiſh ſerous globes, and every one of theſe is compoſed of ſix lymphatic globes; but farther the microſcope does not enable us to proceed. Every ſpecies of matter, however different in denſity, may be conceived to be formed of equal and ſimilar elementary particles. Thus, the particles
FIG. X. *A*, *B*, *C*, compoſed each of ſix equal elementary particles, are different; and theſe particles may, by a different combination, form different ſtill; and theſe repeated coalitions may, by changing the original and ſucceeding numbers and their poſitions, form maſſes of matter differing in endleſs variety.

UNIFORM MOTION.

91. From the ſolidity of matter, whether owing to repulſion or actual contact, reſults its capacity of impulſe or of being protruded, and conſequent mobility of body, as far as the cauſe of mobility ſeems to be known. If the body *A*, in motion, ſtrikes another body *B*, not retained in its place by any force, *B* will be protruded and move; becauſe, from their ſolidity, they cannot penetrate each other's dimenſions; and the communication of motion in this caſe is the neceſſary conſequence of ſolidity. Motion ſuppoſes the ſucceſſive exiſtence of the body moving in different parts of ſpace, and therefore cannot be underſtood without preſuppoſing a knowledge of ſpace and time; which therefore muſt be premiſed.

92. DEF. *Space is that which contains the whole ſenſible creation, is unlimited, and its parts are homogeneous, inſeparable, co-exiſting and unreſiſting.*

93. Cor. Since ſpace is unlimited in every direction, and its parts ſimilar and undiſtinguiſhable, any portion of it can only be aſcer-

aſcertained by its relation to ſome aſſumed ſenſible mark or object. Hence of place, which is a part of ſpace, there are two kinds, abſolute and relative.

94. DEF. *The abſolute place of a body is that portion of this unlimited ſpace, which is occupied by it when fixed and immoveable; and the relative place of a body is its ſituation with reſpect to ſome aſſumed mark or object, which itſelf may be moveable.*

95. Cor. The abſolute and relative place of a body coincide, when it and the aſſumed object are immoveable, or remain in the ſame part of fixed ſpace. But we cannot perceive the abſolute place of any object.

96. DEF. *Duration is that which flows uniformly, is unbounded, continuous, whoſe parts are ſimilar, and no two exiſt together.* An idea of duration is obtained by obſerving the interval between our ideas, or between the ſucceſſive appearances of any external object; and, as it is, ſtrictly, only meaſurable by a portion of duration, and no two parts exiſt together, conſequently cannot be compared by juxta poſition, time, which is a part of duration, is of two kinds, abſolute and relative.

97. DEF. *Abſolute time is a portion of duration, whoſe quantity is only known by a compariſon with another portion; and conſequently the relation between any two parts of abſolute time is undiſcoverable. Relative time is a part of duration which elapſes during any motion of body, or any ſucceſſion of external appearances.*

98. DEF. *An inſtant is the boundary between any two contiguous portions of time, as a point is the boundary of any contiguous lines; and a moment is any ſmall portion of time.*

99. DEF-

99. DEF. *Abſolute motion is a change of abſolute place, and abſolute reſt is a permanence in the ſame abſolute place.*

100. DEF. *The direction of motion is the poſition of the line upon which it is made. When the motion is rectilineal, its direction is this right line; when curvilineal, the direction is the tangent to that point of the curve where the moving point is.*

101. DEF. *Velocity is the quickneſs or ſlowneſs of motion, or the rate at which a body moves.*

102. DEF. *A body is ſaid to move with an uniform, accelerated, or retarded velocity, when it continues the ſame, encreaſes, or decreaſes. When the encreaſe, or decreaſe, of velocity is the ſame in any equal times, the acceleration, or retardation, is ſaid to be uniform; and when this encreaſe or decreaſe of velocity, encreaſes or decreaſes in any equal times, the acceleration, or retardation, encreaſes or decreaſes in the ſame ratio.*

103. DEF. *The line joining all the ſucceſſive places, through which a moving body paſſes, is called the ſpace deſcribed.*

104. PROP. *If* S *repreſent the ſpace uniformly deſcribed with the velocity* V *in the time* T, *and theſe magnitudes be ſuppoſed to vary,* S *will vary as* V × T.*

DEM.

* This propoſition is proved, not inelegantly, by the following proceſs: Let S and s be reſpectively deſcribed uniformly, with the velocities V and v, in the times T and t; and $T : t :: S : \frac{S \times t}{T}$ (38) = the ſpace deſcribed in the time t with an uniform velocity equal to V; and $\frac{S \times t}{T} : s :: V : v$ and $S \times t \times v = s \times V \times T$ (37), and (38) $S : s :: V \times T : v \times t$. Q. E D.

DEM. If either V or T be encreaſed or diminiſhed in the ratio of 2, 3, 4 .... n : 1, the ſpace will evidently be encreaſed or diminiſhed in the ſame ratio; and becauſe V and T are unconnected, or either of them may be changed without affecting the other, S will vary as $V \times T$ (64). Q. E. D.

105. Cor. 1. Becauſe S is as $V \times T$, V will be as $\frac{S}{T}$, T as $\frac{S}{V}$, and, if S be given, T as $\frac{1}{V}$ and V as $\frac{1}{T}$ (65).

106. Cor. 2. If V be given, S is as T, or the ſpaces deſcribed, with the ſame uniform velocity, are true meaſures of time, and may be ſubſtituted for it. And, T being given, S is as V, or the ſpaces deſcribed in the ſame time uniformly, are meaſures of the velocity: if V, or any other ſymbol, be called velocity, it denotes the length or number of feet deſcribed uniformly in one ſecond, or any other time. Let any values of the velocity be to each other as $A : B$, or as 3 : 2, and any cotemporary values of the time be as $C : D$, or as 5 : 4, and the ſpaces deſcribed will be to each other as $X : Z$, or as $3 \times 5 : 2 \times 4$. PLATE I. FIG. III.

107. Cor. 3. If lines therefore be ſubſtituted for V and T, the ſpace S will be as the rectangle, whoſe ſides are theſe lines; and, if numbers be ſubſtituted for them, the ſpace will be equal to the product of theſe numbers, the time equal to the quotient of the ſpace divided by the velocity, and the velocity equal to the quotient of the ſpace by the time. Let V be equal to n feet in one ſecond, and $T = p$ ſeconds; and S is actually equal to $n \times p$ feet, T actually equal to $\frac{S}{V}$ ſeconds, and $V = \frac{S}{T}$ feet in one ſecond.

VARIABLE MOTION.

108. PROP. *In variable finite velocities, the velocity during an infinitely small time, is uniform.*

DEM. The encreaſe, or decreaſe of velocity produced in any finite time, is finite, and, if the whole encreaſe or decreaſe be divided into any infinite number of increments or decrements, each will be infinitely ſmall and vaniſh, compared with the whole velocity, which therefore is uniform. Q. E. D.

109. Cor. If therefore S', V', T', repreſent correſponding increments of S, V, T, reſpectively; V' will be evaneſcent compared with V; S' will vary as $V \times T'$ (104), V as $\frac{S'}{T'}$, and T' as $\frac{S'}{V}$ (105).

PLATE I. FIG. XI.

110. PROP. *If the abſciſſa* AS *of any curve* DEF *repreſent the whole time, and the ordinates* AD, BE, CF, *&c. be as the velocities at the inſtants* A, B, C, *&c.. the ſpaces deſcribed in the times* AB, BC, *will vary as the areas* AE, BF, *&c.*

DEM. For let Am, mn, np, &c. be moments of time, and the ſpaces deſcribed in theſe moments, are as the rectangular parallelograms Aq, mr, nv, (107) &c.; and the whole ſpaces, deſcribed in the ſums of theſe moments, i.e. in the times AB, BC, are as the ſums of theſe parallelograms, or as the areas AE, BF. Q. E. D.

111. Cor. 1. If the relation between V and T, or the ordinate and abſciſſa, be given, the relation between the ſpaces, or the areas AE, BF may be found.

112. Cor.

112. Cor. 2. If the area AE be always as the ſpace deſcribed (S) in the time AB or T, the velocity is as the ordinate BE; for according to this ſuppoſition, S' is as $AD \times Am$, or $AD \times T'$, and (109) as $V \times T'$; therefore V is as AD. PLATE I. FIG. XI.

113. Cor. 3. If AS repreſent the ſpace deſcribed, and the ordinates AD, BE, CF, &c. be always inverſely as the velocities at thoſe points; the times of deſcribing AB, BC, &c. will be as the correſponding areas AE, BF, &c. For the time of deſcribing any ſmall ſpace Am is as $\frac{S'}{v}$, or as $Am \times AD$; and conſequently the ſum of the moments, or whole time of deſcribing AB, is as AE.

114. PROP. *The acceleration and retardation of velocity, vary as the change uniformly produced directly, and the moment of time in which they are produced inverſely.*

If the changes of velocity, uniformly produced in the ſame time, be as 2:1, the acceleration is as 2:1 (102); and if the times, in which the ſame change of velocity is effected, be as 1:3, the law of acceleration is as 3:1, or inverſely as the times; becauſe if the times were as 3:3, the changes of velocity uniformly produced in theſe equal times, which meaſure the ratio of acceleration, would evidently be as 3:1, therefore the acceleration is as $\frac{V'}{T'}$, and in the ſame manner the retardation is as $-\frac{V'}{T'}$. Q. E. D.

115. Cor. If the velocity vary as the time, the acceleration and retardation are conſtant; for $V : v :: T : t$, and, ſuppoſing $n =$ the number of moments of time, or changes of velocity, $\frac{V}{n}(V') : \frac{v}{n}(v') :: \frac{T}{n}(T') : \frac{t}{n}(t')$; or V' is as T' and $\frac{V'}{T'}$ is given.

NOTE.

PLATE I. FIG. XII. *116. PROP. *In variable motions, if the velocity* (V) *in any point* L, *be as any power of the ſpace deſcribed, the time* (T) *of deſcribing that ſpace may be found.*

Let the body begin to move from A, and $AL = z$, and V be as x^n, and T the time of deſcribing AL. $\dot{T}$ is as $\frac{\dot{x}}{V}$ (109) as $\frac{\dot{z}}{x^n}$, and $T = \frac{z^{1-n}}{1-n} + C$ (correction). Q. E. D.

117. Cor. 1. If V be conſtant, or $n = o$; T will be as (z) the ſpace deſcribed.

118. Cor. 2. If V be as the ſpace deſcribed, or $n = 1$; $T = \frac{1}{o}$ or is infinite, and the body will never move from the point A. There are therefore no motions in nature, whoſe velocities are not in a leſs ratio than that of the ſpaces deſcribed, in the beginning of motion.

119. Cor. 3. If V be as the power of the ſpace deſcribed, whoſe exponent is $\frac{1}{2}$, $-\frac{1}{2}$, $-1-2$, &c. the time will be as that power of the ſpace deſcribed, whoſe exponent is $\frac{1}{2}$, $\frac{3}{2}$, 2, 3, &c.

FIG. XIII. 120. Cor. 4. Let the body move in AL, and the velocity (V) be as the ordinates of the curve line AM, which meets LA in A, and conſequently at A, $V = o$. It is evident, that if the time of deſcribing AL be finite, or (118) V be as ſome power of AL, whoſe exponent is leſs than unity, or fractional, the tangent at A will be perpendicular to AL. Let V be as AL^n and $\dot{v}$ as $n \times AL^{n-1} \times \dot{AL}$, and $\dot{v} : \dot{AL} :: n \times AL^{n-1} : 1$; and, if $\dot{v}$ be as any power of AL, whoſe exponent is leſs than unity, viz. $\frac{1}{2}$, $\dot{v} : \dot{AL} :: \frac{1}{2} \times AL^{-\frac{1}{2}} : 1 :: \frac{1}{2AL^{\frac{1}{2}}} : 1 :: \frac{1}{o} : 1$, when AL vaniſhes, and conſequently the fluxion of the ordinate LM is infinitely greater than that of the abſciſs AL.

121. EXAMP. If AMB be a ſemicircle, $AB = 2a$, $AL = s$, and the velocity at any point L, as LM, or ſuch as would deſcribe $n \times LM$ feet in 1″; $T =$ the fluent of $\frac{\dot{s}}{v}$, or of $\frac{\dot{s}}{n \times LM}$, or $\frac{\dot{s}}{n \times \sqrt{2as - s^2}}$, or $\frac{a\dot{s}}{na \times \sqrt{2as - s^2}}$, or $\frac{AM}{n \times AC}$ ſeconds. Therefore the whole time of deſcribing $AB = \frac{AMB}{n \times AC}$ ſeconds, which is a given quantity, and whatever be the length of AB, it will be deſcribed in the ſame time.

PLATE II. FIG. XIV. 122. PROP. *The times of deſcribing* AL *and* al (T *and* t) *with velocities which are always to each other as the ordinates* LM, lm *of ſimilar curves* AM, am, *are equal.*

* Euler's Mechanica.

DEM.

DEM. Let AL and al be homologous ſpaces, whoſe ratio is that of $p : q$, and if $AL = s$, and $LM = v$; $al = \frac{AL \times q}{p}$, and $lm = LM \times \frac{q}{p}$. The time of deſcribing AL or $(T) =$ flu. $\frac{\dot{s}}{v}$, and $t =$ flu. $\frac{\dot{al}}{lm} =$ flu. $\frac{\dot{AL}}{LM} =$ flu. $\frac{\dot{s}}{v} = T$. Q. E. D.

123. DEF. *The ſcale of velocity is a line whoſe ordinates are as the velocities at thoſe points from whence they are drawn. If the body move in* AL, *as in the laſt propoſition, &c.* AM *is the ſcale of velocity.*

124. DEF. *The ſcale of time is a line whoſe ordinates are as the time. If the ordinate* MQ *be always as the time of deſcribing* AM, *the line* AQ *is called the ſcale of time.* PLATE II. FIG. XV.

125. PROP. *If the ſcale of velocity* (V) *be given, the ſcale of the time* (T) *may be found.*

For $\dot{T}$ is as $\frac{\dot{S}}{V}$ and $T =$ flu. of $\frac{\dot{S}}{V} + C$, and if the relation of the ordinate and abſciſs, or V and S be known, the fluent of $\frac{\dot{S}}{V}$ may be found. Q. E. D.

126. Cor. If the ſcale of velocity AN be a circular arc, the time is that arc; for $\dot{T}$ is as $\frac{\dot{S}}{V}$ or $\frac{\dot{S}}{MN}$, or $\dot{AN}$, and T is as AN.

127. PROP. *The ſcale of time* AQ *being given to conſtruct the ſcale of velocity.*

$\dot{T}$ is as $\frac{\dot{S}}{V}$, and V as $\frac{\dot{S}}{\dot{T}}$ or $\frac{MQ}{MO}$, ſuppoſing QO to be perpendicular to the curve. Take therefore $MN = \frac{MQ}{MO}$, which is $= \frac{\dot{S}}{\dot{T}}$ or as V, and AN is the ſcale of velocity.

128. Cor. 1. If AQ be a right line, and T as $m \times S$; $\dot{T}$ is as $m \times \dot{s}$, and V is as $\frac{\dot{S}}{\dot{T}}$ as $\frac{\dot{S}}{m \times \dot{s}}$ as $\frac{1}{m}$, and AN is a right line.

129. Cor. 2. If T be as S^m and $\dot{T}$ as $m \times S^{m-1}\dot{s}$; V will be as $\frac{\dot{S}}{m \times S^{m-1}\dot{S}}$, or as $\frac{1}{m \times S^{m-1}}$. If AQ be the common parabola, or $m = \frac{1}{2}$; $\frac{1}{m \times s^{m-1}}$ will be equal to $2s^{\frac{1}{2}}$, and AN is alſo a parabola; and the relation of T (MQ) and the abſciſs AM or S being known, the relation of V (MN) to S may always be found.

RELATIVE MOTION.

130. DEF. *Relative motion is a change of relative place, and relative reſt is a permanence in the ſame relative place.* Relative and apparent motion are ſometimes diſtinguiſhed from each other, the firſt being defined to be that which is attributed to a moving object by an obſerver in motion, and the ſecond that attributed to an object really quieſcent by an obſerver in motion.

131. DEF. *The relative velocity of two bodies is the velocity with which they accede to, or recede from, each other.*

132. Cor. 1. Relative motion and reſt of a body coincide with abſolute, when the aſſumed object, by which its ſituation is determined, remains in the ſame part of fixed ſpace. If the earth be quieſcent, every ſhip which moves, or is quieſcent, with reſpect to a fixed object upon the ſhore, moves alſo abſolutely, or is abſolutely quieſcent.

PLATE II. FIG. XVI.

133. Cor. 2. If the object, by which the ſituation of a body is determined, move, abſolute and relative motion and reſt do not coincide. If the body B, fixed at the point B in the line AB, be the aſſumed object with which the ſituation of A, placed in the ſame line and partaking of its motion, be compared, its abſolute velocity will be the ſum or difference of its own velocity and that of the line, according as they move in the ſame, or oppoſite, directions. If the line AB move in the direction YX, with an uniform velocity of 100 feet in 1″, and A alſo move in the ſame direction, with an uniform velocity of 50 feet in 1″; A's whole abſolute velocity in the direction YX is 150 feet in 1″, and its relative velocity, or uniform receſs from B, is 50 feet in 1″. If the line AB move uniformly in the direction YX with a velocity of 100 feet in 1″, and A move in the oppoſite direction XY, with a velocity of 100 feet in 1″, it will be abſolutely quieſcent, and its

relative

relative velocity, or *B*'s acceſs to it, will be 100 feet in 1″ uniformly: if *A*'s velocity, in the laſt ſuppoſition, be 50 feet in 1″ uniformly, its relative velocity, or approach to *B* will be 50 feet in 1″, and its abſolute velocity will alſo be 50 feet in 1″ in an oppoſite direction.

134. Cor. 3. A ſpectator therefore, placed upon the moving line *AB* at the point *B*, only perceives *A*'s relative motion, which may be always different from the true.

*135. PROP. *If two bodies* A *and* B *move at the ſame time from* A *in the directions* AM *and* AL, *with uniform velocities* a *and* b *reſpectively, their relative velocity will be uniform, and to* a *as the ſine of* ∠ BAD : ∠ BDA, *and to* b *as ſin.* ∠ BAD : *ſin.* ∠ DBA *or* ∠ BAF, *ſuppoſing* B *and* D *to be cotemporary poſitions of* A *and* B, *and* AF *to be parallel to* BD. PLATE II. FIG. XVII.

DEM. Let *B*, *D*; *C*, *E*; *M*, *L*; be cotemporary poſitions of *A* and *B*; and (106) *a* : *b* :: *AB* : *AD* :: *AC* : *AE* :: *AM* : *AL*; and conſequently *BD*, *CE*, *LM*, which meaſure the relative velocity, are parallel to each other, and encreaſe uniformly becauſe *AM* does. But the relative velocity is to *a* :: *LM* : *AM* :: ſin. ∠ *MAL* : ſin. ∠ *ALM*, and it is to *b* :: *LM* : *AL* :: ſin. ∠ *LAM* : ſin. ∠ *LMA* or ∠ *MAH*. Q. E. D.

136. Cor. 1. The only ſenſible motion of *B* to a ſpectator placed at *A*, and ſuppoſing himſelf to be quieſcent, will be along *Ah* parallel and equal to *ML*; and when *A* hath really deſcribed *AM*, *B* will appear to have deſcribed *Ah* = *ML* uniformly.

137. Cor. 2. If *A* and *B* move uniformly with any equal velocities in parallel directions *AM*, *BL*, their relative ſituation is not changed, being always equal, and parallel, to *AB*; and if any FIG. XVIII.

ſpace

* Euler's Mechanica.

ſpace *AMBL*, containing any number of bodies, move, their relative ſituations are not affected by it. To a ſpectator therefore placed in *A*, in this moving ſpace, and ſuppoſing himſelf to be quieſcent, any body *B* will appear to be quieſcent.

138. Cor. 3. It is evident that the abſolute motion of a body may be changed into innumerable relative motions uniform and rectilineal, if its abſolute motion and that of the body, by which its ſituation is determined, be ſo.

PLATE II. FIG. XIX. 139. PROP. *If two bodies* A *and* B *move, at the ſame time, from the point* A, *in the directions* AM, AL, *with uniform velocities, as* AM, AL *reſpectively, and* B *be conſidered as quieſcent;* A's *apparent motion will be uniform and its direction and velocity as the diagonal of a parallelogram whoſe ſides are* AM, *and* AD *equal and oppoſite to* AL.

DEM. Let m, l be cotemporary poſitions of A and B, or let $Am : Al :: AM : AL$ and lm, Lm are parallel. But when B is at l and L, A's diſtance is equal to lm, LM; or, ſuppoſing B to be quieſcent at the point A, and AE, AD be reſpectively equal and oppoſite to Al, AL, and En, DN be drawn parallel to AM, A will appear at n and N. But An varies as Am, and therefore encreaſes uniformly, and AN is the diagonal of a parallelogram, whoſe ſides are $AD = AL$, and AM. Q.E.D.

140. Cor. 1. The apparent and real velocities of A are to each other as $AN : AM ::$ ſin. $\angle MAD$: ſin. $\angle NAD$.

141. Cor. 2. Suppoſing A and B to move as before, and A to be quieſcent, the diſtances and directions of A from B will be Ah, and AH, ſuppoſing them to be reſpectively equal and parallel to ml, ML. Whilſt B therefore really deſcribes AL, it appears to deſcribe $AH = AN$, and in the ſame right line with it; and the apparent

apparent motion of *A* and *B*, ſeen from each other, are equal and oppoſite.

142. Cor. 3. An uniform relative motion along the diagonal of any parallelogram *AMND* may be conſidered as reſulting from, and equivalent to, two uniform abſolute motions in the ſides *AM* and *AL* = *AD*; and theſe motions are in the ſame plane, and their velocities are to each other as the diagonal and ſides. FIG. XIX.

143. Cor. 4. If the motions of *A* and *B* be oppoſite, their relative motion is equal to the ſum of their real motions, *AN* being, in that ſuppoſition, equal to *AM* + *AD*. If the motions of *A* and *B* conſpire, their relative motion is equal to the difference of their real motions, or of *AM* and *AD*. And if the real velocities of *A* and *B* be variable, according to the ſame law, their relative velocity will vary according to that law.

144. Cor. 5. The real motions in *AM* and *AL* are ſaid to be equivalent to a motion in *AN*, becauſe they produce the ſame effect in the ſame time, as if *B* were quieſcent at *A*, and *A* were to deſcribe *AN* uniformly in that time. And in the ſame manner two motions in *AN* and *AD* are equivalent to a motion in *AM*, or its oppoſite and equal *AP*, according as the body deſcribing *AD*, or *AN*, is ſuppoſed to be quieſcent.

145. Cor. 6. If the real motion of *A* and *B*, or *AM* and *AL*, and their inclination be known, the relative motion of either of them may be found; for *AM*, *MN* and ∠ *MAD*, and conſequently its ſupplement *AMN*, being known, the baſe *AN*, and the ∠ *MAN*, or the inclination of *A*'s apparent to its real path, may be found.

146. Cor.

146. Cor. 7. The relative and real motion of *A*, or *AM*, *AN*, and the angle *MAN*, being known, the real motion of *B*, which is ſuppoſed to be quieſcent, or $AL = AD$ may be found.

PLATE II. FIG. XX.

147. PROP. *If two bodies* A *and* B *move at the ſame time uniformly in the directions* AM, BL, *with velocities equal to* a *and* b, *the relative motion of* B *will be uniform and rectilineal upon the line* BN, *ſuppoſing* AN *to be always equal, and parallel to right lines joining the cotemporary poſitions of* A *and* B.

DEM. Let *m*, *l*; *M*, *L*, be cotemporary poſitions of *A* and *B*, or let $a : b :: Am : Bl :: AM : BL$, and *ml*, *ML* will be the diſtances of *B* from *A* in the points *m* and *M*. And if *A* be conſidered as quieſcent at *A*, taking *An*, *AN*, reſpectively parallel and equal to *ml*, *ML*, *B* will appear at *n* and *N* in the line *BnN*, which is therefore the apparent path of *B*. But $a : b :: Am\,(nl) : Bl :: AM\,(NL) : BL$; therefore *BnN* is a right line, and encreaſes uniformly, becauſe it varies as *BL*. Q. E. D.

148. Cor. If *A* and *B* move as in this propoſition, and *B* be conſidered as quieſcent, *A*'s apparent path will be in the right line *ADE*, parallel and equal to *BnN*, as is evident by taking *BD* and *BE* reſpectively parallel and equal to *lm* and *LM*. *A*'s velocity will therefore be uniform and equal to *B*'s velocity, when *A* was conſidered as quieſcent.

149. The abſolute and relative motions of *B*, and their directions being known, the direction and velocity of *A*'s motion, which occaſioned *B*'s relative motion, may be found; for, let *A* and *B* be cotemporary poſitions of *A* and *B*, and let *Bl*, *Bn*, be the ſpaces deſcribed in the ſame time by *B*'s abſolute and apparent motion, and if *ln* be joined, *AM* drawn parallel to it, will be *A*'s path, and *A*'s velocity : *B*'s velocity :: *nl* : *Bl*.

150. Cor.

150. Cor. 1. An abſolute uniform and rectilineal motion BL may be changed into any infinite number of uniform relative rectilineal motions, by changing the direction and velocity of A's motion; for BN may be drawn of any length, and in any direction, and the direction and velocity of A, moving uniformly ſo as to produce this relative motion, may be found by drawing AM parallel and equal to NL. FIG. XX.

151. Cor. 2. When two bodies move uniformly in right lines, and one of them is conſidered as quieſcent, the relative motion of the other is therefore uniform and rectilineal; and the ſpaces, deſcribed by it relatively, vary as the velocity multiplied into the time (104), or S varies as $V \times T$, T as $\frac{S}{V}$, and V as $\frac{S}{T}$.

152. Cor. 3. If the relative motion of B be variable, the abſolute motion of either A or B is variable.

153. PROP. *If a body* A *move in any curve line* A m M, *and another body* B *move in any other curve* B I L, B's *apparent motion may be found.* PLATE II. FIG. XXI.

Let m, l, M, L, be cotemporary poſitions of A and B; and B's diſtance and the right lines in which it appears at m and M, are ml and ML. Or, if A be conſidered as quieſcent, and An, AN, be taken reſpectively parallel and equal to ml, ML, B will appear at n and N, and its path will appear to be $Bn N$. Q. E. I.

154. Cor. It is evident that the curve $Bn N$, the relative path of B, may be deſcribed by the motion of A in different curves; but all the curves deſcribed by A will be equal and ſimilar, and have their correſponding parts parallel, becauſe they are always ſubtended by right lines equal and parallel to nl, NL, &c.

155. PROP.

FIG. XXII.

155. PROP. *If* B *be abſolutely quieſcent, and* A *move in any curve line* A m M *uniformly,* B *will appear to move uniformly in a curve equal and ſimilar to* A m M, *and theſe curves are ſimilarly ſituated with reſpect to the points* A *and* B.

Let *m*, *M* be any contiguous poſitions of *A*, which being conſidered as quieſcent at the point *A*, the cotemporary poſitions of *B* are *n* and *N*, ſuppoſing *An*, *AN* to be reſpectively parallel and equal to *Bm*, *BM*. And becauſe *An* = *Bm* and *AN* = *BM*, and the angle *NAn* = angle *mBM*, the ſmall arc *Nn* = *mM*, and they make equal angles with the diſtances *AN*, *BM*, and *An*, *Bm*. Q. E. D.

156. Cor. 1. If *B* move in the curve *BnN*, and *A* be quieſcent at the point *A*, it will appear to deſcribe the curve *AmM* ſimilar and equal to *BnN*.

PLATE III. FIG. XXIII.

157. Cor. 2. If *A* and *B*, placed in the ſame right line *ABC*, deſcribe the circles *AmM*, *BlL* in the ſame time uniformly, and *A* be conſidered as quieſcent, *B*'s apparent path is a circle whoſe center is *A* and radius *AB*. For let *m*, *l*, and *M*, *L*, be cotemporary poſitions of *A* and *B*, and *B* will appear at *l* and *L*; or, ſince *A* is conſidered as quieſcent, if *An*, *AN*, be drawn parallel and equal to *ml*, *ML*, it will appear at *n* and *N*, and its apparent diſtance from *A* always = *AB*, and the direction of *B*'s apparent motion is the ſame with that of *A* and *B*.

158. Cor. 3. If *B* be conſidered as quieſcent, and they move as in the laſt corollary, *A*'s apparent path will be a circle whoſe center is *B* and radius *BA*, and the direction of its motion is the ſame with that of *B* in that corollary. For taking any cotemporary poſitions *m*, *l*, and *M*, *L*; and, drawing *Bn*, *BN* reſpectively parallel and equal to *ml*, *mL*, *A* will appear at *n* and *N*, and its apparent diſtance from *B* always = *AB*.

159. Cor. 4. The relative motions of *A* and *B* ſeen from each other, are equal and in ſimilar curves. For let *m* and *M* be any contiguous poſitions of *A*, and *l*, *L* correſponding poſitions of *B*; and joining *m l*, *ML*, *B*'s relative motion, whilſt it really deſcribes *lL*, will make it deſcribe *nN*, ſuppoſing *A* to be quieſcent, and *An*, *AN* to be reſpectively equal and parallel to *l m*, *LM*. Suppoſing *B* to be quieſcent, and *Bb*, *BH* to be equal and parallel to *m l*, *ML*, or *An*, *AN*, *A* will appear to deſcribe *bH*, which is equal and ſimilar to *Nn*. FIG. XXIV.

160. Cor. 5. If *B* be immoveable and not placed in the plane of *A*'s motion, it will appear to deſcribe a line equal and ſimilar to the line deſcribed by *A*, and they will be in parallel planes; for taking any two contiguous portions of *A*'s path, the right lines joining the real and apparent places of *A* and *B* are equal and parallel, and conſequently the ſmall right lines joining them are equal and parallel: and this and the preceding corollaries are true wherever the eye's imaginary place is.

SCHOLIUM.

161. To diſtinguiſh real and abſolute, from relative motion, is an important, but very difficult problem; becauſe the ſame apparent motions may reſult from real motions combined in endleſs variety. Every apparent motion of a body reſults from, and may be explained by, its real motion and that of the ſpectator and *v*,*v*; and therefore its real motion, and the real motion of the ſpectator, or this, and the apparent motion of the body, muſt be preſuppoſed, and, with the aſſiſtance of mathematics, the other may then be detected. A ſpectator ignorant of the earth's annual and diurnal motion, and ſuppoſing himſelf to be quieſcent, muſt draw erroneous concluſions, in all his reaſonings, concerning the abſolute motion of any body, becauſe theſe motions of the earth will communicate an apparent motion to a body abſolutely quieſcent, and affect the abſolute motion of a body moving (134). The relative motions of bodies muſt therefore be aſcertained from obſervation, and their real motions, when

diſcoverable, are deduced from theſe, the properties of real motion, and the quantity of mechanical powers, or qualities in matter, that are found to generate motion. If the properties, invariably attached to all real motions, obtain in any obſerved motion; or if any mechanical cauſe be proved to exert an influence, which is exactly competent for the production of any obſerved motion, it may ſafely be inferred that this motion is not imaginary, but real.

EXAMP. I. The variation of diſtance between a ſhip and a remote object is owing to the motion of the ſhip, when the wind and current act and are competent for its production.

FIG. XXV. EXAMP. II. A ſhip ſailing from ſouth to north at the rate of five miles in an hour, obſerves another ſhip which ſailed from the ſame point *E* going to the ſouth-weſt at the rate of $7\frac{1}{10}$ miles in an hour nearly, and from hence it appears, that the laſt ſhip ſailed from eaſt to weſt at the rate of five miles in an hour nearly (139).

EXAMP. III. The magnitude of the earth's attractive power, or any other mechanical cauſe, is incompetent for the production of the diurnal revolution of the heavenly bodies, which is therefore probably apparent.

EXAMP. IV. The aberrations of the fixed ſtars are proved geometrically to reſult neceſſarily from the progreſſive motions of light and of the ſpectator combined, and are conſequently only apparent.

EXAMP. V. A real circular motion is inſeparably attended with a centrifugal force, and diſtinguiſhable therefore by this effect. Thus the diminution of gravity, which is obſerved in acceding towards the equator, affords a proof of the diurnal rotation of the earth.

CHAP. IV.

INERTIA OF MATTER.

162. DEF. *POWER and force are used synonimously to signify any action upon a body, which produces motion, or a tendency to motion, as animal exertions and the influence of physical causes, gravity, elasticity, magnetism, &c. When a force acts always with the same intensity, or produces the same effect in a given time, it is said to be uniform or constant, and variable when it does not.*

163. DEF. *Any momentary impression upon a body producing motion, or a tendency to motion, is called an impulse, or percussion, of a power or force.*

164. DEF. *Whatever resists the action of a force is called an obstacle.*

165. DEF. *Inertia, or vis inertiæ, of matter, is that quality by whose influence a change, in the direction or quantity of its motion, cannot be produced without the application of a force.* The cause of a body's continuing in a state of rest, or of uniform rectilineal motion, is not any external force, but the nature and constitution of matter; and this internal cause or principle is called its inertia.

166. This property of matter, or inertia, is essential in the constitution of a system, whose preservation is necessarily dependent upon the regular observance of prescribed, determinate, laws; but

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its exiſtence can only be collected from experience. *Firſt*, Every change in the ſituation of a body, from reſt to motion, and from motion to reſt and to an encreaſe or decreaſe of motion, indicates an inertia, which is found to pervade every ſpecies of matter acceſſible to obſervation, the particular facts, adduced in proof of it, being innumerable and concurring to eſtabliſh its univerſal exiſtence. A quieſcent body is never diſcovered to move, and motion, or change of motion, is never induced, without the actual impreſſion of a cauſe able to produce theſe effects; for matter not only continues in a ſtate of reſt, by an incapacity to give motion to itſelf, but never ceaſes to move, or changes the quantity and direction of its motion, without the application of ſome philoſophic influence adequate to their production, as magnetiſm, elaſticity, gravity, &c. or animal exertion, as percuſſion, protruſion, &c. The time of the motion of a wheel upon its axis, or braſs topp upon a poliſhed ſurface, is encreaſed with the diminution of friction upon the axis, or ſurface; and the motion of a body, placed upon the deck of a ſhip, and partaking of its motion, continues in the ſame direction after the ſhip has ceaſed to move; and theſe motions are evidently diſcontinued by the operation of a cauſe, i. e. friction, competent to deſtroy them. New motions are obſerved without any ſenſible material impulſe, reſulting apparently from an innate tendency to motion; thus, a body not ſupported deſcends towards the earth, and, projected in a direction not perpendicular to the earth's ſurface, deviates from the line of projection with a velocity perpetually variable; and new motions ariſe amongſt the minute particles of bodies; but theſe are the neceſſary reſult of eſtabliſhed natural powers, gravity, elaſticity, &c. *Secondly*, This quality is ſometimes called the vis inſita, or vis inertiæ, of matter, from the ſimilitude of its effects to thoſe of animal powers exerciſed upon a body, both producing a change of motion. If a body *A*, placed upon a poliſhed table, or ſuſpended by a rope, be quieſcent, it will continue in that ſtate till urged by ſome external cauſe; and if another body *B* be projected with any velocity, and impinge upon *A*, it will communicate motion to it, and be itſelf retarded. When the effect of *B*'s

impact is conſidered in relation to the change produced in *A*, *B* is ſaid to act upon *A*; and, when conſidered in relation to the change of motion produced in itſelf, it is ſaid to be reſiſted by *A*. Action is uſually aſcribed to a moving, and reſiſtance to a quieſcent, body; but they may both be conſidered as actions, becauſe they produce ſimilar effects, that is, a change of motion. *A*, by its vis inertiæ, deſtroys a part of *B*'s motion, and *B*, by endeavouring to retain its preſent ſtate, that is, by its vis inertiæ, protrudes, and communicates motion to, *A*. *Thirdly*, Every change in the ſituation of a body is therefore univerſally allowed to indicate ſome philoſophical influence, or animal exertion; and whether a body be quieſcent, or moving, the quantity of its inertia is invariably the ſame; for it is diſcovered from experiments, the only ſource of information, that a force, communicating a velocity equal to *a* to the quieſcent body *A*, will communicate an encreaſe of velocity, equal to *a*, to that body moving. The force of gravity, which communicates a velocity nearly equal to thirty-two feet in one ſecond of time, to a body falling from a ſtate of reſt, communicates an encreaſe or decreaſe of velocity equal to this, in one ſecond, to a body already moving, according as it conſpires with, or is oppoſite to, the direction of the body's motion. And if the body *B*, moving with a velocity equal to *b*, impinge upon *A* at reſt, and communicate a velocity to it equal to *a*, and loſe a velocity equal to *l*, it appears from experiments, that *B* moving with the velocities $b + m$, $b + 2m$, $b + 3m$, &c. will communicate an encreaſe of velocity equal to *a*, and loſe a velocity equal to *l*, by impinging on *A* moving in the ſame direction with velocities equal to m, $2m$, $3m$, &c. Conſequently the vis inertiæ of *A*, eſtimated by the velocity, and encreaſe or decreaſe, communicated to it, is the ſame in a ſtate of motion and reſt. *Fourthly*, As the whole vis inertiæ of a body is compoſed of that of all its parts, and as we cannot conceive the vis inertiæ of the ſame or equal particles to be encreaſed or diminiſhed, the whole vis inertiæ of different bodies will vary as the number of equal particles, or quantities of matter, contained in them. The invariable reſult of experiment is, that bodies equal

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to A, $2A$, $3A$, &c. and heterogeneous bodies, whose weights are as 1, 2, 3, &c. receive the same velocity by the action of forces, whose magnitudes are as 1, 2, 3, &c.

167. DEF.* *The moment, quantity of motion, vis insita, of a body, are used synonimously to denote the impetus, or force, with which it moves, or its capacity to communicate motion or pressure.*

168. PROP. *If* M, Q, V, *represent moment, quantity of matter, and velocity, respectively, and be supposed variable,* M *will vary as* Q × V.

DFM. Presuming that equal particles of matter have an equal inertia, it is evident that the pressure of one particle upon an immoveable obstacle, or the force requisite to generate or destroy its velocity, will vary as this velocity, or as V; and because the impetus of any body is composed of that of every particle or Q, and Q and V are independent, M will vary as $V \times Q$ (64). Q. E. D.

Another demonstration.

The moments of different bodies vary as the uniform forces capable of generating or destroying them, in equal times, being their whole cotemporary effects; but forces equal to F, $2F$, $3F$, &c. will evidently communicate, in the same time, the same velocity to 1, 2, 3, &c. equal particles endued with an equal inertia, and velocities as 1, 2, 3, &c. to one particle. Therefore F, which is as M, is encreased in the same ratio, with the velocity or V, and number of equal particles or Q; and, these being independent, vary as $Q \times V$ (64). Q. E. D.

* Keil's Physics, Lect. IX.

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SCHOLIUM.

169. These, or similar demonstrations, are usually adduced in support of this proposition, which is perhaps more properly and with more conviction, demonstrated by experiments. The moments of different bodies are collected by measuring the magnitudes of the forces required to produce them, or the magnitudes of their cotemporary effects similarly produced, in the simplest and most intelligible instances, which may be deemed the common measure of their moments.

EXP. I. If two unequal spherical bodies, moving in opposite directions, meet and after impact be quiescent, their moments must be equal; but their quantities of matter are always found to be inversely as their velocities. Or, if they move in the same direction, and one overtakes the other, the velocity gained by the struck body, and lost by the striking body, are always found to be inversely as their quantities of matter.

EXP. II. If a body A be placed on the same side of the fulcrum of a straight lever, at the distance of 1, 2, 3, &c. feet from A, it will move with velocities as 1, 2, 3; and be restored to an equilibrium by the bodies A, $2A$, or $3A$, &c. placed, at the distance of one foot, on the other side. And, in general, a body, whose weight is $n \times A$ pounds, at the distance of one foot from the fulcrum, is found to equilibrate with bodies, whose weights are $\frac{n \times A}{2}$, $\frac{n \times A}{3}$, $\frac{n \times A}{4}$, &c. at the distance of 2, 3, 4, &c. feet from the fulcrum respectively. The pressures or moments, are justly inferred from these experiments, to be as their weights multiplied into their distances, or as the quantities of matter multiplied into their velocities. And the same conclusion results from experiments upon every other, however complicated, machine, when allowance is made for friction, and the velocity is properly estimated.

170. Cor. 1. Since M varies as $\mathcal{Q} \times V$, V will vary as $\frac{M}{\mathcal{Q}}$, and $\mathcal{Q}$ as $\frac{M}{V}$ (55). If lines be taken in the ratio of $\mathcal{Q}$ to V, M will vary as the area of a rectangle, whose ſides are theſe lines; and if numbers be taken in that ratio, M will vary as their product.

171. Cor. 2. If S repreſent the ſpace deſcribed, in the time $\mathcal{T}$, with the velocity V, M, varying as $\mathcal{Q} \times V$, will vary as $\frac{\mathcal{Q} \times S}{\mathcal{T}}$ (105), S, varying as $V \times \mathcal{T}$, will vary as $\frac{M \times \mathcal{T}}{\mathcal{Q}}$, and $\mathcal{T}$ will vary as $\frac{S \times \mathcal{Q}}{M}$.

172. Cor. 3. If two bodies therefore A and B, moving in oppoſite directions with velocities reſpectively equal to a and b, meet, and after impact be quieſcent; or if their effects to produce motion upon any machine be oppoſite and equal, and their velocities, when properly eſtimated, be a and b; $A \times a = B \times b$, and $A : B :: b : a$ (38), or A and B are to each other inverſely as their velocities. The converſe of this is true, and if the bodies be inverſely as their velocities, or $A : B :: b : a$, their moments are equal, or they are in equilibrio upon any machine, and $A \times a = B \times b$ (37).

SCHOLIUM.

173. Forces are diſtinguiſhed by ſome foreign writers into two kinds; 1ſt, of bodies at reſt, and 2dly, of bodies in motion.

First, *The force of a quieſcent body, ſuch as is conceived to reſide in one lying upon a table, ſuſpended by a ſtring, ſuſtained by ſprings, &c. is called its preſſure, tenſion, force, ſolicitation, vis mortua, &c. and is eſtimated by the weight with which the table is preſſed, the ſtring ſtretched, ſpring bent, &c. To this kind are referred centripetal and centrifugal forces, as their effects are ſimilar to thoſe of weights, preſſures, tenſions.*

Secondly,

Secondly, *The force of a moving body, ariſing from its inertia, by which it communicates motion, or a change of motion, to another body by impact, overcomes gravity, friction, and other preſſures, and is only deſtroyed by an extinction of its motion, is called the vis motrix of that body, or its vis viva, to diſtinguiſh it from the vis mortua.*

Concerning the meaſure of the firſt of theſe forces no doubts are entertained, the preſſure of one particle, upon the arm of a lever, being univerſally allowed to be as its velocity, and of a number of particles, as that number and velocity conjointly; but the meaſure of the vis viva hath long been a ſubject of warm contention between the adherents of Newton and Leibnitz, the former maintaining it to be the product of the quantity of matter and velocity, and the latter the product of the quantity of matter and ſquare of the velocity. The term force being defined to be that, which, acting upon a body, communicates motion, or a tendency to motion, the magnitude of the force of a moving body, at any inſtant of time, may be beſt, and indeed can only be clearly, conceived by meaſuring the motion communicated by it; and in this menſuration three things are to be conſidered, viz. the magnitude of the body or quantity of matter to be moved, the velocity communicated, and the time in which it is communicated. Some of theſe circumſtances may be, as they have been, omitted, and different meaſures of the ſame force have reſulted. The followers of Newton conceive forces to act, for the ſame time, with their reſpective intenſities continued uniformly, and eſtimate their magnitudes by their cotemporary effects. If two forces F and f be ſuppoſed to act, at the ſame inſtant, upon two bodies A and B, with uniform intenſities, and communicate velocities to them, equal to V and v reſpectively, in the ſame time, the magnitudes of theſe forces are to each other as $A \times V : B \times v$. And in the communication of motion by the impact of one body upon another, this law is found to obtain, wherever the effects are diſtinctly underſtood, and can be aſcertained, the quantity of motion, if meaſured by the product of the quantity of matter and velocity, remaining invariable, when eſtimated in the ſame direction. But the followers of Leibnitz, adopting a different definition of force, derive a different concluſion: they do not ſuppoſe the force to

act with uniform intenſity, as it may decreaſe gradually to evaneſcence, which happens in the colliſions of bodies, and actions of ſprings; and the time of action, and ſometimes the direction, is diſregarded, and not deemed to affect the reſult. Though it be true in ſome particular caſes of the communication of motion from one body to another, that the force, according to their acceptation of the term, varies as the product of the quantity of matter and ſquare of the velocity, or that this product is the ſame before and after impact, this concluſion cannot be affirmed to obtain generally. The doctrine advanced by Newton is univerſally true, according to his meaning of the term force; but whether the opinion of Leibnitz be true or not, is beſt known from experiments, the reſult of which is generally repugnant to it: and it would therefore, perhaps, create leſs confuſion to adhere to the old definition of force, include the time of action, and ſuppoſe the intenſity of the force, during that time, to be the ſame. The diſtinction between theſe two kinds of forces hath often been urged to be ſuperfluous, for the following reaſons. *Firſt*, The force of a moving body is a vague and undefinable term; for there is no force in a body conſidered abſolutely, except its inertia, which is always the ſame, whether the body be quieſcent or moving; but if a moving body impinge upon another body either moving or quieſcent, its inertia exerts itſelf as a force, whoſe magnitude is relative and depends upon its velocity, and the magnitude and velocity of the ſtruck body. If the body A, moving with the ſame velocity a, impinge upon the quieſcent bodies B, $2B$, $3B$, &c. or upon the ſame body B quieſcent, and moving with different velocities equal to b, $2b$, $3b$, &c. it will in every caſe produce a different effect, and the change of ſtate, both in the impinging and ſtruck body, will be different. The force of ſprings, and animal exertions, is alſo relative, and it ſeems therefore improper to talk of the abſolute force of a moving body, ſprings, &c. becauſe it is relative. *Secondly*, No idea can be formed of an inſtantaneous communication of motion; for, in the colliſion of bodies, the parts which come into contact firſt, are diſplaced and move, and ſome time elapſes before motion be communicated to the whole body. This interval of time between the firſt contact of the neareſt parts of the impinging

ing bodies, and their motion, is the time of colliſion, in which the bodies exert a mutual, and perpetually variable preſſure, by which their ſtate is gradually changed. This is moſt obſervable in ſoft bodies, or thoſe whoſe parts yield to percuſſion; and, as the parts of all bodies do yield, obtains univerſally, in a greater or leſs degree, according to the different contexture of their parts. The forces of percuſſion are therefore preſſures, exerted with variable intenſity for a ſhort time; and, to comprehend their magnitude, this time ought to be aſcertained, the quantity of preſſure, for every inſtant of this time, computed, and the whole collected into one ſum. This diſcrimination of forces ſeems therefore to be unneceſſary, becauſe the action of colliſion is nothing more than the operation of a continued preſſure, and preſſures and percuſſions are ſimilar, and properly expreſſed by the ſame term, force. The arguments adduced, in ſupport of their opinion, by the advocates of Leibnitz, are derived from experiments upon, the colliſion of bodies, the action of elaſtic ſprings, the compoſition and reſolution of motion, the indentings or cavities formed in clay, tallow, &c. by falling bodies, and the velocity of fluids in hydraulics. I will only produce a few experiments, which may convey ſome uſeful knowledge, are moſt ſtrongly urged in ſupport of this hypotheſis, and appear moſt to militate againſt the old opinion.

EXP. I. If one ſpring be requiſite to deſtroy the motion of a body, whoſe velocity is 1, four ſprings, equal to it, are requiſite to deſtroy its motion when its velocity is 2, nine ſprings when its velocity is 3; and generally the number ſprings varies as the ſquare of the velocity of the moving body.

EXP. II. The number of men, horſes, &c. of equal ſtrength requiſite to communicate velocities, as 1, 2, 3, &c. to any body, are as 1, 4, 9, &c. or as the ſquare of the velocity.

Theſe ſimilar experiments may be true, and indeed ſeem to be eſtabliſhed

eſtabliſhed by Graveſand, Deſaguliers, &c.; but they prove nothing againſt the common opinion of the force of bodies, which is not meaſured by effects produced in any unequal times. And beſides, the effect of any number of agents, as ſprings or animal exertions, cannot properly be ſaid to meaſure their force; becauſe their whole force is not exerted, that of each, conſidered individually, being greater than when acting in conjunction with the reſt, and will be greater or leſs according as the number of the reſt is leſs or greater.

EXP. III. If the velocity of water, ſtriking upon the float-board, or ladle-board, of a mill, be as 1, 2, 3, &c. the effect of the wheel is found to be as 1, 4, 9, &c. or as the ſquare of the velocity of the ſtream; and the force of the water, being meaſured by its effect, varies therefore as the ſquare of the velocity. In this experiment the number of particles of water ſtriking the board in a given time, encreaſes as the velocity, and, the force of each being encreaſed in the ſame ratio, the effect ought to be as the ſquare of the velocity. Theory is very ſeldom confirmed by practice without allowances for the operation of collateral cauſes, which, perhaps, cannot be made with demonſtrative accuracy. Such experiments as this are too imperfectly underſtood to juſtify any general concluſions againſt experimental proofs clearly comprehended, or theoretic demonſtrations, reſulting from data, which, perhaps, do not take place in the experiment.

EXP. IV. Mr. Smeaton has proved, by ſome very ingenious experiments (Phil. Tranſ. Vol. LXVI. pag. 469.), that the mechanic power to be expended, varies as the ſquare of the velocity to be generated, and the velocity as the impelling power multiplied into the time of action. But the mechanic power, according to Mr. Smeaton, is meaſured by the weight multiplied into the ſpace deſcended, and from this definition, his concluſion is inevitable: but this power is different from what is uſually meant by moment, force, &c. In N°. 2, 3, the weight *S* deſcends through

ſpaces

ſpaces equal to 10, and $2\frac{1}{4}$, turns, in $28\frac{1}{4}''$ and $14\frac{1}{4}''$ reſpectively, and communicates velocities nearly as 2 : 1; and in this experiment the weight S acts with the ſame intenſity for times, whoſe ratio is 2 : 1, but its capacity to communicate motion, if meaſured by the ſpace, muſt be as 4 : 1.*

EXP. V. Equal cavities are formed in clay, tallow, &c. by equal bodies falling through ſpaces inverſely as their quantities of matter; but the cavities being equal, the cauſes, or forces of the bodies, are equal, or as $\frac{S}{S}$ (ſuppoſing S to repreſent the ſpace) or as $S \times Q$, from the ſuppoſition, or as $Q \times V^2$.

EXP. VI. A ball ſhot with velocities as 1, 2, 3, &c. is found to form cavities in wood, clay, &c. whoſe depths are as 1, 4, 9, &c. or as the ſquares of the velocities.

The two laſt experiments prove nothing againſt the common doctrine; and though they are of practical utility, yet admitting the propriety of meaſuring forces by their whole effects produced in any unequal times, they do not vary, in theſe experiments, as the ſquare of the velocity: becauſe the cavities formed are not the whole effect, a greater or leſs motion being communicated to the parts contiguous to the cavity in the ſtruck body, according to the magnitude and velocity of the ſtriking body. A ſmall body, moving with a great velocity, may by impact overcome the coheſive force of the particles of the ſtruck body, and effect a ſeparation between them; and from its great velocity, or ſhort time of action, little motion will be communicated to the contiguous parts; but

* Theſe experiments are immediately deducible from mechanical principles. Let $F =$ the radius of the barrel M; $V =$ velocity generated in K in the time T; X and $Z =$ the reſpective ſpaces paſſed through by S and K in the time T; and $1 = K$'s diſtance from the axis Be. And from eſtabliſhed principles, the force impelling K is .8 oz. $\times F$, or as F, and, becauſe F is conſtant, $F \times T$ is as V. $F \times T^2$ is alſo as Z; but $X : Z :: F : 1$, therefore X (or the ſpace deſcended by S, which is as the mechanic power) $= Z \times F$, and is as $F^2 \times T^2$, or as V^2. (Phil. Tranſ. Vol. LXVI. p. 469.)

but a great body, moving ſlowly, will form no cavity in the obſtacle; becauſe the moment of thoſe parts of its ſurface in contact, is leſs than the coheſive force of the parts of the obſtacle, and the parts ſtruck will, by their unknown connection with the parts adjoining, communicate motion to them, and theſe to the next, till the whole obſtacle move. Two bodies therefore moving with the ſame moment, may produce quite diſſimilar effects; and as lines, ſurfaces, &c. are meaſured by the application of a common meaſure, the magnitudes of forces are to be meaſured by their effects, which ought to be ſimilar in every reſpect, and this ſimilitude is moſt obſervable and beſt underſtood in experiments upon the lever and other ſimple machines.*

LAWS OF MOTION.†

174. The laws of motion are general rules, or conſequences, reſulting from the nature and conſtitution of matter, and its relation to mechanical forces, the cauſes of motion, by which it is governed, and from which it cannot deviate without ſuffering a total change of its nature. Their truth is eſtabliſhed by a number of concurring and uncontroverted obſervations, all information upon natural powers and motions derived from them being only deducible from thence; and, when thus eſtabliſhed, they are eſteemed to be uniform characteriſtic marks obtaining in all material motions.

FIRST

* Let s repreſent the effect, or ſpace through which any obſtacle is impelled by a moving body, v be the velocity of the body: and if s be as v^2, $\dot{s}$ is as $2 v \dot{v}$, or as $v \dot{v}$, or as $\frac{\dot{v} \times s}{\dot{t}}$ (if t be the time), and $\dot{v}$ therefore is as $\dot{t}$. The decrement of velocity is therefore as the time in which it is produced, and the reſiſtance muſt be conſtant; which ſeems to be a neceſſary property of the vis viva; but as this ſeldom happens, and the vis viva is really a preſſure, and may be meaſured in the ſame manner with the vis mortua, the term force may expreſs them both.

See Deſagulier, Vol. II. p. 51. Maclaurin's Account of Sir I. Newton's Diſcoveries, p. 178. Diſcours ſur les Loix de la comm. du Movement, Oper. Tom. III. and Diſſertat. de vera notione virium vivarum. Act. Petropol. Tom. I. p. 131. Muſchen. Int. ad Phil. Nat. Vol. I. p. 83, &c. Phil. Tranſ. No. 371, 375, 376, 396, 400, 401, 459.

† Maclaurin, Book II. Chap. II. Newt. Prin. p. 13. Keil's Phyſics, Lect. XI, XII. Helſham, Lect. III. IV.

FIRST LAW OF MOTION.

175. *Every body perſeveres in a ſtate of reſt, or of uniform rectilineal motion, unleſs affected by ſome external cauſe, as animal exertion or phyſical power.*

The truth of this law is collected by obſervation. It is nearly ſynonimous to the inertia, or that quality, of matter, by which it continues in every new ſtate; for, this being eſtabliſhed, it is a neceſſary reſult that it cannot begin to move from a ſtate of reſt, nor, if in motion, can it accelerate, retard, or change the direction of that motion.

176. Cor. Every body, moving in a curve line, or in a right line with a perpetually varying velocity, is acted upon without intermiſſion during its motion, by ſome external force; and every body, moving in a curve line, has a perpetual tendency to move in a right line, and to leave the curve in the direction of a tangent to that point of the curve where the body is.

SECOND LAW OF MOTION.

177. *Motion, and change of motion, are proportional to, and in the direction of, the force impreſſed.*

The motion communicated to a quieſcent body is proportional to the cauſe producing it; and when a body is accelerated or retarded, during its motion, the acceleration and retardation are proportional to the force producing them. If a body move upon an inclined plane AB, or in any curve line LM, by the action of a force tending to any point S, the change of motion is not proportional to the whole force directed to that point, but to that part which acts in the direction AB, or NT touching the curve where the body is; for this part, only, accelerates or retards the FIG. XXVI.

body's motion. When water or air act upon the vanes of a mill, or ſails of a ſhip, the change of motion is not proportional to the whole force of the water or air, but to that part which is actually impreſſed upon them; for, if the velocity of the water or air be equal to that of the vanes or ſails, they will move on together without any acceleration; and, if the direction of the air or water be oblique to the motion of the vanes or ſhip, ſome force will be ineffectual, and the change of motion will be proportional to the remainder, acting in the direction of their motion.

The truth of this law is demonſtrated by numberleſs experiments upon the motion, and change of direction and motion, communicated by material impulſe. Every experiment upon the effects of conſpiring and oppoſite forces, and the effects of forces, acting obliquely, or reſulting from the compoſition and reſolution of forces, demonſtrated experimentally, exhibit concurring proofs of its truth; for were motion, and change of motion, not proportional to, and in the direction of, the force impreſſed, it may be proved geometrically that theſe effects would not take place. The concluſion is therefore inevitable, and, being thus eſtabliſhed by uniform experience, may be deemed a fixed principle in nature, and applied not only to the explication of thoſe particular experiments from whence it was deduced, but of all other natural phenomena. This law is alſo a proof of the inertia of matter, or, that being eſtabliſhed, a corollary from it; for if matter can produce no change in itſelf, it muſt move in the direction of the force impreſſed; and, ſince the vis inertiæ of a body is the ſame, whether moving or quieſcent, it is evident that the geneſis, encreaſe, and decreaſe, of velocity equal to V in any body, require exactly the ſame force. If the force of colliſion, or impulſe of any force ſuch as gravity, be capable of generating a velocity, equal to V, in the body A, it will in the ſame time generate an encreaſe, or decreaſe, of velocity equal to V in that body, according as it conſpires with, or oppoſes its motion.

178. Cor. 1. The velocity generated by one ſingle impulſe equal to nF, n being a number, is equivalent to that generated by n ſucceſſive

ceſſive conſpiring impulſes, each of which is equal to F; and conſequently the velocity communicated to a body by any number of forces acting in the ſame direction is the ſame, whether they act together or ſeparately; becauſe the geneſis, and encreaſe, of a velocity $= V$, require exactly the ſame force.

179. Cor. 2. The velocity generated, in any body, by any number of unequal conſpiring impulſes X, Y, Z, &c. is as their ſum; for let x, y, z, &c. be the velocities reſpectively generated by them in any body A, and (177) $X : Y :: x : y$, and $X : X+Y :: x : x+y$, and $X : X+Y+Z :: x : x+y+z$, &c. And the velocity, communicated to any body by a force $= F$, in a given time, is as the magnitude of that force; for ſuppoſing this force to act by impulſes, whoſe magnitudes are X, Y, Z, &c., $F = X+Y+Z$, &c.

180. Cor. 3. The magnitudes of any forces are therefore as the ſpaces uniformly deſcribed in a given time, by the velocity which they communicate to the ſame body (106).

181. Cor. 4. The velocity generated in a body in the ſame time by two forces X, Y, acting in oppoſite directions, is as their difference; for (177) $X : Y :: x : y$ and $X : X-Y :: x : x-y$.

THIRD LAW OF MOTION.

182. *Action and reaction are always equal and oppoſite; or the mutual actions of two bodies are always equal, and in oppoſite directions.*

This is another rule obſervable in all the motions of nature, reſulting, like the two firſt, from the inertia of matter. Were matter diveſted of this property, motion would be communicable without reſiſtance, and conſequently without effecting any change in the force communicating it. The action of all forces, whether operating by the viſible impact of one body upon another, or the

inviſible agency of gravity, magnetiſm, &c. conſiſts in producing preſſure and motion; and reaction in ſupporting this preſſure, or reſiſting the production of motion. And theſe this law aſſerts to be equal, when eſtimated in oppoſite directions; which, being proved experimentally, like the two firſt, in all communications of motion with which we are acquainted, may be eſteemed a general principle pervading the whole material ſyſtem.

In the communication of preſſure upon any immoveable plane, whether ariſing from the protruſion, gravity, or force of impact, of a body; the meaning of the law is, that the reſiſtance of the plane, and an oppoſite force equal to that producing the preſſure, have preciſely the ſame effect, as they only deſtroy the force of protruſion, weight, or impact. In the communication of motion by viſible impact, the meaning of the law is, that action is mutual, equal and oppoſite, or that the quantities of motion loſt and gained, which meaſure this action and reaction, are equal when eſtimated in oppoſite directions. It is always ſuppoſed, that the quantity of motion is eſtimated by the product of the quantity of matter and velocity. No idea can be formed of the loſs of motion, except by communication; and that the quantity, loſt by the impinging body, is gained by the ſtruck body, appears from innumerable experiments upon the colliſion of bodies. If a perfectly hard, or a ſoft body, A, moving with the velocity V, impinge upon an equal unelaſtic body B, they will move together, after impact, with a velocity equal to $\frac{V}{2}$; and if A, moving with the velocity $V+u$, impinge upon B, moving in an oppoſite direction with the velocity u, they will move together, after impact, with a velocity equal to $\frac{V}{2}$. And whatever be the magnitudes of A and B, it is the invariable reſult of experiments, that the quantity of matter in A, multiplied into the velocity loſt by it, is equal to the quantity of matter in B, multiplied into the velocity which it gains by impact; or if l and g repreſent the velocities loſt by A and gained by B reſpectively, $A \times l = B \times g$. When A and B are perfectly elaſtic, the velocities loſt and gained are doubled, and the law ſtill obtains, $A \times 2l$ being equal to $B \times 2g$. If motion be communicated to any body A, by

any

any force *X* protruding, pulling, &c. the meaning of the law is, that the reaction, or reſiſtance, of *A* deſtroys ſuch a part of *X*'s force, as would be deſtroyed by a ſimilar force, capable of generating that motion in *A*, acting in oppoſition to *X*. In the communication of motion by unknown means, as by gravity, magnetiſm, repulſion, &c. the law aſſerts that the body, attracting or repelling, moves in an oppoſite direction to that of the body attracted or repelled, and with an equal quantity of motion. The attraction between the earth, and any body upon its ſurface, is mutual and equal; for, were it not, a rectilineal motion would enſue from the ſtronger attraction, which is contrary to experience. And, ſince gravity is an innate principle, it, and its effects will remain the ſame when that body is detached from the earth, and conſequently their attractions continue to be mutual and equal, and they will meet with equal moments. If two magnets *A* and *B*, whoſe weights are unequal, be placed upon two pieces of wood, floating in water within the reach of attraction, they will meet with velocities inverſely as their quantities of matter; and, if a reed be inſerted between them to prevent their junction, they will be quieſcent, which they would not be, were their attractions unequal. When the weight of *A* is equal to 2, 3, 4, &c. times that of *B*, its velocity, in an oppoſite direction, is equal to $\frac{1}{2}$, $\frac{1}{3}$, &c. of *B*'s, the products of their weights and velocities being always found to be equal. And if *A* is repelled, *B* is alſo found to be repelled in an oppoſite direction, and their velocities are always inverſely as their weights. This law, being found to obtain in all actions of bodies within the reach of experiments, is inferred to obtain univerſally through the material ſyſtem.

183. Cor. In the impact of bodies therefore the quantity of motion, eſtimated in the ſame direction, is the ſame before and after impact. If *A*, moving with a velocity equal to *a*, impinge upon *B*, moving in the ſame, or an oppoſite, direction, with a velocity equal to *b*, the ſum of their moments after impact, is equal to $Aa + Bb$, or $Aa - Bb$, according as they move in the ſame, or oppoſite directions; for, if they move in the ſame direction, the encreaſe

creaſe of moment communicated to *B* is deſtroyed in *A*, and their ſum continues the ſame; and, if they move in oppoſite directions, the leaſt moment, and a part of the other body's moment equal to it, are deſtroyed, ſo that their ſum after impact continues to be equal to $Aa - Bb$, the ſame as before impact.

COMPOSITION AND RESOLUTION OF FORCES.

184. *The ſame motion may be communicated to a body *B* by a ſingle force *Z*, and any number of conſpiring forces, into which it is ſaid to be reſolvable, and they are ſaid to be compounded into *Z*; thus the body *B* may deſcribe the line *BP*, in the ſame time, by a force *Z* acting in that direction, or by two, three, &c. forces *X*, *Y*, &c. inclined to it. For it is evident, that *B*, acted upon at the ſame time, by two forces *X*, *Y*, in directions making an angle, which ceaſe to act after the body has left the point *B*, will move in ſome intermediate rectilineal direction, and this, by changing the inclination and magnitude of *X* and *Y*, which are variable without limit, may be any intermediate line whatever *BP*. The force *Z* is ſaid to be reſolvable into the two, *X* and *Y*, producing the ſame effect with it; and, vice versâ, *X* and *Y* are ſaid to be compounded into one, *Z*, which produces the ſame effect with them.

PLATE III. FIG. XXVII.

185. PROP. *A body* B *urged at the ſame time, by two forces* x, y, *whoſe action ceaſes when the body has left the point* B, *and whoſe magnitudes and directions are as two right lines* BM, BN, *making any angle, will move as if it were impelled by one force* z, *whoſe magnitude and direction are as* BP, *the diagonal of a parallelogram, whoſe ſides are* BM *and* BN.†

FIG. XXVIII.

DEM.

* Newt. Princip. p. 14. Muſchen. Ch. X. Helſham, Lect. IV. Maclaurin's Newt. Ch. II. Graveſ. Lect. I. Ch. XIII. Hermannus, Lect. I. Ch. II. Varignon. Tom. I. Sect. I.

† The magnitudes of forces, whether animal exertions as percuſſions, protruſions, &c. or philoſophic powers, as gravity, magnetiſm, &c. can only be compared by meaſuring their effects, which are ſuppoſed to be produced uniformly in the ſame time. And, in this ſuppoſition, it is evident, that the concluſions will be the ſame, whether the forces *X*, *Y* be impulſes, or the ſame number of impulſes always equal to themſelves.

DEM. The acceſs of B to, or receſs from, MP, is not affected by the action of y; nor its acceſs to, or receſs from, NP, by the action of x (ſecond law of motion): therefore they will carry B to MP and NP reſpectively, in the ſame time, whether they act together or ſeparately. But if they act together, B, being carried to both MP and NP, muſt be found at P their interſection, and deſcribe BP uniformly (firſt law of motion); which is the magnitude and direction of z (180). Q. E. D.

Otherwiſe,

Let BM, moving parallel to NP uniformly, arrive at NP in the ſame time that B deſcribes BM uniformly, which conſequently at the end of that time will arrive at P. And if npm, be any new poſition of BM, and the body at p; $Bn : np ::$ velocity of BM: velocity of the body $:: BN : BM$ (106); therefore p is always in the diagonal BP; Bp encreaſes uniformly becauſe Bn does; and BP is the magnitude and direction of z (180). Q. E. D.*

186. Cor. 1. A force z, producing the ſame effect with two x and y, which are as BM, BN, is as twice Bs, ſuppoſing s to be the biſection of BP.

187. Cor. 2. If any two forces act upon a body, in directions which make an angle, it cannot be quieſcent.

188. Cor. 3. A force repreſented by a ſide of a triangle BP, may be ſubſtituted for two repreſented by the remaining ſides BM, MP; and it is ſaid to be equivalent to them, becauſe they produce

* This propoſition, which is deduced from the ſecond law of motion, may be demonſtrated not inelegantly from the third. The forces x and y, urging the body B obliquely, partly oppoſe each other, and ſince, from the third law of motion, the oppoſite parts are equal, the path of B will be equally diſtant from any cotemporary poſitions of it, M and N, when they act ſeparately; which therefore is Bs, s being the biſection of BP. And becauſe each of the forces x, y carry B through Bs, they will both carry it through $2Bs$ or BP, the diagonal of a parallelogram, whoſe ſides are BM and BN.

duce the ſame effect, or make a body deſcribe *BP* in the ſame time. And theſe three forces *BM*, *BP*, *BN* are in the ſame plane (Euc. B. XI. P. II.)

FIG. XXVIII. 189. Cor. 4. A force *BM* is equivalent to *BA* and *AM*; and *BN* to *BC* and *CN*; and therefore theſe forces *BA*, *AM*, *BC*, *CN*, are equivalent to, and may be ſubſtituted for, the force *BP*. And any number of forces, whoſe directions are in the ſame plane, may be reduced to one in that plane producing the ſame effect with them.

FIG. XXIX. 190. Cor. 5. A force *AH* is equivalent to two repreſented by *AB* and *AG*; and *AD* to *AH* and *AF*; therefore any number of forces *AG*, *AB*, *AF*, &c. in different planes, may be reduced to one *AD* producing the ſame effect with them.

FIG. XXVIII. XXIX. 191. Cor. 6. The converſe of this is true, and one force *BP*, or *AD*, may be reſolved into any number, either in the ſame, or different planes, producing the ſame effect with it.

FIG. XXX. 192. Cor. 7, The velocity generated by z: velocity generated by $x + y :: BP : BM + BN$; and the quantity of motion is therefore diminiſhed by compoſition, and encreaſed by reſolution; but, when eſtimated in any given direction *BL*, it remains invariable. For let *BP*, *BM*, *BN*, be each reſolved into two, one in the direction *BL*, and the other perpendicular to it; and from ſimilar triangles

$$Py : Dy :: yL : yn,$$

and comp. $PD : nL :: Dy : yn :: BE : Bm,$

therefore $BL = Bm + Bn.$

193. Cor. 8. The ſame force z, and conſequently the ſame velocity, may be generated by an infinite number of pairs of forces, becauſe

becauſe the ſame right line may be the diagonal of an infinite number of parallelograms.

194. Cor. 9. The parts, of the two forces, directly oppoſed to each other, are to the parts, acting in the diagonal, as $Mm + Nn$ to $Bm \pm Bn$, according as the angle MBN is not greater, or greater than a right angle. If x and y are given, and the angle MBN be ſuppoſed variable, and become equal to two right angles, then N will come to N', P to P', s to s' (s always biſecting BP and MN) and $2Bs'$, or the conſpiring parts of x and y, $= BP' = BM - BN$; if this angle vaniſh, then N will come to N'', P to P'', s to s'', and $2Bs''$, or the conſpiring parts of x and y, $= BP'' = BM + BN$. FIG. XXXI. FIG. XXXII.

195. Cor. 10. If BP and the angle BMP be given, the curve line paſſing through M, in different poſitions of M, is a circular arc ſubtended by BP; if BP and $BM + MP$ be given, this curve line is an ellipſe, whoſe focal diſtance is BP; and if BP and the difference of BM and MP be given, the curve is an hyperbola and BP its focal diſtance. PLATE IV. FIG. XXXIII.

196. PROP. *Any three forces* x, y, z, *whoſe directions are* Bx, By, BN *in the ſame plane, acting upon a body* B *without producing motion, are to each other as the three ſides of a triangle reſpectively parallel to their directions.* FIG. XXXIV.

DEM. Let BN be the magnitude of z, and be reſolved into two, in the directions yB, xB; viz. BM, BP; which muſt be reſpectively equal to x and y, becauſe in equilibrio with them, and acting in the ſame directions; therefore x, y, z, are to each other as BM, BP (MN), BN reſpectively. Q. E. D.

197. Cor. 1. x, y, z are to each other as the three ſides of a triangle reſpectively perpendicular, or equally inclined to their directions; for this is ſimilar to the former.

198. Cor. 2. Any two of these forces are to each other inversely as the sines of the angles, which their directions make with the direction of the third. For,

$z : y :: BN : BP ::$ sin. $\angle BPN$ or PBM : sin. $\angle BNP$ or NBM,
$z : x :: BN : BM ::$ sin. $\angle BMN$ or MBP : sin. $\angle MNB$ or NBP,
and $x : y :: BM : MN ::$ sin. $\angle BNM$ or NBP : sin. $\angle MBN$.

199. Cor. 3. The angle xBy, and magnitude of x and y, being given, the magnitude and direction of z may be found; for BM, MN and the angle BMN, the supplement to the angle xBy, being known, BN, and the angles MBN and MNB or NBP, may be found by trigonometry.

FIG. XXXV. 200. Cor. 4. Any number of forces in the same plane, acting upon a body B which remains quiescent, may be reduced to two equal and opposite: if BM, BN, BD, act upon B, they are equivalent to BP and BC in opposite directions, which must be equal, because B is quiescent.

201. Cor. 5. Any number of forces in different planes, urging a body without producing motion, may be reduced to two in the same plane, equal and opposite. If BD and DC be elevated above the plane BNM, and PBC be the common intersection of the planes BMN and BDC; BP, which is equivalent to BM and BN, must be equal to BC, which is equivalent to BD and DC, because they are opposite and destroy each other.

202. Cor. 6. If more than three forces BM, BN, and BD, each of which is combined from two, act in different planes, upon a body B without producing motion, and are estimated in any direction BL by letting fall parallel lines upon it, the forces resulting will produce no motion in that direction; for the parts of BM, BN, resulting from this resolution, which are in the direction BL, are equal and opposite to the part of BD reduced to the same direction, and the sums of the opposite parts, on each side of BL, must also be equal, because B is supposed to be quiescent.

203. Cor.

203. Cor. 7. If the forces *BM*, *BN*, *BC*, which act upon a body without producing motion, be reduced to any plane *FH*, by reſolving each into two, one perpendicular to it, and the other parallel to the lines joining the points, where the perpendiculars meet it, the forces reſulting will produce no motion in that plane. For *BP*, being taken equal and oppoſite to *BC*, will be equivalent to *BN* and *BM*, and *BC*, *BP* will be projected into equal ſtraight lines *bc*, *bp*; but *BN*, *MP*, being equal and parallel, are projected into equal and parallel lines *bn*, *mp*, and the figure *bmpn*, is a parallelogram. And *bm*, *bn*, being equivalent to *bp*, will be equivalent to its equal and oppoſite *bc*. FIG. XXXVI.

204. PROP. *If a body be acted upon by two ſimilar variable forces, in directions parallel to* BP, BQ, *making any angle, which act when the body hath left the point* B, *it will deſcribe a right line.* FIG. XXXVII.

DEM. Let the forces act by impulſes at the beginning of equal particles of time, and let *BD*, *DE*, *EF*, and *BG*, *GH*, *HI* be the relative magnitudes of correſponding impulſes. By the action of the two firſt impulſes *BD*, *BG*, the body will move in the direction *BK* (185); by the two next *DE*, *GH*, it will deſcribe, in the ſame direction, *KL*, &c.; and, becauſe the forces are ſimilar, *BD* : *DE* :: *BG* : *GH*, and componendo *BD* : *BG* :: *BE* : *BH*, and conſequently *BKL* is a right line. Q. E. D.

205. Cor. 1. Since this demonſtration does not depend upon the magnitude of the particles of time, into which the whole time is ſuppoſed to be divided, it will obtain when theſe particles are evaneſcent and the forces act inceſſantly.

206. Cor. 2. If the forces be conſtant, the velocity in *BM* is uniformly accelerated; for, in this ſuppoſition, *BD*, *DE*, &c. are equal, and *BD* : *DE* :: *BK* : *KL*; but *BK*, *KL* which are therefore equal, &c. meaſure the increments of velocity communicated at *B* and *K* (106).

207. Cor. 3. Every body moving in a curve line, muſt be acted upon by, at leaſt, two diſſimilar forces.

208. Cor. 4. The whole force in the direction *BP* is the ſum of the impulſes *BD*, *DE*, *EF*, &c. and the force in the direction *BM*, is the ſum of the impulſes *BK*, *KL*, *LM*, &c. and theſe forces are ſimilar; for *BD*, *DE*, &c. meaſure the intenſity of the force in the direction *BP* at the points *B* and *D*; and *BK*, *KL*, &c. meaſure the intenſity of the force in the direction *BM*, at *B* and *K*, and $BD : DE :: BK : KL$.

FIG. XXXVII.

209. PROP. 86. *If a body be urged at the ſame time by two conſtant, or ſimilar variable, forces* x, y, *whoſe magnitudes and directions are the two ſides of a parallelogram* BF, BI, *it will move in the ſame manner as if it were urged by a conſtant or ſimilar variable force* z, *repreſented by the diagonal.*

DEM. The impulſe *BK* is equivalent to *BD* and *BG*; *KL* to *DE* and *GH*; *LM* to *EF* and *HI*, &c. conſequently the ſum of theſe impulſes *BM* is equivalent to *BF* and *BI*. Q. E. D.

210. Cor. 1. A force repreſented by one ſide of a triangle *BM*, may be ſubſtituted for two ſimilar forces repreſented by the remaining ſides *BF*, *FM*.

211. Cor. 2. A force repreſented by *BM* may be reduced into any number of forces *BR*, *RS*, *SM*, ſimilar to it, and vice verſâ.

212. Cor. 3. Three ſimilar variable forces, urging a body without producing motion, are to one another as the three ſides of a triangle, parallel or perpendicular to their directions; and they are to each other inverſely as the ſines of the angles, which their directions

directions make with the direction of the third (198); and any number of ſimilar forces in the ſame or different planes, in equilibrio, may be reduced to two, in the ſame plane, equal and oppoſite.

SCHOLIUM.

213. Prop. (204) may be demonſtrated per ſaltum, though perhaps leſs intelligibly, by the following proceſs. Let a body B be urged, at the ſame time, by any forces x and y, in the directions BM, BN, which carry it reſpectively through Bm, Bn and BM, BN, in equal times; and it is evident that, at the end of thoſe times, B will be in d and D. If x and y act only at the point B, or if $Bm : BM :: Bn : BN$, the path of B is the diagonal; if they act at B, m, n, M, N, &c. and Bm be to BM as the times of deſcription, and Bn be to BN as the ſquares, cubes, &c. of thoſe times; $Bn : BN :: Bm^2 : BM^2$ or $Bm^3 : BM^3$, &c.; and the path of B is a parabola, &c. FIG. XXXVIII.

214. PROP. 87. *A body* B *impelled by two forces tending to two equidiſtant points*, Q, R, *which at equal diſtances are equal, and at unequal diſtances are variable according to any law whatever, will deſcribe a right line.* FIG. XXXIX.

DEM. Let theſe forces act by impulſes at the beginning of equal particles of time, and BE, BF being the magnitude of the two firſt, will make B deſcribe BD, which produced biſects the baſe QR; and DL, DM, the two next, will make it deſcribe DN, biſecting the baſe QR: therefore BN is a right line; and the demonſtration obtains when the particles of time are evaneſcent, and the action of the forces inceſſant. Q. E. D.

215. Cor. The direction of the combined attraction of all the particles, compoſing a ſphere, paſſes through the center: for let it be divided into thin laminæ parallel and contiguous to each other,

and

and let Q, R, be any corpuſcules in a lamina, equidiſtant from PB paſſing through the center, and what has been proved of theſe two may be proved of every two equidiſtant from P, which compoſe the whole lamina; and the ſame may be proved of every lamina, and conſequently of the whole ſphere.

SCHOLIUM.

216. Three forces, acting upon a body without producing motion, are to each other as the three ſides of a triangle parallel to their direction, which conſequently meet in the ſame point of the body, and are in the ſame plane (EUC. B. XI. P. II.). This may be evinced otherwiſe; for ſince a body, acted upon by any number of forces, cannot be at reſt, unleſs they oppoſe each other, and the oppoſite parts be equal, and in the ſame direction; it is clear that a plane AB may paſs through P, acted upon by x, y, z in different planes, ſo that they ſhall be on the ſame ſide of AB, and therefore, as they partly conſpire, they muſt communicate motion to the point P, and to the whole body. And if any two of theſe forces, x, y, act againſt the ſame point p of the body AB, and x acts againſt q; x and y will communicate motion to p (187) and z to q, and AB cannot therefore be quieſcent. If the directions of x and y meet in a point p without the body, and z act at the point q, AB cannot be at reſt; becauſe x and y have the ſame effect with, and are equivalent to, ſome force in an intermediate direction pd, which is not oppoſite to the direction of z, and cannot therefore deſtroy it. It is ſuppoſed, that the directions of theſe forces are inclined to each other; for, if they be parallel, BA may be quieſcent, when they act upon different points.

PLATE V. FIG. XL. FIG. XLI. FIG. XLII.

FIG. XLIII. 217. PROP. *If a body* B *be acted upon by any number of forces, at the ſame time, whoſe magnitudes and directions are* BC, BA, BF, BH, *&c. and from the biſection,* m, *of the diagonal* BD *of a parallelogram, whoſe ſides are* BC, BA, *a right line be drawn to the extremity* F, *of* BF, *cutting the diagonal* BE, *of a parallelogram whoſe ſides are* BD, BF, *in* n, *and from* n *a right line be drawn to the extremity,* H, *of* BH,

cutting the diagonal BG *of a parallelogram, whoſe ſides are* BE, BH, *in* p, Bp : BG :: *unity* : *number of forces.*

DEM. The triangles Bpn and GpH, Bnm and nEF, are ſimilar, and conſequently $Bp : pG :: Bn : GH(Bn+nE) :: Bm : Bm+EF(Bm+BD$ or $3Bm)$; therefore $Bp : BG :: Bn : 4Bm :: 1 : 4$. The proceſs is ſimilar when there are more forces. Q. E. D.

218. Cor. 1. It is evident, from the conſtruction of the figure, and ſimilar triangles, that $CA : Cm :: 2 : 1$,
$mF : mn :: 3 : 1$,
$nH : np :: 4 : 1$; and if the number of forces were equal to any number, m, nH would be to $np :: m : 1$.

219. Cor. 2. The force BG, reſulting from the action of any number of forces BC, BA, BF, BH, &c. either in the ſame, or a different, plane, is to their ſum as $BG : BC+BA+BF+BH$, &c. and if the magnitudes and directions of theſe forces be given, the magnitude and direction of BG may be found; for CB, BA, and the $\angle CBA$ being given, BD, and the $\angle$s CBD, DBA, are known; and DB, BF, and the $\angle DBF$ (which may be found) being given, BE is alſo given, and in the ſame manner any other diagonals may be inveſtigated.

220. Cor. 3. If a body therefore be acted upon by any number of forces BA, BC, BD, BE, BF, BG, the directions of the forces reſulting from the action of two, three, four, &c. are found by joining AC, biſecting it in m, and taking $mD : mn :: 3 : 1$, $nE : nP :: 4 : 1$, $pF : pq :: 5 : 1$, $qG : qr :: 6 : 1$, and the directions are Bm, Bn, Bp, Bq, Br. Their magnitudes are $2Bm$, $3Bn$, $4Bp$, $5Bq$, $6Br$, &c. FIG. XLIV.

221. Cor.

FIG. XLV. 221. Cor. 4. The ſame force BP may be generated by the action of 1, 2, 3, &c. forces, either in the ſame, or different, planes, whoſe directions and quantities are variable in infinitum: for let it reſult from the combined action of four forces, and taking $BP : Bq :: 4 : 1$, through q draw any line whatever qA, and take $qA : qP :: 3 : 1$; through p draw any line pC, and let pC be to $pn :: 2 : 1$; and through n draw any line nD, and taking nE equal to it; the forces BA, BC, BD, BE, are equivalent to BP. The lines qA, pC, nD, &c. may be drawn in any directions, in any different planes, and of any different lengths.

FIG. XLVI. 222. PROP. *The directions of three forces* x, y, z, *acting upon a body* B *without producing motion, will meet in the center of gravity of a triangle, whoſe diſtances from the angular points, are as the magnitudes of the forces.*

DEM. Produce AB, and taking $BE = AB = z$, complete the parallelogram $BDEC$ by drawing from E lines parallel to BC, BD; BE is equivalent to BC and BD, and equal to z, which is equivalent to x and y, which muſt therefore be equal to BC, and BD, reſpectively; but $BG = \frac{BE}{2} = \frac{AB}{2}$, and B is therefore the center of gravity of the triangle. Q. E. D.

Otherwiſe:

Let BA, BC, BD, be the magnitudes of z, x, y, reſpectively, and joining DC and biſecting it in G, and joining GA, $AB = 2BG$ (217). Q. E. D.

FIG. XLVII. 223. PROP. *If a body* B, *be acted upon by four forces, in different planes,* x, y, z, w, *or* BA, BC, BE, BF, *and remain at reſt, they are to each other as the three ſides and diagonal of a parallelopiped parallel to their directions reſpectively.*

DEM.

DEM. The forces BA, BC are equivalent to BI, and BI, BE to BD, which muſt be equal and oppoſite to w or BF, becauſe B is quieſcent. Q. E. D.

224. Cor. An infinite number of parallelopipeds may be deſcribed, whoſe ſides and diagonal are the ſame: for let x, y, z, w, be invariable, and taking BC, BA, equal reſpectively to y and x, making any angle whatever ABC, and BD, ID in a different plane, reſpectively equal to w and z, draw BE parallel to ID, and DE to BI. Biſect BI in H, and join EH, interſecting DB in G; and becauſe the triangles BGH, EGD are ſimilar, $EG : GH :: ED\ (2BH) : BH :: 2 : 1$; therefore theſe two forces combined with BE produce a force paſſing through G (217); and becauſe $DG : GB :: EG : GH :: 2 : 1$ and $DB : GB :: 3 : 1$, the force w is equal to DB. But the angle CBA is infinitely variable, and BD, FD may be drawn in any planes whatever. FIG. XLVII.

225. PROP. *If four forces*, x, y, z, w, *which are as* BA, BD, BE, BF *reſpectively, act in different planes, upon the body* B *without producing motion*, B *is the center of gravity of a triangular pyramid whoſe baſe is* EAD *and vertex* F. FIG. XLVIII.

DEM. Join AD, and biſect it in m, and, taking mn to $nE :: 1 : 2$, n will be the center of gravity of the triangle EAD, and nB is the direction of the force reſulting from x, y, z combined, and its magnitude is equal to $3 \times Bn$, which muſt be equal and oppoſite to w or BF, becauſe B is quieſcent: BF is therefore equal to $3Bn$, and B conſequently the center of gravity of a pyramid, whoſe baſe is EAD and vertex F. Q. E. D.

226. Cor. 1. It is evident that $BF = 3Bn$, becauſe the force reſulting from $x + y + z$ is to thoſe forces as $3Bn : BA + BD + BE$ (220) and $w : x + y + z :: BF : BA + BD + BE$ (hypoth.) therefore $w = BF = 3Bn$.

227. Cor. 2. The force reſulting from the combined action of *BA*, *BD*, *BE* paſſes through the center of gravity of a triangle, which is formed by joining *A*, *E*, *D*; and the direction of a force, equivalent to them, paſſes through the ſame point.

228. Cor. 3. An indefinite number of pyramids may be deſcribed, having the diſtance of their angular points from the center of gravity always the ſame; for let *BA*, *BD*, *BE*, *BF*, be invariable, and making the angle *ABD* of any magnitude whatever, draw *CD*, *BD*, in any plane whatever, equal reſpectively to *BE*, *BF*, and complete the parallelogram *BCDE*, and the proceſs is the ſame as that in (224).

FIG. XLIX.

CHAP.

CHAP. V.

OF ATTRACTION.

229. DEF. *THAT power or principle in nature, by whoſe influence bodies, or the conſtituent parts of bodies, accede, or have a tendency to accede, to each other, without any ſenſible material impulſe, is called attraction.*

230. DEF. *That natural power, by whoſe influence different bodies, or different parts of the ſame body, recede, or have a tendency to recede, from each other, without any ſenſible material effect, is repulſion.*

When the changes of motion in the body *A* are uniformly obſerved to depend upon the ſituation and diſtance of another body *B*, a connexion is underſtood to obtain between them, expreſſing ſome quality or mechanical affection of matter, ſuch as gravity, coheſion, elaſticity, magnetiſm, electricity, which appears to reſide in matter, and by whoſe agency this change of motion is conceived to be produced. If the direction of *A*'s motion, or tendency to motion, be towards *B*, it is ſaid to be attracted by *B*; and if it be from *B*, it is ſaid to be repelled by *B*.

231. That there are in nature motions and tendencies to motion, conatus accedendi & recedendi, both in aggregate bodies, and in their minute conſtituent particles, without any ſenſible cauſe, and indeed inexplicable by any known properties of matter, is unqueſtionably certain. Theſe demonſtrate a ſource of motion diſtinct from, and repugnant to, any material impulſe with which

we are acquainted, which is denominated attraction, a term indifferently applied to the mechanical affection and its effects, as all inexplicable powers are only measurable by their effects. These effects being found by observation to be different at different distances, the intensity of the power producing them is inferred to be variable, and the law of variation is discovered by an actual mensuration of these effects at different known distances. By this process, these material affections, though intelligible only in their effects, are considered as quantities capable of mathematical comparison, and their ratios are compared with those of lines and numbers. Attraction is usually divided into two kinds: *first*, that which operates at sensible distances, as gravity, electricity, magnetism; and, *secondly*, that, whose effects are limited to almost insensible distances, which is called the attraction of cohesion.

ATTRACTION of GRAVITY.

232. The existence of this species of attraction is evidenced by uniform experience. Matter when supported is heavy, and, the support being removed, accedes towards the earth; when projected obliquely, it deviates from the line of projection, and vibrates when suspended by a string inclined to the earth's surface. And the direction of this motion of matter, and tendency to motion, is invariably the same, towards the center of the earth nearly. A mechanical affection is justly inferred from these phenomena (230), which is conceived to produce this motion and tendency to motion, and is promiscuously called gravity, gravitation, or the attraction of gravity. But more correctly the tendency of a body towards the earth, which is measured by the velocity acquired in a given time, is called the accelerating force of gravity; the weight or moment of a body, which is measured by the product of the quantity of matter and the accelerating force, is called its vis motrix; and the power conceived to be in the earth, which produces this weight and tendency towards it, is called the absolute force or attraction of gravity; and a body influenced by it, is said to be attracted by, or gravitate towards, the earth. All hard and soft

bodies

bodies are ſubject to this attractive power, and have weight; air, water, and other fluids, and the vapours ariſing from them, and all odorous ſubſtances, and exhalations from all terreſtrial bodies, gravitate towards the earth, as they may be collected in a balance and actually weighed; and the weight of theſe laſt ſubſtances is alſo rightly inferred from the decrement of weight ſuſtained by the evaporable matter. Even fire and light, and the moſt volatile vapours, ſeem to be under the controul of this univerſal principle, and no matter in the vicinity of the earth, acceſſible to experiments, hath yet been diſcovered to be uninfluenced by it, and conſequently all matter may be conſidered as gravitating towards the earth, till future ſatisfactory experiments induce a different opinion. This attractive power is not confined to bodies in the vicinity of the earth, but extends alſo to the moon; for the moon deſcribes equal areas in equal times about the earth's center, and is therefore urged by a force directed to that center (NEWT. Sect. II. P. II.) and coincident in direction with gravity: and it appears, from aſtronomical obſervations, that it is equal in quantity to the force of gravity at that diſtance, and they are conſequently the ſame power. And becauſe the revolutions of their ſatellites round jupiter and ſaturn, and of the primary planets round the ſun, are phenomena ſimilar to that of the moon round the earth, both being acted upon by forces directed to their reſpective centers, which vary according to the ſame law; the ſatellites therefore gravitate towards their primaries, and theſe towards the ſun (7). The primary planets gravitate towards each other; for jupiter and ſaturn, in conjunction or at their leaſt diſtance, are diſcovered to produce very ſenſible irregularities in each other's motions; and the motions of their ſatellites are ſaid alſo to be ſubject to irregularities, which are ſenſible at their leaſt diſtance where their action is greateſt. All the great bodies, compoſing the ſolar ſyſtem, are therefore impreſſed with this principle of attraction; which, being attached to the whole of any body, muſt pervade every conſtituent portion; and the minuteſt particles of matter gravitate, though perhaps inſenſibly, towards each other. The operation of this principle between two ſmall bodies, at the ſurface of the earth, is only rendered inſenſible from the predominant influence of the

earth;

earth; for a pendulous body was obſerved to be conſiderably deflected from its vertical ſituation by the attraction of the mountain Chimborazo in Peru; and, by ſome ingenious experiments made with great preciſion, Dr. Maſkelyne aſcertained the quantity of attraction of the mountain Schehallien in Scotland.* Every mountain therefore, and every leſs portion of the earth, poſſeſſes this quality; which might have been inferred from (215). For if a particle of matter be attracted by every part of a ſphere of matter, equally at equal diſtances, the direction of the combined attraction will paſs through its center and *v . v*; but it appears, from experience, that all bodies deſcend in directions perpendicular to the earth's ſurface, and, becauſe the earth is nearly ſpherical, the whole force, producing this deſcent, is directed nearly to the center, and is conſequently combined of the force of every particle.

233. PROP. *The accelerating force of gravity at equal diſtances from the earth's center, is the ſame in all bodies, whether quieſcent or moving, and whatever be their magnitude, figure, denſity.*

DEM. This propoſition is only demonſtrable from experiments. Two equal wooden boxes, ſuſpended by threads of eleven feet in length, one of which was filled with wood, and an equal weight of gold fixed in the center of oſcillation of the other, were diſcovered by Sir I. Newton, to perform all equal vibrations in the ſame time; and numberleſs experiments demonſtrate that all bodies,

* If a mountain do poſſeſs an attractive power, a body ſuſpended near it will be deflected from its vertical poſition, and point to a falſe zenith, and the arc, meaſuring the diſtance of this from the true, is the meaſure of the mountain's attraction. In an obſervation on the north ſide of Schehallien, the plumb line, being deflected towards the mountain, pointed too much to the ſouth, and gave the diſtance of a ſtar from the zenith too much to the north; and from an obſervation made on the north ſide, the diſtance was too much to the ſouth. The difference of the latitude of the two ſtations, collected by theſe obſervations, muſt be greater than it really is, by the ſum of the arcs meaſuring the deflections from the two zeniths. From obſervations of ten ſtars near the zenith, Dr. Maſkelyne found the difference of the latitude of the two ſtations to be 54″6; and, from a menſuration of their diſtance, it was only 43″: the difference of theſe is 11″6, and the half of it 5″8, meaſures the attraction of the mountain. This experiment is moſt convincing, and deciſive in ſupport of the univerſality of gravitation.

dies, however different their magnitude, figure, and denſity, deſcend in an exhauſted receiver, whatever be its height, exactly in the ſame time; and conſequently the tendency of bodies towards the earth, or their accelerating force, is the ſame whether quieſcent or moving, &c.* Q. E. D.

234. PROP. *The weight of bodies, at the ſurface of the earth, are proportional to their quantities of matter.*

DEM. The weight of a body is evidently as the number of equal particles or quantity of matter contained in it, multiplied into the tendency towards the earth, or accelerating force of each, and this being given (233) varies as the quantity of matter. Q. E. D.

Otherwiſe:

The weight of any two bodies *A* and *B*, or the forces producing them, are clearly proportional to their vis inertiæ; for if the vis inertiæ of *A* were to that of *B*, as 1, 2, 3, &c. : 1, it is evident that the weights or forces, producing the ſame velocities in *A* and *B* in the ſame time, will be as 1, 2, 3, &c, : 1; and conſequently the weight, being as the vis inertiæ, will be as the quantity of matter (166). Q. E. D.

235. Cor. If the accelerating force of gravity were encreaſed in any ratio, the weight of a given body would be encreaſed in the ſame ratio. Subſtituting therefore W, Q, F, for the weight, quantity of matter, and force of gravity, reſpectively, and ſuppoſing them to be variable; W will be as $Q \times F$; F as $\frac{W}{Q}$; Q as $\frac{W}{F}$, and, if W be given, F and Q are inverſely as each other.

SCHO-

* All bodies, whether great or ſmall, denſe or rare, acquire a velocity in falling 1″, which would carry them uniformly through 32.2 feet in 1″, and an encreaſe of velocity, equal to this, is found to be added in every ſucceeding ſecond of time.

SCHOLIUM.*

236. In the ſame place, and at the ſame diſtance from the æquator, bodies are found to deſcend through the ſame ſpace in the ſame time always; but, the force of gravity being diminiſhed unequally by the diurnal rotation of the earth, they do not, and ought not to, deſcend through equal ſpaces, or perform equal vibrations, in the ſame time, at different diſtances from the æquator. However, this unequal diminution of gravity, ariſing from the different centrifugal forces, does not afford a ſolution for the different ſpaces fallen through; and there muſt be ſome other cauſes of inequality, which are probably the difference of diſtance from the center, and different ſpecies of matter near the places of obſervation.

237. PROP. *The force of gravity varies as the ſquare of the diſtance from the center of the earth inverſely.*

PLATE VI. FIG. LI.

DEM. Gravity acts in right lines, and, whatever be the cauſe, is equally diffuſed over every point of the ſurface $ABDC$, equidiſtant from the center of the earth S; and that ſame influence is alſo equally diffuſed over the ſurface $abdc$, ſimilar to the former and ſimilarly ſituated. Taking $almn$ equal and ſimilar to $ABDC$, the influence of gravity upon $almn$: influence upon $abdc$ or $ABDC :: almn (ABDC) : abdc :: SA^2 : Sa^2$. Q. E. D.

Another

* PROP. *Suppoſing the earth to be ſpherical, the diminution of gravity, ariſing from the centrifugal force, varies as the ſquare of the coſine of latitude.*

PLATE VI. FIG. L.

DEM. Let Pp be the earth's axis, and $\text{Æ}\mathcal{Q}$ its æquator, and the centrifugal force at $\mathcal{Q}$: centrifugal force at $A :: \mathcal{Q}C : AD$; the centrifugal force at A: that part oppoſite to gravity :: $AN : AL$ (ſuppoſing NL to be perpendicular to AC) :: $AC : AD$; and conſequently the centrifugal force, or diminution of gravity at $\mathcal{Q}$: the diminution of gravity at $A :: \mathcal{Q}C^2 : AD^2$. This diminution of gravity varies therefore as AD^2, or as the ſquare of the coſine of the place's diſtance from $\mathcal{Q}$. Q. E. D.

Another demonſtration:

The magnitude of the earth's attractive force, at different diſtances, varies as the ſpace through which it impels a body in equal times; but a body at the earth's ſurface falls through 16.1 feet in 1″, and the moon, at her mean diſtance, nearly 60 ſemidiameters of the earth, falls through $\frac{16.1}{60 \times 60}$ feet in 1″ (from obſervation): preſuming therefore that the moon is retained in her orbit by the earth's attractive power, the force of gravity at the earth's ſurface, is to the force at the moon, as $16.1 : \frac{16.1}{60 \times 60} :: 60 \times 60 : 1$. Q. E. D.

238. Cor. 1. The firſt of theſe demonſtrations is applicable to all forces diffuſed by rectilineal effluvia of matter from a center, as heat, ſmells, &c.

239. Cor. 2. Putting d for the ſemidiameter of the earth, and W for the weight of a body at the earth's ſurface, its weight at any other diſtance nd (n being a number) will be equal to $\frac{W}{n^2}$. A weight, of 3600 lb. at the earth's ſurface, is equal to $\frac{3600}{60 \times 60}$ or 1 lb. at the diſtance of the moon.

240. Cor. 3. If BC and bc be homogeneous and ſimilar, their weights at unequal diſtances are equal; for they are to each other as $\frac{BC}{\overline{SA}^2} : \frac{bc}{\overline{Sa}^2}$ (237) as 1 : 1. If they be not homogeneous, their weights will be as their quantities of matter, that is, as their weights at equal diſtances, divided by the ſquares of their diſtances.

SCHOLIUM I.

241. The variation of the force of gravity was collected from obſervation in Peru by Meſſ. Condamine and Bouguer. Condamine found that the ſame pendulum upon mount Pichinca, at Quito, and upon the banks of the river of the Amazons, performed reſpectively 98720, 98740 and 98770 vibrations, in twenty-four hours. And Bouguer obſerved upon the ſummit of Pichinca, and upon the ſea-ſhore, being $\frac{1}{1349}$th part nearer to the center of the earth, that the lengths of iſocronous pendulums were to each other as 438.71 to 439.7. Theſe obſervations demonſtrate a diminution of the force of gravity in receding from the earth's ſurface; but the law of variation cannot be collected from them, or any other ſimilar experiments, with preciſion; becauſe the different ſtates of the atmoſphere, of heat and cold, and different denſities of the earth contiguous to the different places of obſervation, would proportionably affect the experiments, and theſe cannot be aſcertained with ſufficient accuracy. From the obſervations of Bouguer, the force of gravity upon the mountain and upon the ſea-ſhore, is as 99575 : 99802; and, ſuppoſing it to vary inverſely as the ſquare of the diſtance, it is as 99575 : 99722; which differs leſs from the true law than could be expected.

SCHOLIUM II.

242. An inveſtigation of the cauſe of attractions and their mode of operation, and particularly of this mechanical affection of matter, its gravity, ſo univerſally prevalent, hath long been the object of the philoſopher's reſearches, but without effect; the ſubject is ſtill involved in impenetrable darkneſs, and his wiſhes are unſatisfied. Dr. Halley refers it to the immediate agency of the Creator; Mr. Cotes deems it eſſential to matter, like extenſion and mobility, &c. and Sir I. Newton ſeems to entertain a different opinion, and attributes it to ſome undiſcovered and inviſible mechanical affection of matter. Electrical and magnetic experiments prove the exiſtence

ence of a ſubtle fluid pervading the pores of the denſeſt bodies, and the gravity of bodies may ariſe from the action of a fluid, whoſe particles are ſo ſmall as to paſs through all bodies, and does not therefore reſiſt their motion; and, if endued with a ſtrong repulſive power, it will by expanding itſelf preſs upon groſs bodies. This æther, Newton ſuppoſes, is, from its repulſive force, much rarer within the denſe bodies of the ſun and planets, than in empty ſpace, and in receding from them becomes perpetually denſer and more elaſtic, and therefore occaſions their gravity, every body being impelled from the denſer towards the rarer parts of the fluid. This however is conjectural, and its truth or falſehood can only be eſtabliſhed by future experiments. All that is certainly known about this myſterious cauſe, is, that it cannot ariſe from the preſſure of a fluid ſimilar to thoſe with which we are acquainted, whether ſoft or elaſtic, quiet or agitated, for the following reaſons. *Firſt*, Becauſe a fluid, ſubtle enough to penetrate the inmoſt receſſes of the denſeſt bodies, and ſo rare as not to impede their motion, cannot be conceived capable of communicating motion to them. *Secondly*, Becauſe the attraction of gravity penetrates the inmoſt receſſes of bodies, and their weights are proportional to their quantities of matter, not magnitude of ſurface; but the preſſure of every fluid with which we are acquainted, varies as the ſurface oppoſed to it. *Thirdly*, Becauſe the attraction of gravity acts with equal intenſity upon bodies, whether quieſcent or moving; but all known fluids act upon quieſcent and moving bodies with different forces. But, however unſearchable the efficient cauſe of gravity may be, its final cauſe is moſt conſpicuous, being the preſervation of the earth and other planets, and of their periodical revolutions, which are only continued by an uninterrupted exertion of this mechanical affection of matter.

CHAP. VI.

ATTRACTION OF COHESION.

*A SECOND ſpecies of attraction, diſtinguiſhed from that of gravity by the intenſity of its action, and the ſmall diſtances to which its influence extends, is that obſervable between the minute particles of bodies, whether hard, ſoft, or fluid. Hard and ſoft bodies have an appearance of endleſs compoſition; but they are compoſed of inſenſibly minute particles which cohere together and form greater, and theſe, being ſucceſſively compounded by the influence of the ſame principle, form ſucceſſively greater, till, by repeated coalitions, they become objects of ſenſe; and it appears, from many phenomena, that the particles of all known fluids have alſo a tendency to cohere with others. This mutual tendency to accede to each other, of the component parts of hard, ſoft, and fluid bodies, not ariſing from any ſenſible material impulſe, indicates that philoſophical relation denominated attraction (230); which, being great at the point of contact, and evaneſcent at the leaſt ſenſible diſtance, coincides, in theſe marks of ſimilitude, with innumerable phenomena, and the material power, from whoſe agency they are conceived to reſult, is called by the ſame name, the attraction of coheſion, becauſe they are all effected by the mutual action of particles, whoſe force is great when contiguous, and, when removed to any ſenſible diſtance, evaneſcent. But whether the phenomena, which have theſe marks of coincidence and ſimilitude, reſult from a common cauſe, varying at different diſtances, like the attraction of gravity, according to the ſame law of the diſtance, can only be aſcertained by experiments, which are yet too undeciſive to allow of accurate diſcrimination. The laws and limits of the action of theſe minute particles are ſtill unknown,

* Helſham, Lect. I, II. Muſchenbroek, Ch. XVIII. Newt. Opt. p. 380. Hamilton's Tracts, Lect. II.

known, and, from their almoſt inſenſibly minute ſphere of action, perhaps undiſcoverable; but its intenſity ſeems to vary according to ſome higher inverſe law of the diſtance than the duplicate, and therefore ſoon evaneſcent, that it may not interfere with the attraction of gravity.

243. PROP. *If the particles compoſing two ſpherical ſurfaces* AFC, BDE, *attract with forces, equal at equal diſtances, and at unequal diſtances, varying as the* n^{th} *power of the diſtance inverſely, a particle* P *will be attracted by them with a force varying inverſely as that power of the diſtance, whoſe exponent is* $n - 2$. FIG. LII.

DEM. The attraction of P towards theſe ſurfaces, is as the number of particles and power of each, or as $\frac{AFC}{PA^n} : \frac{BDE}{PB^n}$, or as $\frac{PA^2}{PA^n} : \frac{PB^2}{PB^n}$, or as $\frac{1}{PA^{n-2}} : \frac{1}{PB^{n-2}}$. Q. E. D.

244. Cor. 1. If $n = 2$, the attractions of theſe laminæ are as 1 : 1, or equal to each other; and the attraction of the ſolid $BECA$ is equal to that of one lamina multiplied into their number. The attraction therefore of this ſolid is to that of $PAC :: BA : PA$; and conſequently the attraction of a portion of matter, in contact with P, is not much greater than when removed to a ſmall diſtance.

245. Cor. 2. If $n = 3$, the attractive powers of any laminæ BDE, AFC, are to each other as $\frac{1}{PB} : \frac{1}{PA}$ or as the ordinates BI to AL of an equilateral hyperbola; and the whole attractive power of the body $BECA$ is to that of PAC :: area BL : area AR :: a finite quantity : a quantity infinitely greater. According to this ſuppoſition, the attraction of P is not much affected by the addition, or deduction, of new matter at a ſmall diſtance; for the encreaſe, FIG. LII.

encreaſe, or decreaſe, of force reſulting from it, would be finite, and conſequently infinitely leſs than that reſulting from contact. But if the ſurface of *P* were enlarged, and in contact with new matter, attracting according to this law, it's coheſive force would be proportionably encreaſed.

246. Cor. 3. If this attraction, at a finite diſtance, had a finite ratio to that of gravity, at the point of contact it would be infinitely ſuperior to that of gravity; and, if at the point of contact, the ratio between this attraction and gravity were finite, at any aſſignable diſtance it would be evaneſcent.

247. Cor. 4. The attraction of coheſion, being great in contact and inſenſible at a ſmall diſtance, varies in a higher than the inverſe duplicate ratio of the diſtance.

FIG. LII. LIV. 248. Cor. 5. Since the coheſive force of any particle *P*, in contact with the body *PAC*, varies as the quantity of ſurface, it will be greateſt when the ſurfaces of contact are plane. Two ſpecies of matter conſtructed of diſſimilar particles, *a*, *b*, *c*, *d*, *e*, *f*, *g*, &c. *l*, *m*, *n*, *o*, *p*, *q*, &c. have different degrees of hardneſs; for the ſurfaces of contact, and coheſive forces of *a*, *b*, *c*, *d*, &c. are greater than thoſe of *l*, *m*, *n*, &c.

249. Cor. 6. Of unequal ſimilar particles, the ſmalleſt are capable of the firmeſt coheſion, becauſe they have the greateſt ſurfaces of contact compared with their magnitudes, the ſurfaces being diminiſhed only as the ſquares, and the magnitudes as the cubes, of any lines ſimilarly placed in them.

250. Cor. 7. Hard bodies therefore may be conceived to be conſtructed of very ſmall particles, or ſuch as are terminated by plane ſurfaces; for collections of theſe particles cemented by this

principle

principle of cohesion, with which they are proved to be impressed, would constitute hard bodies. And soft bodies may be conceived to be combined from large spherical particles, or such as have many angular points, and do not allow of great surfaces of contact.

SCHOLIUM.

251. The existence of this natural power is collected, and a general idea of it formed, from the following familiar observations and experiments. *First, An attraction subsists between the component parts of hard and soft bodies.* The force required to separate the contiguons parts of hard bodies, which is equal to the force of cohesion, is much superior to their gravity, though they be full of pores and consist of portions collected into one mass, and touching only a few points; and it must be much greater between the smallest particles, whose surfaces are in contact, without any great intermediate vacuities. This attraction is very strong in all tenacious and viscid bodies, as pitch, rosin, &c. which adhere to every thing in contact with them; and if a body very soft and viscid be extended, it will again contract its dimensions by the tendency of the parts to each other. Large ships, floating near each other in a calm sea, have a great tendency to each other, and are with difficulty kept from coming together. If the surfaces of the segments of two leaden bullets, whose diameters are not greater than $\frac{1}{4}$th of an inch, be polished, and compressed together by a gentle twist, it is said that a weight of 100 lb. is frequently required to separate them. And if two polished plates of glass, marble, brass, or any metalline substances, be compressed together and suspended in an exhausted receiver, the weight of the lower plate will not dissolve their cohesion; and if any fine thread be wrapped round one of them several times, at considerable intervals, after compression, their cohesion is still sensible, though they be removed from actual contact by the thickness of the thread. The cohesive forces of these substances is augmented by moistening their surfaces with water, oil, grease, &c. which expels the air from their pores, or, if very tenacious, keeps it confined, and prevents the

action of its repulsive power. The cohesive force of two polished plane surfaces of metal, whose diameters were two inches, heated in boiling water, and besmeared with grease, oil, &c. was overcome by the following weights:

	Cold grease.		Hot grease.
Planes of glass by	130 lb.	by	300 lb.
brass	150		800
copper	200		850
marble	225		600
silver	150		250
iron	300		950.

When these surfaces were moistened with water, oil, &c. and compressed together, their cohèsion was overcome by the weights in the following table:

With water	by	12 oz.
oil		18
Venice terpentine		24
rosin		850 lb.
tallow-candle		800
pitch		1400.

Secondly, An attraction subsists between the particles of any portions of water, oil, mercury, and all other fluids, except air, fire, and light. Small portions of these fluids form themselves into globular drops both in the open air and in vacuo; and if a drop of mercury be poured upon clean paper, or a drop of water upon the leaf of a plant, their spherical figure is not changed, the gravity of their parts being unable to dissolve their cohesion; and two drops of any fluid, not much attracted by the surface on which they are placed, will coalesce into one when in contact, as is often observable in drops of water lodged upon the leaves of plants. If mercury, well purged of air, be poured into a clean glass tube 70 inches long, so that its parts be contiguous to each other and to the glass, after inversion the whole column will remain suspended; but the pressure of the atmosphere sustains only 29 or 30 inches, and the remainder must be supported by some other agent, which is chiefly the mutual adhesion of the parts; for if they be discon-

tinued

tinued by a bubble of air intervening, or by ſhaking the glaſs, the column ſubſides to the height of 29 or 30 inches.

Thirdly, This ſpecies of attraction ſubſiſts between the particles of different fluids, and between them and other ſubſtances. If a piece of fir wood, whoſe ſurface is one ſquare inch, be ſoaked in water and float upon its ſurface, a weight of 50 grains, beſides an equivalent to its own weight, is required to detach it from the fluid; and when its ſurface is enlarged, a proportionably greater weight is required. Water riſes near the ſides of the veſſel containing it, round a glaſs bubble floating upon its ſurface, up capillary tubes of glaſs, plants, &c. A remarkable inſtance of this attraction occurs in the new invented water-pump. If two wheels, or pullies, *B* and *D* in the ſame plane, be made to revolve with great velocity, and *D* be immerſed in water, a column of water will aſcend with the rope; and, if there be two or more grooves in *B* and *D*, and as many ropes paſs over them, at the diſtance of about an inch, the columns raiſed by each rope will cohere, and the quantity of water be much augmented.* Air is incorporated with moſt hard bodies, poſſeſſes their interſtices, and probably ſerves as a bond of union to their conſtituent parts. It appears from many experiments, that the quantity of air, detached from ſome hard bodies in which it was conſolidated, by the action of fire, or ſome particular fermentation, is very conſiderable; and Dr. Hale diſcovered that $\frac{2}{3}$ of a calculus humanus were air. It is attracted by water, and perhaps all fluids, into whoſe pores it inſinuates itſelf, is intimately mixed

FIG. LV.

* There are two of theſe machines, at Windſor, of different dimenſions. The depth of the well at the round tower is 178 feet: *D* is the wheel in the water, its diameter = 12 inches, the thickneſs of the rope *DB* = $\frac{1}{2}$ inch nearly; diameter of the upper wheel *B* = 13 inches; diameter of *C* = 11 inches; diameter of *E* = 4 feet 6 inches; a power, applied at *F* turns the wheel *E* round, and that, by means of the ſtring *EC*, communicates motion to *G*, which has the ſame axis with *B*.

FIG. LV.

In the other machine the depth of the well is 95 feet, and, in this, the quantity of water, raiſed by the utmoſt efforts of a man, was at the rate of nine gallons in a minute. At Paris 500 pounds of water were elevated through an altitude equal to 240 feet, in ten minutes, when the diameter of the rope, ſurrounding the pullies, did not exceed ſix French lines. In the beginning of the motion, the column, adhering to the rope, is always leſs than when it has been worked for ſome time, and continues to encreaſe, till the ſurrounding air partake of its motion.

mixed with them, and coheres too ſtrongly to be ſeparated without the agency of fire, or ſome more attractive ſubſtance. If ſal ammoniac, or corroſive mercury ſublimate, be diſſolved in water, bubbles of air will diſengage themſelves from the water, and, adhering very tenaciouſly to the thin particles of the ſalt, aſcend with them, and burſt upon the ſurface. When water, beer, &c. are poured into a glaſs, or other veſſel, many bubbles of air are detached from the fluid by the ſtronger attraction of the veſſel, and adhere to its ſides and bottom; and, if theſe be rough, or have more points of contact, the number of bubbles will be encreaſed. Light is attracted by glaſs, water, and all tranſparent mediums, as appears by its refraction and reflection; and alſo by all other ſubſtances, as is obſervable in an experiment of Sir I. Newton.* A beam of light admitted through an aperture into a dark chamber, and paſſing by the edge of any ſubſtance, will be deflected from a rectilineal courſe, and by repeated attractions and repulſions deſcribe an undulating line in its paſſage.

OF HARDNESS, SOFTNESS, AND ELASTICITY.

252. DEF. *A hard body is that whoſe parts are not eaſily moved from their places; as wood, metal, ſtones, &c.*

Bodies conſtituted in ſuch a manner that their component parts do not give way to compreſſion, and whoſe coheſive force is inſuperable, may be called perfectly hard. The hardeſt bodies with which we are acquainted, as adamant, flint, gems, tempered ſteel, &c. are full of vacuities, and contiguous portions of them, not being in contact all round, are penetrable, and ſeparable by the action of a ſufficient force. Fire inſinuates itſelf amongſt the vacuities of the denſeſt and hardeſt bodies, and produces fuſion or expanſion, which cannot be effected without an intire ſeparation, and change of place, of their component parts. Perfect hardneſs therefore ſeems to be confined to the elementary particles, or leaſt parts into which bodies can be divided, whoſe figure and dimenſions cannot be ſeparated by any known power, and are impenetrable.

253. DEF.

* Newton's Optics, p. 317.

253. DEF. *A ſoft body is that whoſe parts change their poſition by the action of a ſmall force, and retain it when the force is removed; as butter, ſnow, wax, &c.*

Bodies conſtructed in ſuch a manner that their vacuities are not replete with any fluid, and whoſe parts do not repel each other, and are only retained in their places by their inertia, may be called perfectly ſoft; but no ſpecies of matter is perfectly ſoft, for the particles of all bodies, not poſſeſſed of a repelling power, require a much greater force to ſeparate them, than what is equivalent to their inertia. The degrees of hardneſs and ſoftneſs are infinitely variable, and the limit where hardneſs ends, and ſoftneſs begins, cannot be defined. In the congreſs of hard and ſoft bodies, there is no cauſe of ſeparation after they come into contact, and they will therefore either move on together, or be quieſcent, after impact; and, the effects of colliſion being aſcertained when there is no repulſive power, allowance muſt afterwards be made for their different degrees of repulſion.

254. DEF. *An elaſtic body is that which changes its figure, or the poſition of its parts, by the action of a force, and recovers, or has a tendency to recover, its figure.*

Elaſticity is ſaid to be perfect, when the parts of the body return to their firſt ſituation with a force equal to the force diſplacing them, and imperfect, when they do not.

255. PROP. *If a perfectly hard body* A *impinge upon a perfectly elaſtic immoveable body* B, *it will be reflected with a velocity equal to that of impact.*

DEM. The particles, compoſing the ſurface of *B*, are continually removed from their places by the compreſſion of *A*, till it and their reſiſtance become equal; and then, returning to their firſt ſituation with a force equal to that of compreſſion, and

in a direction oppoſite to *A*'s motion, *A* muſt evidently be repelled with a velocity equal to that of impact. Q. E. D.

256. Cor. 1. If *A* and *B* be both perfectly elaſtic, the particles, compoſing their ſurfaces, recede equally, though the receſs is leſs than when *A* was perfectly hard; but the effect is the ſame, the whole force of reſtitution being equal to that of compreſſion, and conſpiring to repel *A*.

257. Cor. 2. If *B* be moveable, the velocity loſt by *A* is double of that loſt by impact only; for the parts of *B*'s ſurface, contiguous to the point of impact, reſtoring themſelves with a force equal to that which diſplaced them and acting againſt *A*, it will be equally retarded by the forces of impact and reſtitution; and, for the ſame reaſon, the velocity communicated to *B* is double of what it would be, were both bodies perfectly hard.

258. Cor. 3. The relative velocity of *A* and *B* is the ſame before and after impact, or the velocity with which they accede to each other before impact, is equal to the velocity with which they recede from each other after impact; for the forces of impact and reſtitution, being equal and oppoſite, produce the ſame effects in oppoſite directions, and the relative velocity, which is deſtroyed by impact, muſt be reſtored by the force of elaſticity.

SCHOLIUM.

259. The whole time of contact of *A* and *B*, may be divided into two equal periods, the former between their firſt contact and the ceſſation of *A*'s compreſſion, and the latter between this point and their laſt contact, when they are ſeparated by the reſtoration of their relative velocity. And, if the time of *A*'s compreſſion be divided into very ſmall equal parts, *A*'s decrements of velocity produced in them will perpetually encreaſe, from the firſt

contact

contact to the end of compreſſion, where its force of protruſion vaniſhes, and it is ſtationary for a moment, if *B* be fixed, or, if *B* be moveable, its velocity is equal, for a moment, to that of *B*. The particles then returning, by their elaſticity, to their firſt ſituation, will communicate, in equal times, perpetually decreaſing increments of velocity to *A*, equal to the correſponding decrements during its compreſſion, which vaniſh when the ſurface has regained its natural ſtate, when *A* leaves *B*, and is reflected with a velocity equal to that loſt by impact. When *A* and *B* are both perfectly elaſtic, the particles, contiguous to the point of impact, give way equally; and when *A* is perfectly hard, and *B* imperfectly elaſtic, or when they are both elaſtic in different degrees, the particles yield to impact unequally, and a pit or cavity muſt be formed in one of them.

260. Cor. 4. If the times of compreſſion and reſtitution be divided into the ſame number of equal moments, and the decrements and increments of velocity, in correſponding moments of compreſſion and dilatation, be as $n : 1$, the velocity loſt by impact is to that communicated in an oppoſite direction, in the ſame ratio of $n : 1$ (EUC. B.V. P.XII.). And, if this ratio between theſe velocities always obtain, their correſponding increments and decrements will always be to each other in that ratio.

SCHOLIUM.

261. *The exiſtence of elaſticity is demonſtrated by numberleſs experiments. When two bodies impinge, they muſt coaleſce if the ſurfaces of contact be immoveable, or, after receding, remain immoveable; and their ſeparation is a proof of elaſticity. Metals, ſemimetals, ſtones, gems, foſſils, cartilages, moſt fluids, as air and even water, exert an influence oppoſite to the direction of the force compreſſing them, and diſcover a tendency to return to their natural ſtate, which is, in all of them, imperfect and leſs than the force impreſſed, but moſt perfect in glaſs, ivory, hardened ſteel and cartilages.

* Muſchenbroek, Ch. XVI. Deſaguliers, Lect. VI.

lages. Elaſticity is encreaſed by encreaſing the denſity of a body; for metals are rendered more elaſtic by being beaten with a hammer, and their elaſticity, which was not perceptible before, becomes after this very ſenſible. Steel is more elaſtic when tempered, and its denſity is then encreaſed in the ratio of 7809 : 7738. It is alſo ſometimes encreaſed by cold, as the range of a cannon ball is greater when the cannon is cold, than when heated, and the ſtring of a violin, or a ſteel lamina, is inflected, and recovers its ſituation with leſs force in hot than in cold weather. The ſphere of action of the component parts of an elaſtic body, and the moments of time in which they loſe, and recover, their ſituation, are too ſmall to allow of deciſive experiments for aſcertaining their intenſity, and laws of operation, at different diſtances from their natural ſtate; and the reſult of experiments is only the relative magnitude of the velocity loſt by impact, or the whole effect of compreſſion, and that communicated by the whole aggregate force of reſtitution. Metal fibres, and thin ſteel laminæ, exhibit no elaſticity unleſs ſtretched to a certain degree, and inflected by a certain force, as appears from lax chords, which, if a little ſtretched and removed from their natural ſtate, diſcover no tendency to return to it; and, when the inflection of a fibre is very great, the influence of elaſticity ſeems to be annihilated, as appears from fibres of wood, which, if inflected beyond a certain limit, remain quieſcent and have no tendency to recover their ſituation. This is alſo obſervable in elaſtic bodies, for their elaſticity is only diſcovered by impact, and the force of impact may be ſo ſmall as to excite no ſenſible motion of the conſtituent parts, or ſo great as to deſtroy their elaſticity; but the limits where it begins and terminates are unknown. A general idea of elaſticity may be formed by conſidering the moſt ſimple caſes of the vibrations of fibres, or thin ſteel laminæ, and conceiving elaſtic bodies to be compoſed of them.

FIG. LVI. EXP. I. If any fibre, metalline chord, or thin lamina of ſteel, whoſe length is *AB*, be ſtretched and fixed to two immoveable points *A* and *B*, and inflected into the poſition *ACB* by a power which ceaſes to act at *C*, it will return by its elaſticity to its natural ſtate *AB*,

AB, and, proceeding with the velocity acquired, continue to perform nearly equal vibrations on each ſide of AB till its motion be deſtroyed by friction, and the reſiſtance of the air.

Exp. II. If the diſtance of this fibre from a table, to which it is parallel, be equal to D, and a ſpherical ball P, whoſe diameter is $2D$, be rolled againſt it, the fibre will be inflected, and this inflection will encreaſe till P be quieſcent, and, then returning to its firſt ſituation, P will be repelled and detached from it, when arrived at AB, with a velocity nearly equal to that of impact.

Exp. III. Very ſmall inflections PD, PC, of the ſame fire AB, are found to be nearly as the inflecting forces; but when the inflections are conſiderable, they vary as ſome power of the force, whoſe exponent is leſs than unity or fractional. If AB be a ſmall braſs wire tended by a weight W of 3 lb. and inflected at P by weights equal to $\frac{1}{2}$ oz. and 1 oz. ſucceſſively, $PD : PC :: \frac{2}{3} : \frac{4}{3} :: \frac{1}{2} : 1$; or the inflections are as the inflecting forces.

Exp. IV. If the lengths of the wire be multiplied by 2, 3, &c. and the ſmall inflections PD, PC be always to each other as $\frac{1}{2} : 1$; the inflecting forces are found to be as 1 : 2 and 1 : 3, &c. or inverſely as the lengths of the wire.

Exp. V. If the lengths of the wire be the ſame as in Exp. III, W be equal to 3 lb. and 6 lb. and $PD : PC :: 1 : 2$, the ſame as before; the inflecting forces are as 1 : 2, or they vary directly as W.

262. Cor. 1. If F repreſent the inflecting force, L the length of the wire, I a ſmall inflection PD or PC; I is as F (Exp. III.); F is as $\frac{1}{L}$ (Exp. IV.); and F is as W (Exp. V.). And conſequently

if I, F, W be ſuppoſed to vary, the inflecting force F will vary as $\frac{I \times W}{L}$.

263. Cor. 2. Fibres of unequal thickneſſes may be conceived to be compoſed of a greater or leſs number of finer fibres of the ſame thickneſs, and if W, L, I, be given, it is evident that F will be as the number of ſmaller fibres, or as the area of a ſection of the fibre compoſed of them, or as the ſquare of its diameter (D^2); and conſequently F will vary as $\frac{I \times W \times D^2}{L}$.

264. Cor. 3. It is collected from theſe and other ſimilar experiments, that the elaſticity of a ſtretched fibre appears as ſoon as it is inflected by the impact of the ball, and continues to encreaſe to the limit of inflection, where, the moment of the ball and reſiſtance of the fibre becoming equal and oppoſite, the protruſion ceaſes; and, becauſe the velocities of impact and reſilition are always nearly equal whatever be the velocity of impact, the velocities of P are equal, at equal diſtances from the limit of inflection, both in its progreſs and regreſs.

FIG. LVII. 265. Cor. 4. Elaſtic bodies may be conceived to be formed of elaſtic fibres or ſtrata, ſuch as AB; for let the ſphere DBE be imagined to be compoſed of ſuch ſtrata, and ſtricken at D by a body perfectly hard, and the parts neareſt to D, receding by the force of impact, will communicate motion to the contiguous parts, and theſe to the next, till the different ſtrata be inflected as is repreſented by the dotted lines in the figure. When the motion of the impinging body is extinguiſhed, and the particles, compoſing the ſeveral ſtrata, are no longer protruded, they will return, by their elaſticity, to their firſt ſituation; and, if their velocity be perfect, with the ſame force in acceding to, and receding from, D; and conſequently the impinging body will be reflected with a force

equal

equal to the force of impact. And that this is not merely hypothetical, but that motion is diffuſed from the point of impact to the remote parts of elaſtic bodies, is preſumed from the following experiments.

EXP. VI. If a ſpherical ball of ivory *A* be preſſed againſt another *B*, whoſe ſurface is freſh painted with any colour, it will receive a ſmall point of that colour upon its ſurface; but if *A* impinge upon *B* with any velocity, the breadth of the ſpot will be magnified, and become ſtill greater as the velocity of impact is encreaſed. And, becauſe the ball retains its ſpherical figure after impact, the parts of its ſurface muſt have loſt, and recovered, their firſt ſituation.

EXP. VII. If two glaſs balls impinge with a proper degree of velocity, the interior parts of the balls will be broken, though the exterior, contiguous to the point of impact, be unbroken.

EXP. VIII. If two ivory balls *A* and *B* be ſuſpended from the ſame point by two ſtrings of the ſame length, and the leſs ball *A* impinge upon *B* at reſt with a given velocity, *A* will be reflected always to the ſame height, and *B* will be impelled to the ſame height, upon the graduated periphery of a circle whoſe radius is the length of the ſtring. But if either *A* or *B* be hollowed and lead inſerted in the center, or nearer to the poſterior ſurface, neither ball, though their weight be the ſame, will aſcend as high as before the inſertion of lead.

266. Cor. 1. Motion is therefore communicated from the point of impact to the contiguous parts (EXP. VI.), and diffuſed from thence to the remote parts of every elaſtic body (EXP. VII. & VIII.)

267. Cor. 2. It is evident, from Exp. VIII., that the progreſſive motion of the parts, from the point of impact, is ſtopped by the inſertion of lead, and conſequently that the force of reſtitution, and change of figure, is leſs, than before it was inſerted.

Exp. IX. A ſtroke or friction upon the edge of a glaſs, filled with water, communicates a tremulous motion to the parts of the glaſs, which is viſibly communicated to the water. A reed or ſtick, placed acroſs the bottom of a large glaſs bell, will fall when the bell is ſtruck, the ſtroke producing a change of figure; and, if a piece of metal be fixed near the brim or lip of the bell without touching it, and the bell be ſtricken by any hard body, it is ſeen to touch the metal, and a ſucceſſive of ſounds, perpetually decaying, may be heard. If the edge of the bell be pinched, and the fingers ſuddenly withdrawn, the ſame ſound is heard without producing any ſenſible motion towards the metal, or diſplacing the reed acroſs it.

268. Cor. The motion diffuſed from the point of impact, to the remote parts of an elaſtic body, is continued for ſome time, and diminiſhed gradually till it vaniſhes. And there ſeem to be two kinds of vibrations of the parts of an elaſtic body, one of which is quick, and called a tremor of its minute parts, and the other ſlower and longer, by which its figure is changed, and an impinging body repelled.

CHAP.

CHAP. VII.

MECHANICAL POWERS.

*THE exiſtence, and intenſity of operation, of the mechanical affections, gravity, coheſion and elaſticity, and the nature of the other qualities of matter, being aſcertained experimentally, they are aſſumed as eſtabliſhed principles, and their efficacy in the production of preſſure, motion, and other phenomena, is the next object of mechanical philoſophy. There are ſix ſimple machines, commonly ſtiled mechanical powers, from the effects produced, with their intervention, by the action of gravity and animal exertions, viz. the lever, wheel and axis, pulley, wedge, inclined plane and ſcrew. They are all calculated to communicate motion to bodies, and ſuſtain their preſſure, for which, the power unaſſiſted by them, is incompetent; and the artifice in all conſiſts in diſtributing the weight amongſt ſuch a number of agents, that the part ſuſtained by the power may bear a ſmall ratio to the whole. Thus, a power incapable of communicating motion to, or ſupporting the preſſure of, a body, without mechanical aſſiſtance, may effect its purpoſe by transferring a part of the weight upon a fulcrum, diſtributing it amongſt a number of pulleys, or placing it upon an inclined plane or ſcrew; and, by this artifice, a power P may keep a weight ſuſpended which exceeds it in any aſſigned ratio, though without any acquiſition of moment in a given direction; for motion is only communicable according to the eſtabliſhed natural relations ſubſiſting between matter and motion, and the magnitudes of two powers, in equilibrio, are always inverſely as their velocities.

* Keil's Phyſics, Lect. X. Helſham, Lect. VI. Emerſon, Prop. 18, &c. Graves, L. I. C. X. Muſchenbroek, Ch. VIII. Varignon, pag. 305. Maclaurin's Newton, B. II. Ch. III. Hamilton's Eſſay on the Principles of Mechanics. Morgan's Notes to Rohault.

LEVER.

269. DEF. *A lever is a bar of wood or metal, and is uſually repreſented by an inflexible line, without gravity, revolving about a fixed point, called the fulcrum, by the action of a power upon its arms.*

PLATE VII. FIG. LVIII. The points *W*, *P*, where the weight and power act, are the points of ſuſpenſion, and the immoveable point *F*, about which every point of the lever revolves, is called promiſcuouſly the fulcrum, hypo-mochlion, and center of motion. There are three kinds of levers: 1. the fulcrum is between the power and weight, as in the common balance, ſciſſars, ſnuffers, &c. 2. The weight is between the power and centre of motion, as the oars and rudder of a boat, cutting knives fixed at one end, doors, &c. 3. The power is between the weight and fulcrum, as a ladder raiſed againſt a wall, a weight raiſed by the arm, where the center of motion is at the ſhoulder, &c.

FIG. LIX. 270. Cor. 1. Forces whoſe magnitudes are to each other as *PA*, *PB*, *PC*, &c. acting at *P* and terminated by a line *AC*, parallel to *PF*, have the ſame effect: for each may be reſolved into two forces, one perpendicular, and the other parallel, to *PF*; of which, the perpendicular parts are equal and entirely employed in producing a rotation of the lever round *F*, or in ſupporting a body *W* placed on the other ſide of *F*, and acting perpendicularly to *FW*, and the parallel parts only produce a motion in the direction *PF*, and do not produce any rotation, or contribute to the ſupport of *W*.

FIG. LX. 271. Cor. 2. If a given power, repreſented by *PB*, act at the ſame point *P* in any direction *PD*, its efficacy to turn the lever round *F*, or ſupport any body *W*, is as the chord *PC* of the circle whoſe diameter is *PB*; for *PD* being taken equal to *PB* and reſolved

reſolved into two forces, one *DE* perpendicular, and the other *PE* parallel, to *PF*, it appears from ſimilar triangles, that *DE*, the only effective part of the force, is equal to *PC*.

272. PROP. *Two powers* W, P, *acting upon a lever* PW, *whoſe center of motion is* F, *at the points* P *and* W *in the directions* WM, PL *in the ſame plane, and in equilibrio, are to each other inverſely as the perpendiculars let fall from* F *upon their directions.* PLATE VII. FIG. LXI.

DEM. From *F* as a center, with the longer perpendicular *FL*, deſcribe a circular arc cutting the direction of *W* in *D*, and, becauſe the efficacy of theſe forces is the ſame to whatever points of their directions they are applied, let them be applied at *L* and *D*. Let *DE* repreſent the magnitude of *W* and be reſolved into two forces, one *DG* in the direction *FD*, and the other *EG* perpendicular to it; and, becauſe *DG* has no effect in making *DF* revolve, nor conſequently the lever which makes an invariable angle with it, and *EG* and *P* act at equal diſtances from *F*, in directions perpendicular to thoſe diſtances, and are in equilibrio, *P* is equal to *EG*, and $W : P :: DE : EG :: DF (FL) : FM$, from ſimilar triangles. Q. E. D.

273. Cor. 1. In any lever *FP* or *FHK*, thoſe parts of *P* and *W*, which are oppoſite to each other, are inverſely as their rectilineal diſtances from *F*; for let *WA* and *PD*, be the reſpective magnitudes of *W* and *P*, which act at *W* and *P*, and reſolving each into two forces, *WB*, *PE*, coincident with the lever, or arm *FP* which makes an invariable angle with it, and *AB*, *DE*, parallel and oppoſite, and drawing the perpendiculars *AC*, *DG*, to *FP*, and *FM*, *FL*, to the directions; it appears, from ſimilar triangles, that $DE : AB :: DG : AC :: \frac{DP \times FL}{FP} : \frac{WA \times FM}{FW}$ (:: $\frac{1}{FP} : \frac{1}{FW}$, becauſe $DP \times FL = WA \times FM$ from this propoſition. FIG. LXII.

274. Cor.

274. Cor. 2. If the directions of P and W, acting upon the arms of a ſtraight lever, and in equilibrio, be parallel, they are therefore inverſely as their diſtances, or inverſely as the portions of any line drawn through F and terminated by their directions (273). This follows alſo from the propoſition, becauſe the diſtances, or the ſegments of any right line on each ſide of F and terminated by their directions, are, in this ſuppoſition, as the perpendiculars let fall from F upon their directions.

276. Cor. 3. The velocity of any point either in a ſtraight, or curved lever, varies as its rectilineal diſtance from the center of motion F; for all points deſcribe ſimilar circular arcs, having their centers in F. If P and W act upon the ſame right line, and their directions be perpendicular, or inclined in the ſame angle, to their rectilineal diſtances, their velocities will be as thoſe diſtances, being meaſured by the baſes of ſimilar triangles which are deſcribed in the ſame time: their velocities are therefore to each other inverſely as the oppoſite parts of P and W (273).

FIG. LXIII. 277. Cor. 4. If a lever be moveable about an axis AB, or fixed to an axis which is moveable about two centers A and B, and perpendiculars PF, WF, be drawn to this axis from P and W, to which their directions are perpendicular and in the ſame plane, an equilibrium obtains when $P : W$ inverſely as their perpendicular diſtances from the axis.

FIG. LXII. 278. Cor. 5. There will be an equilibrium upon the lever when $P \times FP \times \text{ſin.} \angle FPL$ (or the angle which P's direction makes with FP) is equal to $W \times FW \times \text{ſin.} \angle FWM$ (or the angle which W's direction makes with FW; for $P : W :: FM : FL :: \frac{FW \times \text{ſin.} \angle FWM}{\text{rad.}} : \frac{FP \times \text{ſin.} \angle FPL}{\text{rad.}}$; and $F \times FP \times \text{ſin.} \angle FPL = W \times FW \times \text{ſin.} \angle FWM$, ſuppoſing the radius to be given.

279. Cor.

279. Cor. 6. The intenſities or moments of any powers A, B, C, &c. whoſe directions are parallel, vary as their magnitudes multiplied into their diſtances from the center of motion; for let Q, R, S, &c. acting at the ſame point E, in directions parallel to thoſe of A, B, C, &c. be in equilibrio with them reſpectively, or (Cor. 2.) let $A \times AF = Q \times EF$, $B \times BF = R \times EF$, $C \times FC = S \times EF$, &c.; and the efficacy of A, B, C, &c. to make the lever revolve, or ſupport any power acting againſt them at E, is evidently as $Q + R + S$, &c. or as $\overline{Q + R + S} \times EF$, or, ſubſtituting their equals, as $A \times AF + B \times BF + C \times CF$, &c. FIG. LXIV.

280. Cor. 7. The intenſities or moments of A, B, C, &c. the ſines of whoſe directions with their rectilineal diſtances to the ſame radius are a, b, c, &c. reſpectively, will be as $A \times a \times AF + B \times BF \times b + C \times CF \times c$, &c.; for if Q, R, S act at the ſame point E, in the ſame direction, the ſine of whoſe inclination to $EF = z$, and be in equilibrio with them, $\overline{Q + R + S} \times EF \times z = A \times AF \times a + B \times BF \times b + C \times CF \times c$, &c. (278).

281. Cor. 8. If more than two powers act upon a lever, there will be an equilibrium when the ſum of the products ariſing from multiplying each into the perpendicular diſtance of its direction from the center of motion; or, if their directions be parallel and the lever ſtraight, into its diſtance from F, on one ſide, is equal to the ſum of the products on the other ſide. Whatever be the form of the lever, the value of the perpendicular may be ſubſtiſtituted for it, and an equilibrium obtains when the ſums of the products on each ſide of F are equal.

282. Cor. 9. Becauſe the efficacy of P and W is the ſame to whatever part of their direction they are applied, a bended or curved lever may be reduced to a ſtraight one, making an invariable angle with it, and P and W may therefore be always ſuppoſed to act in the ſame right line.

283. PROP.

PLATE VIII. FIG. LXV.

283. PROP. *When any number of levers* WC, CE, EP, *&c. are combined together in the same direction, the ratio of* P *to* W, *acting in the same plane at their extremities, in parallel directions, and in equilibrio, is that of* WB × CD × EF : BC × DE × FP.

DEM. Let the forces Q, R, P, acting at the points C, E, P, in directions parallel to those of W and P, be respectively in equilibrio with W, Q, R, and consequently (274) $W : Q :: BC : WB$
$Q : R :: DE : CD$
$R : P :: FP : EF$;
and, by composition of ratios, $W : P :: BC \times DE \times FP : WB \times CD \times EF$. Q.E.D.

284. Cor. 1. If P and W act in different directions, and Q and R act also in any other different directions, and Q, R, P be respectively in equilibrio with W, Q, R, perpendiculars, let fall from the centers of motion, B, D, F, upon their directions, are to be substituted for the distances.

285. Cor. 2. If any of the forces, in this and the preceding proposition and corollaries, act in different planes, they are to be reduced to the same plane by resolving each into two forces, one in that plane and the other perpendicular to it, of which the former only are effective, and are to be used in the several analogies.

FIG. LXVI.

286. PROP. *If lines be drawn from* F *parallel to the directions of* P *and* W *which meet in* A; P, W, *and pressure upon* F (Pr) *are to each other as the sides and diagonal* AB, AC, AF, *of the parallelogram* CABF, *respectively.*

DEM. From F let fall the perpendiculars FL, FM, upon the directions of P and W, and the triangles FCM, FLB (having a right angle in each, and the angles FCM, FBL, either equal to or

the

the ſupplements of CAB) are ſimilar; therefore $P : W :: FM : FL :: FC : FB$, and a force, whoſe quantity and direction are AF, is equivalent to P and W (185). Q.E.D.

287. Cor. 1. A power therefore acting at F, whoſe magnitude is to $P + W$ as AF to $AB + AC$, and whoſe directions are FA, AB and AC, reſpectively, will prevent all motion.

288. Cor. 2. The magnitude of P, W or Pr, is as the ſine of the angle formed by the directions of the other two; for

$Pr : P :: FA : AB ::$ ſin. of $\angle FBA$ or BAC : ſin. of $\angle AFB$ or FAC;

$Pr : W :: FA : AC ::$ ſin. of $\angle FCA$ or $\angle CAB$: ſin. of $\angle CFA$ or FAB;

and $W : P :: AC : FC ::$ ſin. of $\angle CFA$ or FAB : ſin. of $\angle CAF$.

289. Cor. 3. Any two of theſe forces, preſſure upon F, P, and W, are to each other inverſely as the perpendiculars let fall upon their directions from any point F in the direction of the third; for $Pr : P$ :: ſin. of $\angle FCA$ or WAH : ſin. of $\angle CAF :: WH : WI$ (ſuppoſing WH and WI to be perpendicular to the directions of P and Pr. and AW to be the radius); and $Pr : W ::$ ſin. of $\angle FBA$ or PAK : ſin. of $\angle BAF$ or $BAN :: PK : PN$, ſuppoſing PK and PN to be perpendicular, reſpectively, to the directions of W and Pr, and AP to be the radius, &c. And if the lever be ſtraight and the directions of P and W parallel, the magnitudes of P, W and Pr, are as the diſtances of the other two, the perpendiculars then becoming the diſtances.

290. Cor. 4. If the extremities of the perpendiculars FL, FM, be joined by a right line LM, Pr, P and W are to each other reſpectively as LM, FM and FL, for this triangle is ſimilar to FAB, as eaſily appears by deſcribing a circle upon FA as a diameter.

FIG. LXVII. 291. PROP. *The distance from* F, *quantity and direction, of any two forces* Q *and* R *acting upon a straight lever in the same plane, being given, to find the magnitude, direction and distance of a force equivalent to them.*

Let the directions of Q and R meet in A, and taking $AB : AD :: Q : R$, and completing the parallelogram, the diagonal AE is the magnitude and direction of a force equivalent to them (185). But QR and the angles AQR, ARQ being given, AQ, AR, and the angle QAR may be found; and AB, AD, and the angle BAD being known, AE, the magnitude of the combined force, and the angle BAE may be found; and QA, and the angles AQN, QAN being found, the angle QNA, or inclination of AN, to FN and QN, are known. Q. E. I.

FIG. LXVIII. 292. Cor. 1. If any number of forces Q, R, S in the same plane, whose magnitudes and directions are AB, AC, ER, act upon the lever FW, and be in equilibrio with any other forces T, V, W, whose quantities and directions are HG, HI, LN, they may be reduced to two which are in equilibrio; for AB and AC are equivalent to AD, and taking EF equal to AD, EF and ER are equivalent to EQ; and in the same manner HG, HI, LN are equivalent to LP, which is in equilibrio with EQ, because the lever is at rest. And the directions, and distances from F, of LP and EQ, are found as in the proposition.

FIG. LXIX. 293. Cor. 2. Any number of forces in the same plane, whose magnitudes and directions are AB, AC, EX, HG, HI, LN, may be reduced to one, which is equal to the pressure upon the fulcrum; for, supposing the forces EQ, and LP, resulting from the other forces combined, to act at their intersection S, a third force equivalent to them, and consequently to the pressure upon F, must pass through S (185), and, taking SU, SV, respectively equal to EQ, LP, and completing the parallelogram, SY will be its magnitude and direction.

294. Cor.

294. Cor. 3. If any number of forces, whoſe quantities and directions are given, act upon a lever, the poſition of a fulcrum, about which they will be in equilibrio, and the quantity and direction of preſſure upon it, may be found; for, let the directions of Q and R meet in A, and taking $AB : AC :: Q : R$, and, completing the parallelogram, its diagonal AD produced, will cut the lever in a point, which being ſupported, Q and R will be in equilibrio (286); and combining AD with S, and the force, reſulting from theſe, with another, &c. the diagonal will always interſect the lever in a point F, about which they will be in equilibrio. FIG. LXVIII.

295. LEMMA. *If right lines be drawn from any point* P *to the extremities of the diagonal, and ſides, of the parallelogram* ABCD, *the triangle* PAC, *having the diagonal for its baſe, is equal to the difference, or ſum of the triangles* PAB, PAD, *having the ſides for their baſes, according as* P *is ſituated between the lines forming the angle* BAD, *or thoſe which form its ſupplement to two right angles.* FIG. LXX.

DEM. CASE I. Let P be ſituated between the lines forming the angle BAD; and, drawing Pnm perpendicular to AB or CD, the triangle $APC = ADPC - ADP$; but $ADPC = ADC + DPC = AB \times \frac{mn}{2} + DC \times \frac{Pn}{2} = AB \times \frac{Pm}{2} = APB$; therefore $APC = APB - APD$.

CASE II. Let P be placed between the lines forming the ſupplemental angle to BAD, and the triangles $ADC \pm DPC = \frac{AB}{2} \times \overline{mn \pm Pn}\,(Pm) = ABP$; and, adding APD to both, $APC = ABP + ADP$. Q.E.D. FIG. LXXI.

PLATE IX. FIG. LXXII. 296. Cor. 1. If P be in one of the ſides containing the angle BAD, the triangle $APC = ADC + DPG = \frac{AB}{2} \times mn + Pn \over (Pm) = PAB$.

FIG. LXXIII. 297. Cor. 2. If P be in the diagonal, the triangle $PAB = ABC \mp BPC = BC \times \frac{mn}{2} \mp BC \times \frac{Pn}{2} = BC \times \frac{Pm}{2} = PAD$. The upper ſign is to be uſed when P is without the figure, the lower when it is within.

298. Cor. 3. If perpendiculars be drawn from P to the diagonal and ſides, Pd, Pm, Pq; $AC \times Pd = AB \times Pm \mp AD \times Pq$; and when P is in the diagonal AC, $AB \times Pq = AD \times Pm$.

FIG. LXXIV. 299. PROP. *If there be any number of forces* Q, R, S, T, *in the ſame plane, which are combined as before, the ſums of the products, ariſing from multiplying each into the perpendicular diſtance of its direction from any point* F, *in the diagonal* CL, *are equal on each ſide of it.*

DEM. Let CD, CG, CH, CK be the relative magnitudes of Q, R, S, T, reſpectively, and compounding them, and drawing perpendiculars, from any point F in the laſt diagonal, upon their directions, viz. Fa, Fb, Fc, Fd, Fg, Fh; from the preceding lemma, $CK \times Fh = CI \times Fg = CE \times Fc - CH \times Fd = CD \times Fa + CG \times Fb - CH \times Fd$, and conſequently CK or $T \times Fh + CH$ or $S \times Fd = CD$ or $Q \times Fa + CG$ or $R \times Fb$. Q. E. D.

300. Cor. A lever therefore paſſing through any point F in the diagonal LC, produced in any direction, and in the ſame plane with the forces which act upon it, will be in equilibrio.

301. LEMMA.

301. LEMMA. *If a right line* PW *revolve round a fixed point* F, *and lines are drawn from its extremities to another fixed point* Q, *to which perpendiculars* FL, FM, *and* Fl, Fm *are drawn from* F, *and* W *is ſuppoſed to aſcend,* FL *has to* FM *a greater ratio than* Fl : Fm. FIG. LXXV.

DEM. Take $Pr = py = FW$, and, drawing the perpendiculars rv, yz; $FL : rv :: \text{ſin.} \angle FWL : \text{ſin.} \angle rPv :: PQ : WQ$; $rv : FM :: Pr\,(FW) : FP$, and comp. $FL : FM :: PQ \times FW : WQ \times FP$. By a ſimilar proceſs, $Fm : Fl :: wQ \times FP : pQ \times FW$; and adding theſe analogies together, $FL \times Fm : FM \times Fl :: PQ \times FW \times wQ \times FP : WQ \times FP \times pQ \times FW :: PQ \times wQ : WQ \times pQ$. But PQ is greater than pQ, and wQ than WQ, and conſequently $PQ \times wQ$ is greater than $WQ \times pQ$, and $FL \times Fm$ than $FM \times Fl$, and the ratio of $FL : FM$ is greater than that of $Fl : Fm$. Q. E. D.

302. PROP. *If any two powers* P and *W*, *whoſe directions always meet in the ſame point* Q, *be in equilibrio upon the lever* PW *in any one poſition of* PW, *they cannot be in equilibrio when it is in any other poſition* pw.

DEM. Let the lever revolve, and be in any other ſituation *pw*, and becauſe $P : W :: FL : FM$, or in a greater ratio than $Fl : Fm$ (301) P will preponderate. Q. E. D.

303. Cor. 1. It is evident that the lever cannot reſt till it paſs through the points *F*, *Q*.

304. Cor. 2. If the directions of *P* and *W* be parallel to each other, they will be in equilibrio in any poſition of the lever, becauſe the perpendiculars drawn from *F* to their directions are always as the diſtances, and conſequently in a given ratio to each other. And, for the ſame reaſon, if there be ever ſo many forces, acting in parallel directions upon the arms of a ſtraight lever,

and in equilibrio in any one ſituation of the lever, they will be in equilibrio in every ſituation of it.

FIG. LXXVI. 305. PROP. *If the center of motion* F *be placed above the ſtraight lever* PW, *and* P *and* W, *acting always in parallel directions, equilibrate in any poſition* PW, *they do not equilibrate in any other,* pw.

DEM. From *F* draw *FM* and *Fm* perpendicular to the lever, and $P : W :: WM : PM :: w m : p m$, or in a leſs ratio than that of $Lw : Lp$ or $LV : LR$, and conſequently much leſs than that of the perpendiculars from the center of motion *F* upon the directions, or $MV : MR$. Q. E. D.

306. Cor. 1. Becauſe $P : W$ in a leſs ratio than that of $MV : MR$, $P \times MR$ is leſs than $W \times MV$, and conſequently *W* will deſcend.

PLATE X. FIG. LXXVII. 307. Cor. 2. If *F* be placed on the other ſide of the lever, the deſcending body will preponderate; for $P : W :: WM : PM :: m w : m p$, and conſequently $P : W$ in a greater ratio than that of $Lw : Lp$ or $LV : LR$, and therefore much greater than that of the perpendiculars upon the directions or $MV : MR$; and $P \times MR$ is greater than that of $W \times MV$.

FIG. LXXVIII. 308. PROP. *If* P *and* W *act always at the ſame diſtance from the lever, in directions parallel to* FM, *and in equilibrio about* F *in the poſition* PFW, *and the lever be moved, the deſcending body will continue to preponderate.*

DEM. Let *FN*, *ps*, *wr*, be drawn parallel to the directions in which the bodies act, *pQw* be the lever, and *Fn* be the poſition of *FN*; and from ſimilar $\triangle$s $Qr : Qs :: Qw : Qp$, and therefore $Qr : Qs$ in a greater ratio than $nw : np$ or $NW : NP$ or $WM : PL$ or

PL or P to W; but $Nr : Ns$ in a greater ratio than $Qr : Qs$, and conſequently $P : W$ in a leſs ratio than $Nr : Ns$, and the body W will continue to preponderate.

309. Cor. When the bodies are placed under the lever, the deſcending body will continue to deſcend, becauſe $P : W$ in a leſs ratio than $Nr : Ns$, as eaſily appears by turning the figure.

SCHOLIUM.

310. In all communications of motion by impact, the quantities of motion loſt and gained being equal and oppoſite, the quantity of motion eſtimated in the ſame direction is invariable, and the quantities of matter vary inverſely as the velocities loſt and gained; and if two bodies A and B act upon a lever, or any other machine, they are ſo connected that A cannot deſcend without making B aſcend with the ſame quantity of motion, and their quantities of matter are therefore inverſely as each other. Theſe caſes, having ſuch marks of coincidence, are inferred to be ſimilar in every reſpect, and the cauſe of an equilibrium in the mechanical powers, is often immediately aſſigned from this equality of momenta; but they are not exactly ſimilar, becauſe when A impinges upon B, ſome part of its motion is transferred to B, and A's motion neceſſarily precedes this communication of motion; but, when they act upon any machine, the deſcending body A cannot be ſaid to communicate any part of its motion to B aſcending; becauſe, from their connection, their motion muſt neceſſarily commence and be extinguiſhed together; and beſides, the power of the lever ought to be conſidered. The ratio of the power and weight may however be aſſigned, in every machine, from their incipient momenta; for P and W, acting upon the arms of a lever, exert a preſſure and have a tendency to move; and if a and b be the velocities with which A and B ſtrike the lever, eſtimated in ſuch directions that their preſſures are ſolely employed in reſiſting each other's efforts to produce motion, no part being loſt by obliquity of direction, $A \times a \times$ into its velocity or diſtance from the centre of motion

motion is equal to $B \times b \times$ into its velocity or diſtance, when there is an equilibrium; and by ſubſtituting preſſures or P and W, for $A \times a$ and $B \times b$, the ratio of $P : W$ is found to be the ſame as was before collected from the reſolution of motion. As the velocity of any point of a lever varies as its rectilineal diſtance from the center of motion, all points deſcribing ſimilar circular arcs round it in the ſame time, if the directions of P and W be perpendicular to their rectilineal diſtances, their velocities will be the ſame as thoſe of the points where they act and wholly efficient, and when there is an equilibrium, P will be to W inverſely as their rectilineal diſtances. But if the direction of P or W be enclined to their rectilineal diſtance, their efficient velocity will not be equal to that of the point where they act; if P's direction be the line PD, it is evident that P will have two motions whilſt the lever revolves, one acceding to, or receding from, F, according as the angle DPF is leſs or greater than a right angle, and the other producing the rotation of the lever; for, deſcribing a circular arc with F as a center, and FD as radius, the power will act at every intermediate point in PE whilſt the lever deſcribes the angle PFD. The motion in the direction of the lever is inefficient, and if PD repreſent the direction and quantity of A's velocity, and be reſolved into two, PC in the direction of PF, and DC perpendicular to it, this laſt only is efficient; and if the angle at F be very ſmall, $A \times DC \times$ its perpendicular velocity or into FD, or $\frac{A \times FP \times PD \times FL}{FP}$, ſuppoſing FL to be perpendicular to the direction, is A's efficacy to turn the lever. The effective part of B's velocity being found in the ſame manner, and theſe values of a and b being ſubſtituted for them in the ſuppoſition of an equality of moments; whatever be their directions, the ratio of P to W is the ſame as that diſcovered by other principles. Thus in an equilibrium $A \times PD \times FL$ is given, and conſequently $A \times PD$ or the preſſure of P in the line PD is as $\frac{1}{FL}$. The demonſtration of this fundamental propoſition, aſcribed to Archimedes, depends upon this principle, that if a number of weights be ſuſpended upon the arms of a lever, at points equidiſtant from each other, whether on the ſame ſide of the fulcrum or not, their

FIG. LXXIX.

efficacy

efficacy to make the lever revolve is the ſame as if they were united in a point biſecting the diſtance of the points of ſuſpenſion. Mr. Huygens ſays, that many fruitleſs attempts have been made to remedy the defects of this demonſtration, and propoſes another founded on this principle, that when two equal bodies are placed upon the arms of a lever, that which is moſt remote from the fulcrum will preponderate. But this principle is not more evident than that of Archidemes, and beſides, his proceſs is prolix and tireſome. Mr. Maclaurin hath given a demonſtration of this propoſition when the arms of the lever are commenſurate, and his method might eaſily be extended to caſes in which they are incommenſurate, and be made general; but this would add to the length of a proceſs already very long. The only principle in Sir I. Newton's demonſtration that hath been controverted is this, which is taken for granted, "that the ſame power will have the ſame effect to whatever point of the direction, in which it acts, it be applied;" yet no doubts are entertained of the truth of it, though, perhaps, from its ſimplicity and intuitive evidence, it cannot be demonſtrated by more ſimple principles. If the line *PC* and the angle *PFC* be invariable, the radii *PF*, *CF* being fixed to *PC* at the points *P* and *C*, it is evident, that two equal forces *P* and *Q*, acting upon the points *P* and *C* in the directions *PC* and *CP*, will deſtroy each other, and the line *PC*, and conſequently *PF* and *CF*, will be quieſcent. If therefore *P* make a body deſcribe the arc *Ww* in any ſmall time, *Q* will make it deſcribe *wW* in the ſame time, or they would not deſtroy each other's effects. Equal forces therefore *P* and *Q*, acting at different points of the ſame direction, in the ſame time make the radii *PF*, *CF* deſcribe angles at *F*, *PFp* and *CFc* equal to *WFw*, and therefore to each other. Though this demonſtration of Newton be general, conciſe, and perfectly ſatisfactory, the great utility of the propoſition may poſſibly render other demonſtrations of it not undeſerving of attention. PLATE VII. FIG. LIX.

DEMONSTRATION OF ARCHIMEDES.

FIG. LXXX. Let AB be a homogeneous cylinder, and C the bisection of its axis, and it is evident, that if a fulcrum, or power equal and opposite to the pressure upon it, be applied at C, the parts AC and CB will be in equilibrio. Let any point D be taken, and, bisecting AD in E, and DB in F, it is clear that two powers, respectively equal to the weights of AD and DB, applied at E and F, will support them, and have the same effect with the fulcrum, or power, applied at C, and be in equilibrio about C: but $CE = CA - AE = \frac{AB-AD}{2} = \frac{DB}{2}$; and $CF = CB - BF = \frac{AB-DB}{2} = \frac{AD}{2}$; and consequently $CE : CF :: DB : AD ::$ force applied at F: force applied at E. Q. E. D.

FIG. LXXXI. 311. LEMMA. *If from any point* P, *in the diagonal of a parallelogram,* ABCD, *two lines* Pm *and* Pq, *be drawn perpendicular to the sides, the perpendiculars and sides are inversely as each other.*

DEM. Draw CE, CF, perpendicular to the sides, and, from similar triangles, $Pq : CF :: AP : AC :: Pm : CE$; therefore $Pq : Pm :: CF : CE :: CD\ (AB) : CB\ (AD)$ (sim. triangles). Or, this follows from (298), where it is proved, that $AB \times Pm = AD \times Pq$, and consequently, $Pm : Pq :: AD : AB$. Q. E. D.

FIG. LXXXII. 312. PROP. *If any three forces* W, P, Z, *whose magnitudes and directions are* AB, AC, AD, *act upon the lever* WP, *which is at rest,* W *is to* P *inversely as the perpendiculars let fall from* F *upon their directions.*

DEM.

DEM. The directions of these forces must be in the same plane, and meet in the same point, (216), and are respectively as the sides and diagonal of a parallelogram parallel to their directions; and $W : P :: AB : AC$ (196) $:: FL : FM$ (311). The effect will evidently be the same when a fulcrum is applied at F instead of the force Z. Q.E.D.

*Dr. Hamilton's demonstration of this proposition depends upon the same principle with the above. Let the forces W, P, Z, act upon the inflexible line WP at the points W, P, F, and let the directions of P and W meet in C, and the direction of a force Z, equivalent to them, must pass through C. Therefore P, W, Z, are to each other as the sides and diagonal of a parallelogram respectively parallel to their directions, FA, FB, FC, and $W : P :: AC : BC ::$ sin. $\angle AFC$ (FCB) $::$ sin. $\angle ACF :: FM : FL$. FIG. LXXXIII.

$W : Z :: AC : FC ::$ sin. $\angle FCB :$ sin. $\angle FBC$ or $BCA :: P\mathcal{Q} : PN$, supposing $P\mathcal{Q}$ and PN to be perpendicular to the directions of Z and W.

$P : Z :: FA : FC ::$ sin. $\angle FCA :$ sin. $\angle FAC$ or $ACB :: WG : WR$, supposing WG and WR to be perpendicular to the directions of Z and P.

The parts of W and P, which act in directions exactly opposite to those of Z, are found by resolving AC and $\mathcal{Q}A$ (BC) into two forces, one parallel to the right line joining W, P, as Am and Bn, and the other parallel to FC as $\mathcal{Q}m$, $\mathcal{Q}n$. The opposite parts Am, Bn, are equal and destroy each other, and the conspiring parts $\mathcal{Q}m + \mathcal{Q}n$ must be equal to Z; and consequently when two forces W and P are in equilibrio with a third force Z, and their directions are all parallel, FIG. LXXXIV.

$W : P :: \mathcal{Q}n : Cn :: PB : BC :: P\mathcal{Q} : \mathcal{Q}W$;
$W : Z :: Cm : \mathcal{Q}C :: CA : CW :: \mathcal{Q}P : PW$; and
$P : Z :: Cn : C\mathcal{Q} :: CB : CP :: W\mathcal{Q} : WP$.

†BALANCE.

313. DEF. *The ancient balance, commonly called the statera romana, or steelyard, is a lever of the first kind supported at the point* F, *placed near* PLATE XI. FIG. LXXXV.

* Essay on the Principles of Mechanics. † Helsham, Lect. VI. Muschenb. Ch. VIII. § CCCLXXXIII. Desaguliers, pag. 95.

near one extremity, about which the brachia FA, FN *equiponderate. On one ſide of* F *at the extremity* A, *an unknown weight,* W, *is ſuſpended, and on the other ſide a known weight,* P, *is moveable upon the arm* FN, *which is divided into parts equal to* FA, *each of which is alſo divided into* 10, 100, *&c. equal parts.*

314. Cor. If P be at x, the fourth diviſion from I, which is the nth diviſion from F, when an equilibrium obtains between it and W, and IK be divided into m equal parts, the weight of W will be equal to $P \times n + \frac{4}{m}$; for $W : P :: Fx : FA$ (274) $:: FA \times n + \frac{4}{m} : FA :: n + \frac{4}{m} : 1$, and conſequently $W = P \times n + \frac{4}{m}$.

FIG. LXXXVI.

315. DEF. *The common, or modern, balance, or a pair of ſcales, is a lever of the firſt kind, as* AB, *ſupported at its biſection* F: *to the extremities* A *and* B *are ſuſpended baſins or ſcales, and the brachia and baſins, on each ſide of* F, *are ſuppoſed to equiponderate.*

316. Cor. 1. If any known weight, P, placed in one ſcale equiponderate with one unknown, W, placed in the other, the weight of W is known, being equal to that of P; for $P : W :: AF : BF$ (274) $:: 1 : 1$, and conſequently $P = W$.

317. Cor. 2. A balance, whoſe arms are unequal in length, is fallacious; for if AF and BF be unequal, P and W, when in equilibrio, cannot be equal, for $W = \frac{P \times BF}{AF}$. But the relation of $BF : AF$ being known, W is alſo known.

318. Cor. 3. If a man, whoſe weight is equal to W, ſtanding in one ſcale and in equilibrio with P placed in the other, preſs the

the beam upwards in D with a force equal to Q, the diminution of W's moment is equal to $Q \times FD$; and becauſe the reaction at the ſcale is equal to Q, the encreaſe of W's moment is equal to $Q \times FA$, and conſequently W will deſcend with a force equal to $Q \times AD$. If the preſſure be upwards at E, W will deſcend with a force, reſulting from this preſſure, equal to $Q \times EF$, and, from the reaction, with a force equal to $Q \times FA$; and therefore the whole force of deſcent is equal to $Q \times EA$. When the preſſure is downwards at D, the encreaſe of W's moment is equal to $Q \times FD$, and the diminution of its moment $= Q \times FA$; and, conſequently, W will aſcend with a force equal to $W \times DA$. If the preſſure be downwards at E, the diminution of W's moment, or encreaſe of P's moment, is equal to $Q \times EF$, and a part, Q, of W's weight being transferred to E, the diminution of its moment, on that account, is equal to $Q \times FA$; and conſequently the whole diminution of W's moment, or force of P's aſcent is equal to $Q \times EA$.

319. Cor. 4. If the center of motion C be in the right line joining the centers of ſuſpenſion, the equilibrium of equal weights P and W will obtain in every poſition; the perpendiculars let fall from C upon the directions being always equal to each other. But when C is above or below WP, an equilibrium of equal weights does not obtain, unleſs WP coincide with the horizontal line AB. When WP coincides with AB, the perpendiculars let fall from C upon the directions of W and P are equal to GB and GA, CG being perpendicular to AB; but when the balance is in any other poſition WP, the perpendicular CI is greater than CH, becauſe gL, which is leſs than CI, is equal to gM, which is greater than CH. W will deſcend and continue to vibrate till its motion be deſtroyed by friction. This corollary is alſo deducible from (305). FIG. LXXXVII.

320. Cor. 5. If P and W be unequal, and C, be in the right line WP, the heavier of them will deſcend till WP be perpendicular to the horizon, or, if the center of motion be not in WP, till $P \times CH = W \times CI$.

321. Cor.

FIG. LXXXVI.

321. **Cor. 6.** In a balance whoſe arms are unequal, the weight of W may be ſtill aſcertained; for let W, ſuſpended at A, be in equilibrio with a known weight Q, ſuſpended at B, and $W \times FA = Q \times FB$, and, ſuſpended at B, let it be in equilibrio with a known weight R ſuſpended at A, and $W \times FB = R \times FA$; conſequently, by multiplying theſe equations together, $W^2 \times FA \times FB = Q \times R \times FA \times FB$, and $W = \sqrt[2]{Q \times R}$.

FIG. LXXXVIII.

322. *Cor. 7. If the beam of the balance be ſuppoſed to have weight and be ſimilar and homogeneous in every part, its center of gravity is in the biſection F; but if it be not homogeneous, or the center of motion be not in the biſection, let G be its center of gravity, and an equilibrium will obtain when $P \times PF + B$ (weight of the balance) $\times GF = W \times FW$.

323. Cor. 8. If from F, a ſtyle FD, perpendicular to WP, be raiſed, the equilibrium of the balance will be affected by it, except it be in an horizontal ſituation, the moment of the ſtyle being meaſured by its weight multiplied into the diſtance of its center of gravity from the line FH, perpendicular to the horizon. But the equilibrium is reſtored by continuing the ſtyle to the other ſide of F, ſo that the moments on each ſide may be equal and oppoſite.

324. Cor. 9. If the center of gravity of the balance, ſcales, and weights, be in the center of motion, F, an equilibrium obtains in every poſition of the balance; but if this center be above or below F, the balance cannot be quieſcent till the right line joining F and this center be perpendicular to the horizon. The beſt poſition therefore of the center of gravity is below F, and as little below it as poſſible, that the arcs deſcribed by it, during its vibrations, may be ſmall and ſoon deſcribed. The points of ſuſpenſion ſhould

* Theſe corollaries may be omitted till the chapter upon the center of gravity be read.

ſhould be in the ſame right line with the center of motion, which ought accurately to biſect their diſtance (317).

325. Cor. 10. The arms of the balance ſhould be as long as can be uſed conveniently; becauſe the moment of a given body varies as its diſtance from the fulcrum, and, therefore, the greater the diſtance, the more diſtinguiſhable will be the moment ariſing from any ſmall difference between *P* and *W*. And to diſtinguiſh very minute differences of weight, the friction upon the axis, in the motion of the beam and ſcales, ought to be as little as poſſible.

CHAP.

CHAP. VIII.

*WHEEL AND AXIS.

326. DEF. *A WHEEL and axis or axis in peritrochio, is a machine compoſed of a circular wheel, in whoſe center a cylindrical axis is inſerted and fixed; and the wheel revolving by the action of a power* P, *the axis, whoſe extremities are ſupported, revolves with it, and the rope, to which a body* W *is appended, is tied to the axis and wrapped round it during its motion.*

FIG. LXXXIX.

327. Cor. It is evident that every point of the axis *B*, *G*, &c. deſcribes a circle round its correſponding center *y*, *z*, &c. in the time of a revolution of the wheel; and that any points of the wheel and axis, *A* and *B* deſcribe ſimilar arcs of circles in the ſame time, and, conſequently, their velocities are as the peripheries or radii of the circle deſcribed by them.

328. PROP. *If the directions of* P *and* W *be perpendicular to the radii of the wheel and axis reſpectively, they are in equilibrio when* P : W :: *radius of the axis : radius of the wheel.*

DEM. The ſame power is required to ſupport *W* to whatever point of the axis it be applied, becauſe the diſtance from the correſponding center of motion is the ſame, and the wheel and axis may be reduced to a bent lever, and conſequently there will be an equilibrium when *P* : *W* :: *W*'s diſtance from the center of motion : *P*'s diſtance :: radius of the axis : radius of the wheel (277). Q. E. D.

This

* Keil's Phyſics, Lect. X. Helſham, Lect. VII. Muſchenb. Ch. VIII. Sect. CCCCXLIII. Emerſon, Prop. XXIV. Varignon, Tom. I. Sect. IV.

Otherwiſe:

This propoſition is uſually proved by the following proceſs: ſince the directions of P and W are perpendicular to their reſpective diſtances from their centers of motion, they are wholly efficient, and P's velocity is to W's velocity as the periphery of the wheel to the periphery of the axis, and conſequently, when there is an equilibrium, $P : W ::$ periphery of the axis : periphery of the wheel :: radius of the axis : radius of the wheel (272). Q. E. D.

329. Cor. 1. If the thickneſs of the rope, to which W is appended, be not inconſiderable, it ought not to be neglected; for, when one or more ſpires of the ropes are folded about the axis, the diſtance of W's direction from the center of motion is encreaſed, being equal to the ſemidiameters of the axis and ropes; and there is an equilibrium when $P : W ::$ the diſtance of W's direction from the center of motion : ſemidiameter of the wheel.

330. Cor. 2. If P and W act in the ſame plane, and in the directions PD, and WD, meeting in D, and be in equilibrio, they are equivalent to a third force, or preſſure upon the axis at A, whoſe direction meets PD, and WD in D (216); and, producing PD, WD, theſe three forces are to each other, as the ſides DF, DE, and diagonal DG, of the parallelogram EF; therefore $P : W :: DF : DE$, or drawing AN, AM, perpendicular to WD and FD reſpectively, $P : W :: AN : AM$ (311). FIG. XC.

331. Cor. 3. The preſſure upon the axis at $A(Pr) : P :: DG : DF ::$ ſin. $\angle DFG$ or PDW : ſin. $\angle FGD$ or ADW; $Pr : W :: DG : DE ::$ ſin. $\angle DEG$ or PDW : ſin. $\angle DGE$ or ADP; and $P : W ::$ ſin. $\angle ADW$: ſin. $\angle ADP$. When the angle PDW is infinitely ſmall, or PD and WD are parallel, the perpendiculars AN, AM, are to each other as $AW : PA$.

FIG. XCI. 332. PROP. *In a combination of wheels* GH, FK, EL, *whoſe axes are* QM, RN, BD, *an equilibrium obtains when* P : W :: QD × RC × AB : DG × CF × AE.

DEM. Let Q, R, W, be reſpectively in equilibrio with P, Q, R; and $P : Q :: QD : DG$, (328)

$Q : R :: RC : FC$,

$R : W :: AB : AE$, and, componendo, $P : W :: QD \times RC \times AB : DG \times FC \times AE$. Q. E. D.

333. Cor. 1. If the ratios of $QD : DG$, $CR : CF$, $AB : AE$ be the ſame, and the number of wheels be n, $P : W :: QD^n : DG^n$; and if this given ratio be that of $1 : r$, $P : W :: 1 : r^n$ and $P = \frac{W}{r^n}$.

334. Cor. 2. If the peripheries QM, RN, were to touch the peripheries FK, EL, and operate upon them by means of teeth made in each, this analogy would ſtill obtain, and P would be to W as the product of the ſemidiameters of the axes, to the product of the ſemidiameters of the wheels. As if $X\Upsilon$ be a combination of wheels, and W be appended upon the axis ΥF, and the power P act at P; $P : W$ :: products of the ſemidiameters of the pinions B, D, F : product of the ſemidiameters of the wheels A, C, E.

FIG. XCII.

335. Cor. 3. Becauſe the number of teeth in the wheels and pinions are to each other as their peripheries, or radii, $P : W ::$ ſemidiameter of the axis to which W is appended multiplied into the number of teeth in the pinions : the length of the lever where P acts multiplied into the number of teeth in the ſeveral wheels.

336. Cor. 4. The number of revolutions of a pinion or wheel being inverſely as the time of one revolution, or inverſely as the periphery or number of teeth in it, the number of revolutions of

the wheel where *P* acts, is to the number of revolutions, in the ſame time, of the axis to which *W* is appended, as the product of the number of teeth in the wheels to the product of the number of teeth in the pinions.

337. PROP. *If a wheel with teeth* C D A *revolve about* C, *and impel the wheel* S B A *round with it, by the action of teeth* B D, b d, *&c. upon* B *and* b, *whoſe curvature is ſuch that* B, b, *deſcribe the lines* B D, b d, *whilſt they deſcribe* B A *and* b A *reſpectively, the moments of theſe wheels are equal.* FIG. XCIII.

DEM. Becauſe the points *B* and *D* come into contact at *A*, at the ſame time, every part of *BA* is applied to *AD*, and is therefore equal to it, and conſequently *B* and *D* move towards it with equal velocities; and therefore if equal weights act at *B* and *D* perpendicular to *SB*, *CD*, they muſt be in equilibrio. Q. E. D.

338. Cor. 1. If *C D n B* be a bent lever whoſe fulcrum is at *C*, equal forces, acting at *D* and *B* in directions perpendicular to *CD*, *SB*, would keep the levers *C D n B* and *S B* in equilibrio.

339. Cor. 2. Becauſe the point *B* moves over *B D* whilſt the arc *BA* rolls over *DA*, the figure of the tooth *B n D* is an epicycloidal arc; and the effect is the ſame whether *B* deſcribe the concave or convex ſide of *B n D*, and conſequently whether the wheel *CDA* impel *S B A* by the action of the convex ſide of the tooth upon *B*; or *S B A* impel *CDA* round with it by the action of *B* upon the concave ſide of the tooth *B n D*.

340. Cor. 3. If any number of epicycloidal teeth *D B*, *d b* and *Aa*, be inſerted in the periphery *AD*, at equal diſtances from each other, and teeth *B*, *b*, *A*, be inſerted in the other wheel *AB*, at equal diſtances, and *Ab* = *Ad*, and *AB* = *AD*, the teeth

B, *b*, *A*, will all act together with equal moments; for becauſe $Ab = Bb$, the velocities and conſequently moments of *B* and *b* are equal, and they act together, becauſe *b* is always found in *bd* and *B* in *B n D*.

341. Cor. 4. The effect is the ſame when the epicycloidal teeth are upon the periphery of the wheel *S B A*; for, whilſt *B* and *D* move to *A*, *B* deſcribes the epicycloid *B n D*, and *D* deſcribes another epicycloid *D m B*, whoſe baſe is *B A*.

SCHOLIUM.

342. The teeth ſhould not act upon each other before they arrive at *SC*, joining their centers, and the machine is more or leſs complete according to the number of teeth acting together. The action of any tooth ſhould not ceaſe before that of the ſucceeding tooth begins.

PULLEY*.

FIG. XCV. 343. DEF. *A pulley is a ſmall circular wheel, as* m E n, *revolving about an axis paſſing through its center, by the action of a power which is applied to a rope paſſing over the pulley.*

344. PROP. *In a ſingle fixed pulley, an equilibrium obtains when the power* P, *is equal to the weight* W.

DEM. When a rope is ſtretched and quieſcent, it is evident that the tenſion of every part is the ſame, otherwiſe motion would enſue; therefore the tenſion of *P m* is equal to that of *W n* and $P = W$. Q. E. D.

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* Muſchenbroek, Ch. VIII. Sect. CCCCXCIV. Varignon, Tom. I. Sect. III. Keil's Phyſics, Lect. X. Helſham, Lect. VII. Hamilton's Principles of Mechanics, pag. 162. Emerſon, Prop. XXVII. Deſaguliers, pag. 99.

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345. This propoſition is ſometimes proved by conſidering the pulley as a lever; for the moments of P and W being the ſame to whatever parts of their directions they are applied, but, if applied at m and n, mEn is a ſtraight lever whoſe center of motion, E, is in its biſection, and conſequently when there is an equilibrium $P = W$ (274). And the concluſion thus deduced is certainly ſatisfactory without any other demonſtration.

346. Cor. 1. If the ſame rope paſs over any number of fixed pulleys, P is equal to W when there is an equilibrium, becauſe the tenſion of the rope is, in every part, the ſame.

347. PROP. *If the weight*, W, *be ſuſtained by a power* P, *applied to a rope paſſing over a moveable pulley* E, P : W :: 1 : 2. FIG. XCVI.

DEM. Let the tenſion of the rope $PA = m$, and that of BC, and DF, is each equal to m, and conſequently the tenſion of EW is equal to $2m$; therefore $P : W :: m : 2m :: 1 : 2$. Q. E. D.

348. Cor. 2. If W be ſupported by P, applied to a rope paſſing over any number of moveable pulleys (n), $P : W :: 1 : 2n$; for the number of ropes ſupporting the weight is equal to $2n$, each ſupports an equal part of it, and the tenſion of the rope, to which P is applied, is equal to that of one of them.

349. Cor. 2. If W be ſupported by P, applied to a rope paſſing over each pulley in two blocks, to the lower of which W is appended; $P : W$ :: 1 : number of ropes at the lower block. For all the ropes A, B, C, D, E, ſupport W, and each ſupports an equal part, becauſe their tenſion is the ſame, and the tenſion of each is equal to that of F to which P is applied. FIG. XCVII.

350. Cor.

350. Cor 3. If a moveable pulley, *L*, be annexed to this ſyſtem, *P* will ſupport a weight equal to $2 \times W$; for the tenſions of the ropes *G* and *H* are equal and they both ſuſtain the weight, which is therefore equal to $2 \times W$.

351. Cor. 4. It is evident that *P* acquires no moment or quantity of motion by this diſtribution of the weight amongſt a number of pulleys; for the velocity of *P* is to that of *W* as the number of ropes, ſupporting the weight, to unity. If *W* be elevated through any ſpace equal to *s*, any point in each of the ropes ſupporting it, muſt move through a ſpace equal to *s*, and *P* conſequently through a ſpace equal to *s* multiplied into the number of ſtrings.

FIG. XCVIII. 352. PROP. *If the body* W *be ſupported by the power* P, *in a ſyſtem compoſed of one fixed, and any number of moveable pulleys, each having a ſeparate ſtring,* P : W :: *unity* : *that power of* 2 *whoſe index is the number of moveable pulleys.*

DEM. Let the tenſion of the ſtring, to which *P* is applied, be equal to *m*, and the tenſion of *A* and *B* is each equal to *m*; that of *C* and *D* is each equal to $2m$; that of *E* and *F* is each equal to $4m$; and that of *GH* to $8m$; therefore $P : W :: m : 8m :: 1 : 8$; and, if the number of moveable pulleys be equal to *n*, it is evident that the tenſion of the ſtring ſupporting *W* is equal to the nth term of the geometric ſeries 2, 4, 8, &c. or to 2^n and $P : W :: 1 : 2^n$. Q. E. D.

353. Cor. 1. $P \times 2^n = W$ and $P = \frac{W}{2^n}$; and if the number of moveable pulleys and *P* or *W* be given, the number of moveable pulleys, or *n*, may be found.

354. Cor.

354. Cor. 2. The parts of *W*, ſuſtained by the ſeveral moveable pulleys, &c. are to each other as 2, 4, 8, 16, &c.

355. PROP. *If the body*, W, *be ſuſtained by the power*, P, *in a ſyſtem of pulleys where the rope paſſing over each pulley is immediately fixed to* W, P : W :: *unity : that power of two, diminiſhed by unity, whoſe exponent is the number of ropes, or number of moveable pulleys encreaſed by unity.* FIG. XCIX.

DEM. Let the tenſion of the rope, to which *P* is applied, be equal to *m*, and it is evident that the tenſions of the ropes *G*, *B*, *D*, *F*, are equal to *m*, 2*m*, 4*m*, 8*m*, reſpectively; but theſe ropes entirely ſupport *W*, and conſequently $P : W :: m : \overline{1+2+4+8} \times m :: 1 : 15$. If the number of ropes fixed to *W* be equal to *n*, it is evident that $P : W :: 1 : 1+2+4+8$, &c. continued to *n* terms $:: 1 : 2^n - 1$. Q. E. D.

356. Cor. 1. $P \times \overline{2^n - 1} = W$ and $P = \frac{W}{2^n - 1}$; and if any two of theſe magnitudes *P*, *W*, or *n*, be given, the other may be found.

357. Cor. 2. *m*, 2*m*, 4*m*, 8*m*, &c. expreſs the ratio of the parts of *W* reſpectively, ſupported by *G*, *B*, *D*, *F*, &c.

358. Cor. 3. If the rope, to which *P* is applied, inſtead of being fixed to *W* paſs over a pulley to which *W* is appended, *P* : *W* :: *m* : 4*m* :: 1 : 4; for *W* is ſupported by the ropes *E*, *G*, *F*, whoſe tenſions, compared with that to which *P* is applied, are reſpectively equal to *m*, 2*m*, *m*, and the ſum of their tenſions = 4*m*. FIG. C.

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FIG. CI. 359. When the directions of the ropes PA, QB, to which two powers Q and P are applied, and the direction in which W acts, are parallel to each other, as is ſuppoſed in the preceding propoſitions, it is evident that W is exactly equal to $P + Q$, becauſe they juſt ſupport it, and their force is all effective, no part being loſt by obliquity of direction. This alſo appears by conſidering BCA to be a lever, for (287) $W : P + Q :: CB + CA : AB$, and conſequently $P + Q = W$ and $P = Q = \frac{W}{2}$. But if the direction in which P acts be changed to ZA, touching the pulley in D, motion will enſue, parallel to the horizon, as P acts partly in that direction, and the quantity and direction of Q muſt be changed to reſtore the equilibrium. It is evident that the pulley cannot be at reſt, till the horizontal parts of the forces P and Q be equal to each other, and the parts contributing to the ſupport of W be each equal to $\frac{W}{2}$. This is alſo obvious from (216); for the pulley BCA is acted upon by three forces, whoſe directions are not parallel, and is quieſcent; and theſe forces are therefore in the ſame plane, their directions meet in the ſame point D, and are conſequently equally inclined to the direction of W, or to the horizontal line BA.

FIG. CII. 360. PROP. *If* W *be ſupported by two powers* P *and* Q, *whoſe directions touch the pulley in* A *and* B, W : P *or* Q :: *ſin.* ∠ *contained between* P A *and* Q B : *ſin. of half that angle.*

DEM. Becauſe the pulley is acted upon by three forces P, Q, W, and kept at reſt, and their directions are perpendicular to the ſides of the triangle CBA, $W : P :: BA : CA$, and $W : Q :: BA : CB$; therefore $W : P$ or Q :: ſin. ∠ BCA or its ſupplement to two right angles BDA : ſin. ∠ BDC (equal to the ∠ CBA or CAB). Q. E. D.

361. Cor.

361. Cor. 1. Becauſe $P : W :: CA : BA$ and $Q : W :: CB : BA$; therefore $P + Q : W :: CA + CB : BA$.

362. Cor. 2. If AB be an arc of 60 degrees, or the angle ADB be equal to 120 degrees, AB is equal to AC or CB, and conſequently $W = P$ or Q.

363. Cor. 3. Becauſe $P : W :: AC : AB$, $P = \frac{W \times AC}{AB}$. If therefore the arc AB vaniſh, or the angle ADB be equal to 180°, $P = \frac{W \times AC}{0}$, or P is infinitely great compared with W. As the arc AB encreaſes to a ſemicircle, P decreaſes and becomes the leaſt poſſible when it is a ſemicircle, becauſe the chord AB is then the greateſt poſſible. In this caſe PA and QB are parallel to each other and to CD, and $W = P + Q$, becauſe $AB = AC + CB$, and conſequently $P = \frac{W \times AC}{AB} = \frac{W}{2}$. As the arc BA encreaſes beyond the ſemicircle, P encreaſes and becomes infinite when it is equal to the periphery.

364. Cor. 4. If P be finite, W is either finite or evaneſcent; for $W = \frac{P \times AB}{AC} = 0$, when AB vaniſhes, and is finite when AB is finite.

365. PROP. *If* W *be ſuſtained by* P *in a ſyſtem of moveable pulleys* v, y, x, *each of which has a ſeparate rope, and the angles contained by the directions of the ropes be* FSE, DTC, BRA; W : P :: EF × DC × BA : vE × yC × xA. FIG. CIII.

DEM. Let W,T,R,P represent the tensions of the strings vW, yT, xR, PG respectively; and (360) $W : T :: EF : vE$

$T : R :: CD : yC$

$R : P :: AB : xA$; and consequently

$W : P :: EF \times CD \times AB : vE \times yC \times xA$.

Q. E. D.

366. Cor. 1. If the pulleys and the angles FSE, DTC, BRA be equal, $W : P :: EF^3 : vE^3$; and, if the number of moveable pulleys be equal to n, $W : P :: EF^n : vE^n$.

367. Cor. 2. If the directions of the ropes become parallel, $W : P :: 2Ev \times 2yC \times 2xA : Ev \times Cy \times Ax$, and, when the pulleys are equal, $W : P :: 2 \times 2 \times 2 : 1$; or as that power of two, whose exponent is the number of moveable pulleys, to unity, which coincides with (352).

368. Cor. 3. If the tension of the rope PG, to which P is applied, be equal to m, $R = \frac{m \times AB}{Ax}$, $T = \frac{m \times AB \times CD}{Ax \times Cy}$, $W = \frac{m \times AB \times CD \times EF}{Ax \times Cy \times Ev}$.

SCHOLIUM.

369. The conclusions, derived from considering the tensions of the several ropes in any system of pulleys, may also be investigated by supposing the moments of P and W to be equal, the velocities involved in these moments being reduced to opposite directions.

1. In fig. 99. the ropes being all parallel to the direction in which W acts, the velocities of P and W are in opposite directions and entirely efficient; and, when an equilibrium obtains, the product of P and its velocity is equal to the product of W and its velocity: for let $Ll = Mm = Nn = Oo = v$, and if the point L be

be elevated to l, through a ſpace equal to v, the pulley EF will deſcend through a ſpace equal to v, and any point of the rope E through a ſpace equal to $2v$, and, when the point M is elevated to m, through $3v$; therefore the pulley BA will deſcend through a ſpace equal to $3v$, and when the ropes A and B are ſtretched, A muſt deſcend through a ſpace equal to $6v$, and when the point N is elevated to n, through $7v$, &c.; conſequently the velocities of W and the ſeveral ſtrings E, C, A, P, are reſpectively as v, $3v$, $7v$, $15v$, and when an equilibrium obtains $P : W :: 1 : 15$. 2. In fig. 98. let W aſcend through a ſpace equal to v, and the ropes F, E, A will evidently be elevated through ſpaces equal to $2v$, $4v$, $8v$, reſpectively, and if the number of moveable pulleys be equal to n, it is clear that the velocity of P : velocity of $W :: 2^n \times v : v :: 2^n : 1$, and when there is an equilibrium P and W are inverſely as their velocities, or as $1 : 2^n$. 3. If the ropes, ſuſtaining the pulleys be not parallel to each other; let EFV be a pulley ſuſtained by two powers E and F, whoſe directions meet in S; and if W be raiſed through a very ſmall ſpace equal to SV, E and F, acting parallel to ES and FS, will deſcribe the ſpaces SE and SF reſpectively, and the velocities of W, E, F, are to each other as SV, SE, SF. Reſolve SF and SE, each into two, Sm, mF, and Sm, mE, of which mF and mE being equal and oppoſite deſtroy each other, and the remainders are wholly efficient; therefore, in an equilibrium, $\overline{E+F} \times Sm = W \times SV$; but $\overline{E+F} \times SF : \overline{E+F} \times Sm$ (or $W \times SV$) $:: SF : Sm : FV : Fm$, and $\frac{\overline{E+F} \times SF}{2} (E \times SE) :$ $W \times SV :: \frac{FV}{2} : Fm :: FV : FE$, or the power or tenſion at E is to the moment of W as $EV : FE$, which coincides with what is proved in (360).

FIG. CIV.

INCLINED PLANE.

PLATE XIII. FIG. CV.

370. DEF. *A plane ſurface inclined, in any angle, to an horizontal plane, is called an inclined plane. If* BA *be drawn upon the inclined plane, and* BC *upon the horizontal plane, from the ſame point* B *of their common interſection, perpendicular to it, the angle* ABC *is the angle of elevation or inclination; and if* PW *be the direction of the power, the angle* PWA *is called the angle of traction.*

371. PROP. *If a body, whoſe weight is* W, *be juſt ſupported upon the inclined plane* AB *by a power* P, *acting in the direction* PW; P : W :: PW : PC *(ſuppoſing* PC *to be perpendicular to the horizontal line* BC) :: *ſin. ∠ inclination* ABC : *coſ. ∠* AWP.

DEM. The weight *W*, acting in the direction *WL* or *PC* perpendicular to the horizon, is ſupported by the power *P*, and reaction of the plane, acting reſpectively in the directions *PW*, and *WC* perpendicular to the plane; and conſequently *P*, *W*, and preſſure upon the plane, are to each other reſpectively as the ſides *PW*, *PC* and *WC* of the triangles *PWC* (196), and *P* : *W* :: *PW* : *PC* :: ſin. ∠ *PCW* or *ABC* : ſin. ∠ *PWC* or coſ. of ∠ *PWA*. Q. E. D.

Another demonſtration:

FIG. XVI.

Let *WZ*, repreſenting the weight of *W*, or its tendency to deſcend in a direction perpendicular to the horizon, be reſolved into two, one *SZ* perpendicular to the plane, and the other *WS* parallel to it. *WS* repreſents the tendency of *W* to deſcend upon the plane, and, taking *Wx* = *WS*, and drawing *xE* perpendicular to the plane, any force *WD*, *WE*, &c. drawn from *W* and terminated by *xE*, will be in equilibrio with *W*, becauſe the only efficient

cient part of WE, reſulting from reſolution, is equal and oppoſite to WS; but $P : W :: WE : WZ :: \frac{WX \times \text{rad.}}{\text{cof.} \angle EWX} : \frac{WS \times \text{rad.}}{\text{ſin.} \angle SZW} ::$ ſin. $\angle SZW$ or ACB : cof. $\angle EWA$.

372. Cor. 1. The ſame force, acting in parallel directions, is required to ſupport the ſame weight upon every part of the plane; becauſe the angle of traction is the ſame, and $P = \frac{W \times \text{ſin.} \angle \text{inclin.}}{\text{cof.} \angle \text{of traction}}$, which is a given quantity.

373. Cor. 2. Becauſe $P = \frac{W \times \text{ſin. of} \angle \text{inclin.}}{\text{cof.} \angle \text{traction}}$, if W and the plane be given, P is the leaſt poſſible when the coſine of the angle AWP is the greateſt poſſible, or when PW is parallel to the plane: as the angle PWA encreaſes from hence, its coſine decreaſes, and conſequently P encreaſes, and becomes equal to W, when PW is perpendicular to the horizon, and infinitely greater than W when PW coincides with WG or WC. FIG. CV.

374. Cor. 3. When PW is parallel to the plane, $P : W ::$ ſin. $\angle$ of inclin. : radius :: $AC : AB$; when it is parallel to the baſe, $P : W ::$ ſin. $\angle$ of inclin. : ſin. $\angle BAC$ (this angle being the complement of the angle of traction) :: $AC : BC$.

375. Cor. 4. If AB be perpendicular to the horizon, and the angle $PWA = 0$, $P = W$; for the cof. of $\angle PWA =$ ſin. of $90° =$ ſin. of $\angle$ of inclination. If, in this ſuppoſition, PW be parallel to the horizon, P is infinite; for cof. of $\angle$ of traction $= 0$.

376. Cor. 5. Let Pr repreſent the preſſure upon the plane, and $Pr : W ::$ ſin. $\angle WPC$: ſin. $\angle PWC$ or cof. $\angle$ of traction, and $Pr = W \times$

$\frac{W \times \text{sin.} \angle WPC}{\text{cos.} \angle PWA} = 0$, when PW is perpendicular to the horizon, and infinite when the $\angle PWA$ is a right angle.

377. Cor. 6. Let CI be perpendicular to P's direction, and the sides of the triangle CIB, CI, CB, and IB, are respectively perpendicular to the directions of P, W, and preſſure upon the plane, and conſequently P, W, and Pr, are reſpectively as CI, CB and IB.

378. Cor. 7. If WCP were an angular balance revolving upon the fulcrum C, and acted upon by two forces in the directions PW and WL, an equilibrium would obtain between them when $P:W$ inverſely as the perpendiculars let fall from C upon their directions, or $P:W::CL:CK$ (272); but $CL:CK::$ sin. $\angle CWL$ or WCP : sin. $\angle CWK$ or $CWP :: PW:PC$.

FIG. CVII. 379. Cor. 8. If P and W be in equilibrio, their perpendicular velocities are to each other inverſely as their magnitudes; for let W deſcend through an infinitely ſmall ſpace WA, and its perpendicular deſcent is WY, and P's perpendicular aſcent is equal to the difference between PA and PW, or Am, if Em be perpendicular to PA. Draw FDn perpendicular to PA, and DZ to FA, and $Am : WY ::$ P's velocity : W's velocity :: $An : DZ :: AF : DF$ (ſim. triangles) :: $W : P$ (377).

FIG. CVIII. 380. PROP. *If two bodies* W *and* V, *placed upon the inclined planes* AB, AD, *ſupport each other by means of a rope paſſing over the pulley* P, V : W :: *coſ.* $\angle$ AVP $\times$ *ſin.* $\angle$ ABC : *coſ.* $\angle$ PWA $\times$ *ſin.* $\angle$ ADC.

DEM. The tenſion of the rope VPW is every where the ſame, or the ſame power, P, is required to ſupport V and W; but

P :

$P : W ::$ fin. $\angle ABC :$ cof. $\angle PWA$; and
$V : P ::$ cof. $\angle AVP :$ fin. $\angle ADC$; therefore
$V : W ::$ fin. $\angle ABC \times$ cof. $\angle AVP :$ cof. $\angle PWA \times$ fin. $\angle ADC$.
Q. E. D.

381. Cor. 1. If PV and PW be parallel to AD and AB reſpectively, $P : W :: AC : AB$,
$V : P :: AD : AC$; therefore
$V : W :: AD : AB$.
This concluſion is alſo derived from the general expreſſion, the coſines of the angles PVA and PWA becoming AD and AB.

382. Cor. 2. If PV and PW be parallel to the baſes of the planes, $P : W :: AC : BC$,
$V : P :: DC : AC$, and
$V : W :: DC : BC$.
This alſo follows from the general expreſſion, the complements of the $\angle$s AVP and AWP, being, in this ſuppoſition, reſpectively equal to DAC and BAC.

WEDGE.

383. DEF. *A wedge is a hard body, generally of a triangular priſmatic figure as* AF, *which is generated by the motion of the triangle* AED *upon the right line* EF *always perpendicular to its plane.* FIG. CIX.

If AED be an iſoſceles triangle, it is called an iſoſceles wedge, if ſcalene, a ſcalene wedge. $ABCD$ is the back of the wedge, upon which a force is impreſſed uſually by percuſſion; and $ABFE$, $DEFC$, are the ſides of the wedge, upon which the reſiſtances of wood, &c. act and counterpoiſe the force of percuſſion. The angle AED is the vertical angle of the wedge.

384. PROP. *If two equal reſiſtances, acting in equal angles upon the ſides of an iſoſceles wedge* ABV, *be in equilibrio with a power,* P, *acting*

FIG. CX. *ing in a direction perpendicular to the back; P is to the resistances, as the rectangle of the sines of half the vertical angle of the wedge and the inclination of the resistance to the sides, to the square of the radius.*

DEM. Let the directions and quantities of the resistances be CD and Cd; resolve each into two, DE and de, in the directions of the sides, and CE, Ce, perpendicular to them, and DE, de, are lost by their obliquity. Resolve EC, eC into two forces, EF, eF, parallel to the base, and FC, FC perpendicular to it; EF, ef, being equal and opposite, destroy each other, and the forces $2FC$, being exactly opposite to, and in equilibrio with P, are equal to it. But $FC : EC ::$ sin. $\angle FEC$ or $\angle BVC$: rad.

$EC : DC ::$ sin. $\angle EDC$: rad.; and

ex æquo $FC : DC ::$ sin. $\angle BCV \times$ sin. $\angle EDC$: $\overline{\text{rad.}}^2 :: 2FC$ or $P : 2DC$ or resistances. Q. E. D.

385. Cor. 1. If the resistances be perpendicular to the sides, the sine of the angle ADC becomes the radius; and consequently P : resistances :: sin. $\angle CVA$: radius :: $AC : AV :: AB : AV + BV$.

386. Cor. 2. If the resistances be perpendicular to the axis, P : resist. :: $BC \times CV : BV^2$; and, when the angle AVB is equal to two right angles, P : resist. :: $BC \times 0 : BC^2 :: 0 : BC$, or P is infinitely less than the resistances.

387. Cor. 3. When the resistances are perpendicular to the back AB, the angle $EDC = BVC$, and P : resist. :: sin.$^2 \angle BVC$: rad.$^2 :: BC^2 : BV^2$. If the angle BVA be equal to two right angles $BC = BV$, and $P =$ resistances; and if the angle BVA be diminished without limit, the resistances are encreased without limit.

388. Cor.

388. Cor. 4. If P be the ſame in the two ſuppoſitions of cor. 1. and 2; reſiſt. in cor. 1 : reſiſt. in cor. 2 :: $CV : BV$.

389. Cor. 5. If the reſiſtances be given in cor. 2, P is the greateſt poſſible when the angle BVA is a right angle.

390. Cor. 6. If the quantities of the reſiſtances be given, and their directions be variable; P is the greateſt poſſible in the common ſuppoſition of cor. 1.; for it varies as the ſine of the angle EDC, which is the greateſt when that angle is right.

SCHOLIUM.

391. The relation, ſubſiſting between the power and reſiſtances in the wedge, has been traced through various proceſſes and modes of reaſoning, by different philoſophical writers*; and different, and frequently contradictory, concluſions have been deduced from different demonſtrations, ſome of which muſt conſequently be erroneous. As in all equilibria of forces, they muſt either obliquely, or directly, oppoſe each other, and their intenſities, eſtimated in oppoſite directions, muſt be equal; one ſource of error hath reſulted from a miſapplication of this equality of moments, which is univerſally true and will never lead to falſe concluſions, if the velocities be reduced to oppoſite directions, and the efficient parts only of the moments be ſuppoſed equal. 1. Let two equal reſiſtances R and r act perpendicularly upon the ſides of an iſoſceles wedge ABD, and be in equilibrio with a power P acting perpendicularly upon the baſe AB; and taking Dd, the continuation of PD, very ſmall, and drawing dE, de parallel, and DE, De perpendicular, to the ſides, the velocities of P, R, r, are to each other as Dd, DE, De reſpectively, theſe being deſcribed by them in the ſame time. Reſolve DE, De into two, EL and eL parallel FIG. CXI.

* Rohault Not. ad a, 9. Maclaurin's Newt. Chap. III. Art. 21. Graves, Lect. I. C. X. Deſaguliers, p. 107. Emerſon, Prop. 30. Muſchenbroek, Sect. CCCCLXIII. and CCCCCXCI.

rallel to the baſe, which being equal and oppoſite deſtroy each other, and DL, DL perpendicular to the baſe, which being oppoſite to P's direction, are wholly efficient; and becauſe there is an equilibrium $\overline{R+r} \times DL = P \times Dd$, but $\overline{R+r} \times DL$ or $P \times Dd : \overline{R+r} \times DE :: DL : DE :: AP : AD :: AB : AB + AD$, the ſame as (385).

When R and r act in any other direction, the relation of their moments to that of P is diſcoverable by a ſimilar proceſs. If they be parallel to the baſe, draw Mdm parallel to their direction, and the velocities of P, R and r, are reſpectively as Dd, DM and dm; and reſolving DM, dm into two DE, de perpendicular, and ME, me parallel, to the ſides, the laſt not being oppoſed to the ſides are quite inefficient; and repeating the proceſs above $\overline{R+r} \times DL = P \times Dd$; and $P \times Dd : \overline{R+r} \times DE :: AP : AD$

$\overline{R+r} \times DE : \overline{R+r} \times DM :: DE : DM :: PD : AD$

and $P \times Dd : \overline{R+r} \times DM :: AP \times PD : AD^2$; which is the ſame as (386).

A different analogy is inveſtigated by Rowning, from the ſame principle, viz. the power : the reſiſtances :: $AP : PD$.

2. Another ſource of error is an improper uſe of this principle, "that if three forces act upon a body, which remains at reſt, they are to each other as the three ſides of a triangle, reſpectively parallel or perpendicular to their directions;" which certainly is untrue, if any parts of them be inefficient and loſt by obliquity of direction; for the force FG will have exactly the ſame effect upon the ſides of the wedge AD with FH, FI, or the perpendicular FL, ſuppoſing GL to be parallel to AD, and of the parts, reſulting from a reſolution of each into two forces, one perpendicular to, and the other coincident with, the ſides, theſe laſt, Fx, &c. are loſt. When the wedge does not fill the cleft, and the reſiſtances act perpendicularly upon its ſides, Maclaurin and Varignon have applied the above principle and deduced different concluſions, both of which cannot be true. Dr. Hamilton, Graveſands, Deſaguliers, Emerſon, Muſchenbroek aſſert, that the power is to the reſiſtances as half the back is to the height, and Keil, Whiſton

and

and Nicholſon, aſſign this ratio to be that of the whole back to the height. The firſt analogy coincides with this general theorem, "that the power is to the reſiſtances, when in equilibrio, as a line drawn from the biſection of the baſe to one ſide, parallel to the reſiſtance upon that ſide, to the height of the wedge; and this theorem is preſumed to be erroneous for the following reaſons.

1. If the directions of the reſiſtances be parallel to the axis, their ſum is equal to the power, according to the theorem, which cannot be true; becauſe the power acting perpendicularly is wholly efficient, but part of the reſiſtance is loſt by obliquity of direction.

2. If the vertical angle of the wedge be diminiſhed without limit, a line drawn, from the biſection of the baſe to a ſide, parallel to the reſiſtance, accedes to equality with the height when the direction of the reſiſtance is parallel to the height, and the power and reſiſtance become equal, according to the theorem; but, the power continuing the ſame, the directions of the reſiſtances accede to a paralleliſm with the ſides, and they become wholly inefficient.

3. When the reſiſtances act perpendicularly to the axis, and the vertical angle of the wedge accedes to two right angles; according to the theorem, the ratio of the power to the reſiſtances encreaſes without limit, which cannot be true, becauſe the inefficiency of the reſiſtances evidently encreaſes without limit, and conſequently the ratio of the reſiſtances to the power encreaſes without limit, which is directly the reverſe of the theorem.

4. If the power be the ſame in the two caſes where the directions of the reſiſtances are perpendicular to the ſides and axis, of the wedge, the reſiſtances are, according to the theorem, as the ſide and height of the wedge reſpectively; or greater reſiſtances are required to ſuſtain a given power, when their directions are perpendicular to the ſides, and therefore entirely efficient, than when they are oblique and conſequently not wholly efficient, which certainly is untrue.

It is preſumed, for theſe reaſons, that the analogy, derived from the theorem, and conſequently the theorem itſelf, cannot be generally true; and were theſe reaſons leſs deciſive, it would not be difficult to point out the ſeveral overſights in the demonſtration which induced a falſe concluſion*.

FIG. CXIII. 392. PROP. *If the power and reſiſtances* P, R, *and* r, *act perpendicularly upon the back and ſides of a ſcalene wedge* ABD, *and be in equilibrio*, P : R + r :: *back of the wedge : ſum of its ſides.*

DEM.

*THEOREM. If a power *P*, acting perpendicularly upon the back of an iſoſceles wedge *ABC*, be in equilibrio with the equal reſiſtances *E* and *F*, acting perpendicularly upon its ſides, *P* : *E* + *F* as a line *PE* drawn from the biſection of the baſe *P* to one ſide, parallel to the reſiſtance upon it, to the height of the wedge *PB*.

FIG. CXII.

DEM. Let the directions of *E* and *F* meet in the biſection of the baſe *P*, and *PE* = *PF*, and, compleating the parallelogram, P : *E* + *F* :: *PN* : *PE* + *PF* (196) :: *PH* : *PE* :: *PE* : *PB*.

Cor. If *PN* be the force of *P*, *PE* and *PF* will repreſent the force with which *P* protrudes the reſiſtances in directions perpendicular to the ſides.

THEOREM II. If the directions of the reſiſtances be any other lines *PD*, *PO*, equally inclined to the ſides, the power is to the reſiſtances (*E* + *F*) as *PD* to *PB*.

DEM. Reſolve *PE* and *PF* into two, *PG* and *PK* in the directions of *PD* and *PO*, and *GE*, *FK* perpendicular to them; and theſe laſt forces, acting perpendicularly to the reſiſtances, are loſt. If *PN* be the force of *P*, *PE* and *PF* are its force perpendicular to the ſides, and *PG* + *PK* the force in equilibrio with the reſiſtances; therefore *P* : *E* + *F* :: *PN* : *PG* + *PK* :: *PH* : *PG* :: *PD* : *PB*, becauſe $PE^2 = PG \times PD = PH \times PB$, and conſequently *PH* : *PG* :: *PD* : *PB*. Q. E. D.

In this demonſtration, *EG* and *FK*, being inclined to the ſides of the wedge, are not inefficient, and, not being oppoſite, they do not deſtroy each other, and conſequently ought not to be neglected. And, beſides, if the power eſtimated in the directions of *PD* and *PO* be equal to *PG* + *PK*, theſe will be equal to the power eſtimated in the direction *PN*, or equal to *PN*. Reſolve *PG* and *PK* into two, *GL*, *OL*, perpendicular to the axis, which being equal and oppoſite, deſtroy each other, and *PL* and *PL* are the only remaining parts of the force, and theſe are never equal to *PN*, unleſs *PD* and *PE* coincide. *Hamilton on the Principles of Mechanics.*

DEM. Becauſe the power and reſiſtances act perpendicularly upon the back and ſides, they are wholly efficient, their directions are in the ſame plane, meet in the ſame point (216), and their magnitudes are to each other as the three ſides of a triangle parallel, or perpendicular, to their directions; therefore $P : R + r :: AB : AD + DB$. Q. E. D.

393. Cor. If PM, RE, re, be the relative magnitudes of P, R, r, in equilibrio, and lines be drawn through M, E, and e, parallel to the ſides of the wedge reſpectively, any forces, whoſe magnitudes are PL, RF, rf, drawn from P, R and r, terminated by the lines drawn parallel to the ſides, will be in equilibrio; for their perpendicular and only efficient parts PM, RE and re are in equilibrio.

SCREW.

PLATE XIV. FIG. CXIV.

*394. DEF. *If a right line, divided into equal parts* AC, CE, EG, *&c. repreſenting equal inclined planes, be ſo wrapped round the convex and concave ſurfaces of two cylinders with equal baſes, that* AB, CD, EF, *&c. the horizontal baſes of the planes, may be bent into the peripheries of circles parallel and equal to the baſes of the cylinders; equal ſpirals will be formed upon their ſurfaces, whoſe lengths are* AC, CE, EG, *&c. and diſtances* CB, ED, FG, *&c. the perpendicular heights of the planes. The convex cylinder is inſerted in the concave, and ſo adapted to it that the ſpirals protuberant upon one cylinder may exactly fill the excavated ſpiral or groove upon the other: the firſt is called the external, and the ſecond the internal, ſcrew.*

Another definition:

If a cylinder move uniformly about its axis, whilſt a point moves uniformly upon its ſurface in a right line parallel to the axis, the line, deſcribed by this componnd motion, is a ſpiral, which, being raiſed upon the external ſurface of the cylinder, forms the external ſcrew; and a ſimilar ſpiral groove being cut upon the internal ſurface of a hollow cylinder,

* Maclaurin, Chap. III, XXII. Keil's Phyſics, Lect. X. Rohault, Not. ad 9. Emerſon's Mechanics, Prop. 29.

linder, of the ſame diameter, to receive the protuberant ſpiral, forms the internal ſcrew. Either of theſe ſcrews is fixed, and the other is moveable by a lever paſſing through the center, and in the plane, of its baſe.

FIG. CXV. 395. PROP. *There is an equilibrium upon the ſcrew, when the power,* P, *is to the weight,* W, *or reſiſtances acting parallel to the axis, as the diſtance between two contiguous ſpirals, to the periphery of the circle deſcribed by the power.*

DEM. It is evident that W, acting upon either of the ſcrews, in a direction parallel to its axis, will equally preſs every point of the ſpirals of the other in contact with it, in directions perpendicular to their baſes. If ABD be the baſe of one ſpiral, p, the magnitude of a power acting at B perpendicular to BC, and in equilibrio with the preſſure pr, upon one point of the ſpiral, P' a power acting at P perpendicularly to PC, and in equilibrio with p or pr; (374) $p : pr ::$ diſtance between two contiguous ſpirals $(d) : ABD$; $P' : p :: BC : PC :: ABD$: periphery of the circle deſcribed by the power, therefore $P' : pr :: d$: periphery of this circle, and the ſum of all the P's, or P is to the ſum of all the pr's, or W in the ſame ratio, that is, $P : W :: d$: periphery of the circle deſcribed by P. Q. E. D.

Another demonſtration from def. 2.

Whilſt B or P makes one revolution, W is elevated through a ſpace equal to d, therefore the velocity of P is to the velocity of W, as the periphery of the circle deſcribed by P to the diſtance between two contiguous ſpirals, and conſequently when there is an equilibrium, $P : W ::$ diſt. between two ſpirals : to the periphery deſcribed by P. Q. E. D.

396. Cor. 1. If the direction of W be inclined to the axis, and P do not act in the plane of the baſe, but in any other direction, the ratio of P to W may be found by art. 371.

397. Cor.

397. Cor. 2. The preſſure ſuſtained by any point of the ſpirals is to the part of *W* incumbent upon it, as the length of a ſpiral to its baſe *ABD*.

398. Cor. 3. In an endleſs or perpetual ſcrew, acting upon a wheel, the diſtance of whoſe teeth is equal to *AB*, the diſtance of two contiguous ſpirals, and in equilibrio with a body *W*, ſuſpended from the axis *EF*; $P : W :: AB \times EF$: diameter of the wheel × periphery of a circle whoſe radius is *PG*; for if *R* be the reſiſtance of a tooth to a ſpiral of the ſcrew, $P : R :: AB$: per. of the circle deſcribed by *P*, $R : W :: EF$: diameter of the wheel; therefore $P : W :: AB \times EF$: per. of the circle deſcribed by *P* × diameter of the wheel. PLATE XII. FIG. XCIV.

SCHOLIUM.

399. The ſecond demonſtration of this propoſition is generally deemed unſatisfactory, becauſe the moments of *P* and *W* are not reduced to oppoſite directions; but the ratio of *P* to *W* may be inveſtigated by finding the oppoſite and efficient parts of a power ſuſtaining a body upon an inclined plane, and combining it with the power of the lever. Let *WC* be an inclined plane, or ſpiral of the ſcrew, *W* a weight acting perpendicularly to the horizon *WE*, and ſupported by a power *P*, acting parallel to *WB*; and if *W* be elevated through a very ſmall ſpace *Ww*, or perpendicular height *Hw*, it is evident that *P*, acting parallel to *WE*, will deſcend through a ſpace equal to $WE - we$ or *WH*; and conſequently the velocities of *W* and *P*, eſtimated in oppoſite directions, are as *Hw* to *HW*, or as the height of the plane to its baſe, and when an equilibrium obtains, $P : W ::$ height of the plane : its baſe or *ABD*. But, from the nature of the lever, a power, acting at the diſtance *PC*, muſt be diminiſhed in the ratio of *BC* : *PC*, or of the circumference *ABD* : circumference deſcribed by the power acting at *P*. FIG. CXVI. FIG. CXV.

CHAP.

CHAP. IX.

CENTER OF GRAVITY.

400. DEF. *THE center of gravity of a body or ſyſtem of bodies is a point about which the parts of the body or ſyſtem are in equilibrio.*

401. PROP. *To find the center of gravity of a body.*

PLATE XIV. FIG. CXVII. Let A, B, C, D, &c. be particles of the body, and finding the centers of equilibrium p and q, of A and B, C and D reſpectively (274); let $A+B$ be placed in p, and $C+D$ in q, and their center of equilibrium, G, will be the center of gravity of the particles A, B, C, D, &c. Becauſe the force of gravity acts upon the particles in parallel directions, the efficacy of A to communicate motion to G is $A \times AG$, and that of B is $B \times BG$ (279) or $A \times \overline{Ap+pG}$ and $B \times \overline{Bp+pG}$, which are equivalent to them (181), or $\overline{A+B} \times pG$, ſince $A \times Ap$ and $B \times Bp$ are equal and oppoſite, and conſequently deſtroy each other. The ſum of the moments of C and D is found, by a ſimilar proceſs, to be the ſame as if they were placed in q; and conſequently G, which is the center of gravity of $A+B$ and $C+D$, placed in p and q reſpectively, is the center of gravity of A, B, C, D, placed at the points A, B, C, D, &c. Q. E. D.

402. Cor. 1. The particles of the body cannot be in equilibrio about any other point except G; for, if poſſible, let X be ſuch a point, and it is proved, as before, that the efforts of A and B to move $X = \overline{A+B} \times pX$, and of C and $D = \overline{C+D} \times qX$; therefore the point X is kept in equilibrio by two forces, $\overline{A+B} \times pX$ and

and $\overline{C+D} \times qX$, not acting in oppoſite directions, which is impoſſible (187).

403. Cor. 2. In every ſituation of the body compoſed of the particles A, B, C, D, &c. if the point G be ſupported, the body will be at reſt; for the force of gravity acting always in parallel directions upon the particles, their moments, or efforts to move G, will always be as $A \times AG$, $B \times BG$, &c. which by the proceſs uſed in this propoſition, will always be reduced to two forces that are equal and oppoſite.

404. Cor. 3. If $A+B+C+D$, &c. be equal to $\mathcal{Q}$, and the preſſure of each in parallel directions be equal to q, a force as $\mathcal{Q} \times q$, acting at the point G, in a direction oppoſite to that in which the particles preſs, will remove their preſſure. Or if A, B, C, &c. be deſtitute of gravity, and only reſiſt the action of a force by their inertia, a force P acting at G will communicate equal velocities to every particle; becauſe their reſiſtances, being exerted in directions oppoſite to that of P (3d law of motion) and therefore parallel to each other, vary as their diſtance from G, and conſequently the ſums of the reſiſtances on each ſide of G are equal. And $v.v$, if $\mathcal{Q}$ be moving and without gravity, a force applied, at G (the center of inertia) equal to the moment of $\mathcal{Q}$, will deſtroy all motion.

SCHOLIUM.

405. The particles which compoſe a body, being connected together by the force of coheſion, every line of particles may be conſidered as a lever, impreſſed in different points by the action of gravity, or any force which acts in parallel directions. The particle A therefore is connected with G by the coheſion of the intermediate particles, and, an infinite number of levers terminating in G will therefore be formed, upon which the particles, in any one line, act with intenſities varying as their magnitudes multiplied into their diſtances.

FIG. CXVIII.

406. PROP. *The ſum, or difference, of the products, which reſults from multiplying each particle* A, B, C, D *into its perpendicular diſtance from any plane* LN, *according as they are on the ſame or different ſides of the plane, is equal to the product of all the particles multiplied into the diſtance of their center of gravity,* G, *from that plane.*

DEM. Let P and Q be the centers of gravity of A and B, C and D, and drawing right lines through P, Q, G, parallel to the plane, which interſect the perpendiculars drawn from thoſe points reſpectively; and $A : B :: BP : AB :: Bn$ or $Bb - Pp : Am$ or $Pp - Aa$,

and $A \times \overline{Pp - Aa} = B \times \overline{Bb - Pp}$, or

$$A \times Aa + B \times Bb = \overline{A + b} \times Pp.$$

By a ſimilar proceſs it appears, that $C \times Cc + D \times Dd = \overline{C + D} \times Qq$. But $A + B : C + D :: QG : PG :: Gv$ or $Gg = Qq : Px$ or $Pp - Gg$, and $\overline{A + B} \times \overline{Pp - Gg} = \overline{C + D} \times \overline{Gg = Qq}$, or, by tranſpoſition and a ſubſtitution of equals, $A \times Aa + B \times Bb = C \times Cc = D \times Dd = \overline{A + B + C + D} \times Gg$, where the higher or lower ſigns are to be uſed, according as the bodies are on the ſame, or a different, ſide of the plane. Q. E. D.

FIG. CXIX.

407. Cor. 1. If the particles be placed upon the ſame right line, or Aa, Bb, Cc, Dd, Gg, become Ag, Bg, Cg, Dg, Gg, reſpectively, it is evident, that $A \times Ag + B \times Bg = C \times Cg = D \times Dg = \overline{A + B + C + D} \times Gg$; or the ſum, or difference, of the products reſulting from the multiplication of each particle into its diſtance from any point g, according as they are on the ſame, or a different, ſide of that point, is equal to the product of their ſum multiplied into the diſtance of their center of gravity from that point.

408. Cor. 2. The whole moment of a body, acting upon a lever, being equal to that of every particle, or to the ſum of the products which reſults from the multiplication of each particle into its diſtance from the center of motion (279), is equal therefore to the

the product of the whole body into the distance of the center of gravity from the center of motion, and is consequently the same as if it were collected in the center of gravity. The demonstration of this proposition obtains therefore when A, B, C, D, are collections of particles or bodies, whose centers of gravity are the points A, B, C, D. And to find the center of gravity of a system of bodies, it is evident, that, in the proposition (401), bodies, whose centers of gravity are A, B, C, D, &c. may be substituted for particles.

409. Cor. 3. If A, B, C, D, be bodies acting upon any plane LN, in parallel directions, the sum of their efforts to move it is the same as if they were collected in their center of gravity; for, if A, B, C, D, be the respective centers of gravity of each body, this sum is equal to $A \times Aa \times Bb \pm C \times Cc \pm D \times Dd = \overline{A+B+C+D} \times Gg$; or, if they be placed upon a lever, the sum of their efforts to make it revolve is the same, as if they were placed at G. When the center of gravity therefore is in the plane, or at the fulcrum of a lever, the plane and lever are quiescent. And if any point Z be taken in NL, $A \times aZ + B \times bZ + C \times cZ + D \times dZ = \overline{A+B+C+D} \times gZ$; for if a plane pass through Z, the proof is the same as that of this proposition. FIG. CXVIII.

410. Cor. 4. The distance of any plane from the common center of gravity of A, B, C, D, &c. or Gg is equal to $\frac{A \times Aa + B \times Bb \pm C \times Cc \pm D \times Dd}{A+B+C+D, \&c.}$; and its distance from a plane passing through any point Z is equal to $\frac{A \times Za + B \times Zb \pm C \times Zc \pm D \times Zd}{A+B+C+D}$, where the lower signs are to be used for those bodies not on the same side of Z with A and B.

FIG. CXX. 411. Cor. 5. A right line drawn from A through the center of gravity G of any number of bodies A, B, C, D, &c. will pass through the center of gravity of the remainder; for $B \times Bb + D \times Dd = C \times Cc$, and consequently the center of gravity of B, C, D is in the plane passing through AG, and if this plane revolve, their center of gravity is always in the plane passing through AG, and consequently it must be in the line AG produced, which is the common intersection of the planes. If r be this center, $\overline{B+C+D} \times Gr = A \times AG$, and if the bodies be equal and n their number, $AG = \overline{n-1} \times Gr$.

FIG. CXXI. 412. Cor. 6. If a circle or sphere be described about the center of gravity G, of any number of bodies A, B, C, &c. and any point P be taken in the periphery of the circle, or surface of the sphere, $PA^2 \times A + PB^2 \times B + PC^2 \times C$, &c. is a given quantity; for, drawing GP and the perpendiculars to it Aa, Bb, Cc, $A \times Ga = B \times Gb + C \times Gc$ (409), or, by substitution of equals, $A \times \frac{\overline{GA^2 - PA^2 + GP^2}}{2GP} = B \times \frac{\overline{PB^2 - BG^2 - GP^2}}{2GP} + C \times \frac{\overline{PC^2 - GP^2 - GC^2}}{2GP}$, or, $A \times PA^2 + B \times PB^2 + C \times PC^2 = A \times \overline{GA^2 + GP^2} + B \times \overline{GB^2 + GP^2} + C \times \overline{GC^2 + GP^2}$, and this side of the equation is invariable in whatever point of the periphery or surface P be placed.

FIG. CXXII. 413. PROP. *If* A, B, C, D, *&c. be particles of a body urged by forces in parallel directions, whose magnitudes are* A a, B b, C c, *&c. the sum of their weights is equal to the weight of* A + B + C, *&c. acted upon by a force whose magnitude is* G g.

DEM. The weights of A, B, C, &c. are $A \times Aa$, $B \times Bb$, $C \times Cc$, &c. (235), and consequently the sum of their weights is equal to $\overline{A+B+C}$, &c. $\times Gg$; but this product is the weight of $\overline{A+B+C}$, &c. acted upon by the force Gg. Q. E. D.

414. Cor.

414. Cor. If the forces Aa, Bb, Cc, &c. be equal to each other, Gg is equal to one of them, or if the particles A, B, C, &c. be acted upon by the same force, their weight is the same as if they were collected in their center of gravity and acted upon by that force. The tendency therefore of a body to descend is the same as if it were collected in its center of gravity, and, consequently, if a line drawn from that center perpendicular to the horizon, fall within the base of the body, it cannot fall, and, if without the base, it cannot stand.

415. PROP. *If any number of bodies* A, B, C, *&c. move in parallel directions, with any velocities, the center of gravity will describe a right line parallel to them.* FIG. CXXIII.

DEM. Let A and B, a and b, be cotemporary positions of the bodies A and B, and G, g, their centers of gravity, and through g draw a line xy parallel, and consequently equal, to AB. From the nature of the center of gravity, $A : B :: BG : AG :: bg : ag :: yg : xg$ (sim. triangles); and the point g divides the parallel and equal lines AB, xy, in the same ratio, and Gg is a right line parallel to Aa or Bb. If H be the center of gravity of A, B, C, it is proved in the same manner, that it cuts the parallel and equal lines GC, vz, in the same ratio, and Hh is consequently a right line parallel to Gg. Q. E. D.

416. Cor. 1. If any number of bodies A, B, C, &c. ascend, or descend in parallel right lines, the sum of the products resulting from the multiplication of each body into the space described by it, is equal to the product of their sum and the space described by their center of gravity G; for, let a, b, c, g, be cotemporary positions of A, B, C, G, and, drawing any plane NL, $A \times Am + B \times Bn + C \times Cq = \overline{A+B+C} \times Gh$ (406), and $A \times am + B \times bv + C \times cq = \overline{A+B+C} \times gh$; and consequently by addition $A \times Aa + B \times Bb + C \times Cc = \overline{A+B+C} \times Gg$. FIG. CXXII.

417. Cor.

FIG. CXXIII. CXXIV. 417. Cor. 2. If any number of bodies therefore move in parallel directions with any unequal velocities, or they be placed upon the lever XY, and receive unequal impulses from any force at the same time in parallel directions, the center of gravity will, in the beginning of its motion, move uniformly in a right line parallel to them, and its velocity is equal to the products of each body into its velocity, divided by the sum of the bodies; for the spaces Aa, Bb, Cc, Gg are described in the same time, and vary as the velocities,

and Gg (or velocity of G) $= \frac{A \times Aa + B \times Bb + C \times Cc}{A + B + C}$.

FIG. CXXV. 418. PROP. *The surface, or solid, described by the line or surface* AB, *moving round an axis passing through* C, *is equal to the surface or solid formed by the multiplication of* AB *into the line described by the center of gravity*, G, *of* AB.

DEM. For if AB be covered with physical points of the same thickness, AD, DE, EF, &c. $AD \times CA + DE \times CD + EF \times CE$, &c. $= \overline{AD + DE + EF}$, &c. or $AB \times CG$ (407), or because the arcs Aa, Dd, Ee, &c. are similar, $AD \times Aa + DE \times Dd + EF \times Ee$, &c. (= the sum of all the superficial, or solid, annuli Ad, De, &c.) $= AB \times Gg$.

FIG. CXXVI. 419. PROP. *The content of the solid generated by the revolution of a plane figure* ABC *round an axis* AC, *is equal to that of the solid whose base is* ABC, *and perpendicular height the periphery of the circle described by the center of gravity*, G.

DEM. For the moment of ABC or $ABC \times GD$, is equal to the sum of the moments of the elementary parts of ABC, or to the sum of all the small rectangles En multiplied into the distance of their center of gravity from AC, or to the sum of all the $y \times mn \times \frac{y}{2}$ or $\frac{y^2}{2} \times mn$; therefore $ABC \times GD$ is equal to the sum of

all

all the $\frac{y^2}{2} \times mn$, and $p \times ABC \times GD$ to the ſum of all the $\frac{py^2}{2} \times mn$; but if p be the periphery of a circle whoſe radius is unity, $p \times GD$ is the periphery of a circle whoſe radius is GD; $\frac{p \times y^2}{2}$ is the area of a circle whoſe radius is y, and the ſum of all the $\frac{py^2}{2} \times mn$, is therefore equal to the ſolid deſcribed by ABC.

420. DEF. *The center of gravity of a line or ſurface, is the center of gravity of equal phyſical points, which are ſuppoſed to compoſe that line or ſurface.*

421. Cor. 1. The center of gravity of a right line is evidently in its biſection, and the center of gravity of a parallelogram, priſm, cylinder, are in the biſection of the diameter or axis, becauſe the number of phyſical lines in a parallelogram, or of phyſical laminæ in the priſm and cylinder, on each ſide of this point, are equal.

422. Cor. 2. The center of gravity of any number of lines AB, CD, EF, &c. is found by joining the centers of gravity m, n, of any two AB, CD, and taking a point p, ſo that $pm : pn :: CD : AB$, and joining p, and q the center of gravity of EF, and taking a point r ſo that $pr : rq :: EF : AB + CD$, &c. (401). The center of gravity of the ſides of a triangle ABC may be found as above, or it may be found by biſecting the ſides in m, n, p, joining the points of biſection, and biſecting the angles mpn, and nmp, by the lines pr and mq, whoſe interſection, G, is the center of gravity; for $pq : qn :: pm : mn :: AC : BC$, or the center of gravity is in qm; and $mr : rn :: mp : pn :: AC : AB$, or this center is in pr, and therefore muſt be in their interſection G.

FIG. CXXVII.

FIG. CXXVIII.

423. PROP.

FIG. CXXIX. 423. PROP. *If a regular polygon* ABCDE *be inſcribed in the ſegment of a circle whoſe center is* F, *half the ſum of its ſides is to the ſine of half the arc* :: *perpendicular let fall from* F *upon a ſide* : *the diſtance of* G *from* F.

DEM. For let m, n, p, q, be reſpectively the centers of gravity of the ſides, and joining $v\,s$, the centers of AB, BC, and CD, DE, it is clear that the center of gravity of all the ſides will be in $v\,s$, and it will be alſo in FC, and conſequently at G the interſection of FC and $v\,s$. But from the ſimilar triangles $s\,F\,q$, EID, ED : EI (:: $ED + DC : EC$) :: $Fq : Fs$, and from the ſimilar triangles $G\,s\,F$, CEH, $CE : HE :: Fs : FG$, and, by adding theſe analogies together, $ED + DC : EH :: Fq : FG$. Q. E. D.

424. Cor. 1. If a regular polygon be inſcribed in a circle, its center of gravity is the center of the circle; for $FG =$ $\frac{\text{ſine of half the periphery} \times Fq}{\frac{1}{2} \text{ the ſum of the ſides}} = \frac{0 \times Fq}{\frac{1}{2} \text{ the ſum of the ſides}}$.

425. Cor. 2. As the arc EC : ſine of that arc :: FE : diſtance of the center of gravity of twice EC from the center F; for, let the ſides of the polygon inſcribed, be diminiſhed without limit, ſo as to coincide with the circular arc and be equal to it, and Fq is then equal to the radius. If the arc be a ſemicircle, the quadrant $CK : FC :: FC : FG$; and the center of gravity of the whole periphery is in F, becauſe $FG = \frac{0 \times FC}{KCL} = 0$.

426. PROP. *The diſtance of the center of gravity of a triangle from any of its angles, is equal to two third parts of the line drawn from that angle to the biſection of the ſide oppoſite to it.*

DEM.

DEM. Let Ap bisect the opposite side BC, and drawing ab, cd, ef, &c. infinitely near and parallel to BC, each will be bisected, and the center of gravity of each, and consequently of all, which make up the triangular surface, will be in Ap; and, for the same reason, it is in Bq bisecting AC, and therefore must be in their intersection G; but, from similar triangles, $AG : Gp :: AB : pq :: BC : pC :: 2 : 1$. Q.E.D. FIG. CXXX.

427. Cor. 1. The center of gravity of any right lined figure is found by dividing it into triangles, and considering them as bodies: let m be the center of gravity of ABC, and n of BDC and joining mn, and taking a point G, so that $mG : nG :: DBC : BAC$, it will be the center of gravity of the trapezium $ABDC$ (401). The process is similar when the figure has more sides. FIG. CXXXI.

428. Cor. 2. The center of gravity of a regular polygon, inscribed in a circle, is the center of that circle; for drawing a right line BH, from any of the angles through the center, the figures on each side are similar and equal, and the center of gravity is in BH; and, for the same reason, it is in DI, and therefore must be at C, and consequently the center of gravity of a circle is its center. FIG. CXXXII.

429. PROP. *The distance of the center of gravity of a regular polygon, inscribed in a sector of a circle* FEAC, *from its center, is equal to two thirds of distance of the center of gravity of the periphery* EDABC. FIG. CXXXIII.

DEM. Find the center of gravity, H, of the periphery (423), and, taking $IE = \frac{1}{3}FE$, describe a polygon similar to $EDABC$. The centers of gravity of the triangles FED, FDA, FAB, FBC, are at L, S, T, V, the bisections of IK, KN, NP, PQ; and the centers of gravity of $FEDA$ and $FABC$, are at R, and X, the bisections of SL, VT, and the center of the whole figure is at G, the bisection of RX; but $FE : EI :: FM : LM$, therefore $LM = \frac{1}{3}FM$, and, for the same reason, $RO = \frac{1}{3}FO$ and $GH = \frac{1}{3}FH$. Q.E.D.

430. Cor. 1. The diſtance of the center of gravity of a ſector of a circle from the center, is therefore equal to two thirds of the diſtance of the center of gravity of the circular arc upon which it ſtands.

431. Cor. 2. As the arc AE : ſine of AE :: radius : diſtance of the center of gravity of twice AE from F, or FH (425); but $FG = \frac{2}{3} \times FH$; therefore AE : ſine of AE (:: $EABC$: its ſubtenſe EC) :: $\frac{2}{3}$ radius : FG.

SCHOLIUM.

432. The diſtance, from the vertex, of the center of gravity of a parabolic ſpace is equal to three fifths, and of a paraboloid to two thirds, of the axis; but theſe, and the moſt difficult propoſitions upon the center of gravity, are beſt inveſtigated by a fluxional proceſs.

FIG. CXXXIV. 433. PROP. *If one or more of the bodies* A, B, C, *&c. move uniformly in the ſame right line, with velocities equal to* a, b, c, *&c. their common center of gravity will move uniformly.*

DEM. Let A and B move uniformly in the ſame, or an oppoſite, direction, P be their center of gravity, and D their diſtance: and becauſe the motions of A and B are uniform, D either continues the ſame, or encreaſes and decreaſes uniformly; but $AP = \frac{D \times B}{A+B}$, and conſequently varies as D, and P moves uniformly. If another body C move uniformly in the ſame right line, and R be the center of gravity of A, B, C; the diſtance CP either continues the ſame, or encreaſes and decreaſes uniformly, becauſe C and P move uniformly; but $PR = \frac{CP \times C}{A+B+C}$, and conſequently varies as CP, or R moves uniformly. Q. E. D.

434. Cor.

434. Cor. 1. The velocity of the center of gravity is equal to $\frac{Aa \pm Bb \pm Cc}{A+B+C}$; for, let p, r, a, b, c, be cotemporary poſitions of P, R, and the bodies, and (407) $A \times Ap$ or $\times \overline{Aa+ap} - B \times Bp$ or $\times \overline{bp \pm Bb} = \overline{A+B} \times Pp$, and $Pp = \frac{A \times Aa \pm B \times Bb}{A+B}$, becauſe $A \times ap - B \times bp = 0$. And, placing $A+B$ in P and repeating the above proceſs, it appears that $Rr =$ the velocity of R (106) $= \frac{A \times Aa \pm B \times Bb \pm C \times Cc}{A+B+C}$. It is from hence again collected, that the velocity of R is uniform; becauſe Aa, Bb, Cc are conſtant, and conſequently their ſum, or difference, multiplied into the ſame given quantities, or the velocity of R, is always the ſame.

435. Cor. 2. Becauſe $\overline{A+B+C} \times Rr = A \times Aa \pm B \times Bb \pm C \times Cc$, the velocity of the center of gravity is ſuch as would be communicated to the ſum of the bodies acted upon by a force equal to $A \times Aa \pm B \times Bb \pm G \times Cc$.

436. *PROP. *If one or more bodies* A, B, C, *&c. move uniformly in right lines, either in the ſame or different planes, their common center of gravity* S *will move uniformly in a right line.* FIG. CXXXV.

DEM.

* This propoſition is proved very neatly, though, perhaps, leſs intelligibly by the following proceſs.

CASE I. Let two bodies move, in the ſame plane, in the directions DE, AB; and let D and A, E and B be cotemporary poſitions, and H, K, the centers of gravity in thoſe poſitions, reſpectively; and taking $BP = AD$, joining EP and drawing DL parallel to HK, $DE : AB$ in the given ratio of the motions of the bodies; and, becauſe the angle EDP is given, all the angles of the triangle EDP are given, and DP is to PE in a given ratio: but $PE : PL :: BE : BK$, which is a given ratio, therefore $DP : PL$ in a given ratio; and, becauſe all the angles of the triangle DPL are given, the angle PDL is given, and L is always in DL. By the nature of the center of gravity, $DA : DH :: EB : EK :: PB$ or $DA : LK$; therefore $DH = LK$, and $DHKL$ is a parallelogram, HK is parallel to DL, and the angle BHK is given, and the center of gravity K is always in the right line HK given in poſition. And, becauſe all the angles of the triangles DPL and DLE are given, the lines DP, DE, FIG. CXXXVI.

DEM. 1. Let B describe Bb uniformly in the time T, and P, Q, be the centers of gravity of A and B; and $A+B : B :: AB : AP :: Ab : AQ :: Bb : PQ$ (EUC. B. 6. P. 5.), and PQ is parallel to Bb, and equal to $\frac{Bb \times B}{A+B}$, and varies therefore as Bb or uniformly. Let A describe Aa uniformly in the time T, either in the same plane with Bb, or not, and R be the center of gravity of A, and B placed at b; and QR, the path of the center of gravity, will appear, by the same process with the above, to be parallel to Aa, and equal to $\frac{Aa \times A}{A+B}$, and consequently it varies as Aa, or encreases uniformly. When both bodies move at the same time, the point P will have two motions PQ and QR, and will consequently describe the diagonal PR uniformly in the time T (185).

2. Let a third body C be added, and the common center of gravity be S, and CS produced will pass through the center of gravity of A and B (411). From the nature of the center of gravity, $A+B+C : A+B :: CP : CS :: CQ : CT :: QP : ST$, and $ST = \frac{}{A+B}$

DL, that is, AB, DE, HK, are in a given ratio, and consequently the point K moves uniformly in HK. The demonstration is the same if one of the bodies moves from B towards A.

CASE II. Let the paths of the bodies AB and DE be in different planes; and through AB draw a plane Bde parallel to DE, and through DE draw the plane $DdeE$ perpendicular to Bde; produce RA to d, and let Dd, Ee, be perpendicular to de, and the planes DdA, EeB, will be perpendicular to the plane edB. Let A and D, B and E be cotemporary positions of the bodies. If the body at D were to move in de, the center of gravity would move uniformly in some line HK (case 1.); through HK erect the plane $HKkb$ perpendicular to HBK. From similar triangles, and the nature of the center of gravity, $Ab : bD :: AH : Hd :: BK : Ke :: Bk : kE$; therefore hk is the path of the center of gravity of the bodies moving in AB, DE. And, because $Dd : Hb :: Ad : AH :: Re : BK :: Ee$ or $Dd : Kk$, $Hb = Kk$ and kb is equal and parallel to HK; therefore the center of gravity of the bodies, moving uniformly in AB, DE, moves uniformly in hk.

CASE III. The common center of gravity of two bodies and a third body, is either at rest, or moves uniformly in a right line; for two may be placed in their common center of gravity, which was proved to move uniformly, and the center of gravity of the three or more bodies is proved, by the same process as before, to move uniformly.

$\frac{\overline{A+B} \times 2P}{A+B+C}$, and varies as $2P$ or uniformly; and for the ſame reaſon TV, the motion of T ariſing from A's motion, is equal to $\frac{2R \times \overline{A+B}}{A+B+C}$, and therefore varies as $2R$ or uniformly (caſe 1.). When A and B move together, the motions ST, TV, will be combined into one, SV; and if C deſcribe Cc uniformly in the time T, the common center of gravity will deſcribe VY, and this new motion, combined with SV, will make it deſcribe SY uniformly in the time T. Q. E. D.

437. Cor. 1. It is evident, that the paths of the center of gravity, ariſing from the motion of any one body, is always parallel to that of the moving body: PQ and ST are parallel to Bb; QR and TV are parallel to Aa and VY to Cc.

438. Cor. 2. The centers of gravity of two, three, &c. bodies will deſcribe polygons or curves ſimilar to that of the moving body to which their motion is owing; and if the velocity of the body be variable, the velocity of each center will be variable according to the ſame law.

439. Cor. 3. The velocity of the center of gravity of two, three, &c. bodies is the ſame as if they were placed in it, and acted upon by forces, equal to the moments of the moving bodies, in their reſpective planes and directions; for $B \times Bb = \overline{A+B} \times PQ$ and $A \times Aa = \overline{A+B} \times QR$; and if $A+B$ were placed at P, and acted upon by forces equal to $B \times Bb$ and $A \times Aa$ in the planes and directions of Bb and Aa, they would deſcribe the diagonal PR (185).

440. PROP. *The common center of gravity of two or more bodies is not affected by any action of the bodies upon each other.*

DEM.

FIG. CXXXVIII.

DEM. Let A and B be two bodies in a ſyſtem, acting upon each other, G their common center of gravity, and Aa, Bb, the velocities loſt by A and gained by B reſpectively in oppoſite directions, and $A \times Aa = B \times Bb$ (3d law of motion), or $A : B :: Bb : Aa :: BG : AG :: bg : aG$, or $A : B ::$ B's diſtance from the center of gravity : A's diſtance from it; and conſequently the ſame point G is ſtill the center of gravity of A and B, or it has been immoveable. What is proved of theſe two, is true of every two bodies, and therefore of all. Q. E. D.

441. Cor. If two parts of a ſyſtem A and B, attract or repel each other, or moving with unequal rectilineal motions, diſturb each others motion by the force of their inertia, the center of gravity will not be affected by their mutual action.

CHAP.

CHAP. X.

COMMUNICATION OF MOTION BY DIRECT IMPACT.

442. DEF. *TWO bodies are said to impinge directly, when the right line, in which their centers of gravity move, passes through the point of contact.*

443. DEF. *The center of gravity of a body, or system of bodies, supposed to be without gravity, is the same point with that center when its influence obtains.*

LEMMA. If two bodies X and Y, consisting of any number of particles without gravity A, B, C, and D, E, &c. be immoveably connected to the right line SR, passing through their centers of gravity G and H, which is perpendicularly impressed at F by a force F, the moments communicated to these bodies are inversely as the distances of their centers of gravity from the point where F acts. FIG. CXXXIX

DEM. The sum of the resistances of D and E to the action of F is $D \times Fd + E \times Fe$ (279) $= \overline{D+E} \times FH$ (407), and consequently if d, e, h, be the respective velocities of D, E, and H, and $D+E=Y$ be placed in H, $D \times d + E \times e = Y \times b$; and for the same reason $A \times a + B \times b + C \times c$, &c. $= X \times g$, supposing a, b, c, g, to be the respective velocities of A, B, C, and of X collected at G. Let a fulcrum be placed at G, and because F is in equilibrio with

with $D \times d + E \times e$ or $\Upsilon \times b$, $F : \Upsilon \times b :: GH : FG$, and if a fulcrum be placed at H, $X \times g : F :: FH : GH$, and ex æquo $X \times g : \Upsilon \times b :: FH : FG$. Q. E. D.

444. Cor. Becauſe $g : b :: FH \times \Upsilon : FG \times X :: D \times Fd + E \times Fe : A \times Fa + B \times Fb + C \times Fc$, the velocities of G and H, and of the points A, B, C, &c. are the ſame, whether the particles be placed in thoſe points, or collected in their centers of gravity G and H; and the effect is evidently the ſame, whether G and H be in the right line SR, or in $P\mathcal{Q}$, making an invariable angle with SR, and at the ſame perpendicular diſtances from F's direction.

445. PROP. *If a material ſurface* SUR, *compoſed of the particles* A, B, C, D, *&c. be impreſſed by a force equal to* F, *acting in the plane of the ſurface at the center of gravity* F, *and perpendicularly to a right line* SFR *paſſing through it, the particles will move with equal velocities in directions parallel to that of* F.

DEM. Let the particles, on one ſide of F's direction, $A + B + C$, &c. $= X$ be placed at their center of gravity G, and $D + E$, &c. on the other ſide at their center of gravity H, and GFH is a right line (411). But $g : b :: \Upsilon \times FH : X \times FG :: 1 : 1$ and $g = b$; and the incipient motions of X and Υ are parallel to F's direction (2d law of motion). Since X and Υ begin to move with equal velocities, in parallel directions, they are relatively at reſt, and conſequently will not diſturb each others motions; and becauſe the relative ſituations of the points A, B, C, &c. are always the ſame, they will move with velocities equal to thoſe of G and H, and in parallel directions. The effects are the ſame whether A, B, C, &c. be in their real places, or collected in their centers of gravity (444); and the initial motions of G and H are not diſturbed by the mutual actions of the particles (441). Q. E. D.

446. Cor.

446. Cor. 1. If any particles *B*, *C*, &c. be not in the ſuperficies *SR*, but on different ſides of it, their center of gravity will be in *q* (411), and their efforts, reſulting from their inertia, to diſturb the incipient motion of the particles, are meaſured by the products of each particle into its perpendicular diſtance from the plane *SR*(279), and theſe being equal and oppoſite, and conſequently deſtroying each other, the particles will continue to move with their initial velocities. If a body therefore be impelled by any power *F*, in a direction paſſing through its center of gravity, its conſtituent particles will move with equal velocities, in directions parallel to that of *F*; and if the particles be equal, and their number *n*, the velocity of each, and of the center of gravity, is the ſame whether that center be impelled by the force *F*, or each particle by a force equal to $\frac{F}{n}$, in the direction of *F*. FIG. CXXXIX.

447. Cor. 2. In the impact of one body *A* upon another body *B*, either moving or quieſcent, when the right line joining their centers of gravity, and the lines in which they move, are in the ſame right line, the forces of impact and reſiſtance produce a change of velocity, in each body, only in this line, or their impact is direct.

448. PROP.* *Let a body* A, *moving with a velocity equal to* a, *impinge directly upon* B, *moving in the ſame, or an oppoſite, direction, with a velocity equal to* b, *to find their common velocity.*

If *A* and *B* be inelaſtic, (3d law of motion) $Aa \pm Bb$ is the ſame before and after impact (where the higher ſign is to be uſed when the bodies move in the ſame direction, and the lower when they move in oppoſite directions,) and, becauſe they move together, if *v* be their common velocity, $Aa \pm Bb = \overline{A+B} \times v$ and $v = \frac{Aa \pm Bb}{A+B}$. Q. E. I.

449. Cor.

* Newt. Cor. 3. ad leges motus. Maclaurin's Newt. Chap. IV. Rohault. Not. Part I. Ch. II. Art. 6. Helſham. Lect. V. and Appendix. Nov. Com. Petropol. Tom. XVII. pag. 315.

449. Cor. 1. The velocity, which A loſes by impact, is equal to the difference between its velocities before and after impact, or to $a - v$; and the velocity which B gains by impact, in the direction of A's motion, is equal to the difference between its velocities after and before impact, or to $v \mp b$. Subſtituting the value of v, $a - v = a - \frac{Aa \mp Bb}{A+B} = \frac{Aa + Ba - Aa \mp Bb}{A+B} = \frac{B \times \overline{a \mp b}}{A+B} = l$, and, reſolving this equation into a proportion, $A + B : B :: a \mp b : l$. The velocity gained by $B = g = v \mp b = \frac{Aa \mp Bb}{A+B} \mp b = \frac{Aa \mp Bb \mp Ab \mp Bb}{A+B} = \frac{A \times \overline{a \mp b}}{A+B}$, and $A + B : A :: a \mp b : g$. From hence we have the following rules.

1.* The ſum of the bodies is to the ſtruck body as the difference or ſum (according as they move in the ſame, or an oppoſite, direction) of the velocities, before impact, to the velocity loſt by the ſtriking body.

2. The ſum of the bodies is to the ſtriking body as the difference or ſum of the velocities, before impact, to the velocity gained by the ſtruck body.

450. Cor. 2. If A and B move in oppoſite directions with velocities that are always inverſely as the bodies, their common center of gravity will not be affected by their motion; but, l and g, repreſenting the velocities loſt by A and gained by B, are made in oppoſite

* Theſe rules are inveſtigated differently by the following proceſs:

1. $A \times l = B \times g$ (3d law of motion) and $g = \frac{A \times l}{B}$; but $a - l$ (A's velocity after impact) $= g \pm b$ (B's velocity after impact) $= \frac{A \times l}{B} \pm b$ and $B \times a - B \times l = A \times l \pm B \times b$ and $l \times \overline{A+B} = B \times \overline{a \mp b}$, and $\overline{A+B} : B :: \overline{a \mp b} : l$.

2. $l = \frac{B \times g}{A}$ and $a - l = a - \frac{B \times g}{A} = g \pm b$, (becauſe the bodies move on together) and $Aa - B \times g = Ag \pm A \times b$ and $\overline{A+B} \times g = A \times \overline{a \mp b}$, and $A + B : A :: a \mp b : g$.

oppoſite directions, and $A \times l = B \times g$ or $A : B :: g : l$, or g and l are inverſely as the bodies, and conſequently the velocity of the center of gravity of A and B is not affected by impact, and is, therefore, both before and after impact, equal to their common velocity, v.

451. PROP. *If* A, *moving with a velocity equal to* a, *impinge upon* B, *moving in the ſame, or an oppoſite, direction with a velocity equal to* b, *and* A *and* B *be perfectly elaſtic, or one of them be perfectly hard, and the other perfectly elaſtic, to find the velocity loſt by* A (L), *and that gained by* B (G).

When A and B are inelaſtic, $A + B : B :: a \mp b : l$, and $A + B : A :: a \mp b : g$; but $L = 2l$, and $G = 2g$ (257); therefore $A + B : 2B :: a \mp b : L$, and $A + B : 2A :: a \mp b : G$; and we have theſe rules.

1. The ſum of the bodies is to twice the ſtruck body as the difference or ſum of the velocities, before impact, to the velocity loſt by the ſtriking body.

2. The ſum of the bodies is to twice the ſtriking body as the difference or ſum of the velocities, before impact, to the velocity gained by the ſtruck body. Q. E. I.

452. Cor. 1. $L : G :: 2l : 2g :: B : A$ and $A \times L = B \times G$; therefore in all perfectly elaſtic bodies $L = \frac{B \times G}{A}$ and $G = \frac{A \times L}{B}$.

453. Cor. 2. A's velocity after impact is equal to the difference between its velocity before impact and the velocity loſt, or to $a - \frac{2B \times \overline{a \mp b}}{A + B} = \frac{Aa + Ba - 2Ba \pm 2Bb}{A + B} = \frac{\overline{A - B} \times a \pm 2Bb}{A + B}$; B's velocity after impact is equal to the ſum of its velocity before,

and the velocity gained, or to $\pm b + \frac{2A \times a \mp b}{A+B} = \frac{2Aa \pm Bb \mp Ab}{A+B}$.

If $A = B$, $\frac{A-B \times a \pm 2Bb}{A+B} = \pm b$, and $\frac{2Aa \pm Bb \mp Ab}{A+B} = a$, or the bodies move with interchanged velocities.

454. Cor. 3. If A be greater or leſs than B, L is leſs or greater than $a \mp b$, and G greater or leſs than $a \mp b$. If A be to B, as m to n, $L = \overline{a \mp b} \times \frac{2n}{m+n}$, and $G = \overline{a \mp b} \times \frac{2m}{m+n}$.

455. Cor. 4. If there be any number of bodies A, B, C, D, &c. in geometric progreſſion, encreaſing or decreaſing, and A, moving with a velocity equal to a, communicate motion to B at reſt, and B, moving with the velocity gained, communicate motion to C at reſt, &c. the velocities communicated to B, C, D, &c. will be in geometric progreſſion, decreaſing or encreaſing. For (451)

$A+B : 2A :: a :$ velocity of B

$B+C : 2B ::$ vel. of B : vel. of C

$C+D : 2C ::$ vel. of C : vel. of D

$D+E : 2D ::$ vel. of D : vel. of E. And, becauſe A, B, C, &c. are in geometric progreſſion, $A+B : 2A :: B+C : 2B :: C+D : 2C :: D+E : 2D$; and conſequently a : vel. of B :: vel of B : vel of C :: vel of C : vel. of D, &c. And if the bodies encreaſe or decreaſe in magnitude, a is greater or leſs than the velocity of B, or the velocities communicated decreaſe or encreaſe.

456. Cor. 5. If the number of bodies in geometric progreſſion be equal to n, a : velocity of the laſt body $:: \overline{A+B}^{n-1} : \overline{2A}^{n-1}$; for a : vel. of the laſt body in a ratio compounded of the ratios of a : vel. of B, vel. of B : vel. of C, vel. of C : vel. of D, &c. each of which is equal to the ratio of $A+B : 2A$, and the number of ratios is equal to $n-1$. The velocity of A, or a, is alſo to the velocity of the laſt body $:: \overline{A+B} \times \overline{B+C} \times \overline{C+D}$, &c. $: A \times B \times C$, &c. (the product of all except the laſt) $\times 2^{n-1}$.

457. Cor.

457. Cor. 6. The velocities loſt by A, B, C, &c. are in geometric progreſſion encreaſing or decreaſing, according as the bodies decreaſe or encreaſe; for,

$A+B : 2B ::$ a : vel. loſt by A

$B+C : 2C ::$ vel. of B : vel. loſt by B

$C+D : 2D ::$ vel. of C : vel. loſt by C, &c.

But A, B, C, &c. being in geometric progreſſion, $A+B : 2B :: B+C : 2C :: C+D : 2D$, &c. and conſequently a : vel. loſt by A :: vel. of B : vel. loſt by B :: vel. of C : loſt by C, &c.; therefore the ratios of the velocities loſt and gained are the ſame, and the laſt being in geometric progreſſion (456), the firſt are ſo too.

458. PROP. *If there be three perfectly elaſtic bodies,* A, X, Q, *and* A, *moving with a velocity equal to* a, *impinge upon* X *at reſt, and* X *impinge upon* Q *at reſt,* Q's *velocity is the greateſt poſſible when* X *is a mean proportional between* A *and* Q.

DEM. Let q be the velocity of $\mathcal{Q}$, and $a : q :: \overline{A+X} \times \overline{X+\mathcal{Q}}$ $4AX$ (456) $:: A+X+\Upsilon+\mathcal{Q} : 4A$ (ſuppoſing A to be to X as Υ to $\mathcal{Q}$, and conſequently $A+X : X :: \Upsilon+\mathcal{Q} : \mathcal{Q}$, and for $\overline{A+X} \times \mathcal{Q}$, ſubſtituting its equal $\overline{\Upsilon+\mathcal{Q}} \times X$); and $q = \frac{4Aa}{A+X+\Upsilon+\mathcal{Q}}$, and, $4Aa$ being given, q varies $\frac{1}{A+X+\Upsilon+\mathcal{Q}}$, and is greateſt when their ſum is leaſt, or when $X = \Upsilon$; for $A \times \mathcal{Q}$ being given, $X \times \Upsilon$ is given, and the ſum of two factors containing a given product is leaſt * when they are equal. Q. E. D.

459. Cor. 1. The velocity, communicated to $\mathcal{Q}$, will be encreaſed, by encreaſing the number of bodies in geometric progreſſion, between it and A, and arrive at its limit when that number

* Let the given product be repreſented by the given rectangle AB, contained by two unequal lines AL, LB. Make the ſquare LE equal to the rectangle AB and $AL + LB = AD = 2CM$ is always greater than $2LM$ or $LM + LF$. FIG. CXL.

number is infinitely great, and then $a : q :: \sqrt{2} : \sqrt{A}$. Let the ſucceſſive differences of the bodies be x, y, z, &c. or $B = A + x$, $C = B + y$, $D = C + z$, &c. and let their reſpective velocities be a, b, c, c, d, &c.; becauſe $A + B : 2A :: a : b$ and $B = A + x$, by ſubſtitution, $A + A + x : 2A$ or $A + \frac{x}{2} : A :: a : b :: \sqrt{B} : \sqrt{A}$ (31); $B + C : 2B$ or $2B + y : 2B$ or $B + \frac{y}{2} : B :: b : c :: \sqrt{C} : \sqrt{B}$; and, for the ſame reaſon, $C + \frac{z}{2} : C :: c : d :: \sqrt{D} : \sqrt{C}$, &c. but $a : d$ in a ratio compounded of the ratios of $a : b$, $b : c$, $c : d$, &c. or their equals $\sqrt{B} : \sqrt{A}$, $\sqrt{C} : \sqrt{B}$, $\sqrt{D} : \sqrt{C}$, &c. or of the ſquare root of the laſt body to the ſquare root of the firſt (41); and conſequently $a : q :: \sqrt{2} : \sqrt{A}$.

460. Cor. 2. Becauſe $A \times L = B \times G$, $A : B :: G : L$; but G and L are made in oppoſite directions, and are to each other as the ſpaces deſcribed by the bodies in the ſame time, and being inverſely as the diſtances from the center of gravity, this center will evidently not be affected by impact, but will continue to move with a velocity equal to v, their common velocity after impact when inelaſtic. This alſo appears from article 440.

461. PROP. *If two perfectly elaſtic bodies* A *and* B *impinge directly, the ſums of the products, reſulting from multiplying each body into the ſquare of its velocity, is the ſame before and after impact.*

DEM. Retaining the ſame notation, $a - v = l$, and $2a - 2v = L$, and $2v \mp 2b = G$; and conſequently A's velocity after impact is equal to $a - 2a + 2v = 2v - a$, and B's velocity $= \pm b + G = 2v \mp b$; but $A \times \overline{2v - a}^2 + B \times \overline{2v \mp b}^2 = A \times 4v \times \overline{v - a} + a^2 + B \times 4v \times \overline{v \mp b} + b^2 = A \times a^2 + B \times b^2$, becauſe $A \times a + B \times \pm b = \overline{A + B} \times v$, and conſequently $A \times \overline{v - a} + B \times$

$B \times \overline{v \mp b} = 0$, or, multiplying this equation by $4v$, $A \times 4v \times \overline{v - a} + B\,4v \times \overline{v \mp b} = 0$*. Q. E. D.

462. Cor. 1. Whatever therefore be the number of elaſtic bodies A, B, C, &c. which impinge ſucceſſively, beginning with A, the ſums of the products, reſulting from the multiplication of each body into the ſquare of its velocity, are the ſame before and after impact.

463. Cor. 2. The relative velocities of A and B are the ſame before and after impact; for, before impact, the relative velocity is equal to the velocity of A diminiſhed or encreaſed by that of B, according as they move in the ſame, or an oppoſite, direction, or equal to $a \mp b$; and, after impact, it is equal to B's velocity diminiſhed or encreaſed by that of A, or equal to $2v \mp b - 2v + a = a \mp b$, the ſame as before impact.

464. Cor. 3. In this propoſition the force of elaſticity is equal to that of compreſſion, and this obtains very nearly in ſome kinds of bodies, as glaſs, ivory, tempered ſteel, &c. and, in theſe, the conſervatio vis vivæ is preſerved, or the products of the bodies into the

* This propoſition may be proved a little differently by the following proceſs: let p and q be equal to the velocities of A and B reſpectively, after impact, and $A \times a \pm B \times b = B \times q \pm Ap$ (3d law of motion) and $Aa \mp Ap = Bq \mp Bb$. But the relative velocities of A and B are the ſame before and after impact, or $a \mp b = q \mp p$, and $a \pm p = q \pm b$, and, multiplying $Aa \mp Ap$ into $a \pm p$, and $Bq \mp Bb$ into $q \pm b$, the reſults are

$$A \times a^2 \mp Apa$$
$$\pm Apa - Ap^2 = B \times q^2 \mp Bqb$$
$$\pm Bqb - Bb^2, \text{ or}$$
$$A \times a^2 + B \times b^2 = B \times q^2 + A \times p^2.$$

EXAMP. Let the ratios of $A : B$, and $a : b$, be reſpectively as $1 : 9$, and $6 : 1$, and, before impact, $A \times a^2 + B \times b^2 = 1 \times 36 + 9 \times 1 = 45$, and, after impact, $A \times p^2 = A \times \overline{a - \frac{2B \times a - b}{A + B}}^2$, and $B \times q^2 = B \times \overline{b + \frac{2A \times a - b}{A + B}}^2$; the firſt $= \overline{6 - \frac{18 \times 5}{10}}^2 = \overline{\frac{60 - 90}{10}}^2 = \overline{-3}^2$ or 9, and the ſecond $= 9 \times \overline{1 + \frac{2 \times 5}{10}}^2 = 9 \times 4 = 36$, and $A \times p^2 + B \times q^2 = 45$.

the ſquare of their velocities, are the ſame before and after impact. But in all bodies, endued with imperfect degrees of elaſticity, the equality of theſe products is not preſerved.

465. PROP. *When either* A *or* B *is perfectly hard, and the other imperfectly elaſtic, or when they both are imperfectly elaſtic, and the whole force of reſtitution is to that of compreſſion, as any number* n : 1, *to find the velocities of* A *and* B *after impact.*

DEM. When A and B are inelaſtic, let the velocities loſt by A and gained by B, reſpectively, by the force of impact, be l and g; and $1 : n :: l : nl =$ the velocity which A loſes by the force of reſtitution, and $nl + l = A$'s whole loſs of velocity. Let $m = n + 1$ and $a - ml = A$'s velocity after impact, $= \left(\text{becauſe } l = \frac{B \times g}{A}\right)$ $\frac{Aa - mgB}{A}$. B's velocity after impact $= \mp b + g + ng = \mp b + mg$. Q. E. I.

466. Cor. 1. Becauſe $l = \frac{B \times \overline{a \mp b}}{A + B}$, $\overline{n + 1} \times l$, or A's whole loſs of velocity, $= \overline{n + 1} \times \frac{B \times \overline{a \mp b}}{A + B}$, and conſequently $A + B : \overline{n + 1} \times B :: a \mp b$: velocity loſt by A. And becauſe $\overline{n + 1} \times g$, or B's whole gain of velocity, $= \overline{n + 1} \times \frac{A \times \overline{a \mp b}}{A + B}$, $A + B : \overline{n + 1} \times A :: a \mp b$: velocity gained by B.

467. Cor. 2. It is proved in the ſame manner, as when the bodies were perfectly elaſtic, that the velocities loſt and gained, by a ſeries of imperfectly elaſtic bodies in geometric progreſſion, which are all at reſt, except the firſt, are in geometric progreſſion; for let the

the velocities of A, B, C, D, &c. be a, b, c, &c. and

$$A+B : \overline{n+1} \times A :: a : b$$
$$B+C : \overline{n+1} \times B :: b : c$$
$$C+D : \overline{n+1} \times C :: c : d,$$

and becauſe $A : B :: B : C :: C : D$, &c.

$A+B : \overline{n+1} \times A :: B+C : \overline{n+1} \times B :: C+D : \overline{n+1} \times C$, &c.;

or $a : b :: b : c :: c : d$, &c.

468. Cor. 3. If elaſticity be equal to the reſiſtance made to compreſſion, $n = 1$, and, ſubſtituting p and q for the velocities of A and B after impact, $p = a - \frac{mBg}{A}$, and $q = mg \mp b$. Let elaſticity be $\frac{1}{2}, \frac{1}{3}, \frac{1}{4}$, &c. of the reſiſtance, or $n = \frac{1}{2}, \frac{1}{3}, \frac{1}{4}$, &c.; and $p = a - \frac{\frac{3}{2}Bg}{A}$, $a - \frac{\frac{4}{3}Bg}{A}$, $a - \frac{\frac{5}{4}Bg}{A}$, &c. and $q = \frac{3}{2}g \mp b$, $\frac{4}{3}g \mp b$, $\frac{5}{4}g \mp b$, &c.: if therefore A, B, g and n be given, the ratio of the relative velocities, or of $a \mp b : q \mp p$ may be found; and $v : v$, if the ratio of the relative velocities, and A, B, a, g be known, the degree of elaſticity, or n, may be found: for $p = a - \frac{mBg}{A}$ and $q = \mp b + mg$, and the ratio of $q - p \left(\mp b - a + g + \frac{\overline{Bg}}{A} \times m\right) : a - b$ is a given ratio, and conſequently $m(n+1)$ is known.

469. Cor. 4. The converſe of prop. (461) is true, and if the products of A and B into the ſquares of their velocities, be the ſame before and after impact, the force of reſtitution is equal to that of compreſſion; and generally if the products of A and B into that power of the velocity, whoſe exponent is any number r, be ſuppoſed equal before and after impact, the relation between the forces of elaſticity and reſiſtance may be found: for $a - \frac{mBg}{A} = p$ and $\mp b + mg = q$, and by ſolving the equation $A \times a^r +$

$B \times b^r = A \times a - \overline{\frac{mBg}{A}}^r + B \times \pm \overline{b + mg}^r$, m, and consequently n may be found.

FIG. CXLI. 470. LEMMA. *If two ſperical bodies* A *and* B *move from* A *and* B *at the ſame time, with velocities which are to each other as* a : b, *or* AC : BD, *to find a plane that ſhall touch both bodies at the point of impact.*

Join AB, and deſcribe the parallogram AH, whoſe ſides are AC and AB; join DH, and from C, as a center, deſcribe a circular arc, with a radius equal to the ſemidiaters of the bodies, cutting DH in L; draw LE parallel to AC, and EF parallel to the line joining C and L, and the bodies will at the ſame time be in E and F, and a plane perpendicular to EF will touch both bodies at the point of impact; for $DE : EL$ or $FC :: DB : BH$ or AC, and

$DB : DB \pm DE$ or $BE :: AC : AC \pm FC$ or AF,

and $DB : AC :: BE : AF :: b : a$, and BE, AF are therefore deſcribed in the ſame time by B and A, and becauſe $EF = CL =$ the ſum of the ſemidiameters of the bodies, they will be in contact at P, with a plane perpendicular to EF. Q. E. I.

FIG. CXLII. 471. LEMMA. *If two ſperical bodies* A *and* B *inpinge obliquely, to determine the velocities loſt by* A *and gained by* B, *and the velocity of each after impact.*

Caſe 1. Suppoſe A and B to be inelaſtic, and to meet in D, and Ll to be a plane in contact with both the bodies, and the velocities to be FD and GD. Reſolve each velocity into two, FL, and GM, perpendicular to the plane, and DL, DM, parallel to it: DL and DM are not affected by impact, and FL, GM, are directly oppoſite to each other. Taking therefore $DH = \frac{A \times FL - B \times GM}{A + B}$ (448),

(448), and Dm, Dl respectively equal to DM, DL, A and B will describe the lines DQ, DR respectively.

Case 2. If A and B be either perfectly or imperfectly elastic, they will be reflected, and the velocities DE, DH be equal respectively to $FL - \frac{2B \times \overline{FL+GM}}{A+B}$ and $-GM + \frac{2A \times \overline{FL+GM}}{A+B}$ (453): taking therefore $Dm = DM$ and $Dl = DL$, A will be reflected along DK, and B along DP; for the velocities DM, DL remain after impact, and these, compounded with DH and DE respectively, will make A and B describe the diagonals of parallelograms, whose sides are DE, Dl, and DH, Dm. Q. E. I. FIG. CXLIII.

472. *LEMMA. *To find the spontaneous center of conversion of the particles* P *and* Q, *without gravity, or a point about which the right line* SR, *adhering to those particles, begins to revolve, when impressed perpendicularly by a force* F, *acting at a point* F *which is not the center of gravity* G. FIG. CXLIV.

Let pqS be a new position of SR, infinitely near to the former, and the point S is evidently stationary whilst P and Q describe the small spaces Pp and Qq: but $Q \times FQ : P \times FP :: Pp : Qq$ (443) $:: SP$ or $SF + FP : SQ$ or $SF - FQ$, and $Q \times FQ \times SF - Q \times FQ^2 = P \times FP^2 + P \times FP \times SF$, and $SF = \frac{P \times FP^2 + Q \times FQ^2}{Q \times FQ - P \times FP} = \frac{P \times FP^2 + Q \times FQ^2}{P + Q \times FG}$. Q. E. I.

473. Cor. 1. Whilst F acts at the same point, the point S is always the same whatever be the magnitude of F, because $\frac{P \times FP^2 + Q \times FQ^2}{P + Q \times FG}$ is a given quantity.

474. Cor.

* Philos. Trans. for 1780, pag. 550, where this subject is treated with great perspicuity by Mr. Vince.

474. Cor. 2. To whatever point of QP the ſame force F be applied, the incipient motions of Q and P or $Q \times Qq + P \times Pp$, are invariably the ſame (2d law of motion); and conſequently the velocity of the center of gravity, or Gg, is always the ſame as if both particles were placed at G and acted upon by the ſame force F; for $Gg = \frac{P \times Pp + Q \times Qq}{P + Q}$ (406).

FIG. CXLV. 475. Cor. 3. If SUR be a material ſurface compoſed of the particles A, B, C, &c. and a force F act in the line PF placed in the ſurface, and perpendicular to a line SG drawn through the center of gravity G, each particle will receive an impulſe in a direction parallel to PF (2d law of motion); and becauſe G is not affected by the action of the particles upon each other, it will move in a right line (440), and the center of ſpontaneous converſion will be in ſome point of the line SG perpendicular to PF. Let S be that center, and the whole plane will begin to revolve about S; but if a force Q equal to F were to act in an oppoſite direction, all motion would evidently be deſtroyed, and conſequently the combined force of every particle in the ſurface (revolving round S, which reſults from the action of F), to make it revolve about F and deſtroy the action of Q would be equal to nothing. But the force of any particle $A = A \times SA$ multiplied into the perpendicular diſtance of its direction from $F = A \times SA \times Fm$, or, becauſe (letting fall Sa perpendicular to SF) $Fm : Fn :: Sa : SA$, and $Fm = \frac{Fn \times Sa}{SA}$ and $A \times SA \times Fm = A \times Fn \times Sa = A \times Sa \times SF - Sn$ $= A \times Sa \times SF - A \times SA^2$: and by a ſimilar proceſs $B \times Sb \times SF - B \times SB^2 =$ B's force: conſequently $SF = \frac{A \times SA^2 + B \times SB^2 \&c.}{A \times Sa + B \times Sb \&c.}$ $= \frac{A \times SA^2 + B \times SB^2 \&c.}{A + B \&c. \times SG}$. If S be the center of ſuſpenſion, F will therefore be the center of oſcillation (art. 512).

476. Cor.

476. Cor. 4. If $p\,q\,S$ be the next position of SR, and $x\,z$ be drawn parallel to it, P has been progreſſive through $x\,p$, and Q regreſſive through $z\,q$, ſubtending an angle at g equal to that at S. The initial motion of the center of gravity is not affected by the unequal motions of P and Q, becauſe their actions upon it, or $P \times p\,g$ and $Q \times q\,g$ are equal and oppoſite, and the motion of G is conſequently rectilineal and uniform (1ſt law of motion); and becauſe the incipient angular motions of P and Q about g continue to be uniform, it is evident that when the angle $G\,S\,g$ would become equal to four right angles, or P and Q have made one revolution round g, $G\,g$, the line deſcribed by the center of gravity, would be equal to the periphery of a circle whoſe radius is $S\,G$. FIG. CXLIV.

477. PROP. *Let a body* B, *be impelled by a force* F, *acting in the direction* F D *not paſſing through its center of gravity* G, *to define its motion.* FIG. CXLVI.

Through G draw a right line SR perpendicular to FD produced, and, if S be the ſpontaneous center of converſion of the plane ſurface SUR, every particle will receive an impulſe, and begin to move in a direction parallel to this ſurface (2d law of motion), and conſequently to revolve round an axis paſſing through S perpendicular to it. And if the parts of every ſection of the body, perpendicular to DF, on each ſide of the plane SUR, be ſimilar and ſimilarly ſituated, the plane of converſion SUR will not be affected by either the progreſſive or rotatory motion of the particles: for their effects upon SUR, ariſing from their progreſſive motion, are as the ſums of the products reſulting from the multiplication of each particle into its diſtance from this plane, which are equal and oppoſite; and if p and q be two equal particles, ſimilarly ſituated in any plane perpendicular to DF, their effects, ariſing from their rotation, being meaſured by the product of each particle into the diſtance from the axis, will be in that plane, and equal and oppoſite to each other. Conſequently the incipient plane of rotation remains unaltered, and if a right line be drawn through G, perpendicular to the plane SUR, every particle

ticle will move round this line as an axis, whilſt G moves uniformly in a right line.

478. Cor. 1. In a body, B, revolving by the action of a force impelling it in a direction not paſſing through the center of gravity, the diſtance of the ſpontaneous center of converſion from the interſection of F's direction with a right line paſſing through the center of gravity, that is, SD is equal to the ſum of the particles multiplied into the ſquare of the diſtance of each, divided by B multiplied into SG.

FIG. CXLV. 479. Cor. 2. $A \times SA^2 = A \times \overline{SG^2 + GA^2 + 2SG \times Ga}$ (Euc. B. 2. P. 12).

$$B \times SB^2 = B \times \overline{SG^2 + GB^2 + 2SG \times Gb}$$
$$C \times SC^2 = C \times \overline{SG^2 + GC^2 + 2SG \times Gc}$$
$$D \times SD^2 = D \times \overline{SG^2 + GD^2 - 2SG \times Gd}, \text{ \&c.}$$

and, becauſe $A \times 2SG \times Ga + B \times 2SG \times Gb + C \times 2SG \times Gc - D \times 2SG \times GD$, &c. $= 0$, $A \times SA^2 + B \times SB^2 + C \times SC^2 + D \times SD^2 = A \times \overline{SG^2 \times GA^2} + B \times \overline{SG^2 + GB^2} + C \times \overline{SG^2 + GC^2}$, &c.;

therefore $SF = SG + GF = \dfrac{A \times \overline{SG^2 + GA^2} + B \times \overline{SG^2 + GB^2}}{A + B + C, \text{ \&c.} \times SG}$, &c.

&c.; and $FG = \dfrac{A \times GA^2 + B \times GB^2 + C \times GC^2}{A + B + C, \text{ \&c.} \times SG}$, &c., $SG \times GF$ is equal to a given quantity, or SG and GF vary inverſely as each other.

FIG. CXLVI. 480. Cor. 3. Becauſe the velocity of G is the ſame as if the particles were concentrated in G, and acted upon by the force F, the time of deſcribing the angle GSg or qgz is the ſame to whatever point F be applied: but, Gg being given, the angle GSg varies inverſely as SG, or directly as GF (laſt cor.). If different forces act at the ſame point, Gg, or the angle of rotation, will evidently be as the magnitude of the force; and, conſequently, the angular velocity will vary generally as $F \times GF$, or as the magnitude of the force multiplied into the perpendicular diſtance of the center of gravity from its direction.

481. PROP.

481. PROP. *Let a body, whoſe quantity of matter is* Q, *moving with a velocity equal to* V, *impinge upon the body* B, *in the direction* FC *paſſing through the center of gravity of* Q, *to find the velocity of the center of gravity,* G, *of the body* B. FIG. CXLVI

Let g be the velocity of G, and S the ſpontaneous center of converſion of B; and $SG : SD :: g$: velocity of D, which is therefore equal to $\frac{SD \times g}{SG}$. $V - \frac{SD \times g}{SG}$ is therefore equal to the velocity loſt by Q in the direction FC, and (3d law of motiou) $Q \times V - \frac{SD \times g}{SG} = B \times g$, and $\frac{Q \times V \times SG - SD \times g}{SG} = B \times g$, and $g = \frac{Q \times V \times SG}{B \times SG + Q \times SD}$. Q. E. I.

482. Cor. 1. If the bodies be perfectly elaſtic, the velocity of G, after impact, is equal to $\frac{2Q \times V \times SG}{B \times SG + Q \times SD}$.

483. Cor. 2. Becauſe the velocity of Q, after impact, is equal to that of D, or to $\frac{SD \times g}{SG}$, or, ſubſtituting the velocity of g, equal to $\frac{Q \times V \times SD}{B \times SG + Q \times SD}$; $V - \frac{Q \times V \times SD}{B \times SG + Q \times SD}$ is Q's loſs of velocity, when the bodies are inelaſtic, which is equal to $\frac{B \times V \times SG}{B \times SG + Q \times SD}$ = Q's loſs of velocity, and conſequently Q's velocity after impact, when the bodies are perfectly elaſtic, is equal to $V - \frac{2B \times V \times SG}{B \times SG + Q \times SD} = \frac{V \times Q \times SD - B \times SG}{B \times SG + Q \times SD}$.

484. Cor.

484. Cor. 3. If FC paſs through the center of gravity G, of the body B, or the impact become direct, $SG = SD$, and G's velocity $= \frac{2\mathcal{Q} \times V \times SG}{B \times SG + \mathcal{Q} \times SG} = \frac{2\mathcal{Q} \times V}{B + \mathcal{Q}}$. $\mathcal{Q}$'s velocity $= \frac{V \times \overline{\mathcal{Q} \times SD - B \times SD}}{B \times SG + \mathcal{Q} \times SD}$ $= V \times \frac{\overline{\mathcal{Q} - B}}{B + \mathcal{Q}}$; and rules are deduced from theſe expreſſions, which are the ſame as in direct impact before inveſtigated.

485. Cor. 4. Becauſe $\mathcal{Q} \times V = \overline{\mathcal{Q} + B} \times g$ (3d law of motion) $g = \frac{\mathcal{Q} \times V}{\overline{\mathcal{Q} + B}}$, or the progreſſive motion of B is the ſame upon whatever point of B the body $\mathcal{Q}$ impinges.

486. Cor. 5. If Υ be the magnitude of a body placed at D, which receives the ſame velocity from the impact of $\mathcal{Q}$, that was communicated to the point D, and, conſequently, the velocity of Υ, after impact, will be equal to $\frac{\mathcal{Q} \times V}{\mathcal{Q} + \Upsilon} = \frac{\mathcal{Q} \times V \times SD}{B \times SG + \mathcal{Q} \times SD}$, and $\Upsilon = \frac{B \times SG}{SD}$. Hence if the direction does not paſs through the center of gravity of $\mathcal{Q}$, find the diſtance of the ſpontaneous center of converſion of $\mathcal{Q}$, s, and its center of gravity I, and a body whoſe magnitude is equal to $\mathcal{Q} \times \frac{sI}{sd}$ impinging directly, would have the ſame effect upon B, whoſe velocity conſequently may be eſtimated as above.

CHAP.

CHAP. XI.

*CENTERS OF PERCUSSION, GYRATION AND OSCILLATION.

487. DEF. *THE center of percuſſion of a body, or ſyſtem of bodies, is a point, which being ſtopped by an immoveable obſtacle, the body or ſyſtem is perfectly quieſcent.*

If *A*, *B*, *C*, &c. be particles of a body, or bodies, whoſe centers of gravity are the points *A*, *B*, *C*, &c. connected by inflexible lines, and moving with equal velocities, in directions parallel to any right line *DN*, an immoveable obſtacle oppoſed to the center of gravity *G* in the direction *ND* will deſtroy all motion. For, when *G* is ſtopped, each particle will endeavour, by its inertia, to proceed in the line in which it was moving, with a moment equal to the product of its quantity of matter and velocity; and, if any plane be drawn through *DGN*, the effort of each particle to communicate motion to it varies as its moment multiplied into its perpendicular diſtance (279). But, the velocities of *A*, *B*, *C*, &c. being equal, the ſums of theſe efforts to move the plane, on each ſide of it, are equal (409), and being oppoſite they conſequently deſtroy each other, and *A*, *B*, *C*, &c. are perfectly quieſcent. If different bodies, or particles of the ſame body *A*, *B*, *C*, &c., whoſe relative ſituation is unchangeable, revolve about an axis paſſing through any point *S*, and a plane be drawn through their center of gravity *G* perpendicular to the axis, each particle will deſcribe a plane parallel to this plane, their angular velocities will be equal, and their lineal velocities will be as their perpendicular diſtances from the axis of ſuſpenſion.

FIG. CXLVII.

FIG. CXLVIII.

* Simpſon's Fluxions, pag. 210. Lyons's Fluxions, pag. 244. Emerſon's Mechanics, Sect. VI.

ſion. And if, as before, a plane be drawn through G, parallel to the axis, the ſums of the moments of A, B, C, &c. multiplied into their perpendicular diſtances, on each ſide of this plane, are not equal, becauſe the velocities are not equal; and conſequently if G be ſtopped, A, B, C, &c. will not be quieſcent. But the lateral efforts to move the plane paſſing through SG perpendicularly to the axis, being ſuppoſed equal, it is evident that the center of percuſſion will be in SG.

FIG. CXLVIII.

488. PROP. *Let* A, B, C, *&c. be particles of a body, revolving about an axis paſſing through the point* S, *it is required to find the center of percuſſion.*

Let A, B, C, &c. be the places of the particles reduced to the plane paſſing through SG, perpendicular to the axis, by letting fall perpendiculars from them upon it; and let A's moment or $A \times SA$, becauſe its velocity is as SA, be repreſented in quantity and direction by Ap perpendicular to SA, and reſolved into two forces Aq perpendicular, and pq parallel to SG. The whole moment of A: its force perpendicular to $SG :: Ap (A \times SA) : Aq :: SA : Sa$ (ſim. triangles), and $Aq = \frac{A \times SA \times Sa}{SA} = A \times Sa$; and, ſuppoſing P to be the center of percuſſion, the efficacy of A to communicate motion to P is equal to its perpendicular moment multiplied into the diſtance at which it acts $= A \times Sa \times Pm = A \times Sa \times \overline{SP - Sm} = A \times Sa \times SP - \frac{SA^2}{Sa} = A \times Sa \times SP - A \times SA^2$. By a ſimilar proceſs it appears, that the efficacy of B, C, &c. to communicate motion to P, is $B \times Sb \times SP - B \times SB^2$, $C \times SC^2 - C \times Sc \times SP$, &c.; and, becauſe P is quieſcent, theſe forces are equal on each ſide of it, or $A \times Sa \times SP - A \times SA^2 + B \times Sb \times SP - B \times SB^2 = C \times SC^2 - C \times Sc \times SP$, and conſequently $SP = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2}{A \times Sa + B \times Sb + C \times Sc}$, &c. Q. E. I.

489. Cor.

489. Cor. 1. Becauſe $A \times Sa + B \times Sb + C \times Sc$, &c. $= \overline{A+B+C}$, &c. $\times SG$ (410), $SP = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2}{\overline{A+B+C}, \text{ &c.} \times SG}$, &c.

490. Cor. 2. The diſtance of the center of percuſſion from the center of gravity, or GP, is equal to $\frac{A \times GA^2 + B \times GB^2 + C \times GC^2}{\overline{A+B+C}, \text{ &c.} \times SG}$, &c. (479).

491. Cor. 3. In the ſame body, or ſyſtem of bodies, A, B, C, &c. $\overline{A+B+C}$, &c. $\times SG \times GP = A \times GA^2 + B \times GB^2 + C \times GC^2$, &c. $SG \times GP$ is alſo a given quantity, wherever the point of ſuſpenſion be placed, becauſe $\frac{A \times GA^2 + B \times GB^2}{\overline{A+B}, \text{ &c.}}$, &c. is given; and if SG be infinitely great, or the velocities of A, B, C, &c. be equal to each other, GP is evaneſcent.

492. Cor. 4. If a circle be deſcribed from G as a center, with a radius equal to SG, and, the plane of motion remaining as before, the points of ſuſpenſion be in different points of the periphery of this circle, the diſtance between the centers of gravity and percuſſion will be invariable; for SG being given, GP is given (laſt cor.)

493. Cor. 5. If particles, whoſe magnitudes are $\frac{A \times SA^2}{SP^2}$, $\frac{B \times SB^2}{SP^2}$, $\frac{C \times SC^2}{SP^2}$, &c. be concentrated in P, the ſame angular velocity will be generated, in theſe particles, by a force F acting for a given time, and in A, B, C, &c. at their reſpective diſtances SA, SB, SC, &c. For, let X, Y, Z, &c. be reſpectively in equilibrio with A, B, C, &c. and their moments are inverſely as their perpendicular diſtances (272), or $A \times SA : X \times SP :: SP : SA$, and $A \times SA^2 = X \times SP^2$,

$\times SP^2$, and $X = \frac{A \times SA^2}{SP^2}$. By a ſimilar proceſs it is proved that $Y = \frac{B \times SB^2}{SP^2}$, and $Z = \frac{C \times SC^2}{SP^2}$.

494. Cor. 6. A pendulous body moving with a given angular velocity, will have the greateſt effect upon another body againſt which it impinges, when the point of impact is the center of percuſſion; for in this caſe all its motion is communicated. But when the direction of impact does not paſs through this center, it will have a lateral motion, or endeavour to continue its rotation.

495. Cor. 7. If the points *A*, *B*, *C*, &c. and *G* be reduced to any plane perpendicular to the axis, and the center of percuſſion be ſuppoſed to be in this plane, its diſtance from the axis of ſuſpenſion is found, by ſubſtituting the diſtances of their places in this plane from the axis, inſtead of *SA*, *SB*, &c. in the expreſſion $\frac{A \times SA^2 + B \times SB^2}{A + B, \text{ \&c.} \times GS}$, &c.

496. LEMMA. *The velocity* V, *generated in a body whoſe quantity of matter is* Q, *by the action of a conſtant force* F, *for a given time, will vary as the force directly and quantity of matter inverſely.*

DEM. Let *V*, *Q*, *F*, be variable, and it is evident that *V* will be encreaſed and diminiſhed in the ſame ratio with *F* directly, and in the ſame ratio with which the inertia or (pag. 63.) *Q* is diminiſhed and encreaſed; or *V* varies as $\frac{F}{Q}$. Q. E. D.

497. Cor. Becauſe the velocity is equal to the moment of a body divided by its quantity of matter, if *m* repreſent the quantity of motion generated in a given time by *F*, or the numeral product of

of the velocity and quantity of matter in a given body, V will always be equal to $\frac{m}{2}$.

498. PROP: *If any conſtant force* F *act, for a given time, perpendicularly upon the line* SV, *at the point* V, *and* SV *and the particles* A, B, C, *&c. whoſe center of gravity is* G, *are connected to an axis paſſing through a fixed point* S, *the velocity communicated to the point* V *will be as* $\frac{F \times SV^2}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, *&c.* FIG. CXLVIII.

DEM. Suppoſe particles, whoſe magnitudes are $\frac{A \times SA^2}{SV^2}$, $\frac{B \times SB^2}{SV^2}$, $\frac{C \times SC^2}{SV^2}$, &c. to be concentrated in V; and they would be in equilibrio with A, B, C, &c. reſpectively (493), and conſequently equally reſiſt the action of F. But the velocity generated in theſe particles, collected in V, is as $\frac{F}{2}$ (496), or as $\frac{F}{\frac{A \times SA^2 + B \times SB^2 + C \times SC^2}{SV^2}}$, &c. or as $\frac{F \times SV^2}{A \times SA^2 + B \times SB^2 + C \times SC^2}$. Q. E. D.

499. Cor. 1. If m, as before (497), repreſent the abſolute quantity of motion generated by F in a given time, then the velocity of $V = \frac{m \times SV^2}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c.

500. Cor. 2. Becauſe all points deſcribe equal angles at the axis, in equal times, the velocity of V is to the velocity of $A :: SV : SA$, and the velocity of $A =$ velocity of $V \times SA = \frac{m \times SV \times SA}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c.; and by a ſimilar proceſs, the velocity

velocity of $B = \frac{m \times SV \times SB}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c.; and the velocity of $C = \frac{m \times SV}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c.

501. Cor. 3. The angular velocity of a body, being as its lineal velocity directly and distance inversely, the angular velocity of A, or B, &c. $= \frac{m \times SV}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c. And the moment of a body being measured by the quantity of matter and velocity, the sum of the moments communicated to A, B, C, &c. will be equal to $\frac{A \times SA + B \times SB + C \times SC, \text{ &c.} \times m \times SV}{A \times SA^2 + B \times SB^2 + C \times SC^2}$ (last cor.), &c.

FIG. CXLIX. 502. Cor. 4. If A, B, C, &c. be collected in any point L, the quantity of motion generated in them, in a given time, by the action of the constant force F at V is equal to $\frac{A+B+C, \text{ &c.} \times SL \times m \times SV}{A+B+C, \text{ &c.} \times SL^2}$ (500) $= \frac{A \times SA + B \times SB + C \times SC, \text{ &c.} \times m \times SV}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c. and consequently $SL = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2, \text{ &c.}}{A \times SA + B \times SB + C + SC, \text{ &c.}}$: but $A \times SA + B \times SB + C \times SC = A + B + C$, &c. $\times SG$, and $SL = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2}{A + B + C, \text{ &c.} \times SG}$, &c., and L is the center of percussion. If therefore any system of particles be concentrated in the center of percussion, the quantities of motion generated in them, in a given time, placed in that point and at their respective distances, SA, SB, &c., by the action of F at any point V, are the same.

SCHOLIUM.

503. In the preceding proposition and corollaries A, B, C, &c. are supposed to be unaffected by gravity, and motion to be communicated

municated by ſome conſtant external force F, which is only reſiſted by their inertia; but the rules inveſtigated are applicable when F is the force of gravity, or that force acts in conjunction with F: for during an infinitely ſmall time the force of gravity may be conſidered as conſtant. If a ſyſtem of bodies A, B, C, &c. whoſe center of gravity is G, be ſuſpended from an horizontal axis paſſing through S, the ſum of their efforts to deſcend is the ſame as if they were collected in G, and they will therefore deſcend till SG be perpendicular to the horizon. In any other poſition of SG, let GL repreſent the force of deſcent in a direction perpendicular to the horizon, and be reſolved into two forces, GE touching the arc, and EL in the direction of SG. EL is the tendency from S, and GE is that part of the whole force of gravity which produces a rotation about S, and may be deemed conſtant whilſt G deſcribes an infinitely ſmall arc, and is to be added to, or ſubtracted from, F, according as they conſpire with, or oppoſe, each other. FIG. CL.

CENTER OF GYRATION.

504. DEF. *The center of gyration of a body, or ſyſtem of bodies*, A, B, C, &c. *is a point* Y, *in which, if* A+B+C, &c. *be collected, the ſame angular velocity will be generated, in a given time, by any conſtant force* F, *acting at any point* V *in a given direction, whether* A+B+C, &c. *be collected in* Y, *or be at their original diſtances* SA, SB, SC, &c. FIG. CLI.

505. PROP. *To find the center of gyration of the particles* A, B, C, &c. *which are connected to an axis paſſing through the point* S, *and preſerve their relative ſituation.*

Let SA, SB, SC, &c. be the perpendicular diſtances of A, B, C, &c. from the axis; and, ſuppoſing the quantity of motion generated by F, in a given time, to be m, their angular velocity is equal

to

to $\frac{m \times SV}{A \times SA^2 + B \times SB^2 + C \times SC^2, \&c.}$ (501); and, when $A + B + C$, &c. are concentrated in Y, their angular velocity $= \frac{m \times SV}{A + B + C, \&c. \times SY^2}$. But, from the definition of the center of gyration, $\frac{m \times SV}{A \times SA^2 + B \times SB^2, \&c.} = \frac{m \times SV}{A + B + C \times SY^2}$, and $SY^2 = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2, \&c.}{A + B + C, \&c.}$, and $SY =$ the distance of the center of gyration from $S = \sqrt{\frac{A \times SA^2 + B \times SB^2 + C \times SC^2}{A + B + C, \&c.}}$, &c.

506. Cor. 1. If therefore $p =$ a particle of a material surface or body, B, $d =$ its perpendicular distance from the axis of suspension passing through S, the distance of the center of gyration from the axis is equal to the sum of all the $\frac{d^2 \times p}{B}$.

507. Cor. 2. If any part of a system of particles A, B, &c. be collected in their center of gyration, the center of gyration of the whole system will continue the same; for the same force will communicate an equal angular velocity to A and B and $A + B$ placed in their center of gyration. A, B, C, &c. may consequently be considered as bodies of any magnitude, whose centers of gyration are the points A, B, C, &c. respectively.

508. Cor. 3. Because $\overline{A + B + C, \&c.} \times SY^2 = A \times SA^2 + B \times SB^2 + C \times SC^2$, &c. $= \overline{A + B + C} \times SG \times SP$ (489), therefore $SY^2 = SG \times SP$, or the distance of the center of gyration from the axis of suspension is a mean proportional between the distances of the center of gravity and the center of percussion from that axis.

509. Cor.

509. Cor. 4. If a ſyſtem of bodies A, B, C, &c. whoſe ſum $= \mathcal{Q}$, connected as in this propoſition, be ſtruck by a given moment at the point V, in a direction perpendicular to a line SV, drawn from V through the center of gravity and perpendicular to an axis paſſing through S, their angular velocity may be found: for, let Υ be the center of gyration, G the center of gravity, and the angular velocity of A, B, C, &c. is the ſame, whether $\mathcal{Q}$ be collected at Υ, or a body equal to $\frac{\mathcal{Q} \times S\Upsilon^2}{SV^2}$ (489), or $\frac{\mathcal{Q} \times SG \times SP}{SV^2}$ be directly oppoſed to the impinging body at the point V. But $A+B+C$, &c. or $\mathcal{Q}$ being given, and alſo the quantity of matter and velocity of the ſtriking body, the velocity of $\mathcal{Q}$ may be found by the common rules in the direct impact of bodies (449). And the arc deſcribed in a given time by $\mathcal{Q}$ and the diſtance SV, being known, the angle which it ſubtends may be found. The converſe of this, or the velocity of the impinging body, may be found, if its quantity of matter, and $\mathcal{Q}$ and its velocity, be given. FIG. CLI.

510. Cor. 5. In a given ſyſtem of bodies A, B, C, &c. whoſe center of gravity is G, if a circle be deſcribed from G as a center with any radius, and the center of ſuſpenſion S be in its periphery, the diſtance of the center of gyration from S is always the ſame; for $S\Upsilon^2 = \frac{A \times SA^2 + B \times SB^2 + C \times SC^2, \text{ \&c.}}{A+B+C, \text{ \&c.}}$, which is a given quantity (412).

511. Cor. 6. If the periphery of a circle, compoſed of the particles A, B, C, &c. were to revolve about an axis perpendicular to its plane and paſſing through its center, the center of gyration will be in the periphery; for $S\Upsilon = \sqrt{\frac{A+B+C, \text{ \&c.} \times \text{rad.}^2}{A+B+C}} =$ radius. The angular velocity is therefore the ſame as if all the matter were collected in any one point of the periphery; and if all the matter in a gyrating body is to be placed in the center of gyration Υ, it may be placed in any point of the periphery of a

circle whose radius is SY, or collected into two equal portions, and placed in two points diametrically oppoſite to each other, and whoſe diſtances from $S = SY$; for then the center of gravity will be in S, and there will be no lateral motion.

CENTER OF OSCILLATION.

FIG. CLII.

512. DEF. *The center of oſcillation of a body, or ſyſtem of bodies,* A, B, C, *&c. connected to an axis paſſing through* S, *and moving by the action of gravity, is a point, in which, if the body or ſyſtem be collected, it, and* A, B, C, *&c. placed at their original diſtances* SA, SB, SC, *&c. will deſcribe equal angles at the axis in the ſame times.*

513. PROP. *Suppoſe* A, B, C, *&c. to be particles of a body connected to an horizontal axis paſſing through* S, *and acted upon by the force of gravity in a direction parallel to the vertical line* SV, *to find their center of oſcillation.*

Let SGO be drawn in the plane deſcribed by the center of gravity G, and O be the center of oſcillation, and the lines SO, SA, SB, &c. will deſcribe equal angles at the axis in equal times. If the weight of A, which is as A (234), acted perpendicularly to SA, its moment would be $A \times SA$: let this be repreſented by Ap, perpendicular to the horizon, aud reſolved into two, Aq perpendicular to SA, and qp parallel to it, and this laſt being loſt, Aq is the only efficient part of A's moment. But $Ap\,(A \times SA) : Aq :: SA : Aa$ (ſim. triangles) and $Aq = \frac{A \times SA \times Aa}{SA} = A \times Aa$*; and the angular velocity of A generated in a given time is (501) $\frac{A \times Aa}{A \times SA^2 + B \times SB^2 + C \times SC^2}$, &c. By a ſimilar proceſs the angular velocities of B, C, &c. generated in the ſame time, are $-B \times b$

* This follows immediately from (279), for Aa is equal to the perpendicular let fall from the center of motion upon the direction of A's weight.

$\frac{-B\times Bb}{A\times SA^2+B\times SB^2+C\times SC^2}$, &c., $\frac{-C\times Cc}{A\times SA^2+B\times SB^2+C\times SC^2}$, &c.

When $A+B+C$, &c. are concentrated in O, the angular velocity of O generated in the ſame time, would be as $\frac{A+B+C,\&c.\times Oo}{A+B+C,\&c.\times SO^2}$ $=\frac{Oo}{SO^2}=\frac{Gg}{SG\times SO}$ (ſim.trian.): therefore $\frac{A\times Aa-B\times Bb-C\times Cc}{A\times SA^2+B\times SB^2+C\times SC^2}$ $=\frac{Gg}{SG\times SO}$; but $A\times Aa-B\times Bb-C\times Cc=A+B+C,\&c.\times Gg$, and conſequently by ſubſtitution, $SO=\frac{A\times SA^2+B\times SB^2+C\times SC^2}{A+B+C,\&c.\times SG}$.

514. Cor. 1. The diſtances of the centers of oſcillation and percuſſion from the axis are equal, each being equal to $\frac{A\times SA^2+B\times SB^2+C\times SC^2}{A+B+C,\&c.\times SG}$, &c., and conſequently $SG\times GO$ equal is to $\frac{A\times GA^2+B\times GB^2}{A+B+C,\&c.}$, &c. (490), and SG and GO are inverſely as each other. If SG be infinitely great, or A, B, C, &c. move with equal velocities in parallel lines, GO is evaneſcent, or the centers of gravity and oſcillation coincide.

515. Cor. 2. If any number of particles be connected to an axis and revolve round it, retaining their relative ſituation, by the action of a force whoſe direction is in the plane of motion and perpendicular to the axis, the time of deſcribing any given angle is the ſame as if they were concentrated in O and urged in the ſame direction by the ſame force; and the points where the forces act are transferred from A, B, C, &c. to O. But in the center of gyration Y, the ſame force is ſuppoſed to act at the ſame point, when A, B, C, &c. are placed at their reſpective diſtances SA, SB, SC, &c. and concentrated in Y.

516. Cor. 3. If A, B, C, &c. be bodies compoſed of any number of particles, let l, m, n be the reſpective diſtances of their centers of gravity, and p, q, r, the diſtances of their centers of oſcillation from the axis, and SO will be equal to $\frac{l \times p \times A + m \times q \times B}{A + B + C, \&c.}$ $\frac{+ n \times r \times C}{\times SG}$: for let a, b, c, be particles of A, B, C, and x, y, z, their reſpective diſtances from the axis, and, by this propoſition, $SO =$ $\frac{\text{ſum of all the } a \times x^2 + \text{ſum of } b \times y^2 + \text{ſum of } c \times z^2}{SG \times A + B + C}$; but the ſums of all the $\frac{a \times x^2}{l \times A}$, $\frac{b \times y^2}{m \times B}$, $\frac{c \times z^2}{n \times C}$ are reſpectively equal to p, q, r, and conſequently, the ſums of $a \times x^2 + b \times y^2 + c \times z^2 = p \times l \times A + q \times m \times B + r \times n \times C$, and $SO = \frac{l \times p \times A + q \times m \times B + r \times n \times C}{A + B + C, \&c.}$.

FIG. CXLVIII. 517. Cor. 4. If A, B, C, conſiſting of a number of particles, were urged by a conſtant force F at the point V, as in (498): let q, r, s, &c. be particles in A, t, u, v, &c. particles in B, and x, y, z, &c. particles in C, and $A = q + r + s$, &c., $B = t + u + v$, &c., $C = x + y + z$, &c.; and the velocity communicated to V in a given time is as $\frac{F \times SV^2}{q \times Sq^2 + r \times Sr^2 + s \times Ss^2, \&c. + t \times St^2 + u \times Su^2, \&c. + x \times Ss^2 + y \times Sy^2, \&c.}$; but if P, p, π be the centers of percuſſion, and G, g, γ the centers of gravity of A, B, C, &c. reſpectively, then (489)

$$q \times Sq^2 + r \times Sr^2 + s \times Ss^2, \&c. = SP \times SG \times A$$
$$t \times St^2 + u \times Su^2 + v \times Sv^2, \&c. = Sp \times Sg \times B$$
$$x \times Sx^2 + y \times Sy^2 + z \times Sz^2, \&c. = S\pi \times S\gamma \times C;$$

and the velocity of V is as $\frac{F \times SV^2}{SP \times SG \times A + Sp \times Sg + B + S\pi \times S\gamma \times C}$.

FIG. CLIII. 518. PROP. *If* O *be the center of oſcillation when the axis of ſuſpenſion paſſes through* S, *the point* S *will be the center of oſcillation when the axis of ſuſpenſion paſſes through* O, *the plane of motion being ſuppoſed to be unaltered.*

DEM.

DEM. When S is the point of ſuſpenſion, the diſtance of the center of oſcillation from the center of gravity G, or $GO = \frac{A \times AG^2 + B \times BG^2 + C \times CG^2}{A + B + C, \&c. \times SG}$, &c. (514); and when the axis paſſes through O, the diſtance of the center of oſcillation from $G = D = \frac{A \times AG^2 + B \times BG^2}{A + B + C \times OG}$, &c.; and conſequently $SG \times GO = D \times GO$ and $SG = D$, and the diſtance of the center of oſcillation from $O = SO$. Q. E. D.

519. Cor. 1. If two circles be deſcribed from G as a center with the radii GS and GO, the diſtances of the centers of oſcillation from the points of ſuſpenſion would be the ſame in whatever parts of the peripheries they were placed; for SG, or GO being given, the other is given (491), and conſequently the times of deſcribing equal angles at the axis will be equal, if the points of ſuſpenſion be any where in theſe peripheries.

520. Cor. 2. If the axis of rotation paſſed through the center of gravity G, and Υ were the center of gyration, $G\Upsilon^2$ would be equal to $\frac{A \times GA^2 + B \times GB^2 + C \times GC^2}{A + B + C}$ (505) $= SG \times GO$, and conſequently GO is a third proportional to SG and $G\Upsilon$.

521. Cor. 3. Becauſe $SG \times GO$ is a given quantity, $SG + GO$ is the leaſt poſſible when the peripheries of the circle, whoſe radii are SG and GO, meet in Υ, becauſe in that ſuppoſition $SG = GO$ (note to 458). And becauſe in this caſe SO is the leaſt poſſible, the time of deſcribing a given angle at the axis is the leaſt poſſible. But becauſe GO encreaſes as GS decreaſes, the time of deſcribing a given

a given angle at the axis decreaſes and arrives at its limit when V and S coincide in the center of gyration Y, and no point of ſuſpenſion can be aſſumed, where the time would not be greater than when the axis paſſes through Y. As GS encreaſes from GY to infinity, GO is diminiſhed without limit, and the time of deſcribing a given angle, whether the axis paſſes through S or O, is perpetually encreaſed.

CHAP.

CHAP. XII.

RECTILINEAL MOTION OF BODIES.

522. LEMMA. *IF a ſide* AB *of a right-angled triangle* ABC *be divided into very ſmall equal parts,* A b, b c, c d, d e, *&c. and rectangular parallelograms be deſcribed upon them about the triangle, the ſum of the rectangles is equal to the area of the triangle, when* A b, b c, *&c. are diminiſhed without limit.* FIG. CLIV.

For the difference between the triangle and the ſum of the rectangles, is the ſum of the triangles $Alm+mnp+pqr$,&c. which is equal to $\frac{Ab \times BC}{2} = 0$ when Ab vaniſhes. Q. E. D.

523. PROP.* *If a quieſcent body be acted upon by a conſtant force in the ſame right line, and any right line* AB *repreſent the time, and* LM, *perpendicular to it, the velocity communicated in the time* AL, *the ſpace deſcribed in the time* AL *will vary as the triangle* ALM.

DEM. Let AB be divided into very ſmall equal parts Ab, bc, cd, &c. and let the forces act only at the beginning of each part, and the velocity conſequently during each will be uniform. If the velocity communicated at A be repreſented by bm, the increments communicated at b, c, d, &c. will be each equal to bm, and conſequently LM encreaſes in the ſame ratio with AL, and AM is a right line. But the ſpaces deſcribed in the particles of time Ab,

* Keil's Phyſics, Lect. XI. Graves, Lect. I. Ch. XIV. Muſchenbroek, Ch. VI. CLVIII. Cotes de Deſcenſu Gravium. Morgan's Notes to Rohault. Maclaurin's Phil. Diſc. B. II. Ch. V. Emerſon, p. 5, &c.

Ab, bc, cd, ef, &c. are as the rectangles Am, bp, cr, ds, &c. (107), and the whole ſpace deſcribed in the time AL, is as the ſum of theſe rectangles, which, when Ab, bc, cd, &c. vaniſh and the force acts inceſſantly, are equal to the triangular area (ALM). Q. E. D.

524. Cor. 1. If the velocity and time be repreſented by V and T, and be divided into very ſmall increments V' and T', whoſe number is n, $V = n \times V'$ and $T = n \times T'$.

525. Cor. 2. If V, T and v, t repreſent correſponding velocities and times, $V : v :: T : t$ and $\frac{V}{v} = \frac{T}{t}$; and, if for v a number of feet uniformly deſcribed in t ſeconds be ſubſtituted, $V = \frac{v \times T''}{t''}$ will be the number of feet deſcribed in t'' by the velocity V.

526. Cor. 3. Whatever be the magnitude of the conſtant force, the ſpace deſcribed, S, will be repreſented by a triangular area, and conſequently S, or the ſpaces deſcribed by the action of different conſtant forces, are generally as $V \times T$, and, when numbers are ſubſtituted for V and T, S is equal to the product of $\frac{V \times T}{2}$*. In the ſame conſtant force, the triangular areas ALM and ABC are always ſimilar, and V and T are directly as each other, and conſequently S is as V^2 or T^2. If therefore the time be divided into equal parts, the ſpaces deſcribed in theſe times are as the odd numbers 1, 3, 5, 7, &c.; for the ſpaces deſcribed in 1, 2, 3, 4, &c. parts of time, are as 1, 4, 9, 16, &c. and conſequently the ſpaces deſcribed in the 1ſt, 2d, 3d, &c. alone are as 1, 3, 5, 7, &c.

527. Cor.

* This equation may be deduced from finding the ſum of an arithmetic progreſſion: let V' and T' be increments of V and T, and $S = \overline{1 + 2 + 3 + 4 \ldots n} \times V'T' = \frac{n^2}{2} \times V'T$ (becauſe n is infinitely great, and conſequently vaniſhes compared with n^2) $= \frac{nV \times nT}{2} = \frac{V \times T}{2}$.

527. Cor. 4. The ſpace which is deſcribed in any time T from a ſtate of reſt, is half of that deſcribed, in the ſame time, with the laſt velocity, V, continued uniform: for, in the firſt caſe, the ſpace $= \frac{V \times T}{2}$ (526), and, in the ſecond, the ſpace $= V \times T$ (107).

528. Cor. 5. If a body, projected with any velocity, be acted upon by a conſtant force, in a direction oppoſite to its motion, it will be uniformly retarded: for the force will evidently deſtroy equal parts of velocity in equal times. A body therefore projected with the laſt acquired velocity, will aſcend to the point from whence it fell, and the velocities in the aſcent and deſcent are the ſame at the ſame point. And, if bodies be projected with different velocities and reſiſted by the ſame conſtant force, the time that elapſes, T, till the velocity be deſtroyed, will vary as the velocity of projection V; the ſpace will vary as the ſquare of the time T^2, or ſquare of velocity V^2; the ſpaces deſcribed in equal portions of time, will be as the odd numbers in a retrograde order 7, 5, 3, 1; and, whether theſe retarding forces be the ſame or different, the ſpace will vary as $V \times T$, and be equal to $\frac{V \times T}{2}$.

SCHOLIUM.

529. At the ſurface of the earth the force of gravity is conſtant, for a body deſcends through $16\frac{1}{12}$ feet nearly in the firſt ſecond, and conſequently acquires a velocity that would make it deſcribe $32\frac{2}{12}$ feet uniformly in 1″; and this is found to be the velocity communicated in every ſucceeding ſecond. Any of theſe quantities, ſpace deſcribed S, velocity acquired, or time T, being known, the others may be diſcovered.

1. The proper meaſure of velocity is the ſpace uniformly deſcribed by it in any given time: if therefore a body fall by the force of gravity for t'', and acquire a velocity which would make

it deſcribe V feet uniformly in 1″, V and 32 are the proper meaſures of the velocities communicated in t'' and 1″ (106), and $V : 32 :: t'' : 1''$ (525), and $V = 32 \times t''$. If $t = 2, 3, 4$, &c. ſeconds, $V = 2 \times 32$, 3×32, 4×32, &c. feet reſpectively.

2. If V, or the number of feet uniformly deſcribed in 1″, by the velocity acquired in falling for an unknown time, be given, this time may be found; for it is equal $\frac{V}{32}$ ſeconds. If $V = 192$ feet, the time of falling $= \frac{192''}{32} = 6''$.

3. If Y be the ſpace deſcribed in falling t'', $16 : Y :: 1^2 : t''^2$ (526), and $Y = 16 \times t''^2$ feet. If $t = 2, 3, 4$, &c. ſeconds, $Y = 16 \times 2^2$, 16×3^2, 16×4^2, &c. feet reſpectively. Or Y may be found by knowing the velocity (V) at the end of the deſcent; for $Y : 16 :: V^2 : 32^2$, and $Y = \frac{16 \times V^2}{32^2} = \frac{16 \times V^2}{4 \times 16^2} = \frac{V^2}{64}$ feet. If $V = 192$ feet, $Y = \frac{192^2}{64} = 576$ feet.

4. If Y, or the number of feet deſcribed in falling, be known, the time of deſcent, and velocity acquired, may be found; for $Y = 16 \times t''^2$, and conſequently $t'' = \frac{\sqrt{Y}}{4}$. If $Y = 576$ feet, $t = \frac{\sqrt{576}}{4} = \frac{24}{4} = 6$ ſeconds. And becauſe $Y = \frac{V^2}{64}$, $V = \sqrt{Y} \times 8$. If $Y = 576$ feet, $V = \sqrt{576} \times 8 = 24 \times 8 = 192$ feet.

530. PROP. *If bodies be acted upon by different conſtant forces, the velocities communicated will vary in a ratio compounded of the forces and times.*

Let

Let S, V, T, repreſent force, velocity and time, and be ſuppoſed variable, and it is evident that the velocity will be encreaſed and diminiſhed in the ſame ratio with both the force and time, and, theſe being independent of each other, V will be as $F \times T$. Q.E.D.

531. Cor. 1. V therefore is as $F \times T$, and if F be compared with the force of gravity f, or any other known force, capable of generating a velocity equal to v in the time t, then $V : v :: F \times T : f \times t$, and $\frac{V}{v} = \frac{F \times T}{f \times t}$.

532. Cor. 2. Becauſe, in all conſtant forces, the ſpace varies generally in a ratio compounded of the velocity and time, and the velocity varies generally as the force and time; the following analogies are general:

S is as $V \times T$, or as $F \times T^2$, or as $\frac{V^2}{F}$;

T varies as $\frac{S}{V}$, or as $\sqrt{\frac{S}{F}}$;

V varies as $\frac{S}{T}$, or as $\sqrt{S \times F}$; and

F varies as $\frac{V}{T}$, or as $\frac{S}{T^2}$, or as $\frac{V^2}{S}$.

If numbers be ſubſtituted for V, F, and T; or the number of feet deſcribed in a given time 1, by the action of any conſtant force F, be ſubſtituted for the force; the number of feet which would be uniformly deſcribed in this given time 1, by the velocity acquired in the time T, $= V$; and $T =$ the number of parts of time each equal to 1, contained in the whole time in which the velocity is communicated: then (106) V and $2F$ are proper meaſures of the velocity acquired in the times T and 1, and $V : 2F :: T : 1$ (525) and $V = 2F \times T$; and ſubſtituting this value of V in the general equation $\left(S = \frac{V \times T}{2}\right)$, the following general equations are deduced:

$$S = \frac{V \times T}{2} = F \times T^2 = \frac{V^2}{4F} \text{ feet;}$$

$$T = \frac{2S}{V} = \sqrt{\frac{S}{F}}, \text{ equal portions of time, each of which is equal to 1; and}$$

$$V = \frac{2S}{T} = \sqrt{S \times 4F} \text{ feet.}$$

533. Cor. 3. Theſe equations and analogies are applicable to all accelerating and retarding forces, ſuch as gravity, and to all reſiſtances that are conſtant and produce equal decrements of velocity in equal times. If the motion of a ball ſhot into a bank of earth or piece of wood, be uniformly reſiſted, and the magnitude of this reſiſtance compared with gravity, and the velocity of impact, be known; the depth, or ſpace through which it moves before all motion is deſtroyed, may be diſcovered; and vice versâ *.

FIG. CLV. 534. PROP. *If a body deſcend down an inclined plane* AB *by the action of a conſtant force* F, *whoſe direction is perpendicular to any right line* BC; F *will be to that part of* F *which makes the body deſcend, as the radius to the ſine of the plane's inclination to* BC.

DEM. Let any given line *LM*, perpendicular to *BC*, repreſent the conſtant force *F*, in quantity and direction, and be reſolved into two forces, *LN* parallel, and *MN* perpendicular, to the plane; *MN* is deſtroyed by the reſiſtance of the plane, and *LN* is the only part of *F* that communicates motion to the body; therefore *F*:

* EXAMPLE. Suppoſe a reſiſtance were equal to the reſiſtance of gravity *F*, when a body is projected perpendicularly upwards, multiplied into any number *n*, and all motion were deſtroyed in *t''*, then *S* (being equal to the force multiplied into the ſquare of the time) $= n \times 16 \times t^2$. If the velocity of projection were ſuch as would make a body deſcribe *f* feet in a ſecond uniformly, then *S* (being equal to $\frac{\text{vel.}^2}{4 \times \text{force}}$) $= \frac{f^2}{4 \times n \times 16}$ $= \frac{f^2}{n \times 64}$. If the ſpace deſcribed and force be known, then the time is equal to $\sqrt{\frac{S}{n \times 16}}''$, and the velocity $= \sqrt{S \times n \times 64}$ feet.

F: that part of F which makes the body move $(A) :: LM : LN :: AB : AC$ (sim. triangles) :: rad. : sin. of $\angle ABC$. Q. E. D.

535. Cor. 1. F is to that part of F which is destroyed by the reaction of the plane as $LM : MN :: AB : BC$ (sim. triangles) :: radius : cos. $\angle ABC$; and consequently the part of F, destroyed by the resistance of the plane, $= \frac{F \times \text{cos. } \angle ABC}{\text{radius}}$, which is constant upon the same, or parallel, planes, and upon different planes, not parallel, varies as the $\frac{\text{base}}{\text{length}}$, if F be given.

536. Cor. 2. Because the accelerating force $LN = A = \frac{F \times AC}{AB}$, and F is given, A is constant upon the same, or parallel planes, and, upon different planes, inclined in unequal angles to BC, it varies as the height divided by the length, or as $\frac{H}{L}$, calling H the perpendicular height and L the length.

537. Cor. 3. Because the force upon the same plane is constant, the analogies and equations in (526) are applicable to the motion of a body upon the same plane; and the analogies and equations in (532) obtain when bodies move upon different planes. If BC be horizontal, and F be the force of gravity, then the space described upon the plane in $T'' = S = A \times T''^2 = F \times T^2 \times \frac{H}{L}$ (536) $= \frac{16 T^2 \times H}{L}$; $V = \frac{2F \times T'' \times H}{L} = \frac{32 T'' \times H}{L} = 8 \times \sqrt{H}$ feet; and $T'' = \frac{V \times L}{32 \times H} = \frac{L}{4 \times \sqrt{H}}$.

538. Because the space described is generally as the force multiplied into the square of the time (532), the spaces that are to each

each other as the forces muſt be deſcribed in the ſame time, or when S is as F, T is given. If therefore two bodies deſcend at the ſame inſtant, one down the plane AB, and the other in AC perpendicular to BC, and CP be drawn perpendicular to AB, P and C are cotemporary poſitions of the bodies; for $AP : AC :: LN : LM :: A : F$, that is, the ſpace is as the force, and T^2 and T are given. If the diameter AD of a circle be perpendicular to the horizon, a body will deſcend through it, and any chord AP drawn from its extremity A, in the ſame time, becauſe the angle APD is a right one; and the times of deſcent through all the chords drawn from A are conſequently equal to each other.

FIG. CLVI.

539. Cor. 5. The velocities acquired in falling down different inclined planes, are as the ſquare roots of their perpendicular heights; for V^2 is always as the ſpace multiplied into the force, or as $L \times A$, or as $\frac{L \times H}{L}$ (536), or as H, and V is as $\sqrt{H}$; this alſo follows from art. 537. The velocities therefore acquired in falling down the perpendicular AC, and any planes AB, AE, AG, &c. drawn from A and terminated by the baſe CB, are equal to each other. And becauſe V is always equal to $2A \times T$, and in this cor. V is given, the times of falling are as the forces inverſely, or as the lengths of the planes. Or becauſe S is as $V \times T$, and V is given, T is as S, that is, as the length.

FIG. CLV.

540. Cor. 6. The times of deſcending through different planes are as the lengths directly and ſquare roots of the heights inverſely; for the time is generally as the ſpace deſcribed directly and laſt velocity inverſely (532), or T is as $\frac{L}{V}$, or as $\frac{L}{\sqrt{H}}$ (laſt cor.); this alſo follows from art. 537. The times therefore of deſcribing different planes, equally inclined to the direction of F, are as the ſquare roots of their lengths; for H is as L (ſim. triangles), and conſequently $\frac{L}{\sqrt{H}}$ is as $\frac{L}{\sqrt{L}}$, or as $\sqrt{L}$ or T.

541. PROP.

541. PROP. *The velocity acquired in falling down any number of contiguous planes, ſuppoſing none to be loſt in paſſing from one plane to another, is equal to the velocity acquired in falling down the ſame perpendicular altitude.* FIG. CLVII.

DEM. The velocities acquired in falling down AB and EB, $AB + BC$ and EC or PC, $AB + BC + CD$ and PD, or down the perpendicular PR, are equal (539). Q. E. D.

542. Cor. The velocities, acquired in falling down any ſyſtems of planes, are therefore as the ſquare roots of their perpendicular heights; and if the body be projected from D with the velocity acquired, it will aſcend through this or any other ſyſtem of planes to the ſame perpendicular altitude.

543. PROP. *The velocity loſt in paſſing from any plane to the next, is to the whole velocity as the ſine of the angle of their inclination to the radius.* FIG. CLVIII.

DEM. Let CB repreſent the velocity acquired in falling down AC, and be reſolved into two, CP coincident with the plane CD, and BP perpendicular to it; and this laſt is evidently deſtroyed by the reſiſtance of the plane: but $BP : CB ::$ ſin. of $\angle PCB$ or $\angle PCA$: radius. Q. E. D.

544. Cor. 1. $CB : CP$ (velocity upon the plane CD) :: radius : coſine of $\angle PCB$ or PCA. If the angle ACD become equal to two right angles, or ACD be any circular arc, CP and CB coincide, or the velocity loſt is equal to nothing; and conſequently a body moving in any circular arc ſuſtains no loſs of velocity by changing the direction of its motion; and a body, projected with the velocity acquired, up any curvilineal arc, will riſe to the ſame height from whence it fell.

545. Cor.

545. Cor. 2. If ACD be any circular arc, the velocity acquired in falling from A to D is conſequently equal to that acquired in falling through the ſame perpendicular height; and the velocities acquired or deſtroyed in deſcending or aſcending through two curve lines are as the ſquare roots of their perpendicular altitudes: for every curve may be conſidered as conſiſting of an indefinite number of inclined planes.

FIG. CLVII.

546. PROP. *The times of deſcribing two ſyſtems of inclined planes* ABCD *and* abcd, *whoſe number, inclinations, and ratios of their lengths are the ſame, are to each other as the ſquare roots of the lengths of the planes.*

DEM. Becauſe the planes are equally inclined to the direction of the force, the time of falling down AB is as $\sqrt{AB}$ (540), or as $\sqrt{EB}$, or $\sqrt{EC}$ (hypoth.), or as the time down EB, or EC; and, dividendo, the time of falling down BC, after having fallen down AB or EB, is as $\sqrt{AB}$; conſequently the time of falling down $AB + BC$ is as $\sqrt{AB}$, or as $\sqrt{AB + BC}$, &c.: for from the ſuppoſition $\sqrt{AB} : \sqrt{ab} :: \sqrt{AB+BC} : \sqrt{ab+bc}$, &c. Q. E. D.

547. Cor. 1. The times of deſcribing ſimilar parts of ſimilar curves, equally inclined, in ſimilar parts, to the direction of the force, are as the ſquare roots of their lengths.

548. Cor. 2. If two bodies vibrate in ſimilar circular arcs, the times of performing theſe vibrations are as the ſquare roots of the lengths of theſe arcs, or as the ſquare roots of their radii.

SCHOLIUM.

549. In the preceding propoſitions and corollaries, inclined planes and bodies, deſcending or aſcending upon them, are ſuppoſed to be without any aſperities upon their ſurfaces, and the bodies are ſuppoſed to move by the action of a force in a given direction,

direction, without any retardation from friction, or rotation about an axis. In this ſuppoſition, the tendency of each particle of a body to deſcend, when impelled by the force of gravity, is equal to the particle multiplied into $\frac{H}{L}$, and the tendency of the body W is equal to $W \times \frac{H}{L}$, and is the ſame as if it were collected in its center of gravity. But if the parts of W and the inclined plane adhere together, the force of this adheſion muſt be eſtimated and allowed for in practice. If W be a ſpherical body, and the parts of its ſurface in contact with the plane adhere by the preſſure of W upon it, their tendency to deſcend will be diminiſhed by this adheſion, and conſequently they will be regreſſive with regard to the center of gravity G, and revolve round it. The abſolute velocities of different particles in W, and conſequently their accelerating forces, are different; and the tendency to deſcend of the center of gravity is diminiſhed by this motion of rotation round it. The angular velocity of every particle round G is the ſame, and the ſame as if all the particles were concentrated in their center of gyration Υ, or a body whoſe magnitude is $\frac{W \times G\Upsilon^2}{GA^2}$ were collected in A (498).

550. PROP. *Suppoſe the ſame ſpherical body to ſlide and roll down the ſame inclined plane, to find the ratio of the forces acting upon it.* FIG. CLIX.

From the nature of the circle, the initial regreſſive velocity of the point A is equal to the progreſſive velocity of the center of the ſphere, or center of gravity G; but the regreſſive velocity of a body whoſe magnitude is $\frac{W \times G\Upsilon^2}{GA^2}$ placed at A (laſt ſcholium), would be deſtroyed by the action of a force in a contrary direction equal to $\frac{H}{L}$; and in this caſe G would not be impeded by the regreſſive motion of A, but G and A would ſlide down with equal velocities; conſequently

the force acting upon W when it ſlides : the force when it rolls down the plane $:: W + \frac{W \times GY^2}{GA^2} \times \frac{H}{L} : W \times \frac{H}{L}$. Q. E. I.

551. Cor. If the center of gyration be found, and GY, and GA be expreſſed in numbers, the ratio of theſe forces will be expreſſed in terms of the weight.

SCHOLIUM.

552. In the communication of motion by the external application of forces ſuch as impact, protruſion, &c. their magnitude, or capacity to communicate motion, is not always meaſurable by their cotemporary effects; but in this chapter every particle of matter is ſuppoſed to be impelled by a force, ſimilar to that of gravity, with the ſame intenſity in parallel directions, which will conſequently communicate the ſame velocity, or change of velocity, to bodies of different magnitudes, whether quieſcent or moving. The magnitude of theſe forces at any inſtant, or the magnitude of their accumulated action, is meaſurable by their cotemporary effects, or by the velocity generated or deſtroyed in equal times; for the increments or decrements of velocity, produced in equal times, by the ſame conſtant force, being equal, the whole velocity is encreaſed or diminiſhed uniformly; and when the forces are unequal, the changes of velocity being as the forces, it is evident that the velocities are proper meaſures of the intenſity of forces, and will vary as the forces multiplied into the times in which they are generated or deſtroyed. And the magnitudes of variable forces, whoſe intenſities and cotemporary effects are perpetually encreaſed or diminiſhed, are meaſured at any inſtant of time by their conſtant action at that inſtant, or by the velocities which they would produce in the ſame time were their intenſity conſtant during that time; and the magnitude of their accumulated actions for any finite time is meaſured by the addition of theſe cotemporary effects.

553. PROP.

453. *PROP. *If* F, V, T, *repreſent any finite variable force, velocity and time, reſpectively, and* $\dot{V}$, $\dot{T}$, *be any ſmall changes of* V *and* T, $\dot{V}$ *will vary as* $F \times \dot{T}$.

DEM. The force *F* being always finite, and being ſuppoſed to encreaſe or decreaſe according to the ſame law, an encreaſe or diminution of it in any finite time muſt be finite, and conſequently, in an infinitely ſmall time, evaneſcent compared with the whole force *F*, which therefore may be conſidered as conſtant during the time $\dot{T}$ in which $\dot{V}$ is generated or deſtroyed; therefore (530) $\dot{V}$ varies as $F \times \dot{T}$. Q. E. D.

554. Cor. 1. If $\dot{V}$ be the fluxion of the velocity, or the change of velocity generated by *F* at any inſtant, ſuppoſed to act conſtantly for any time $\dot{T}$, $\dot{V}$ will therefore vary as $F \times \dot{T}$.

555. Cor. 2. $\dot{T}$ is therefore as $\frac{\dot{V}}{F}$ and *F* as $\frac{\dot{V}}{\dot{T}}$, and the relation of any two being known, the other may be found; and becauſe $\dot{T}$ is as $\frac{\dot{S}}{V}$, $V\dot{V}$ is as $F \times \dot{S}$.

556. PROP. *If any right line* AS *repreſent the time, and* OR *be as the force at any point* O, *the change of velocity at* O *will be as the area* AR. FIG. CLX.

DEM. The increment of velocity $\dot{V}$ is as $F \times \dot{T}$, or as $AB \times Ap$ or as Aq; and the next increment of velocity is as ps, and the ſum of the increments, or the whole change of velocity, is as the ſum of theſe areas; conſequently the velocity communicated in the time *AO* is as *AR*. Q. E. D.

557. Cor. 1. If the time in acquiring any given velocity be known, and the areas *AR* can be ſquared, the velocities communicated in any other time *AO* may be found; and vice versâ.

558. Cor.

* Newt. Prin. Tom. I. Sect. VII. Euler's Mechan. Ch. IIA

558. Cor. 2. If the force F be finite, and the time Ap infinitely ſmall, the increment of velocity, $\dot{V}$, is evaneſcent; becauſe $AB \times Ap =$ a finite quantity multiplied into one that is evaneſcent $= 0$; and conſequently the increment of velocity, or $\dot{V}$, is infinitely ſmall, and no finite change of velocity can be generated by F in an inſtant.

559. Cor. 3. If the body aſcend or deſcend, and the velocity be as the time in which it is acquired or deſtroyed, the force is invariable; for, from this propoſition, the change of velocity is as AR, or as AO (hypoth.), and conſequently AR is a rectangular parallelogram, or OR is conſtant.

FIG. CLXI. 560. PROP. *If* PO *repreſent the ſpace deſcribed by the action of a force tending to* S, *and the ordinate* OR *be the relative magnitude of the force at the point* O, *the velocity*, V, *acquired at* O *will vary in a ſubduplicate ratio of the correſponding area* PR.

DEM. Let V, F, S, be the velocity, force, and ſpace deſcribed, reſpectively, and becauſe $\dot{V}$ is as $F \times \dot{T}$ (554), and $\dot{T}$ is as $\frac{\dot{S}}{V}$; $V\dot{V}$ is as $F \times \dot{S}$, or as $PB \times Pp$, and the fluent of $V\dot{V}$, or $\frac{V^2}{2}$ is as the fluent of $PB \times Pp$ or PR, and V is as $\sqrt{PR}$. Q. E. D.

561. Cor. 1. If x be the diſtance of the moving body from the center of force, S, and the force be as any power of the diſtance, whoſe exponent is $n - 1$; $V\dot{V}$ is as $F \times -\dot{x}$, or as $-x^{n-1}\dot{x}$, and $\frac{V^2}{2}$ is as $\frac{-x^n}{n}$ + correction: but when $V = 0$ at P, $x = SP = p$ and $\frac{x^n}{n} = \frac{p^n}{n}$; therefore the correction $= \frac{p^n}{n}$, and V is as $\sqrt{p^n - x^n}$.

562. Cor.

562. Cor. 2. If the force be conſtant, or $n = 1$, then V being as $\sqrt{p^n - x^n}$ is as $\sqrt{p - x}$, or in a ſubduplicate ratio of the ſpace deſcribed, either in acceding to S from a ſtate of reſt, or receding from S till the velocity be deſtroyed. The fluxion of the time $\dot{T}$ is as the fluxion of the ſpace directly and velocity inverſely; or as $\frac{-\dot{x}}{\sqrt{p-x}} = -\dot{x} \times \overline{p-x}^{-\frac{1}{2}}$, and T is as $\frac{\overline{p-x}^{\frac{1}{2}}}{\frac{1}{2}}$, and when $T = 0$, $x = p$, and $\frac{\overline{p-x}^{1\frac{1}{2}}}{\frac{1}{2}} = 0$; therefore T is as the ſquare root of the ſpace deſcribed from reſt, which coincides with art. 526.

563. Cor. 3. If the force vary directly as the diſtance, or $n = 2$, then V varies as $\sqrt{p^2 - x^2}$, or as the right ſine of a circular arc, deſcribed from S as a center, and radius equal to SP or p, whoſe verſed ſine is the ſpace deſcribed. And deſcribing this circle, the fluxion of the time $\dot{T}$ is as $\frac{\dot{S}}{V}$, or as $\frac{Oo}{OR}$, or as $\frac{Rn}{Sn}$ (ſim. triang.), and the fluent T is as the fraction $\frac{PRD}{SD}$, which is a conſtant quantity. If the force therefore vary directly as the diſtance, the times of deſcent to S from a ſtate of reſt are equal wherever P be taken. FIG. CLXII.

564. Cor. 4. If the force vary inverſely as any power of the diſtance, or n be negative, or leſs than 1, let this power be expreſſed by the number $-m-1$; and V is as $\sqrt{\frac{1}{m \times x^m} - \frac{1}{m \times p^m}}$, or as $\sqrt{\frac{p^m - x^m}{m \times p^m x^m}}$. If the force be inverſely as the diſtance, or $m = 0$, this expreſſion does not ſhew the variation of velocity. If the force be inverſely as the ſquare of the diſtance, or $m = 1$, V is as $\frac{\sqrt{p-x}}{\sqrt{m \times px}}$, or the velocity is as the ſquare root of the ſpace deſcribed directly, and inverſely as the ſquare root of the diſtance from S.

565. PROP.

FIG. CLXIII. 565. PROP. *If the ordinates* PB, AL, OR, *be always proportional to the forces at thoſe points, and the force at* A, *continued conſtant through the ſpace* AM, *communicate a velocity,* V, *equal to that acquired by the body at* O, *deſcending by the variable force, the area* PR *will be equal to the rectangle* AN, *and the body muſt have fallen from* P.

DEM. Let $\dot{v}$ and $\dot{V}$ be the fluxions of the velocities communicated, by the variable and conſtant forces reſpectively, in any periods of their deſcent; and $\dot{v} : \dot{V} :: \frac{PB \times P\dot{O}}{v} : \frac{AL \times A\dot{M}}{V}$ (555),

and $v\dot{v} : V\dot{V} :: PB \times P\dot{O} : AL \times A\dot{M}$, and, taking the fluents, $v^2 : V^2 :: PR : AN$. If therefore $v = V$, the areas PR and AN are equal, and the body muſt have fallen from P. Q. E. D.

566. Cor. 1. If the areas PR and AN be equal, the velocities, acquired by the action of the conſtant and variable forces, whilſt the bodies deſcribe, from reſt, the ſpaces AM and PO, will alſo be equal.

567. Cor. 2. Becauſe the areas AN and PR are always equal, when the velocities at M and O are equal, their increments Or and Mn muſt be equal; and if F be the given force at A, and $y =$ the ſpace deſcribed AM, $F \times \dot{y} = Or = OR \times O\dot{o} =$ the force at O multiplied into the fluxion of the ſpace.

568. PROP. *If a body be attracted towards the point* S, *by forces which always vary as that power of the diſtance whoſe exponent is* n—1, *and begin to move at any given diſtance* SP, *it is required to aſſign the velocity,* V, *acquired in deſcribing any ſpace* PO, *ſuppoſing the magnitude of the force at any given diſtance* SA *to be known.*

Let

Let the magnitude of the force at A be to the force of gravity as $F : 1$, and let

$SA = a$,

$SP = p$,

$SO = x$; and, from the ſuppoſition, F: force at any point $O :: a^{n-1} : x^{n-1}$, and the force at $O = \frac{F \times x^{n-1}}{a^{n-1}}$. But, if y be the ſpace through which a body muſt fall, when acted upon by a conſtant force equal to F, to acquire a velocity equal to that at O, from (567) $F \times \dot{y} = \frac{F \times \overline{x^{n-1} - \dot{x}}}{a^{n-1}}$, and the fluents are equal, or $F \times y = \frac{-Fx^n}{n \times a^{n-1}} +$ correction; but when $F \times y$ vaniſhes, $x = p$, and conſequently the fluent corrected $= \frac{F \times \overline{p^n - x^n}}{n \times a^{n-1}}$. But if s be the ſpace deſcribed by the force of gravity in $1''$, or any other given time 1, and the force of gravity be expreſſed by 1, $V =$ *$\sqrt{4sFy} = \sqrt{\frac{4sF \times \overline{p^n - x^n}}{n \times a^{n-1}}}$ feet in $1''$. Q. E. I.

569. Cor. 1. If the force be as ſome negative power of the diſtance, or $n - 1 = -m$, then F: the force at $O :: a^{-m} : x^{-m}$, and the force at $O = \frac{F \times x^{-m}\dot{x}}{a^{-m}}$; the fluxion of $F \times y = \frac{F \times x^{-m}\dot{x}}{a^{-m}}$ and its fluent $= \frac{F \times x^{1-m}}{1 - m \times a^{-m}} +$ cor. $= \frac{F \times a^m}{1 - m \times x^{m-1}} - \frac{Fa^m}{1 - m \times p^{m-1}}$ $= \frac{F \times a^m \times \overline{p^{m-1} - x^{m-1}}}{1 - m \times p^{m-1}x^{m-1}}$, and $V = \sqrt{\frac{4sF \times a^m \times \overline{p^{m-1} - x^{m-1}}}{1 - m \times p^{m-1}x^{m-1}}}$.

570. Cor.

* Let $f =$ the force of gravity,

$s =$ the ſpace deſcribed by the conſtant action of f in $1'' = 16$ feet nearly, and

$v =$ the velocity acquired in falling $1''$; and

$V^2 : v^2 :: F \times y : f \times s$ and $V^2 = \frac{v^2 \times F \times y}{f \times s}$; but if $f = 1$, $v = 2s$ and $V^2 = 4sEy$ and $V = \sqrt{4sEy}$.

570. Cor. 2. Becauſe $4Fs$ and a^{n-1} are given quantities, V varies as $\sqrt{p^n - x^n}$.

571. Cor. 3. If the body deſcend to the center, or $x = 0$, and the force vary according to any direct law of the diſtance, or inverſe law leſs than the ſimple, that is, if n be any affirmative, whole number, or fraction leſs than unity, $V = \sqrt{\frac{4sF \times p^n}{n \times a^{n-1}}}$ is a real finite quantity. Let the force be as that power of x, whoſe exponent is $-\frac{1}{2}$, 1, 2, 3, &c. or $n = \frac{1}{2}$, 2, 3, 4, &c. and $V = \sqrt{\frac{4sF \times p^{\frac{1}{2}}}{\frac{1}{2} \times a^{-\frac{1}{2}}}}, \sqrt{\frac{4sF \times p^2}{2 \times a}}, \sqrt{\frac{4sF \times p^3}{3 \times a^2}}, \sqrt{\frac{4sF \times p^4}{4 \times a^3}}$, &c.

572. Cor. 4. If the force be inverſely as the diſtance, or $n = 0$, and the body deſcend to the center, as before, $V = \sqrt{\frac{4sF \times p^0}{0 \times a^{-1}}}$ is infinitely great. If the force be inverſely as the ſquare of the diſtance, or $n = -1$, $F \times y = -\frac{Fx^{-2}\dot{x}}{a^{-2}}$ and $Fy = \frac{Fa^2}{x} + \text{cor.} = \frac{Fa^2}{x} - \frac{Fa^2}{p} = \frac{Fa^2 \times \overline{p-x}}{px}$, and $V = \sqrt{4sFa^2 \times \frac{\overline{p-x}}{px}}$. From hence it appears, as before (564), that the velocity varies as $\sqrt{\frac{PO}{OS}}$.

573. PROP. *Suppoſe a body to be impelled by a force varying as that power of the diſtance from the center of force* S, *whoſe exponent is* n — 1, *it is required to aſſign the time of deſcribing any ſpace* P O, *ſuppoſing it to fall from a ſtate of reſt.*

The fluxion of the ſpace $\dot{S} = V \times \dot{T}$, and conſequently $\dot{T}$ is equal to the fluxion of the ſpace divided by the velocity $= -\frac{\dot{x}}{V} =$

—

$-\frac{\dot{x} \times \sqrt{n a^{n-1}}}{\sqrt{4sF \times p^n - x^n}}$; and the time is equal to the fluent of $\frac{\dot{x} \times \sqrt{n a^{n-1}}}{\sqrt{4sF \times p^n - x^n}}$. Or, if $n-1$ be negative and $= -m$, then $\dot{T} = -\dot{x} \times \sqrt{\frac{1 - m \times p^{m-1} x^{m-1}}{4sFa^m \times p^{m-1} - x^{m-1}}}$, and $T =$ its fluent. Q. E. I.

574. Cor. 1. Let the force vary as the diſtance from the center of force S, or $n = 2$, and $T = \sqrt{\frac{2a}{4sF}} \times$ into the fluent of $\frac{-\dot{x}}{\sqrt{p^2 - x^2}} =$ cor. — length of a circular arc, whoſe radius is unity and right ſine $\frac{x}{p}$. If the time vaniſh, or $x = p$, the cor. = length of a circular arc whoſe radius is 1 and right ſine is $\frac{p}{p}$, or 1, and therefore = a quadrantal arc; conſequently the time of deſcribing any ſpace PO is equal to $\sqrt{\frac{2a}{4sF}} \times$ into a quadrant $- \sqrt{\frac{2a}{4sF}} \times$ into the arc whoſe right ſine is $\frac{x}{p}$, the radius being unity. When the body deſcends to the center, or $\frac{x}{p} = 0$, the time is equal to $\sqrt{\frac{2a}{4sF}} \times$ into a quadrant. If the radius of the circle $= r$, and a quadrantal arc of that circle $= \mathcal{Q}$, the quadrant of a circle whoſe radius is unity $= \frac{\mathcal{Q}}{r}$; and the time of deſcent to $S = \sqrt{\frac{2a}{4sF}} \times \frac{\mathcal{Q}}{r} =$ a given quantity.

575. Cor. 2. If the force vary inverſely as the ſquare of the diſtance from S, then $V = \sqrt{\frac{4sFa^2 \times p - x}{px}}$ and $\dot{T} = \dot{x} \times$

$\sqrt{p}$

FIG. CLXVI. $\sqrt{\frac{p}{4sFa^2}} \times \sqrt{\frac{x}{p-x}}$, and $T = \sqrt{\frac{p}{4sFa^2}} \times$ into the fluent of $\dot{x} \times \sqrt{\frac{x}{p-x}}$. With SP or p as a diameter, and from the center C describe a circle, and the fluent of $\dot{x} \times \sqrt{\frac{x}{p-x}}$ is as the area PRS; for this area $=$ sector $PCR +$ the triangle $SRC = \overline{\text{arc } PR + \text{sine } OR} \times \frac{SP}{4}$, and the fluxion of the area $= \overline{Rr + mr}\,(P\dot{R} + O\dot{R}) \times \frac{SP}{4} = \frac{\dot{x} \times CR}{OR} + \dot{x} \times \frac{CO}{OR}$ (sim. triang.), (or $\frac{\dot{x} \times x}{OR}$, or $\frac{x \times \dot{x}}{\sqrt{x \times p - x}}$, or $\dot{x} \times \sqrt{\frac{x}{p-x}}$) $\times \frac{SP}{4}$; and consequently the fluent of $\sqrt{\frac{p}{4sFa^2}} \times \dot{x} \sqrt{\frac{x}{p-x}} = \sqrt{\frac{p}{4sFa^2}} \times \text{arc } \overline{PR + \text{sine } OR}$. And because $\frac{p}{4sFa^2}$ is given, the time of describing PO varies as $PR + OR$, or as $\overline{PR + OR} \times \frac{SP}{4}$, or as the area PRS.

FIG. CLXIII. 576. PROP. *If a body begin to fall from* A, *it is required to determine the space* AO *through which it must descend, when impelled by a force varying as that power of the distance whose exponent is* $n - 1$, *to acquire a velocity,* V, *equal to that communicated, whilst the body describes a space equal to* $\frac{AS}{2}$, *by the constant action of a force equal to that at* A.

Let the force at $A = 1$

$SA = r$

$SO = x$. And the force at A, or 1 : the force at $O :: r^{n-1} : x^{n-1}$, and the force at $O = \frac{x^{n-1}}{r^{n-1}}$, and $\frac{r}{2} \times$ the force at A

$=$

$= \frac{r}{2} =$ the fluent of $- \frac{x^{n-1}\dot{x}}{r^{n-1}}$ (567) $= - \frac{x^n}{n \times r^{n-1}} +$ cor. $=$ $\frac{r^n - x^n}{n \times r^{n-1}}$, and $r^n - x^n = \frac{n r^n}{2}$, and $x = \frac{\overline{2 - n}^{\frac{1}{n}} \times r}{2^{\frac{1}{n}}}$. Q. E. I.

577. Cor. 1. If the force vary directly as the diſtance from the center S, or $n = 2$, $x = \frac{\overline{2 - 2}^{\frac{1}{2}} \times r}{2^{\frac{1}{2}}} = 0$, and the body muſt fall to the center to acquire a velocity equal to that acquired in deſcending through $\frac{SA}{2}$, when acted upon by a conſtant force equal to that at A.

578. Cor. 2. If the force vary inverſely as the diſtance, or $n = 0$, $x = \frac{\overline{2 - 0}^{\frac{1}{0}} \times r}{2^{\frac{1}{0}}}$, which expreſſion does not ſhew the value of x: but it may be found by the following proceſs. The force at A or 1 : force at $O :: x : r$, and the force at $O = \frac{r}{x}$, and $\frac{r}{2} = r \times$ flu. $- \frac{\dot{x}}{x} = r \times -$ hyp. log. of $x +$ cor. $= r \times -$ log. of x $+ r \times$ log. of $r = r \times$ log. of $\frac{r}{x}$.

579. Cor. 3. If the force vary inverſely as the ſquare of the diſtance from S, or $n = -1$; $x = \frac{\overline{2 + 1}^{-1} \times r}{2^{-1}} = \frac{2}{3} \times r$, and the body muſt fall through a third of the diſtance SA, or to m. If the force vary according to any law therefore between the direct ſimple and inverſe duplicate ratio of the diſtance from S, the body muſt fall to ſome intermediate ſpace between S and m. If the force vary as that power of the diſtance inverſely, whoſe ex-

ponent is 3, 4, &c. or $n = -2, -3$, &c.; then $x = \frac{\overline{2+2}^{-\frac{1}{2}} \times r}{2^{-\frac{1}{2}}}$, $\frac{\overline{2+3}^{-\frac{1}{3}} \times r}{2^{-\frac{1}{3}}}$, &c. $= \frac{2^{\frac{1}{2}} \times r}{\overline{2}^{\frac{1}{2}}}$, $\frac{2^{\frac{1}{3}} \times r}{5^{\frac{1}{3}}}$, &c.; and the ſpace fallen through $= r - \frac{2^{\frac{1}{2}} \times r}{4^{\frac{1}{2}}}$, $r - \frac{2^{\frac{1}{3}} \times r}{5^{\frac{1}{3}}}$, &c.

FIG. CLXIV.

580. PROP. *Suppoſe the force at* A *to be* 1, *and in other places to vary as that power of the diſtance whoſe exponent is* n — 1, *it is required to determine the height to which a body will aſcend when acted upon by this variable force, and projected from* A *in the direction* SA *with a velocity equal to that acquired in falling through* $\frac{SA}{2}$, *as in the laſt propoſition.*

Let *B* be the place to which the body aſcends, and the force at *A* or 1 : force at any other point $O :: r^{n-1} : x^{n-1}$, and the force at $O = \frac{x^{n-1}}{r^{n-1}}$. But if the body were impelled by a conſtant force equal to that at *A*, it would aſcend through a ſpace equal to $\frac{r}{2}$, and (567) $\frac{r \times 1}{2}$ = the fluent of $\frac{x^{n-1}\dot{x}}{r^{n-1}} = \frac{x^n}{a \times r^{n-1}}$ + cor. $= \frac{x^n - r^n}{n \times r^{n-1}}$, and $\frac{n \times r^n}{2} = x^n - r^n$, and $x = \frac{\overline{n+2}^{\frac{1}{n}} \times r}{\overline{2}^{\frac{1}{n}}}$. Q. E. I.

581. Cor. 1. Suppoſe the force to vary directly as the diſtance from *S*, or $n = 2$; then $\frac{\overline{n+2}^{\frac{1}{n}} \times r}{\overline{2}^{\frac{1}{n}}} = \frac{4^{\frac{1}{2}} \times r}{2^{\frac{1}{2}}}$, and $x\ (= SB) : r :: 4^{\frac{1}{2}} : 2^{\frac{1}{2}} :: 2^{\frac{1}{2}} : 1$.

582. Cor. 2. If the force vary inverſely as the diſtance from *S*, or $n = 0$, $x = \frac{\overline{0+2}^{\frac{1}{0}} \times r}{2^{\frac{1}{0}}}$, which expreſſion does not ſhew the mag-

magnitude of x; but it may be determined by the proceſs in (578).

583. Cor. 3. If the force vary inverſely as the ſquare of the diſtance from S, or $n = -1$, then $x = \frac{\overline{2-1}^{\frac{1}{-1}} \times r}{\overline{2}^{\frac{1}{-1}}} = 2r = SD$.

If the force therefore vary according to any law between the direct ſimple and inverſe duplicate ratio of the diſtance from S, the body will riſe to ſome intermediate altitude between B and D. If the force vary inverſely as the cube of the diſtance, or $n = -2$, then $x = \frac{\overline{2-2}^{\frac{1}{-2}} \times r}{2^{-\frac{1}{2}}} = \frac{2^{\frac{1}{2}} \times r}{0}$, and is infinitely great. If therefore the force vary according to a law between the inverſe duplicate and triplicate, the body will aſcend to ſome intermediate ſpace between D and infinity.

CHAP.

CHAP. XIII.

PENDULOUS MOTION*.

FIG. CLXV.

584. DEF. *A BODY, or number of bodies, connected to a right line* SP, *and moving about a point* S *to which it is ſuſpended, by the force of gravity, is called a pendulum.*

585. DEF. *The motion of a pendulum in the ſame direction, from a ſtate of reſt, till it begins to return in an oppoſite direction, is one vibration or oſcillation.*

586. Cor. The velocity acquired in deſcending from P to V, ſuppoſing SV to be perpendicular to the horizon, will make the body P deſcribe an arc Vp, whoſe perpendicular altitude is equal to that of VP (542), and the motion through VP is equal to one half of a vibration. And becauſe a pendulum, compoſed of any number of bodies, will perform a given vibration, or equal parts of a vibration, in the ſame time as if they were collected in their center of oſcillation (512); a pendulum compoſed of any number of bodies may be reduced to one, where one body is connected to a right line SP, and the length of a pendulum is always underſtood to mean the diſtance between the centers of oſcillation and ſuſpenſion.

587. PROP. *If a body vibrate in a circular arc* P V p, *that part of the force of gravity, which accelerates and retards it, varies as the right ſine of the arc intercepted between the body and the loweſt point.*

DEM.

* Keil's Phyſ. Lect. XV. Helſham, Lect. X. Muſchenb. Ch. XII. CCXCVII. Maclaurin's Newt. Book II. Ch. V. Emerſon's Mechan. Prop. XI. Hugen. Horol. Oſcil. Part II. Prop. XVI. Rohault's Notes, Part II. Ch. XXVIII.

DEM. Let the force of gravity be repreſented, in quantity and direction, by a given line LP perpendicular to the horizon, and be reſolved into two forces, LM parallel to the ſtring SP, and PM touching the circle in P, of which LM is the tenſion of the ſtring and has no effect upon the body's motion, and it is accelerated and retarded by PM only; therefore the accelerating force (A) : force of gravity (G) :: $PM : PL :: PN : SP$ (ſim. triang.), and $A = \frac{G \times PN}{SP}$, and conſequently A varies PN. Q. E. D.

588. Cor. 1. The velocity at any point Q is equal to that acquired in falling through the perpendicular altitude ND (541), and varies as $\sqrt{ND}$, or $\sqrt{NV - VD}$, or $\sqrt{NV \times 2VS - VD \times 2VS}$, or $\sqrt{PV^2 - QV^2}$ (PV and QV being chords of the arcs PV and QV), or as the right ſine of a circular arc, whoſe radius is the chord PV, and verſed ſine the difference between the chords PV and QV.

589. Cor. 2. If the arc mV be ſuppoſed equal to two inclined planes mn and nV, touching it at m and V, theſe planes are equal, and the velocity in the horizontal plane nV is uniform, and the time of deſcribing it is equal to half the time of falling down mn (527): but the time of falling down mn (t) : time (T) of falling down mV ($= 2mn$), or down the diameter $2SV :: mn : mV :: 1 : 2$, and $t = \frac{T}{2}$; and conſequently the times of deſcribing mn and nV, or the time of half a vibration $= \frac{3T}{4}$, and the time of a whole vibration $: T :: 3 : 2$.

SCHOLIUM.

590. If the body P be acted upon by a force F, perpendicular to the horizon, which is to the force of gravity as the arc PV to its ſine PN, all vibrations are iſochronal; for, let SP repreſent the conſtant force of gravity, and $PL = F$; and by a reſolution of

PL

PL into two, LM parallel to SP, and PM coincident with the tangent, this laſt is the only part of F that accelerates P. But $PL : PS :: PM : PN$ (ſim. triang.), and $PL : PS :: PV : PN$ (hypoth.); and conſequently $PM = PV$, or the accelerating force is as the diſtance from the loweſt point V, and P will always arrive at V in the ſame time (563). The iſochronal force in a circle, F, is therefore equal to $G \times \frac{PV}{PN}$; and, when a pendulum is urged by the force of gravity, the time of a vibration will be encreaſed with the arc of vibration, becauſe the exceſs of F above G is encreaſed with that arc.

FIG. CLXVII.

591. DEF. *If a circle* FPE *revolve upon the right line* BA, *the curve line* BVA *deſcribed by any point* P *of the periphery in one revolution, is called a cycloid:* BA *is the baſe,* VD *biſecting* BA *at right angles is the axis,* V *the vertex,* PM *parallel to the baſe is an ordinate, and* FPE *is the generating circle, of the cycloid.*

592. Cor. Becauſe every point of the periphery of the generating circle has been applied to the baſe BA, it is evident that BA is equal to the periphery, and BD to the ſemiperiphery of the generating circle.

593. LEMMA. *If a circle be deſcribed upon the axis as a diameter, and an ordinate* PM *be drawn from any point* P, *the part of this ordinate* PL, *contained between the point from whence it is drawn and the periphery of the circle, is equal to the circular arc* VL, *contained between the vertex and the interſection of the ordinate and periphery.*

DEM. Let FPE be any poſition of the generating circle, and, becauſe every point of the arc PE has been applied to BE, the right line $BE =$ the arc $PE =$ the arc LD, and the arc $LV = ED = MN = PL$. Q.E.D.

594. Cor.

594. Cor. Because PL is always equal to the arc LV or PF, their cotemporary increments or decrements are equal, that is, the initial motions of the point P, which traces out the cycloidal arc, one parallel to the base BA, and the other in the direction of the tangent to the circle at P, are equal to each other.

595. LEMMA. *An ordinate being drawn from any point* P *of the cycloidal arc, cutting the periphery of the generating circle, whose diameter is the axis* VD, *in* L, *the chord* VL *of the circular arc is parallel to the line touching the cycloid at* P.

DEM. Let GP be a tangent to the circle at P, and producing EP to G, the $\angle CPq = \angle GPE = \angle GEP$ (the tangents DP and DE being equal, EUC. B. III. p. 36.) $= \angle EPN$: but the initial motions of P, in the directions GP and PL, being equal (594), the path of P or Pb will bisect the angle qPp (composition of motion), and consequently the $\angle CPb = \angle EPb$ or Pb is at right angles to EP, and FP, which is parallel to LK, is also perpendicular to EP, and therefore is a tangent to the curve at P. Q. E. D.

596. Cor. A tangent to the cycloid at the vertex V is therefore perpendicular to the axis VD and parallel to the base BA.

597. LEMMA. *The generating circle being described upon the axis as a diameter, and an ordinate being drawn from any point* O, *cutting the periphery of the circle in* R, *the cycloidal arc* VO *is equal to twice the corresponding chord of the circular arc* VR.

DEM. Draw an ordinate ro infinitely near to RO, and rs perpendicular to VR produced, and $Vr = Vs$, the angle at V being evanescent; and $Oo\ (= Rv)$ and Rr are cotemporary increments of the arc VO and chord VR: drawing tangents to the circle at V and R, the triangles VRT and Rrv, having the angles at R ver-

tical, and the angles TVR and Rvr alternate, are ſimilar, and conſequently $Rr = vr$ and Rv or $Oo = 2Rv$. The increment of the arc VO is therefore equal to twice the correſponding increment of the chord VR, and, becauſe they are naſcent and evaneſcent at the ſame time, $VO = 2VR$. Q. E. D.

FIG. CLXVIII.

598. PROP. *To make a body oſcillate in a given cycloid* AVB.

Produce the axis VD making $SD = DV$, and through S draw a line KSH parallel to BA, and let two circles, each equal to DLV, generate two ſemicycloids SA, SB, each equal to BV or AV; and if one extremity of a ſtring SCX, whoſe length is equal to SV or SCA, be fixed at S, a body collected in the other extremity X, will always be found in the cycloidal arc XVP; for, becauſe SCX is a tangent to the cycloid at C, CX is parallel to EA (595), and $CG = EA$; but $CX = 2AE$ (597) $= 2CG$ and $CG = GX$, and the ordinates XL and CE are equidiſtant from AD, or $AF = DN$, and the arc $AE =$ the arc LD, and the chord LD is parallel to AE or XG: but $AG = CE =$ the arc AE, and conſequently the remaining arc $HE(=LV) = GD = XL$, and X is in the cycloidal arc AXV (593).

599. Cor. Becauſe SCX touches the curve at C, it is evident that whilſt X deſcribes a very ſmall arc, C may be deemed quieſcent, or CX is always perpendicular to the cycloidal arc at X; and very near the vertex V, where SV is perpendicular to the curve, a circular arc, whoſe radius is SV, will coincide for a ſmall diſtance with the cycloidal arc.

600. PROP. *If a pendulum begin to vibrate from any point* P, *and a circle be deſcribed, whoſe radius is equal to the cycloidal arc* VP, *the velocity in different points will vary as the right ſine of an arc of this circle, whoſe verſed ſine is the ſpace deſcribed by* P.

DEM.

DEM. The velocity at any point Q is equal to that acquired in falling through the ſame perpendicular altitude NR (545), which is as $\sqrt{NR}$, or $\sqrt{NV-RV}$, or $\sqrt{NV\times VD-VR\times VD}$, or $\sqrt{VF^2-VE^2}$, or $\sqrt{VP^2-VQ^2}$, or $\sqrt{Vn^2-Vq^2}$, or qn. Q.E.D.

601. Cor. 1. The velocity therefore encreaſes from P to V, where it is the greateſt, being as $V\,v$, and then it decreaſes in ſuch a manner that the velocities at all equal diſtances from V are equal; and conſequently the cotemporary changes, or increments as the body accedes to V, and decrements as it recedes from it, are equal at equal diſtances from V.

602. Cor. 2. If s be the number of inches through which a body deſcends from reſt by the force of gravity in 1″, and V be the velocity acquired in vibrating through PQ, or in falling down the perpendicular NR, then $NR : s$ as the ſquares of the velocities acquired in falling through NR and s, or as $V^2 : 4s^2$, and $V = \sqrt{NR\times 4s}$ $= \sqrt{4s\times\overline{NV-VR}} = \sqrt{\frac{4s}{DV}}\times\sqrt{FV^2-EV^2} = \sqrt{\frac{4s}{DV}}\times$ into the right line $\frac{qn}{2}$; and at the vertex the velocity is equal to $\sqrt{\frac{4s}{DV}}\times\frac{Vv}{2}$ inches in 1″.

603. Cor. 3. If a pendulum begin to oſcillate at different diſtances PV and QV from the vertex V, the velocities acquired at V in theſe different vibrations, are as $\sqrt{NV} : \sqrt{RV}$, or as $VF : VE$, or as $VP : VQ$; or the velocity acquired in vibrating from reſt is as the diſtance from the vertex at which it begins to vibrate.

604. Cor. 4. If s be the ſpace deſcribed from reſt, as in cor. 2. the velocities acquired at V, in vibrating from different points P

and $\mathcal{Q}$ are equal to $\sqrt{\frac{4s}{DV}} \times \frac{VP}{2}$, and $\sqrt{\frac{4s}{VD}} \times \frac{qn}{2}$, or such as would carry the body over these numbers of inches in 1″.

605. PROP. *The time in which the pendulum vibrates through any arc* QH, *is equal to the time in which a body would describe the corresponding circular arc* no *with the greatest velocity* Vv *continued uniformly.*

Let M be infinitely near to $\mathcal{Q}$, so that $\mathcal{Q}M$ may be described uniformly, and taking Vp, Vq, Vm, Vh, respectively equal to VP, $V\mathcal{Q}$, VM, VH, and drawing the right line nk parallel to Vp; nk (qm or $\mathcal{Q}M$) : nl :: qn : Vv, or $\mathcal{Q}M$ and nl are to each other as the velocities with which they are described, and are therefore described in the same time. The same may be proved of the other corresponding parts of $\mathcal{Q}H$ and no, which are, consequently, described in the same time. Q. E. D.

606. Cor. 1. The times of describing any arcs $P\mathcal{Q}$, $\mathcal{Q}V$ are to each other as the corresponding circular arcs pn, nv, because they are described with the same uniform velocity; and the time of a whole vibration is as the semiperiphery pvx.

607. Cor. 2. The velocity, with which $\mathcal{Q}M$ is described, is actually equal to $\sqrt{\frac{4s}{DV}} \times \frac{qn}{2}$, and the velocity with which nl is described, is equal to $\sqrt{\frac{4s}{DV}} \times \frac{Vp}{2}$. The time of a vibration is equal to the time in which a body would describe the semiperiphery pvx with an uniform velocity equal to $\sqrt{\frac{4s}{DV}} \times \frac{Vv}{2}$ inches in a second.

608. Cor. 3. If a body begin to oscillate from different points P and Q, the times of their vibrations are equal to the times of describing the semiperipheries of circles, whose radii are VP and VQ, with uniform velocities, which are respectively equal to $\sqrt{\frac{4s}{DV}} \times \frac{VP}{2}$, and $\sqrt{\frac{4s}{DV}} \times \frac{VQ}{2}$; but these times are as the spaces or semiperipheries divided by the velocities, or divided by their radii VP and VQ, and are consequently equal: the times therefore of all vibrations, however different, are equal.

609. Prop. *Supposing a pendulum to begin to oscillate from any point* P, *the time in which it performs one vibration, is to the time of descent down the axis as the periphery of a circle to its diameter.*

Dem. The times of descent down DV and FV are equal (538), and in this time a body would describe a space equal to $2FV$ or PV or pV, with the velocity acquired in falling down FV or PV continued uniform; but this is to the time of describing pvx with the same velocity, or to the time of one vibration (607) as the spaces described, or as $pV : pvx$, or as the diameter of a circle to its periphery. Q. E. D.

610. Cor. 1. The periphery of a circle, being to its diameter in a given ratio, it appears again that the times of all vibrations are as the times of descent down the axis, and consequently are given.

611. Cor. 2. The velocity with which the semiperiphery pvx is described, when the time of describing it is equal to a vibration, is equal to $\sqrt{\frac{4s}{DV}} \times \frac{PV}{2}$ (607), and the time is equal to $\frac{pvx}{\text{vel.}} = \frac{2pvx}{PV} \times \sqrt{\frac{DV}{4s}}$; and the time of falling down $DV = \sqrt{\frac{DV}{s}}$; con-

consequently the time of a vibration is to the time of falling down DV :: $\frac{2 \times pv \times}{PV} \times \sqrt{\frac{DV}{4s}} : \sqrt{\frac{DV}{s}} :: \frac{2 \times pv}{PV} \times \sqrt{\frac{1}{4}} : 1 :: 2PV$: $2PV$, the same analogy as that in this proposition.

612. Cor. 3. The times of vibrations in different cycloids, being equal to the times of descent down their axes multiplied into the same given quantity, will vary as the times of descent down the axes, or lengths of the pendulums; or supposing L to be the length of a pendulum, and T the time of a vibration, and to be variable; T will be as $\sqrt{L}$, and L as T^2.

613. Cor. 4. If the vibrations be very small, the string is not sensibly affected by the cycloidal arcs SA, SB, and the pendulum SP will describe a circular arc, and hence it appears that very small vibrations in circular arcs are performed in equal times. The times of descent down a circular arc and its chord are therefore unequal, the former being to the time of descent down the axis as half the periphery of a circle to its diameter; and the latter is equal to the time of descent down the diameter, or four times the axis, and is consequently to the time of descent down the axis as 2 : 1.

614. Cor. 5. If the pendulum begin to oscillate from B, half the time of a vibration is to the time of descent down the inclined plane BV as $BD : BV$; for half the time of a vibration is to the time of descent down the axis, as the semiperiphery of a circle to its diameter, or as $DFEV(BD)$ is to DV, and the time down DV : time down the inclined plane BV :: $DV : BV$, and, ex æquo, half the time of a vibration : time of descent down the inclined plane BV :: $BD : BV$.

615. Cor. 6. The space described by a falling body in 1″, may be discovered, if the length of a pendulum performing one vibration

tion in a ſecond be known: let the length of this pendulum be 39.2 inches, and (609) 1″: time of deſcent through $\frac{39.2}{2}$ (*t*):: periphery of a circle to its diameter :: 3.14159, &c. (*p*) : 1 and $t = \frac{1}{p}$. But $\frac{39.2}{2}$: ſpace fallen through in 1″ (*x*) :: $\frac{1}{p^2}$: 1² and $x = \frac{39.2}{2} \times p^2 = 193.1$ inches nearly = 16.1 feet nearly.

616. Cor. 7. The length of the pendulum performing one vibration in 1″, may be diſcovered, if the ſpace through which a body deſcends in 1″ be known; for let this ſpace = 193.1 inches, and (laſt cor.) the length of the pendulum $= \frac{2 \times 193.1}{3.14159}$ inches. = 39.2 inches.

617. Cor. 8. The time of one vibration may be diſcovered, if the length of the pendulum be known; for let L be the given length of the pendulum in inches, and T be the time of one vibration, and T : time of deſcent through $\frac{L}{2}$ :: 3.14159, &c. : 1 :: *p* : 1; but the time of deſcent through $\frac{L}{2} = \sqrt{\frac{L}{2s}}$, and conſequently $T = p \times \sqrt{\frac{L}{2s}}$ ſeconds, or parts of ſeconds. If $L = 39.2$ inches, and $s = 16.1 \times 12$ inches, $T = 3.14159 \times \sqrt{\frac{39.2}{2 \times 16.1 \times 12}}$ = 1″ nearly.

618. Cor. 9. The number of vibrations in a given time, being inverſely as the time of one vibration, will be as $\frac{1}{\sqrt{L}}$. If N be

the number of vibrations in a given time T, and t be the time of one vibration, then $N = \frac{T}{t}$; but, the length of the pendulum being L, $t = p \times \sqrt{\frac{L}{2s}}$, and consequently $N = \frac{1}{p} \times \sqrt{\frac{2s}{L}}$. If $T = 60 \times 60''$, then $N = \frac{60 \times 60}{3.14159} \times \sqrt{\frac{193 \times 2}{39.2}} = 60 \times 60$ very nearly.

619. PROP. *Let a pendulum, whose length is* L *inches, lose or gain any number of vibrations expressed by* n, *in any number of hours,* h, *to find the length of a pendulum that shall vibrate once in* 1″.

Let Y = the length of the pendulum required, and let the number of vibrations performed by Y in h hours, or $h \times 60 \times 60'' = m$, and L performs $m \pm n$, vibrations in h hours; but $L : Y :: m^2 \overline{m \pm n}^2$ (618) and $Y = L \times \frac{\overline{m \pm n}^2}{m^2}$.

620. PROP. *If the length of a pendulum and the force of gravity be variable, the time of an oscillation varies as the square root of the length of the pendulum* L, *divided by the square root of the force of gravity,* G.

DEM. The time of one oscillation varies as the time of descent down the axis, and that is as the square root of the axis directly and force inversely, or as $\sqrt{\frac{DV}{G}}$ (532), or as $\sqrt{\frac{L}{G}}$. Q. E. D.

621. Cor. 1. Therefore L is as $T^2 \times G$, and T being given, L is as G: if therefore the lengths of two pendulums, performing a vibration, or the same number of vibrations, in the same time be known,

known, the ratio of the forces of gravity, being the same with the ratio of these lengths, will consequently be known.

622. Cor. 2. Or, if the number of vibrations performed in the same time, in different places, by two pendulums whose lengths are L and l, be equal to m and $m+n$ respectively, the forces of gravity G and g, in the places of observation, may be found: for, the times of one vibration of the pendulums L and l are as $\sqrt{\frac{L}{G}}$: $\sqrt{\frac{l}{g}}$, and $m+n : m$ inversely as the times of one vibration, or as $\sqrt{\frac{L}{G}} : \sqrt{\frac{l}{g}}$ (620), and consequently $G : g :: m^2 \times L : \overline{m+n}^2 \times l$.

623. PROP. *That part of the force of gravity, which accelerates or retards a pendulum vibrating in a cycloid, varies directly as its distance from the vertex.*

DEM. Let the force of gravity be represented, in quantity and direction, by the line DV, and be resolved into two forces, DF parallel to the string, and VF parallel to the tangent at P, or direction in which P moves; and $VF (= 2VP)$, which only accelerates P, varies as VP. Q. E. D.

Otherwise: The velocities at Q and M are as qn, ml; the time of describing QM is as the included circular arc nl; and, supposing the time nl to be very small and given, the accelerating force at Q is as the change of velocity kl (453), or as $\frac{Vq \times nl}{Vn}$ (sim. triangles), or, because nl and Vn are given, as Vq or VQ. Q. E. D.

624. Cor. 1. The force accelerating or retarding the pendulum (A) : whole force of gravity (G) :: $VF : VD :: VP : VB$ and $A = \frac{G \times VP}{VB}$;

$\frac{G \times VP}{VB}$; and the tenſion of the ſtring : $G :: DF : DV$, and this tenſion $= \frac{G \times DF}{DV}$. At the vertex where $DF = DV$ the tenſion of the ſtring $= G$, and $A = o$; and, at B, $VP = VB$ and $A = G$, and the tenſion $= o$.

625. Cor. 2. The tenſion of the ſtring : force accelerating or retarding $P :: DF : VF :: \sqrt{DN} : \sqrt{VN}$ (ſim. triangles).

CHAP. XIV.

PROJECTILE MOTION.

626. DEF. *THE range or random of a projectile, is the rectilineal distance between the point of projection and impulse upon any obstacle; the horizontal range is called the amplitude; and the angle of elevation is the angle contained between the horizon and the direction of projection.*

627. PROP. *A body projected in any direction* DN, *and acted upon by a constant force,* G, *in a direction parallel to a right line* DO *inclined in any angle to* DN, *will describe a parabola.* FIG. CLXIX.

DEM. Let *DO* be described from rest, by the action of *G*, in the same time, *T*, in which *DE* is described by the velocity of projection, and, completing the parallelogram, the body will, at the end of the time *T*, evidently be at *R*; but *DO* varies as T^2 (526), or (because the velocity in *DN* is uniform from the first law of motion, and *T* varies as *DE*) as DE^2 or QR^2, which is a property peculiar to the common parabola. Q. E. D.

628. Cor. 1. The parameter belonging to any diameter *DO* is equal to $\frac{QR^2}{DO}$ or $\frac{DE^2}{ER}$ (conic sect.); and if the parameter belonging to any point *D* be equal to $\frac{DE^2}{ER}$, the parabola will pass through the point *R*.

629. Cor. 2. If the velocity of projection be the same, the parameter belonging to DO will be the same, whatever be the angle of projection; for the projectile velocity and G being given, DE, ER, and consequently $\frac{DE^2}{ER}$, or the parameter, are given.

630. Cor. 3. Let Υ be the space through which a body falls from rest, when acted upon by the constant force G, to acquire a velocity, V, equal to that in any point D of the curve, and let v be the velocity acquired in falling from E to R, by the action of same force G, and $V : v :: DE : 2ER$ (106): but $\Upsilon : ER :: V^2 : v^2$ (526) $:: DE^2 : 4ER^2$, and $\Upsilon = \frac{DE^2}{4ER} = \frac{1}{4}^{th}$ of the parameter belonging to DO.

631. Cor. 4. If G be the force of gravity, the axis and all diameters of the parabola, are perpendicular to the horizon; the velocities are equal at equal distances from the principal vertex; the time of arriving at the vertex of the axis, or at the greatest altitude, is equal to half the time of the flight; the parabola cuts the horizon, and all lines parallel to the horizon, in equal angles; and DE, which is parallel to the ordinate OR, is a tangent to the parabola at D.

FIG. CLXX.

632. Cor. 5. The velocity in different points varies in a subduplicate ratio of the parameter belonging to those points, or, if IX be the directrix and DI perpendicular to it, in a subduplicate ratio of DI or DS, S being the focus, or, in the same parabola, as the perpendicular SY upon the tangent DT. The horizontal velocity DH, determined by drawing perpendiculars from the body upon the horizon, varies as DE, and is consequently uniform; and the velocity, therefore, in any point D, being as DE, is as the secant of the angle of elevation; and at the principal vertex, the velocity in the curve and the horizontal velocity, are equal.

633. PROP.

633. PROP. *To find the directions in which a body, being projected with any velocity, V, from a given point* D, *will pass through any point* P. FIG. CLXXI.

Because V, or the number of feet uniformly described in 1″, with the velocity of projection, is given, the space DE, described from rest to acquire this velocity, is known, being equal to $\frac{V^2}{64}$ (art. 529). Draw DA, equal to $4DE$, perpendicular to the horizon, BC perpendicular to DA through its bisection G, and DC perpendicular to DP; and from C as a center, at the distance CD, describe a circle, and, if R, r, be the intersections of its periphery with a right line, passing through P perpendicular to the horizon, DR, and Dr will be the directions required; for (sim. triang.) $DA : DR :: DR : RP$, and $DA : Dr :: Dr : rP$, and DA (= the parameter) $= \frac{DR^2}{RP}$ or $\frac{Dr^2}{rP}$; and the parabola described by a body projected in either of the directions DR or Dr with the velocity V, will pass through P (628). Q. E. I.

634. Cor. 1. Because the arcs BR and Br are equal, the line DB makes equal angles with the corresponding directions DR and Dr. Drawing $B\mathcal{Q}$ a tangent to the circle at B, a body projected in the direction DB, will pass through $\mathcal{Q}$, and $D\mathcal{Q}$ is the greatest distance upon that line to which the body can be projected with the velocity V.

635. Cor. 2. If DP be horizontal, the range upon the horizon $=$ $DF = RN$, the sine of twice the angle of elevation FDR; for, by the property of the circle $\angle FDR = \angle RAD = 2 \angle RCD$. The horizontal range is therefore the greatest, when the angle of elevation is 45°, the sine of twice that angle, or of 90°, being equal to $\frac{1}{4}DA$, or $\frac{1}{4}$ of the parameter at D; or it is equal to the latus rectum, for that is always equal to $\frac{DM^2}{MV}$, which, in this case, is equal to $\frac{DC^2}{4 \times \frac{1}{4}DC} = DC$. FIG. CLXXII. Because

Because the sine of any angle varies as the radius or diameter, if the circle be described upon any other diameter DE or $\frac{1}{4}^{th}$ of DA, the horizontal range will be equal to the sine of twice the angle of elevation of this circle multiplied into $\frac{DA}{DE}$, or into 4.

636. Cor. 3. If the axis MV, produced, be intersected by the tangent in T, the greatest altitude $MV = \frac{1}{2}MT$ (conic sect.) $= \frac{1}{4}FR = \frac{1}{4}^{th}$ of the versed sine of twice the angle of elevation; and when this angle is right, $\frac{1}{4}^{th}$ of the versed sine $= \frac{1}{4}DA$. Because the versed sines of any angles are as the diameters of the circles described, if the circle be described with a diameter equal to DE, the altitude is equal to the versed sine of twice the angle of elevation of this circle.

637. Cor. 4. The time of the flight is equal to the time of describing DR with the projectile velocity, and varies as DR, or as $\frac{1}{2}DR$, which is the sine of the angle of elevation; and consequently the time is the greatest when the angle $FDR = 90°$, and it is then equal to the time of descent from rest through the parameter AD. The time is also equal to the time of falling from rest through RF, and therefore varies as $\sqrt{RF}$, or as the square root of the versed sine of twice the angle of elevation, or as the square root of $\frac{1}{4}RF$, or the greatest altitude.

638. PROP. *The velocity of projection,* V, *and the angle of elevation being given, to describe the path of the projectile.*

FIG. CLXXIII.

Let V be the number of feet uniformly described in 1″, and $\frac{V^2}{64} = DE = \frac{1}{4}^{th}$ of the parameter, is the same whatever be the angle of elevation, and the periphery of a circle, whose radius is DE, and center D, will pass through the foci of all parabolas described by a body projected from D with the velocity V. Let DE be perpendicular to the horizon, and DR the direction of pro-

projection, and making the angle $SDR = \angle RDE$; S will be the focus; EX drawn perpendicular to DE is the directrix; V the bisection of SX drawn parallel to DE, is the principal vertex, and SV the axis; DM perpendicular to VM is an ordinate; SE bisects DT in R and is perpendicular to it, and RV is a tangent to the parabola at V (conic sect.).

Q. E. D.

639. Cor. Again, it appears that the amplitude DF is (as in art. 635) equal to four times the sine of twice the angle of elevation, for $\angle MDR = \angle RDC = 2\angle RCN$, and $DF = 2DM = 2NV = 4RN$.

FIG. CLXXIV.

640. PROP. *To find the least velocity with which a body projected, from a given point* D, *will hit a given point* P.

Draw BPH perpendicular to the horizon, and, making PB equal to PD joined, bisect the angle DPB by the right line PC, meeting DG perpendicular to DP, in C; and, because the triangles CBP and CDP are equal and similar, $CB = CD$, the $\angle$s CBP and CDP are right angles, and BP is a tangent to the circle described from C, as a center, at the distance CB. Bisect DG, drawn perpendicular to the horizon, in E, and a body projected in the direction DB, with a velocity equal to that acquired in falling through ED, will pass through P (634), and, because DP is the greatest range (634), the velocity must be the least possible. Q. E. I.

641. Cor. If P be in the horizon, CD and GD coincide, and the angle of elevation BDH is equal to 45°.

FIG. CLXXI.

642. PROP. *The range upon any plane* DP, *is equal to the product of the parameter and sines of the angles formed by the plane and direction of projection, and the plane and a perpendicular to the horizon, divided by the square of the cosine of the plane's elevation.*

DEM.

DEM. From trigon. $DP : DR ::$ fin.$\angle DRP$ or $\angle ADR$: fin.$\angle DPF$, $DR : DA ::$ fin.$\angle DAR$ or $\angle PDR$: fin.ARD or $\angle RPD$ or DPF; and conſequently $DP : DA ::$ fin.$\angle ADR \times$ fin.$\angle PDR$: fin.$^2 \angle DPF$ or cof.$^2 \angle PDF$, and $DP = \frac{DA \times \text{fin.} \angle ADR \times \text{fin.} \angle PDR}{\text{cof.}^2 \angle PDF}$.

Q. E. D.

FIG. CLXXV.

643. Cor. 1. Let $S =$ the ſine of the angle contained between the plane and the direction; $\mathfrak{Q} =$ the ſine of the angle contained between the direction and the parameter DA perpendicular to the horizon; and $C =$ the coſine of the angle contained between the plane and the horizon; and the range $DP = \frac{DA \times S \times \mathfrak{Q}}{C^2}$, and, becauſe DA varies as the ſquare of the velocity, or V^2, DP is as $\frac{V^2 \times S \times \mathfrak{Q}}{C^2}$.

This corollary may be demonſtrated differently by the following proceſs: let V be the velocity of projection, or number of feet deſcribed uniformly in 1″, and $V : DR :: 1'' : \frac{DR''}{V} =$ the time of deſcribing DR or RP, and $RP = 16 \times \frac{DR^2}{V^2}$ (529) $= DP \times \frac{S}{\mathfrak{Q}}$; but $DR = DP \times \frac{C}{\mathfrak{Q}}$, therefore $DP \times \frac{S}{\mathfrak{Q}} = 16 \times \frac{DP^2 \times C^2}{V^2 \times \mathfrak{Q}^2}$, and conſequently $DP = \frac{S \times \mathfrak{Q} \times V^2}{16 \times C^2}$.

644. Cor. 2. If DP be biſected in M and MV be drawn perpendicular to the horizon, the greateſt altitude $MV = \frac{1}{2} MT = \frac{1}{4} PR$; but $PR : DP :: S : \mathfrak{Q}$ and $PR = \frac{DP \times S}{\mathfrak{Q}} =$ (ſubſtituting the value of DP) $\frac{V^2 \times S^2}{C^2}$; and conſequently MV, or the greateſt altitude varies as $\frac{V^2 \times S^2}{C^2}$.

645. Cor.

645. Cor. 3. The time of the flight is equal to the time of describing DR, and is as $\frac{DR}{\text{vel.}}$; or, if V = the number of feet described uniformly in 1″ with the velocity of projection, the time is actually equal to $\frac{DR''}{V} = \text{(fig. 171.)}\ \frac{DA \times S}{C \times V}$; and because DA is as V^2, the time varies as $\frac{V \times S}{C}$. The time is also equal to the time of descent from rest through RP, and consequently varies as $\sqrt{PR}$, or as $\sqrt{MV}$. FIG. CLXXV.

646. Cor. 4. Supposing V to be given, the range DP is the greatest when $S = 2$, or when the direction bisects the angle contained between the plane and the vertical DA; and if the plane DP coincide with the horizon, the amplitude $DP = DF \left(= \frac{DA \times S \times 2}{C^2}\right) = \frac{DA \times FR \times DF}{DR^2}$ (making DR the radius) = DF or RN the sine of twice the angle of elevation, DA being equal to $\frac{DR^2}{FR}$, and $\frac{DA \times FR}{DR^2}$ being given. The greatest altitude $= \frac{DA \times S^2}{4C^2} = \frac{DA \times FR^2}{4DR^2} = \frac{1}{4}FR$.

647. PROP. *If both the velocity of projection,* V, *and the angle of elevation, vary, the horizontal range or amplitude will vary as the square of the velocity and sine of twice the angle of elevation.*

DEM. The range, being generally as $\frac{V^2 \times S \times 2}{C^2}$ (643), will, when DP coincides with the horizon, be as $\frac{V^2 \times S \times 2}{\text{rad.}^2}$; and, if the radius be unity, $S \times 2 = \frac{1}{2}$ of the sine of twice the angle of elevation (trigonom.), and the amplitude consequently is as $V^2 \times$ sine of twice that angle, Q. E. D. FIG. CLXXI.

Another demonſtration:

FIG. CLXXVII.

Let V = the number of feet deſcribed uniformly in 1″, by the velocity of projection, and $V : DL :: 1'' : \frac{DL''}{V}$, or the time of deſcribing DL with the velocity of projection, which is equal to the time of deſcribing LF from reſt, and $LF = \frac{s \times DL^{2''}}{V^2}$, ſuppoſing s to be the deſcent from reſt in the firſt ſecond (529); but, deſcribing a circle with any diameter DA, $LF = \frac{DL \times DR}{DA}$ (ſim. triang.); and conſequently $\frac{s \times DL^2}{V^2} = \frac{DL \times DR}{DA}$, and $DL = \frac{DR \times V^2}{s \times DA}$; and $DF \left(= \frac{DL \times RN}{DR} \text{ from ſim. triang.}\right) = \frac{RN \times V^2}{s \times DA}$, and varies as $V^2 \times RN$, becauſe s and DA are given. Q. E. D.

648. Cor. The greateſt altitude is generally as $\frac{V^2 \times S^2}{C^2}$ (644), or when DP is horizontal, as $\frac{V^2 \times S^2}{\text{rad.}^2}$, or, the radius being unity, as $V^2 \times$ verſed ſine of twice the angle of elevation; for $S^2 = \frac{1}{4}$ of this verſed ſine.* This corollary is alſo deducible from the ſecond demonſtration; for the greateſt altitude $= \frac{LF}{4} = \frac{DL \times DR}{4DA} =$ (ſubſtituting the value of DL) $\frac{DR^2 \times V^2}{4s \times DA^2} = \frac{V^2 \times DN}{4s \times DA}$, and conſequently varies as $V^2 \times DN$, s and DA being given.

649. PROP.

FIG. CLXXVI.

* Let the arcs DF, EF, and the angles DCF and ECF, be equal, and, FCD being the angle of elevation, EL drawn perpendicular to the radius CD, is the ſine, and DL the verſed ſine, of twice that angle; and, joining ED and drawing GH from G, the interſection of CF and ED, parallel to DL, $EH = \frac{1}{2}$ the ſine, and $GH = \frac{1}{2}$ the verſed ſine. But the triangles EGH and ECG are ſimilar, the angles at H and G being right, and the $\angle EGH = \angle EDC = \angle CED$; therefore $EG\ (= FN = S) : EH :: CE\ (= 1) : CG\ (= CN = 2)$, and $EH = S \times 2$. And EG or $S : GH\ (= \frac{1}{2}LD) :: CE : EG$, and conſequently $GH = S^2$.

1. Let the parameter $= P$, and, when the angle of elevation is 45°, the amplitude $= \frac{P}{2}$; therefore, the fin. of $2E$: fin. of 90° :: given amplitude : $\frac{P}{2}$, which is therefore known; and the velocity of projection, being equal to that acquired in falling from reſt through $\frac{P}{4}$, is alſo known, being equal to $\sqrt{4s \times \frac{P}{4}}$ feet in 1″ (529).

2. The altitude is found when the parameter is known, by the laſt propoſition.

FIG. CLXXVII.

Or, The altitude is eaſily found by the following proceſs: Biſect the amplitude DF in M, and, drawing MT perpendicular to DF, the angles in the triangle DMT, and the ſide DM, are known, and MT may be found from trigonometry; and conſequently $MV = \frac{1}{2}MT$ is known. Q. E. I.

SCHOLIUM.

651. By a ſimilar proceſs the converſe of theſe propoſitions are eaſily ſolved, that is, 1. the amplitude and altitude being given, to find the velocity of projection and angle of elevation; 2. the velocity of projection and altitude being given, to find the amplitude and angle of elevation; and, 3. and the angle of elevation and altitude being given, to find the amplitude and velocity.

SCHOLIUM II.

652. In the theory of projectiles, the medium is ſuppoſed to be void of reſiſtance, which ſuppoſitiou does not obtain in practice, the reſiſtance of the air being variable according to the different velocities and magnitudes of the projectiles, and always conſiderable.

able. 1. If a muſket ball, of $\frac{1}{4}^{th}$ of an inch diameter, be fired, from a piece forty-five inches long, with half its weight of powder, its velocity is nearly 1700 feet in 1″, and its horizontal range, when the angle of elevation is 45°, ought to be about ſeventeen miles; but from practical writers it appears, that the range is leſs than half a mile. An iron ball of 24 lb. weight, diſcharged with a full charge of powder, has a velocity of 1650 feet in 1″, and its horizontal range at 45° would be about ſixteen miles, were the path deſcribed a parabola; but, from experiments, it appears not to be three miles, and not $\frac{1}{5}^{th}$ part of the ſpace inveſtigated by the theory. When the velocity of the ſhot is about 400 feet in 1″, the reſiſtance of the air is ſtill conſiderable, and neither the amplitude, height or time of flight, correſpond with the theory. This reſiſtance is confirmed by the conſtant obſervation of all converſant in the projection of bombs; for the ranges at elevations equally diſtant from 45°, ought, according to the theory, to be equal; but the ranges of a ſhell projected at an elevation of 15° or 20°, are always found to be greater than thoſe projected at elevations equal to 60° or 65°, though equally diſtant from 45°.

Projectiles, whoſe motion is ſenſible to the eye, are ſeen to deſcend in a curve obviouſly ſhorter, and inclined in a greater angle to the horizon, than that in which they aſcended; and whoever views, in a proper ſituation, the flight of ſtones, arrows, ſhells, &c. projected to any conſiderable diſtance, may ſee evidently that the vertex of the curve or greateſt altitude, divides the path deſcribed into two unequal parts, and is more remote from the point of projection, than where the projectile falls to the ground.

SCHOLIUM III.

653. A body, projected with a conſiderable velocity, is often not only affected by the reſiſtance of the air, and deflected from a parabolic path in a direction perpendicular to the horizon, but is made to deviate laterally and change the plane of motion. The path of a tennis-ball, ſtruck with great force, is plainly obſerved to be incurvated ſideways as well as downwards, and to move in a different plane from that ariſing from the combined

bined action of gravity and force of projection. Bullets are not only depreſſed beneath the line of projection, but deflected to the right or left of that direction by the reſiſtance of the air, or action of ſome other force. Mr. Robins fixed a barrel, carrying a ball of $\frac{3}{4}^{ths}$ of an inch diameter, and, firing at a mark, one foot and $\frac{1}{7}^{th}$ ſquare, at the diſtance of 180 feet, miſſed it only once in ſixteen ſucceſſive trials; but when the ſame barrel was fired with a ſmaller quantity of powder, he found the ball to be deflected 100 yards to the right or left of the line aimed at and placed at the diſtance of 760 yards; and its direction in the perpendicular was equally uncertain, its range differing ſometimes 200 yards. Becauſe the force of gravity acts always in a direction perpendicular to the horizon, a body projected in any direction would, if unreſiſted, be always in the ſame vertical plane, which, as is obſerved, is not true in fact; and, therefore, beſides the reſiſtance of the air to the progreſſive motion of the body, there is another lateral force producing a deviation from the plane of projection, which is probably the inequality of reſiſtance upon its ſurface: for, if the ſurface of a projectile, protruding the particles of a fluid, be equally reſiſted in every point, it is obvious that the plane in which it firſt moves is not altered. But ſuppoſing the reſiſtances upon different ſides of a body to be unequal, it will be impelled, by the greater reſiſtance, towards thoſe parts where the reſiſtance is leaſt; and thus either diverge laterally from the firſt plane of motion, or aſcend, or deſcend in that plane, beyond the altitude inveſtigated by the theory. A motion of rotation round an axis will produce this inequality of reſiſtance upon the different ſides of a projectile, and conſequently its irregular motions; for the parts of a revolving body are expoſed to the air, which is protruded, in different angles of obliquity and with different forces, and muſt therefore be differently reſiſted. If the axis of rotation be perpendicular to the direction, the body will be deflected naturally from the vertical plane; and becauſe the velocity of the body, and conſequently reſiſtance of the air, are variable, this deflection will be different in different points, or it will be a curve line. That this lateral deviation is produced by a motion of rotation ſeems to be confirmed by experiments. Let a ſphere of wood, ſuſpended freely by a cord in a

current

current of air, be made to revolve round a ſtring as an axis, and the parts of its ſurface, on oppoſite ſides, oppoſing or conſpiring with the motion of the particles of the fluid, are unequally impelled by it, and the ſphere is always deflected towards that ſide whoſe reſiſtance is leaſt. Or, let a wooden ball, loaded with lead, be ſuſpended freely in a ſtream of water by a twiſted cord; and, as the cord returns to its natural ſtate, the ball revolves round it, and moves gradually towards the ſide where the reſiſtance is leaſt, or where the parts conſpire with the motion of the water. When the ball arrives at its utmoſt extent, it is quieſcent for a moment, and returns gradually to its firſt ſituation, and is again quieſcent till the motion of the ball twiſt the cord the contrary way, and it then moves alſo towards the other ſide; and in this manner the ball continues to vibrate till its motion be deſtroyed by friction, and it remain quieſcent in its firſt ſituation. The magnitude and direction of reſiſtance of the air, and conſequent deviations from theory, can only be aſcertained by a ſeries of experiments, which, reſulting from the operation of cauſes apparently fluctuating and uncertain, produce an inconſiſtency in the ſame experiments, and render the ſubject at leaſt very complicated and difficult *.

* See Robins's Tracts of Gunnery, p. 183, &c. and Euler's True Principles of Gunnery, by Mr. Brown.

ERRATA ET ADDENDA.

Pag. 2. lin. 7. *for* of that, *read* that.
10. art. 15. *for* the exiſtence of ratios, *read* the exiſtence of the meaſures of ratios.
24. art. 48. ex. 1. for *LA*, read *Lm*, and for *La*, read *LA*.
29. ex. 2. *dele* or cloſeneſs.
37. art. 78. *for* all infinitely great, &c. *read* all infinitely great or ſmall magnitudes compared with each other, admit of the ſame inequality of ratios with finite magnitudes.
42. art. 85. *dele* the remoteneſs of the elementary particles.
67. lin. 8, *after* velocity, *read* when in motion.
fig. 26. the letters *L*, *M*, wanting.
81. art. 194. *for* *MBN*, *read* *PBN*.
82. art. 200. *after* *BD*, *put* *BE*.
83. art. 204. *dele* in the ſame direction.
fig. 48. the letter *D* wanting.
111. ex. 3. *for* fire, *read* fibre.
115. line the laſt. *after* velocities, *put* in oppoſite directions.
148. . *for* fig. 16. *read* fig. 106.
152. l. . by the direction of the reſiſtances is underſtood the right line in which the reſiſting forces act, and by *the quantities of the reſiſtances* are underſtood, not the quantities really exerted upon the wedge, but which would be exerted if no part were loſt.
186. the following corollary wanting to art. 470. If the circle does not cut or touch the line *DH*, the bodies will never meet.
197. art. 500. *for* ± velocity of $V \times SA$, *read* $= \frac{\text{velocity of } V \times SA}{SV}$.
198. art. 500. l. 2. for $m \times SV$, read $m \times SV \times SC$.
231. art. 589. *for* arc, *read* chord, in which corollary, the body is ſuppoſed to vibrate in the chords.

RUSTICI BRITANNICI

Plate I.

FIG. I.

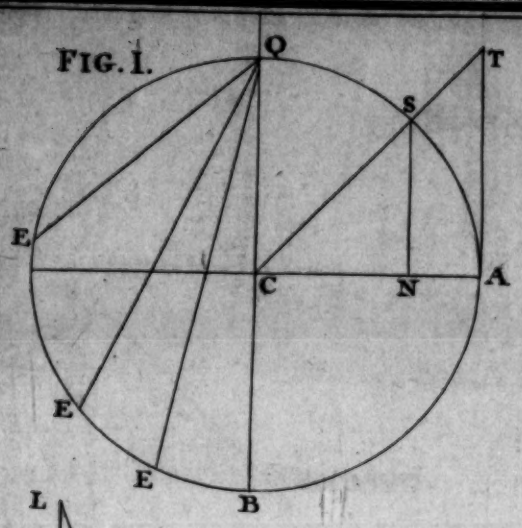


FIG. II.

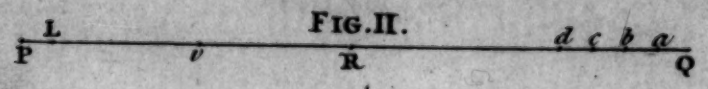


FIG III

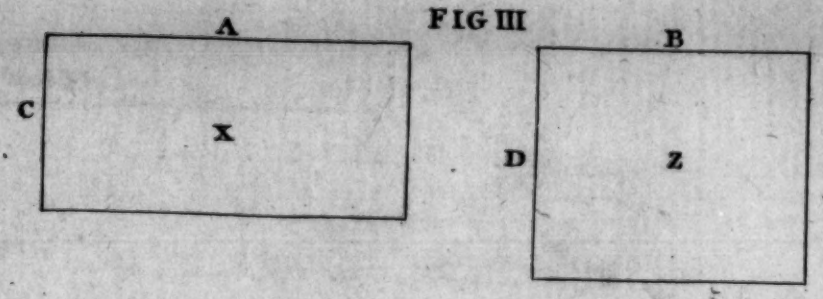


FIG. IV.

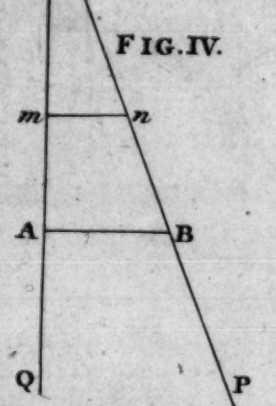


FIG. V.

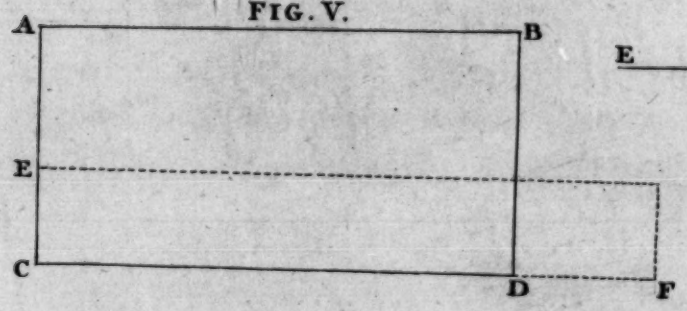


FIG. VI.

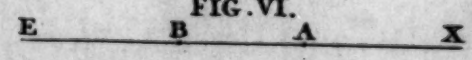


FIG. VII.

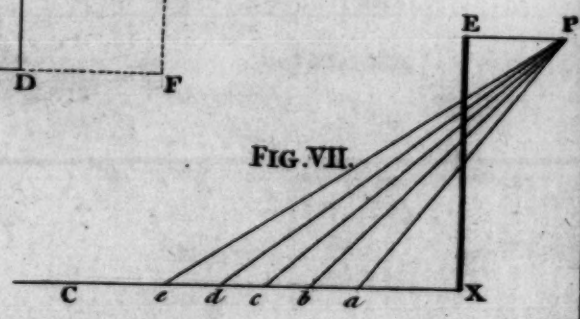


FIG. VIII.

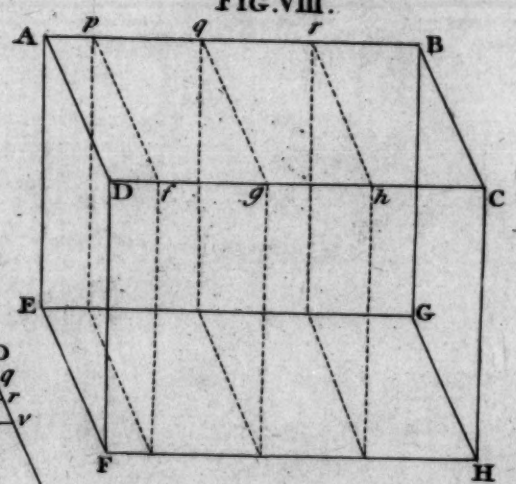


FIG. X.



FIG. XI.

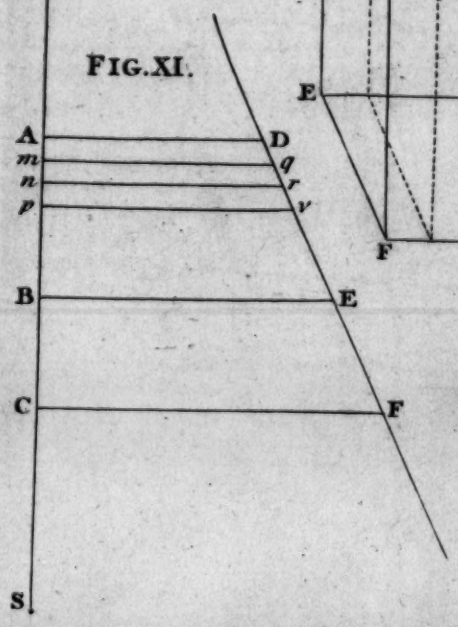


FIG. IX.

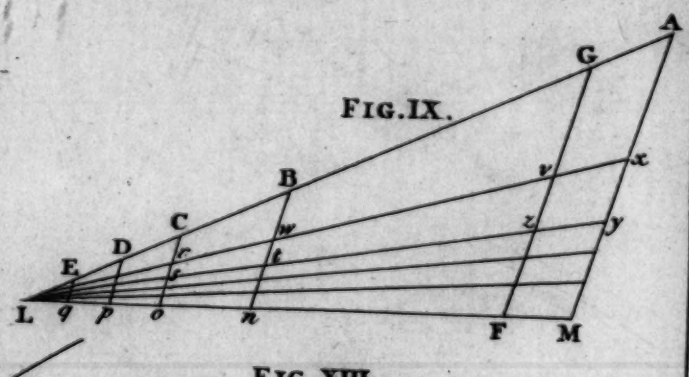
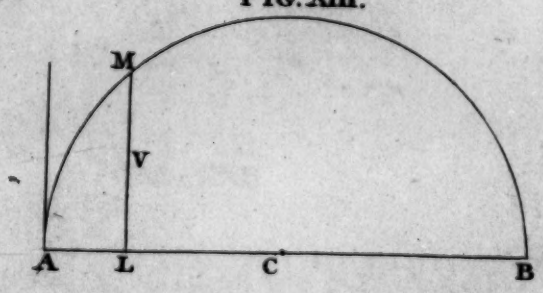


FIG XII



FIG. XIII.



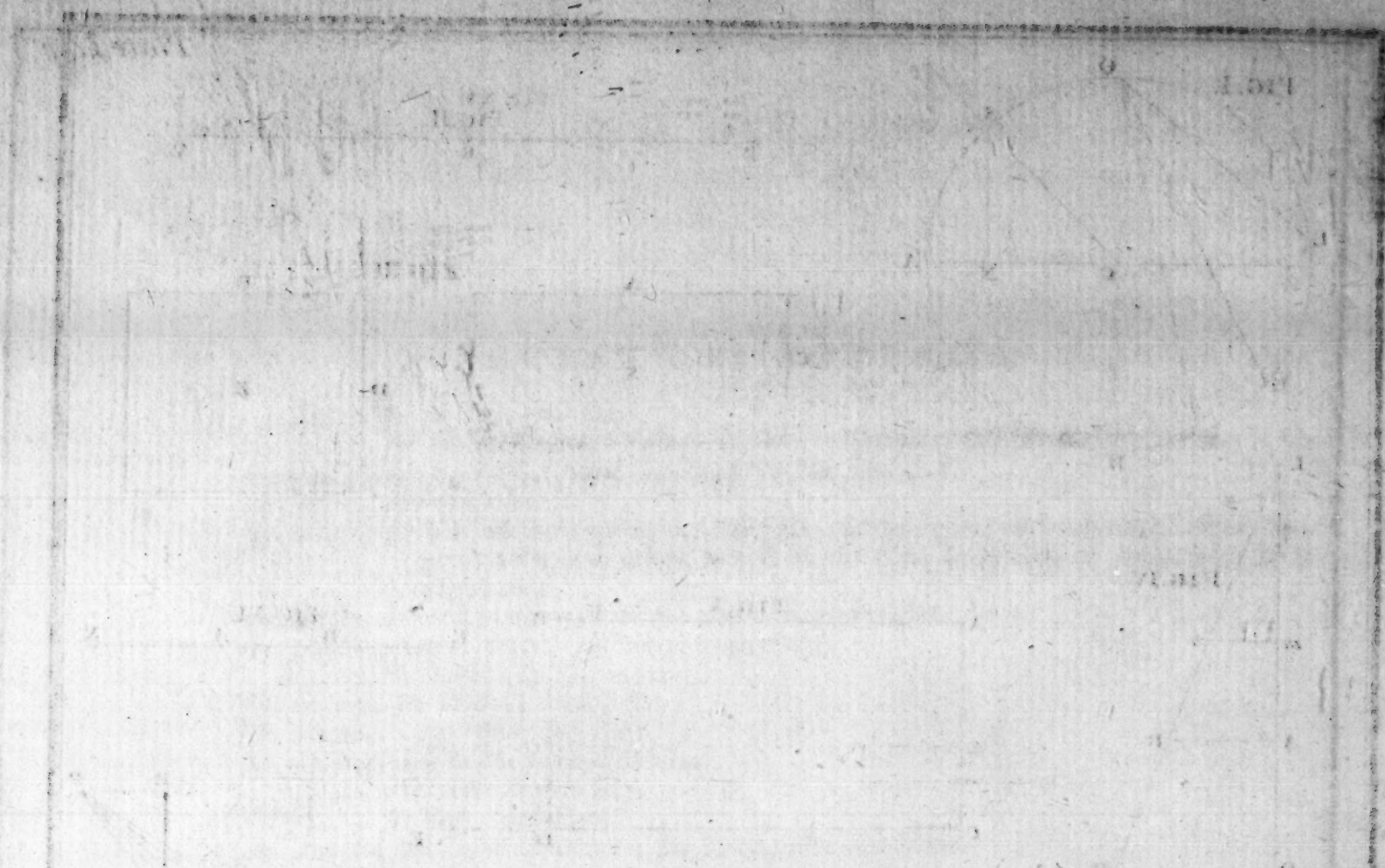
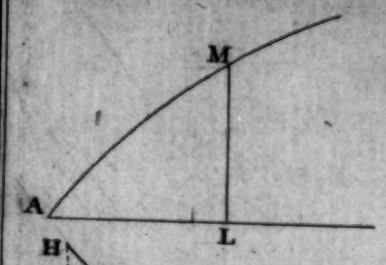


FIG. XIV.



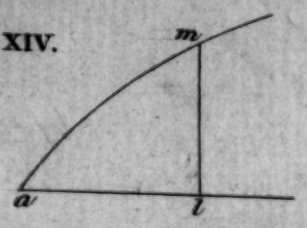


FIG. XV.

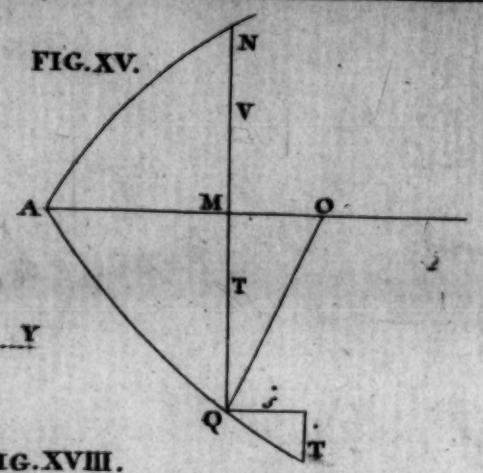


FIG. XVI.

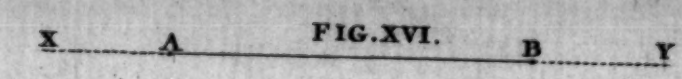


FIG. XVII.

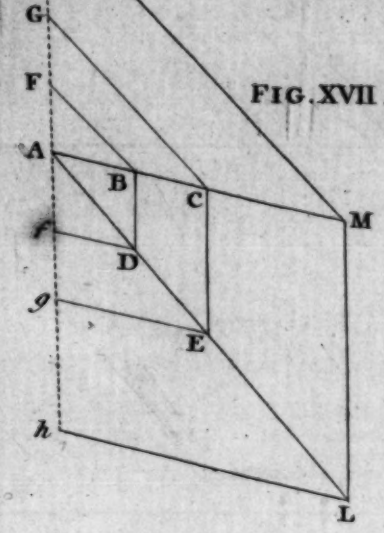
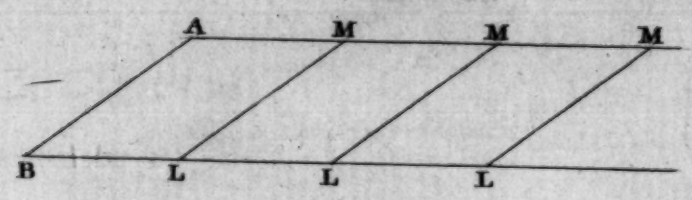


FIG. XVIII.



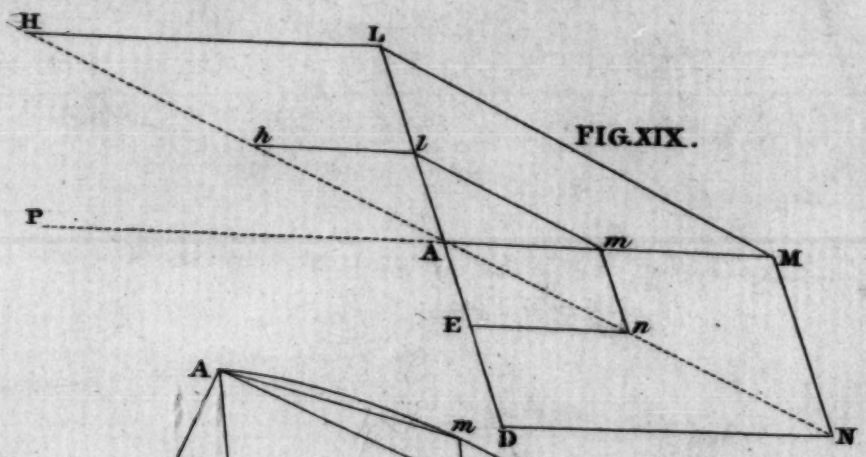
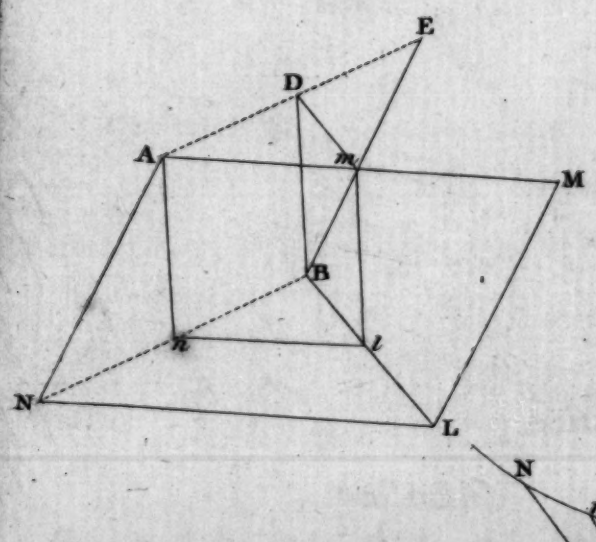


FIG. XIX.

FIG. XX.



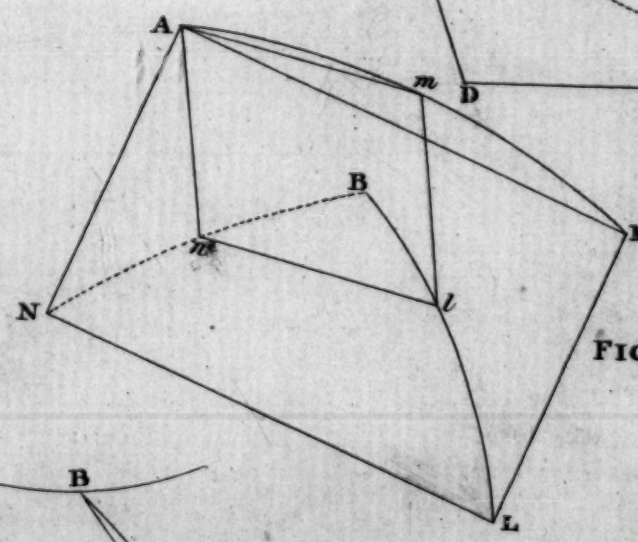


FIG. XXI.

FIG. XXII.

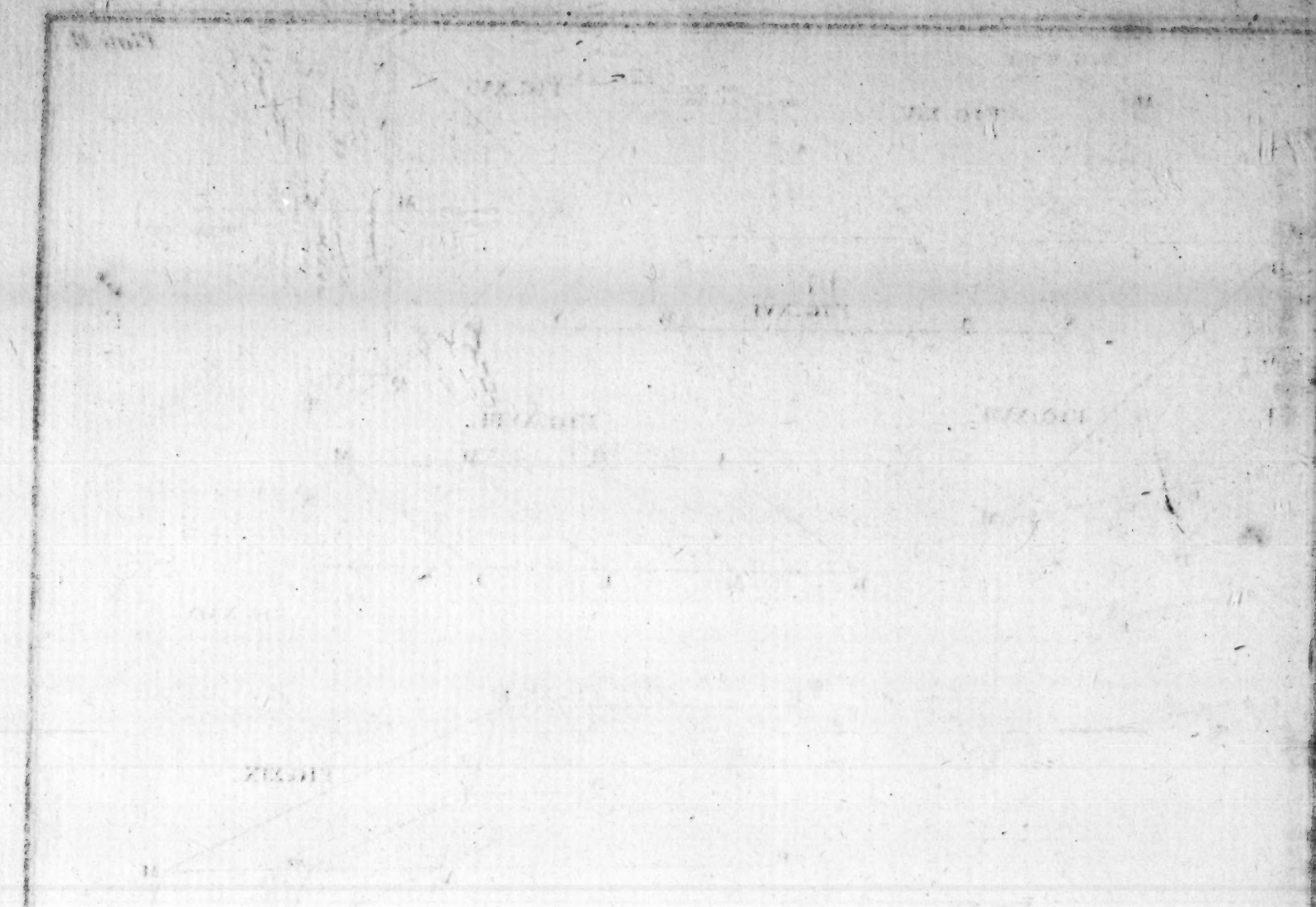


FIG. XXIII.

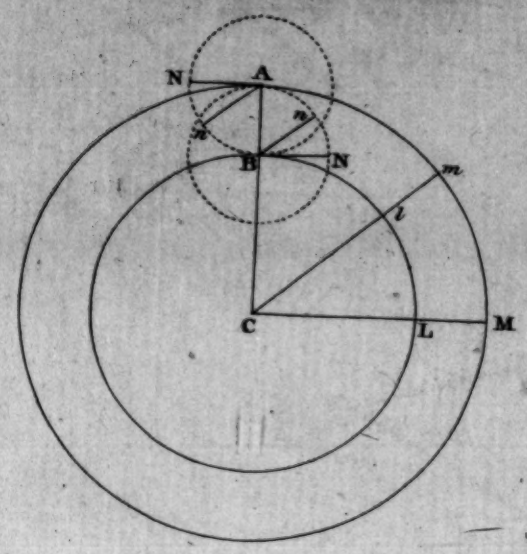
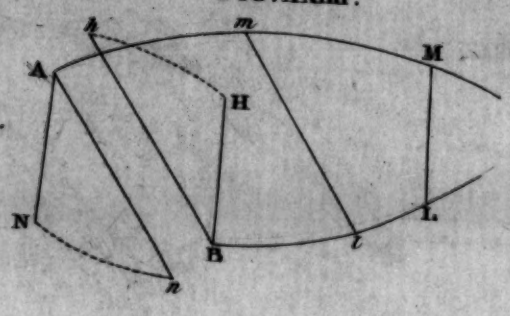


FIG. XXIIII.



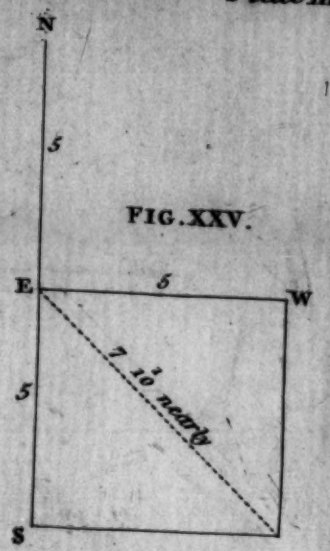


FIG. XXV.

7. 10. nearly

FIG. XXVI.

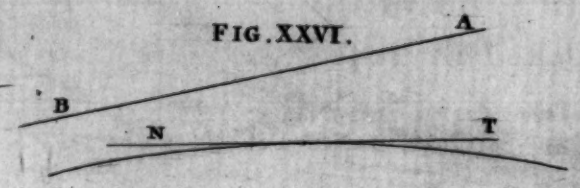
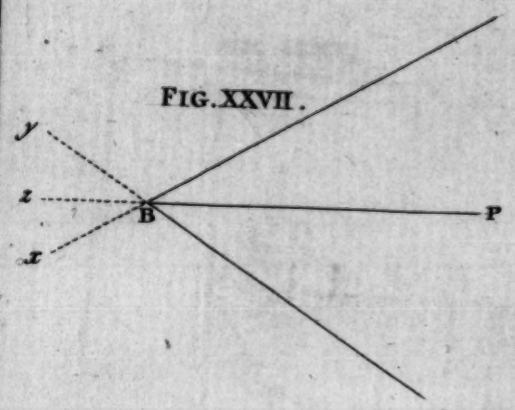


FIG. XXVII.



S.

FIG. XXVIII.

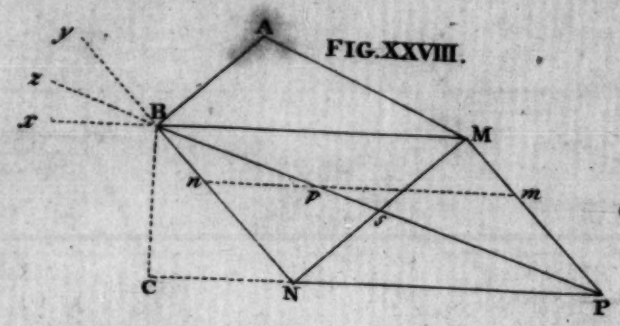


FIG. XXIX.

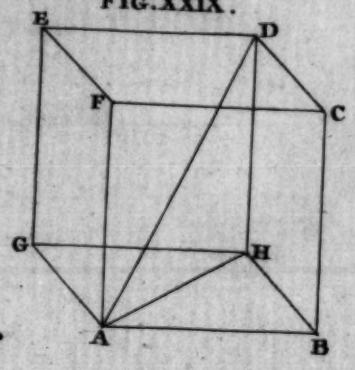


FIG. XXX.

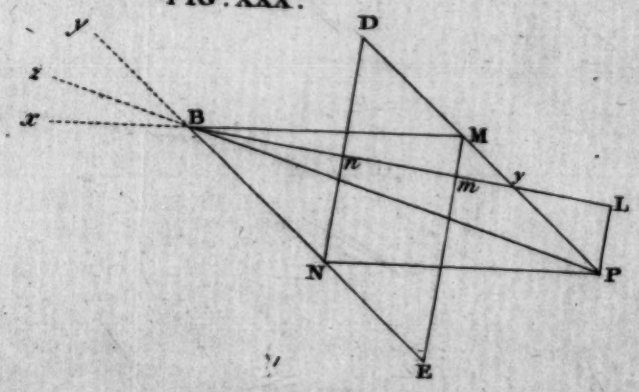


FIG. XXXI.

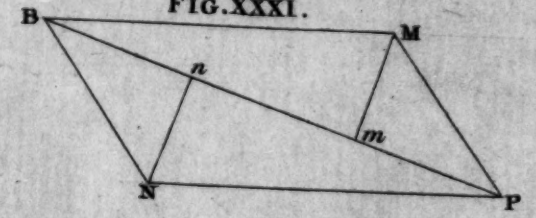


FIG. XXXII.

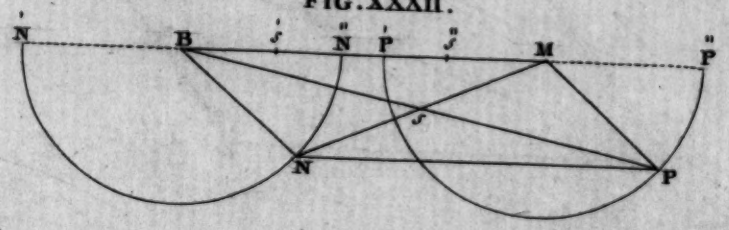
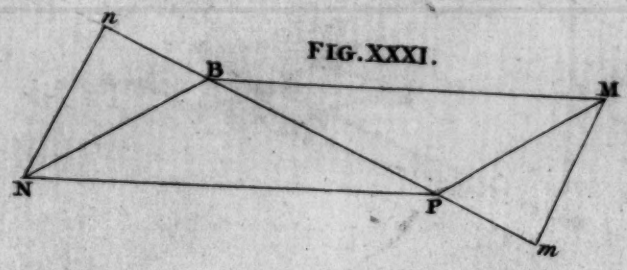


FIG. XXXI.



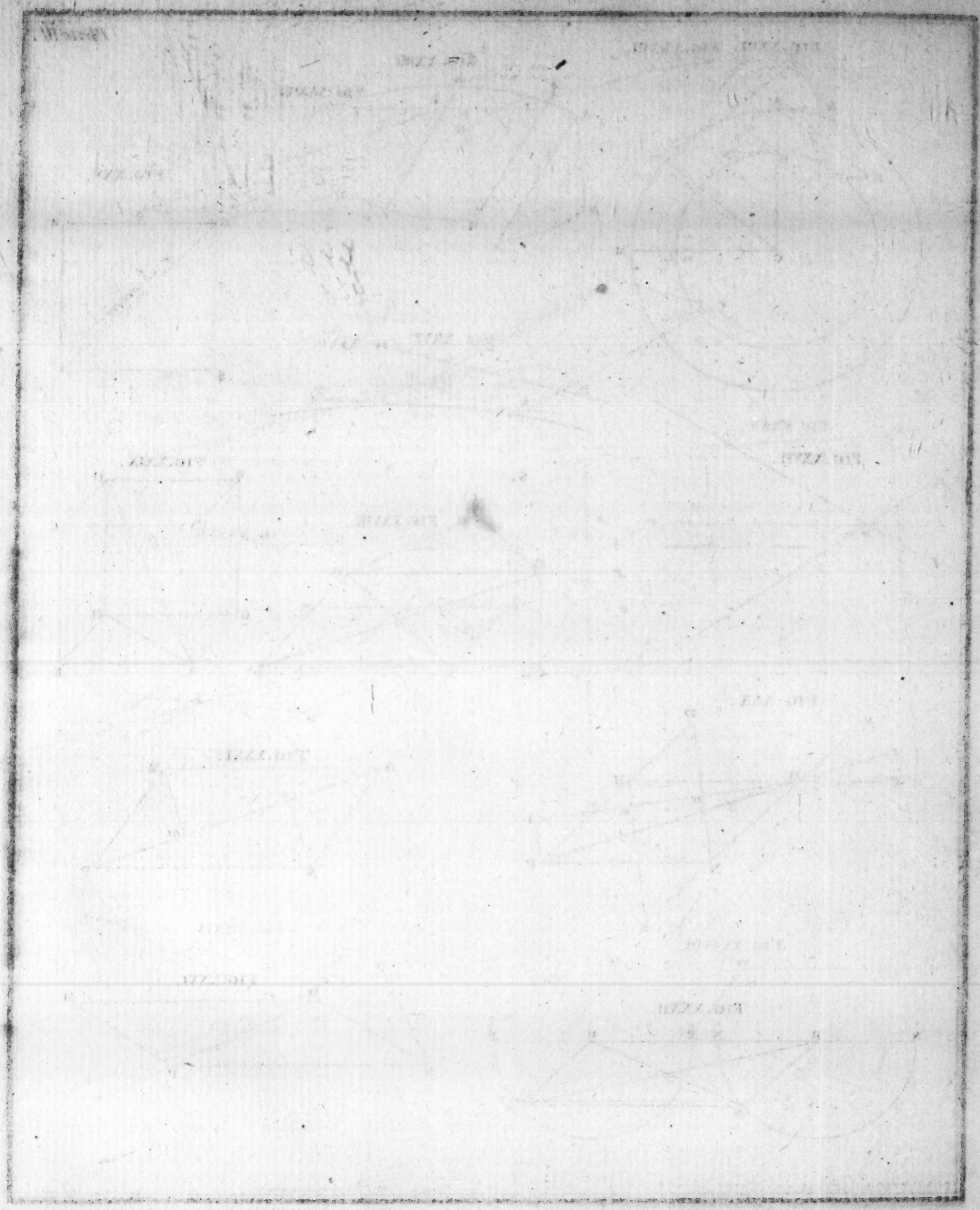


FIG. XXXIII.

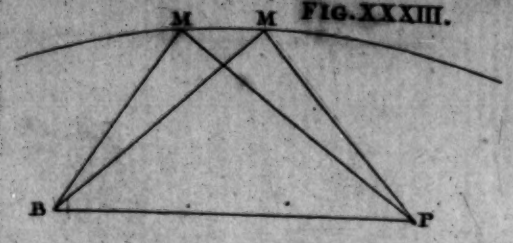


FIG. XXXIIII.

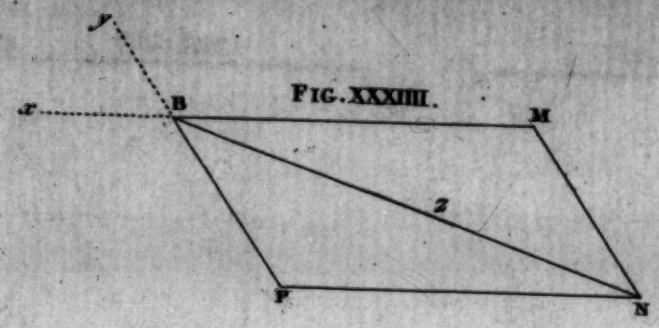


FIG. XXXV.

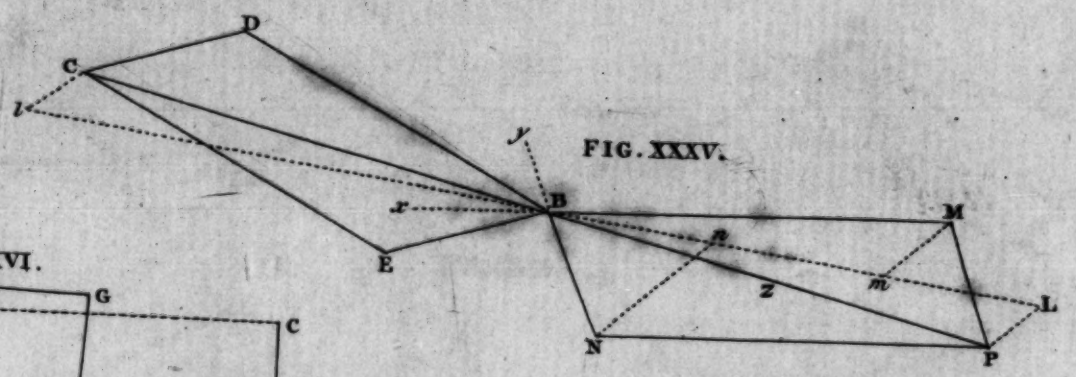


FIG. XXXVI.

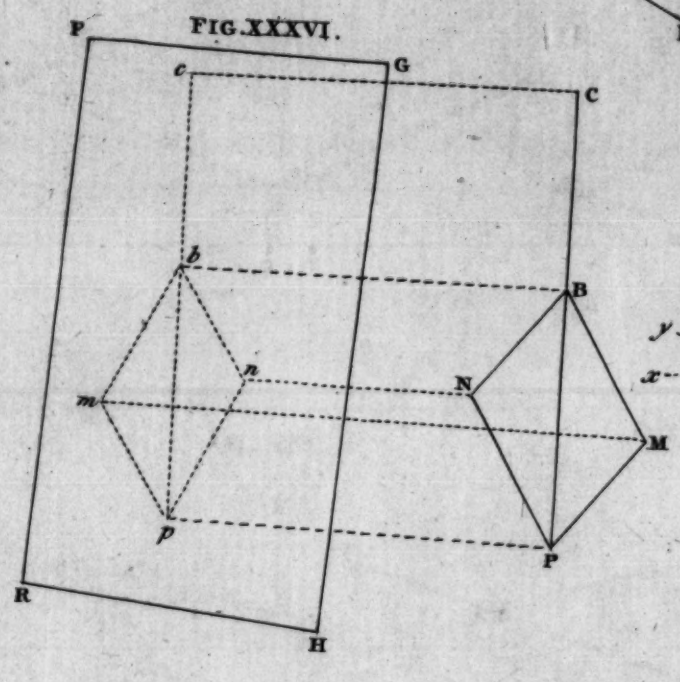


FIG. XXXVII.

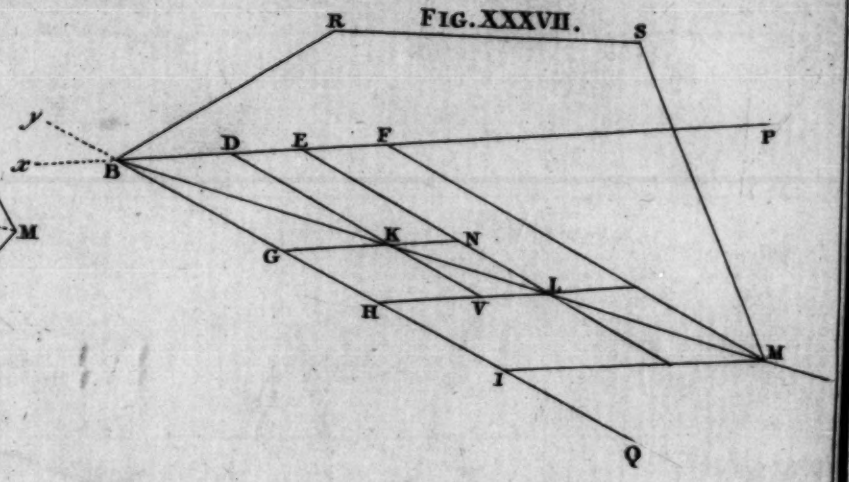


FIG. XXXVIII.

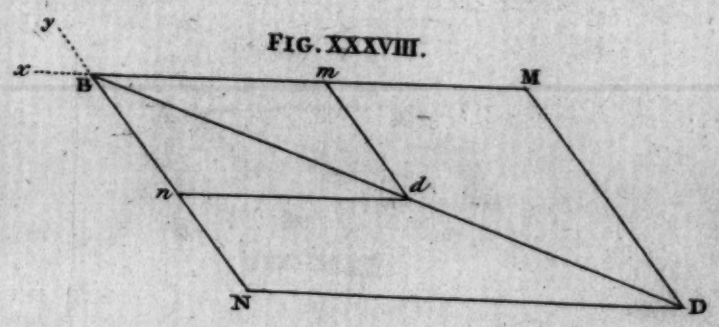


FIG. XXXIX.

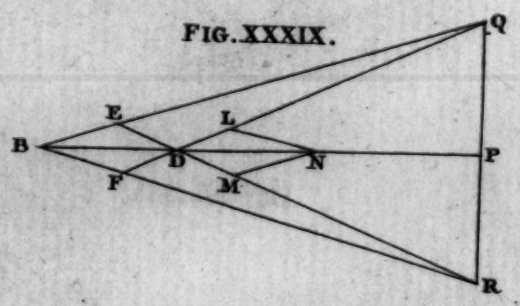


Plate V.

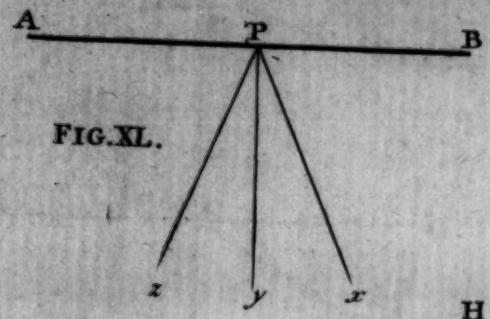


FIG. XL.

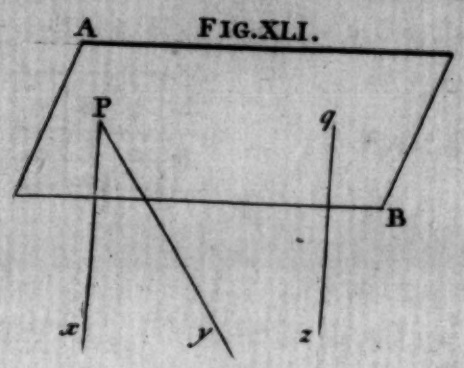


FIG. XLI.

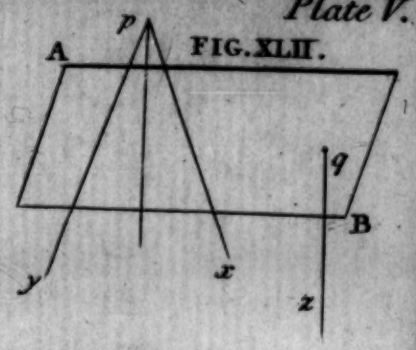


FIG. XLII.

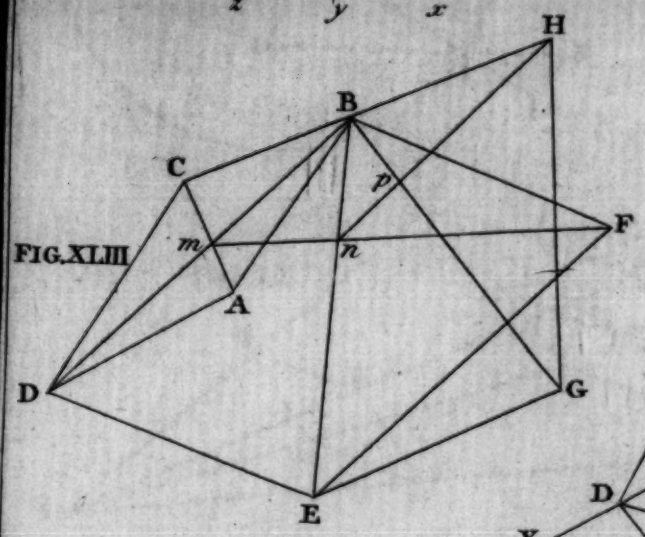


FIG. XLIII.

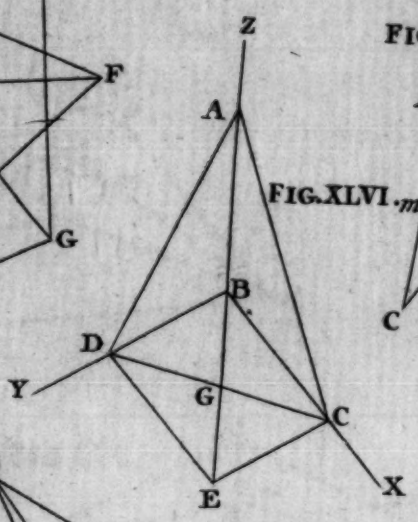


FIG. XLVI.

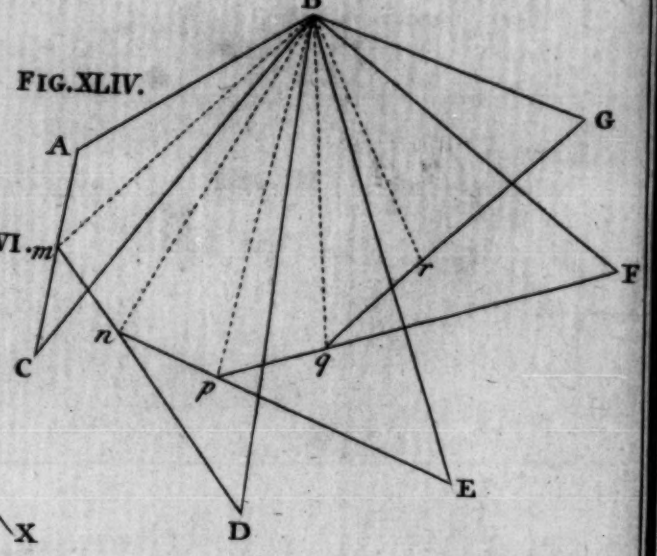


FIG. XLIV.

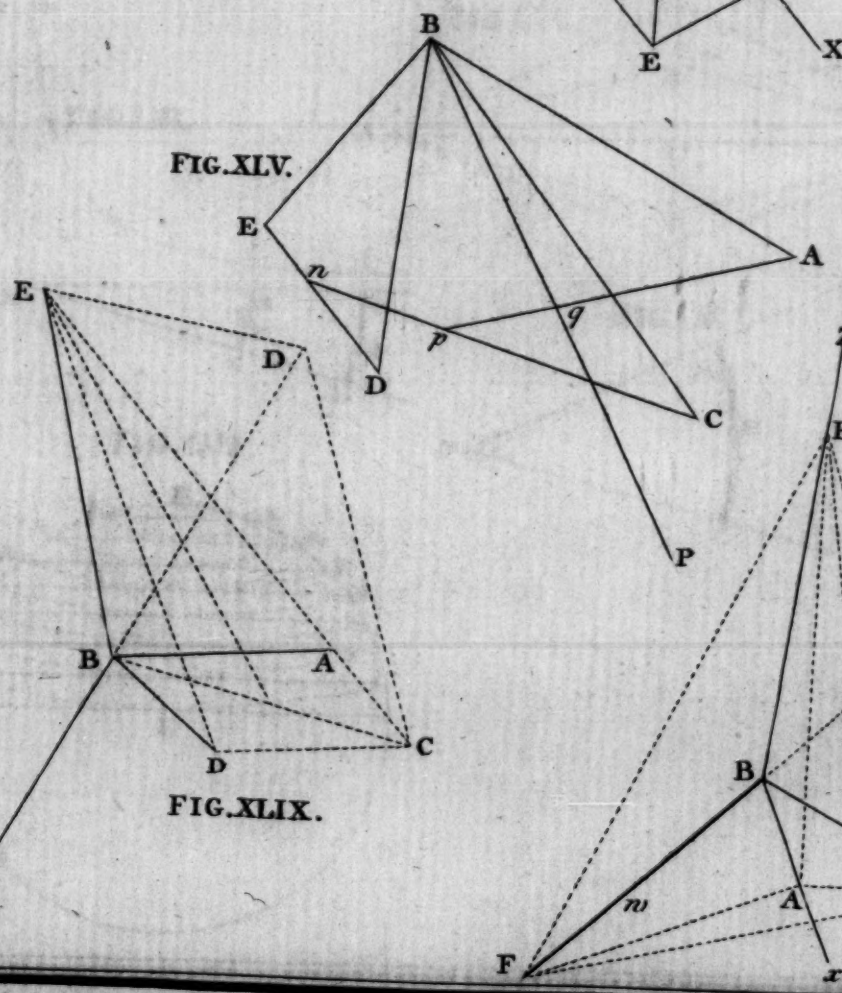


FIG. XLV.

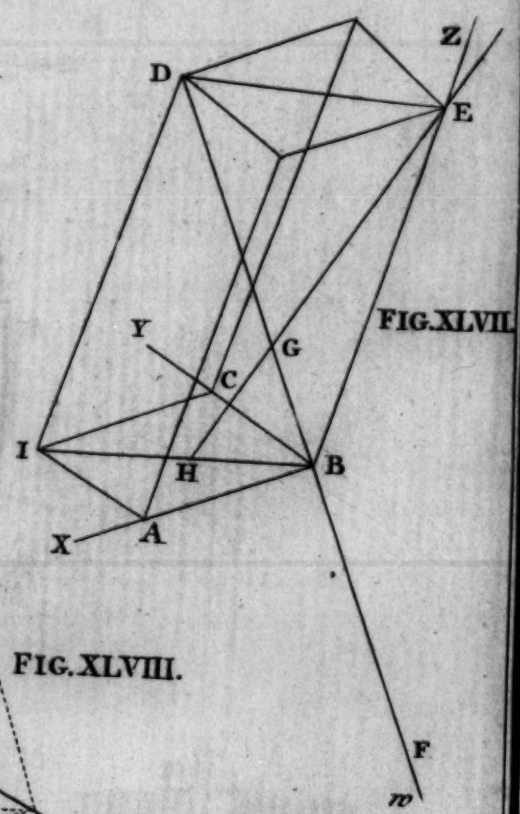


FIG. XLVII.

FIG. XLIX.

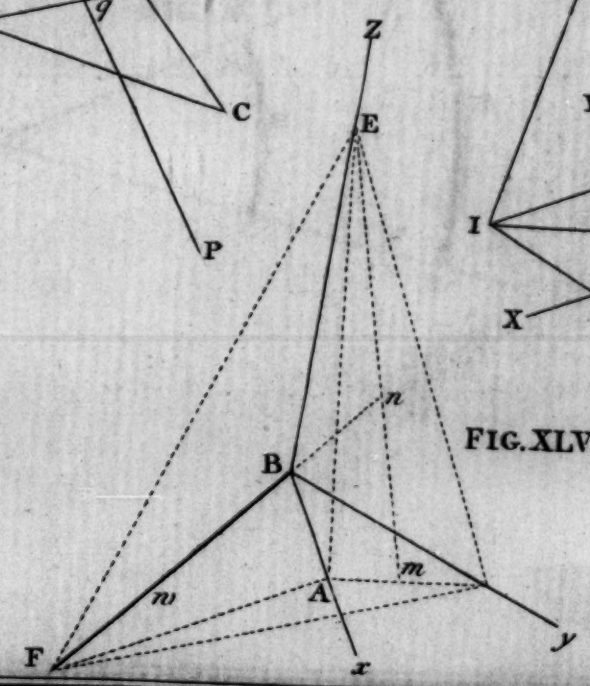


FIG. XLVIII.

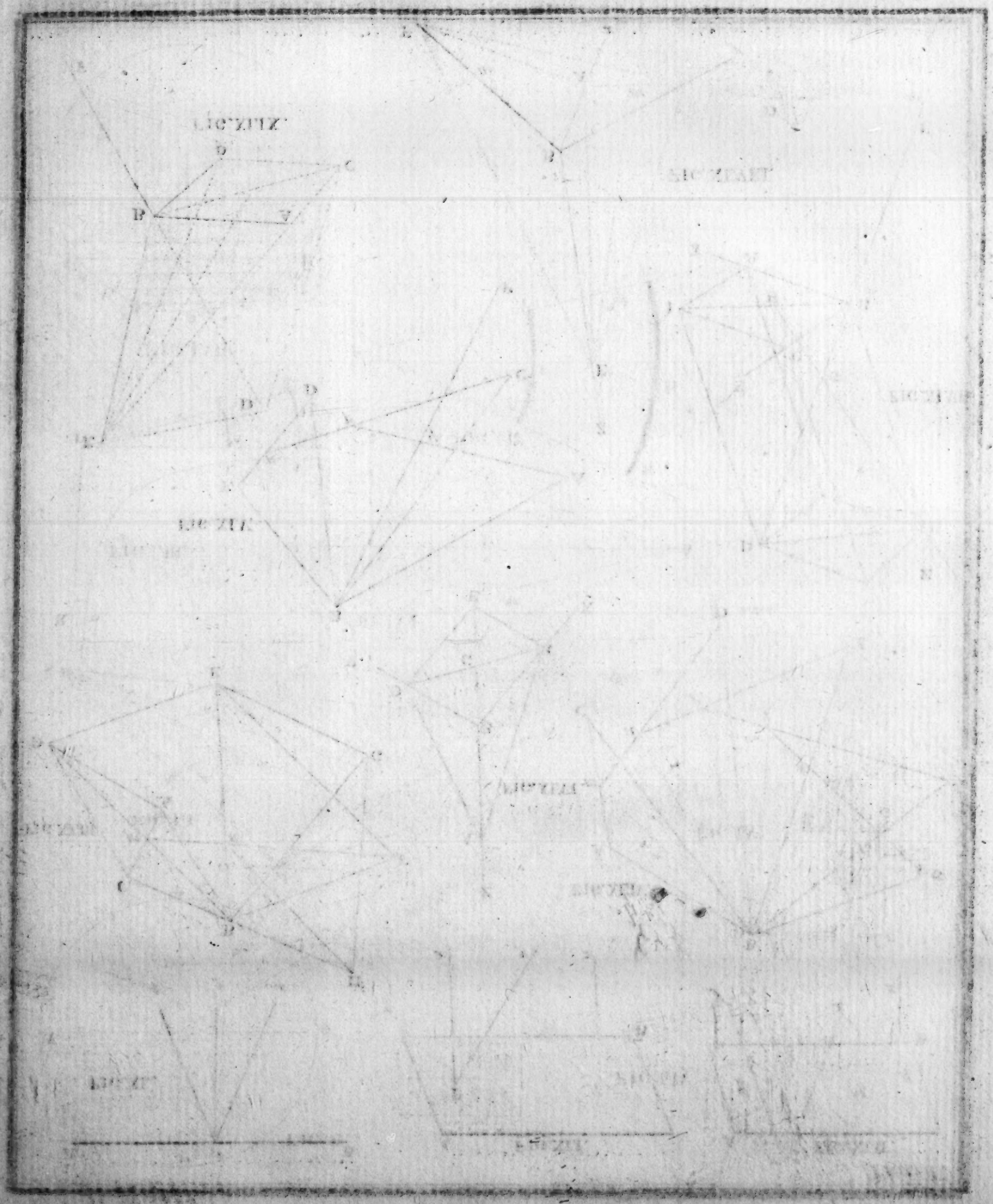
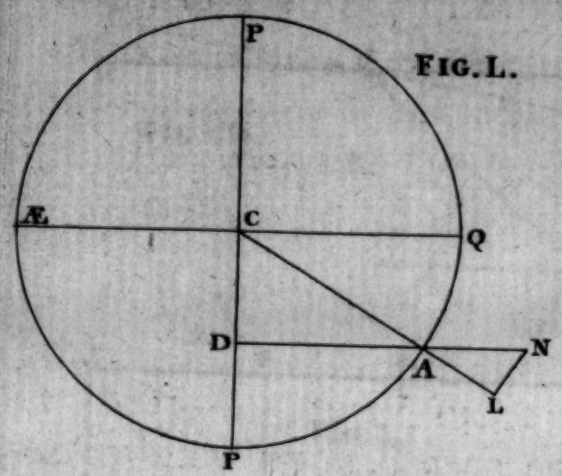


FIG. L.



a	*b*	*c*	*d*
e	*f*	*g*	*h*

FIG. LIV.

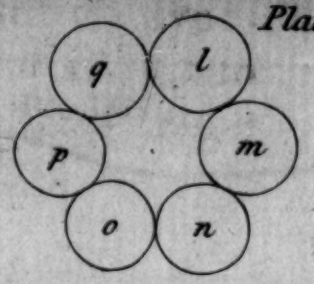


FIG. LV.

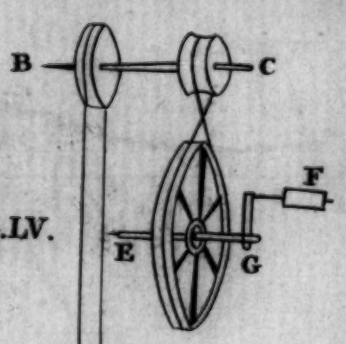


FIG. LI.

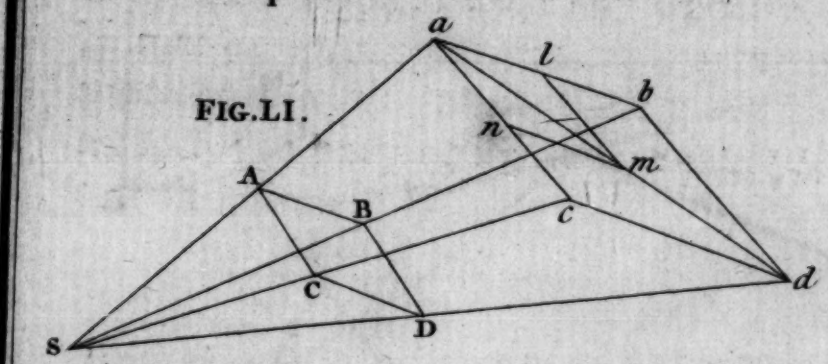


FIG. LIII.

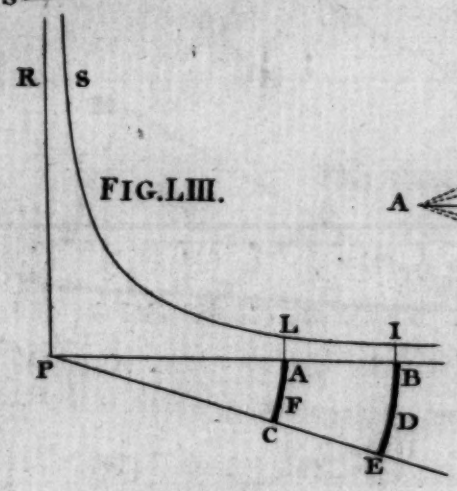


FIG. LVI.

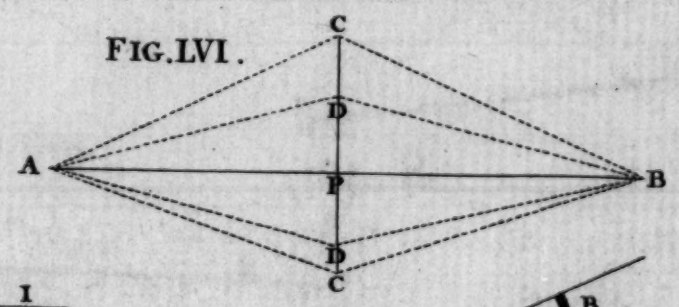


FIG. LII.

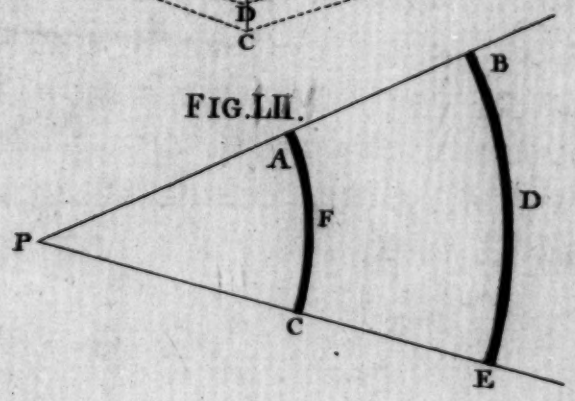
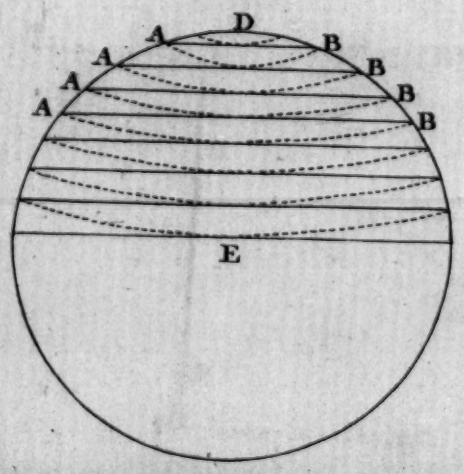


FIG. LVII.



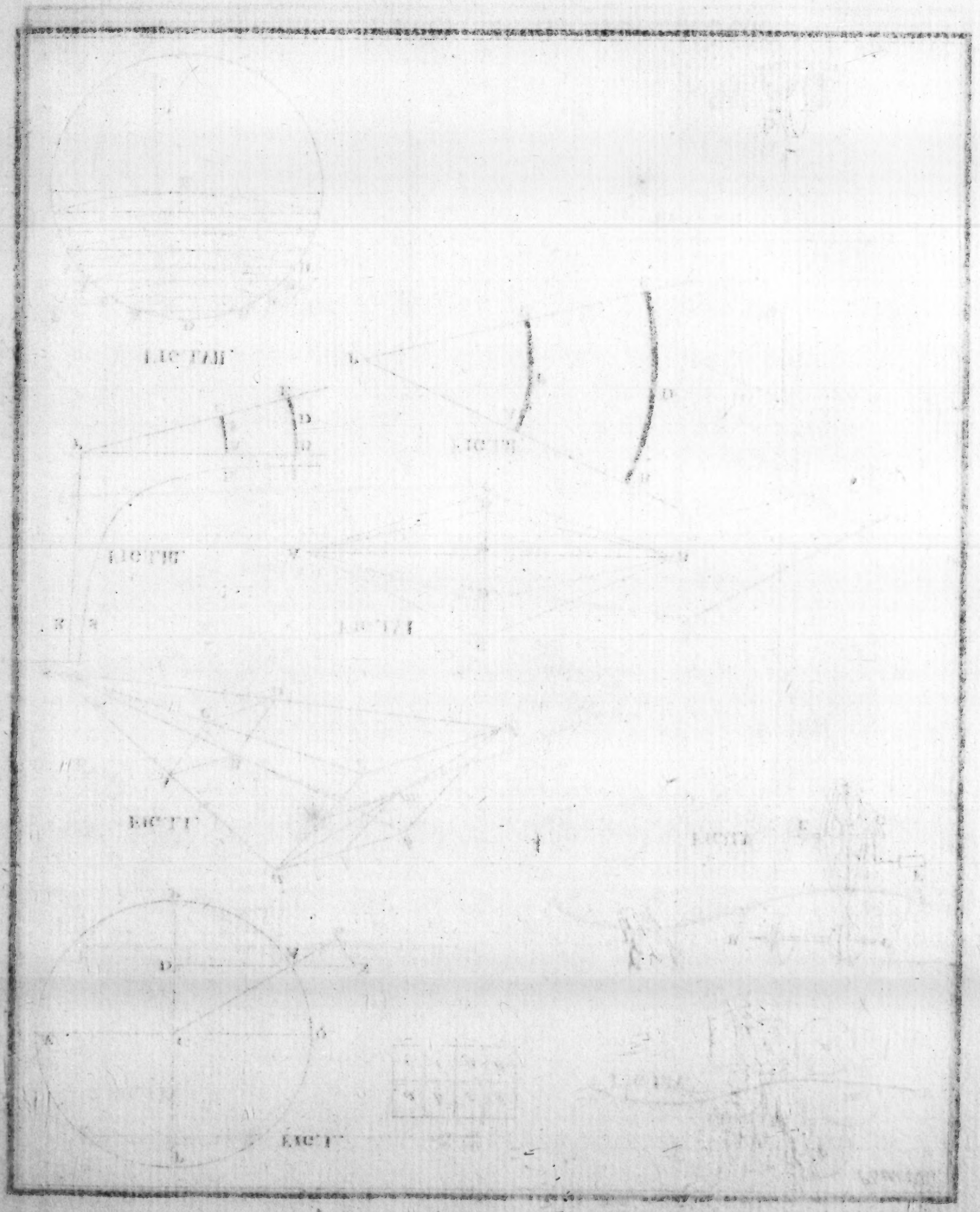


Plate VII.

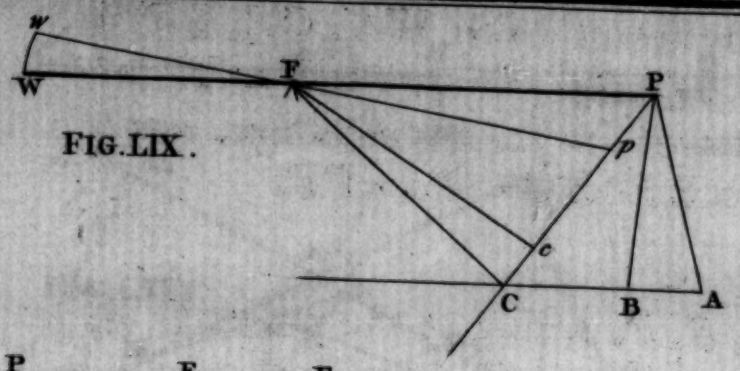


FIG. LIX.

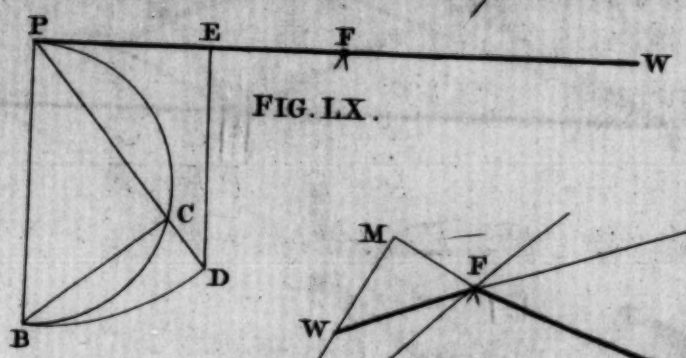


FIG. LX.



FIG. LVIII.



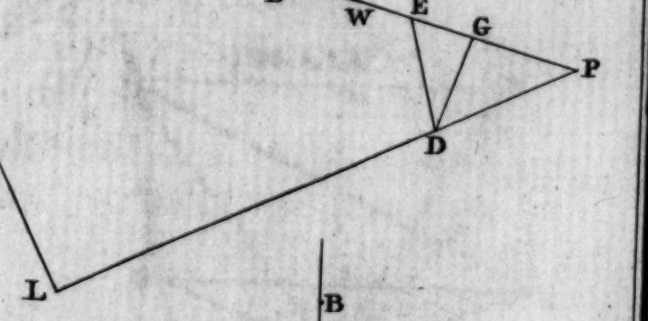


FIG. LXI.

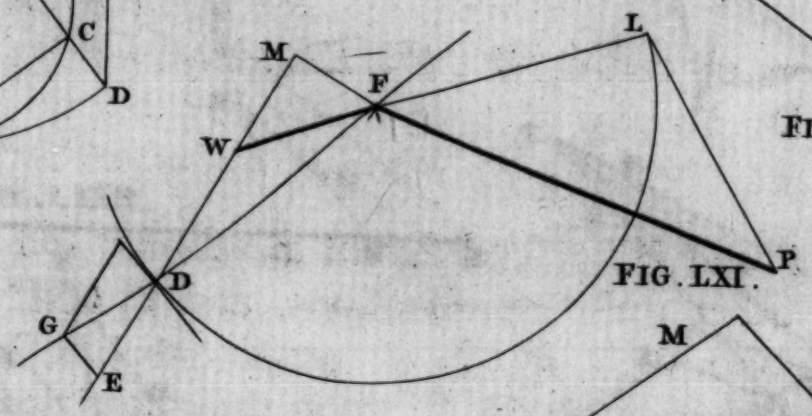


FIG. LXI.

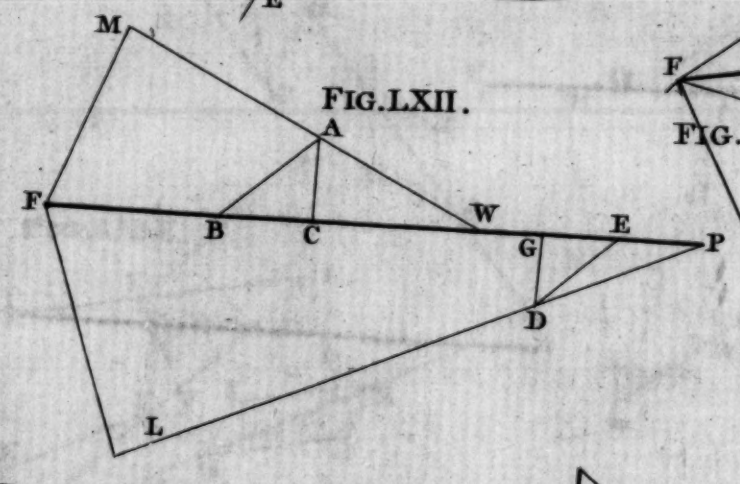


FIG. LXII.

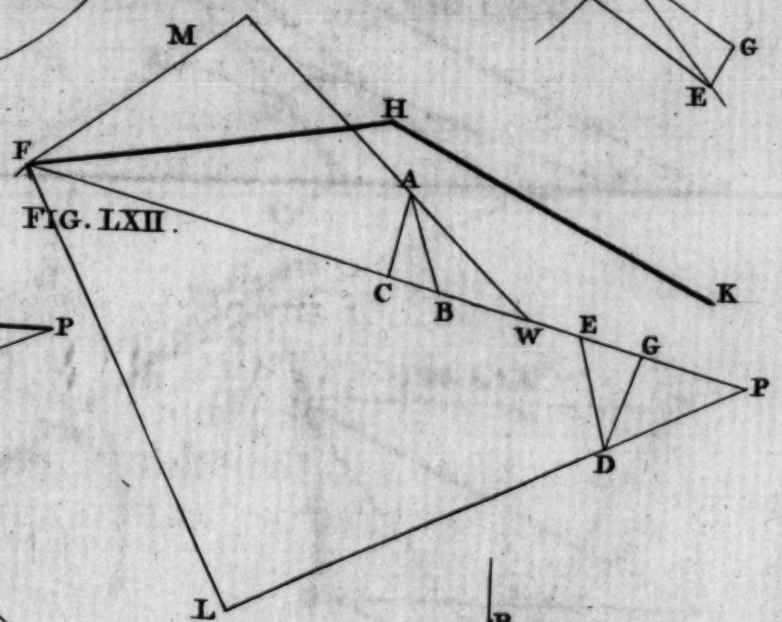


FIG. LXII.

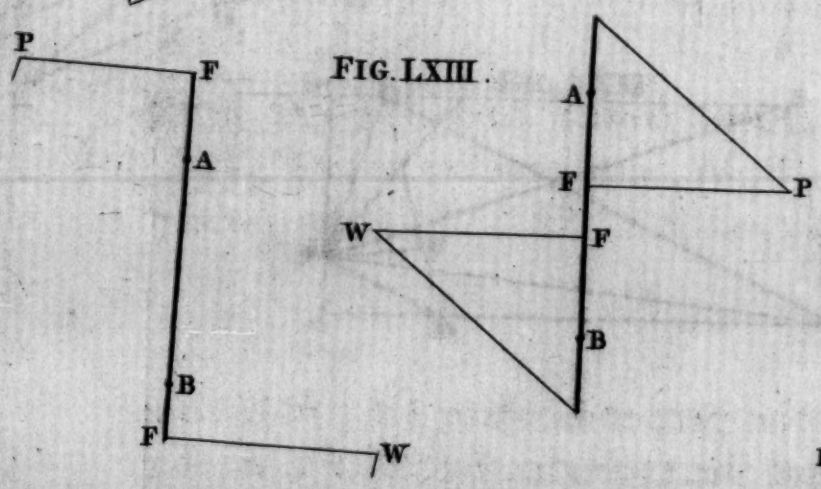


FIG. LXIII.

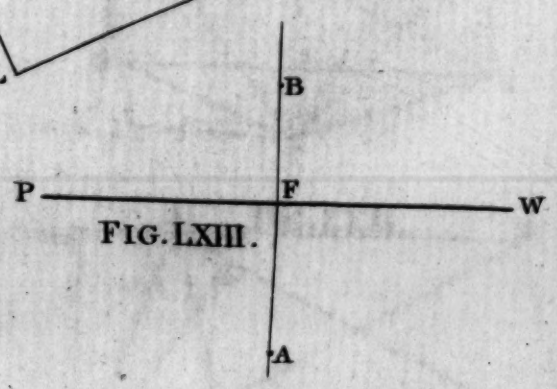


FIG. LXIII.

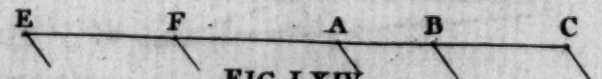


FIG. LXIV.

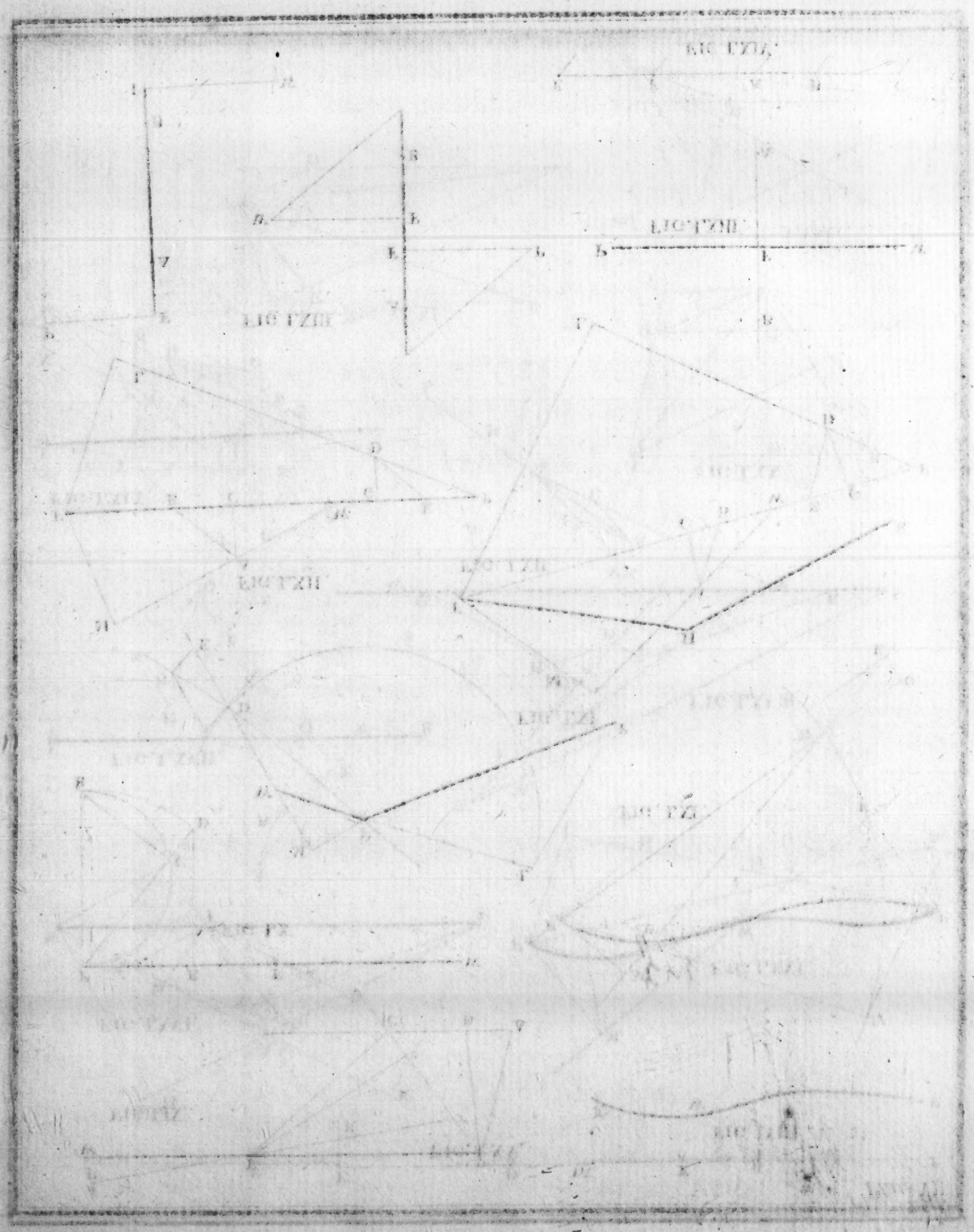


Plate VIII.

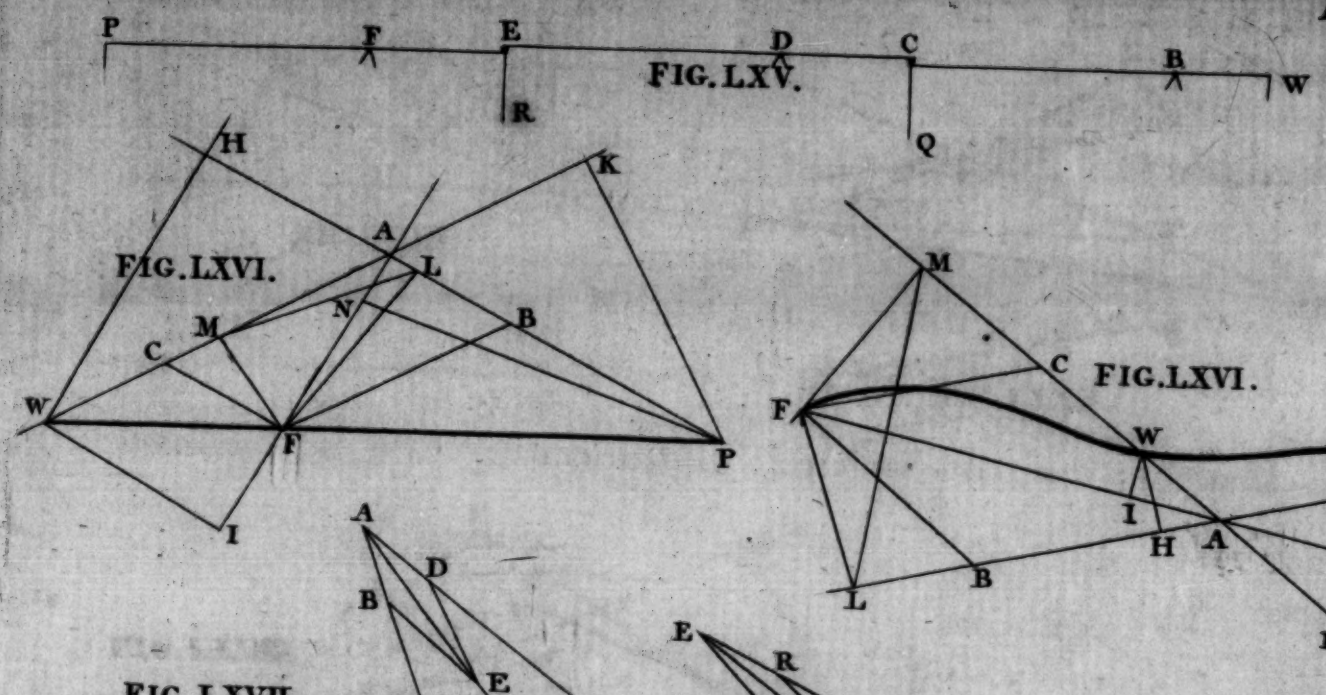


FIG. LXV.

FIG. LXVI.

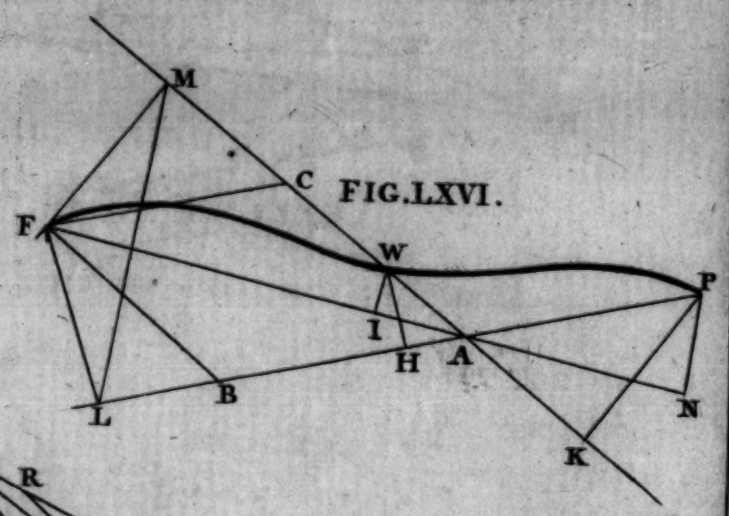


FIG. LXVI.

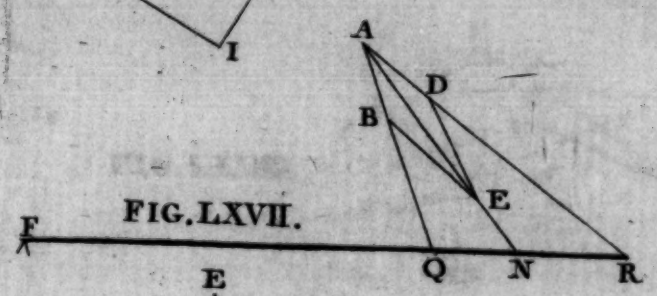


FIG. LXVII.

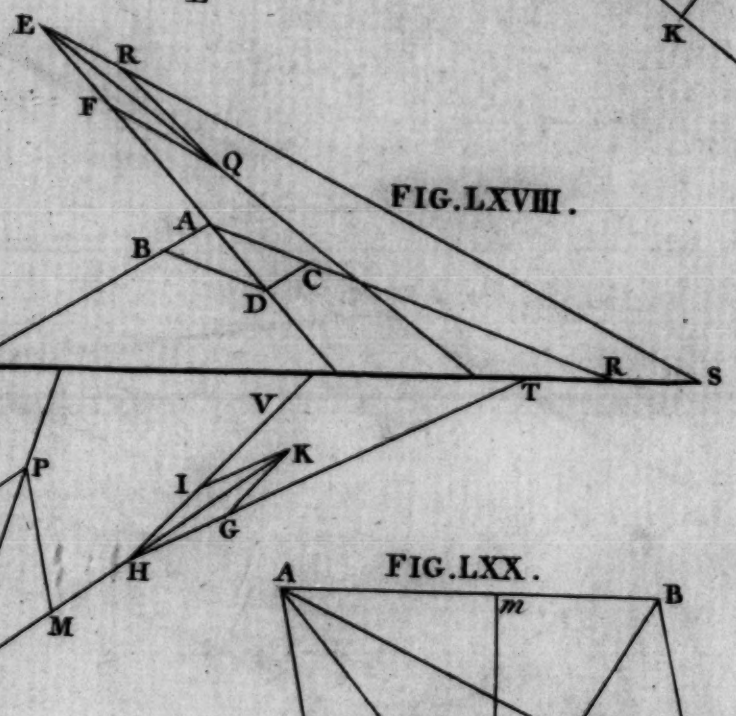


FIG. LXVIII.

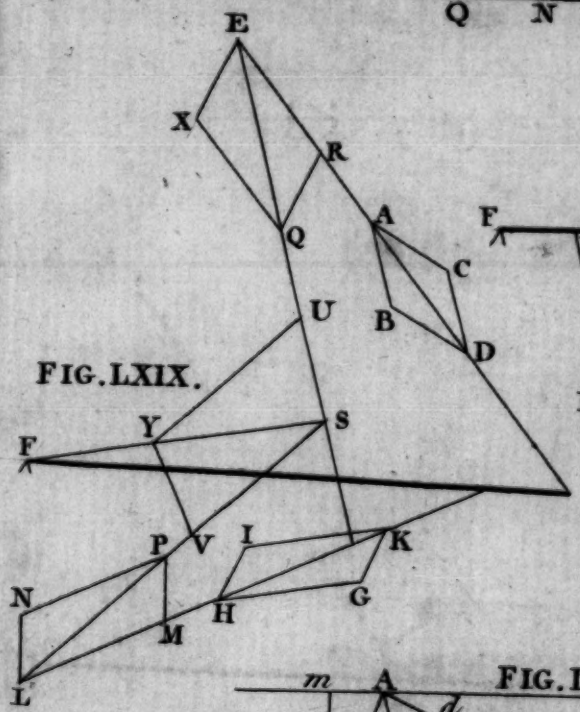


FIG. LXIX.

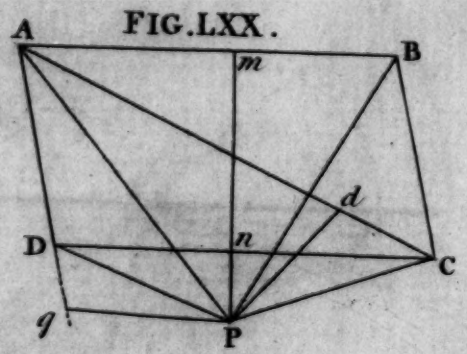


FIG. LXX.

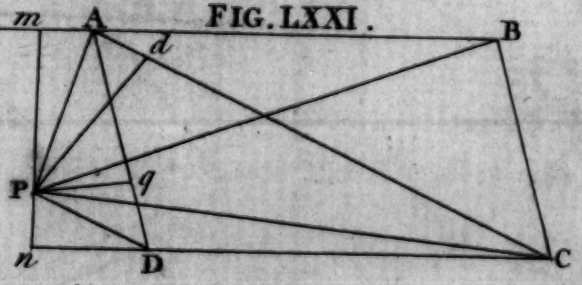


FIG. LXXI.

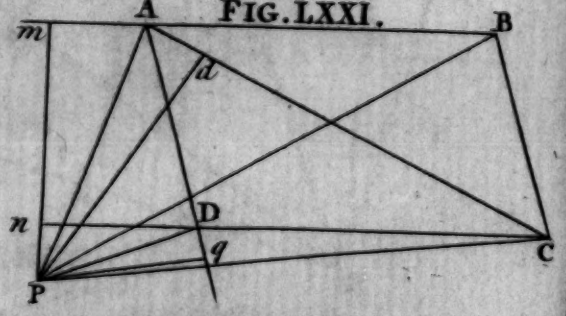
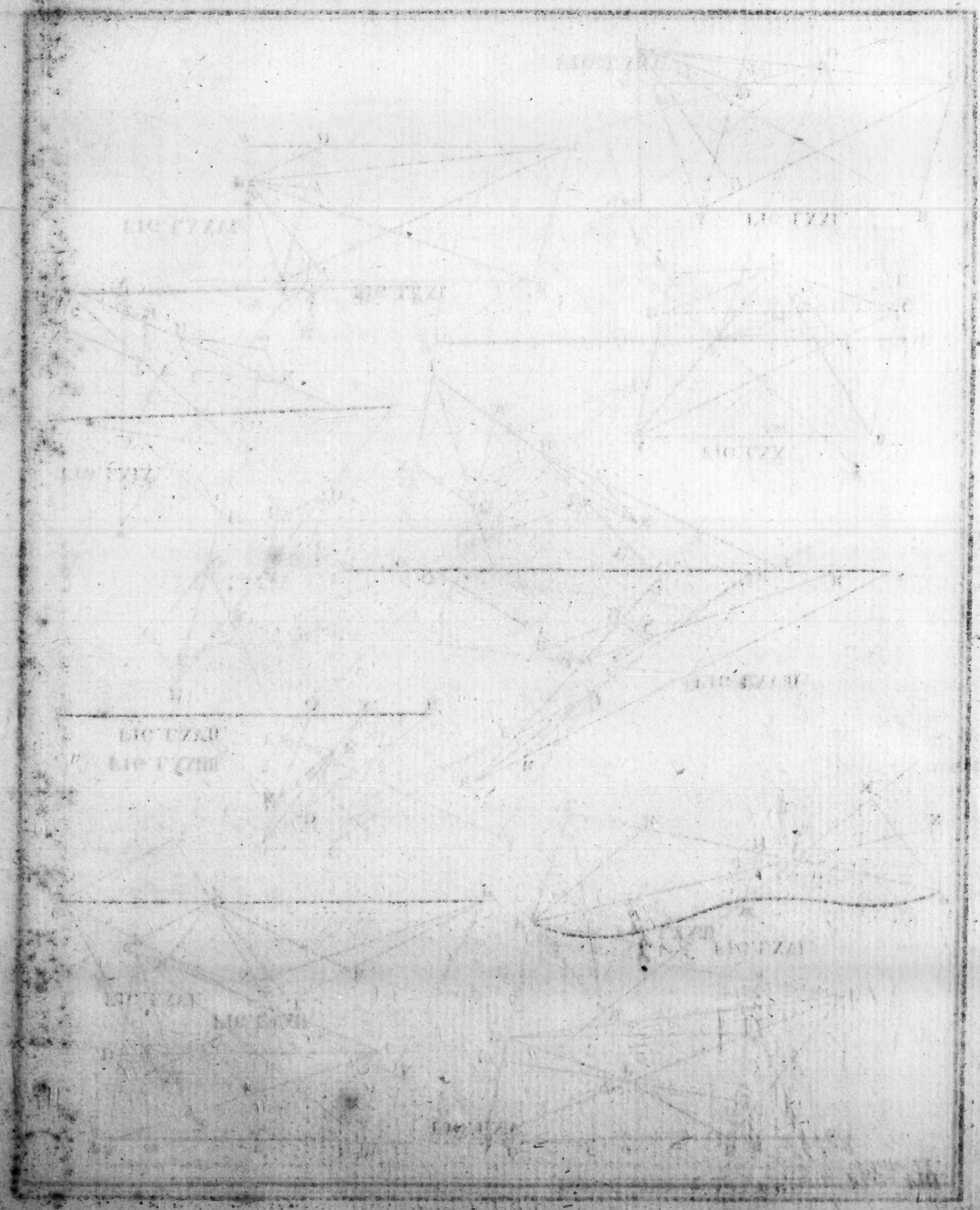


FIG. LXXI.



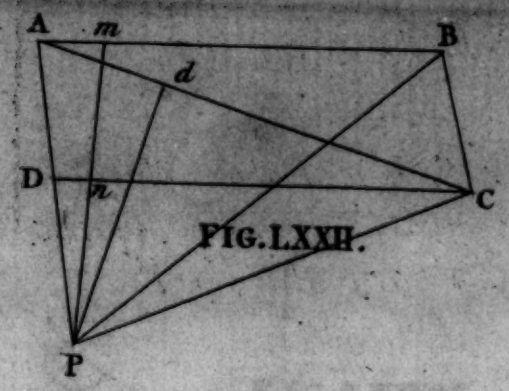


FIG. LXXII.

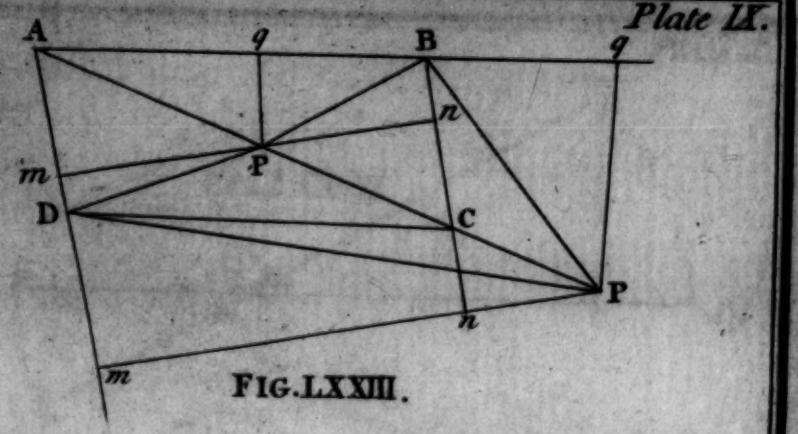


FIG. LXXIII.

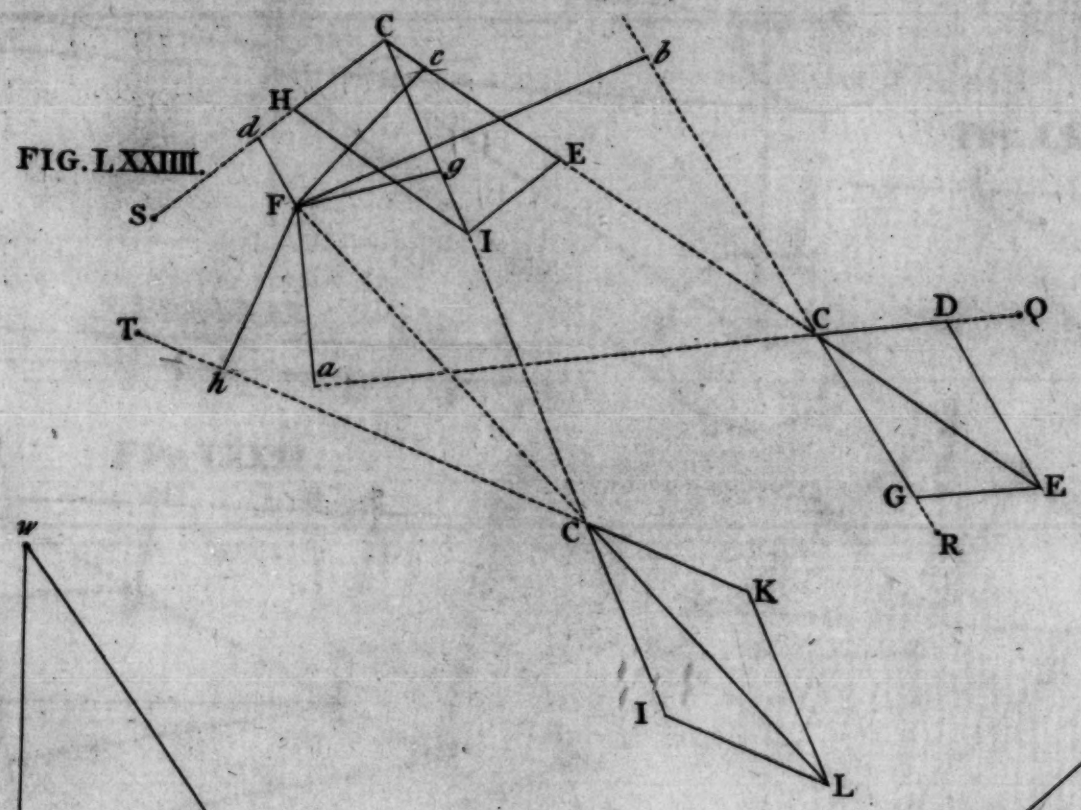


FIG. LXXIIII.

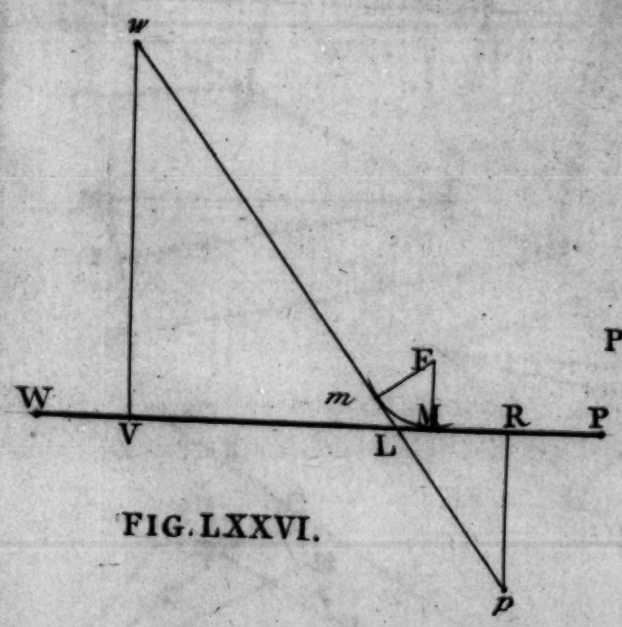


FIG. LXXVI.

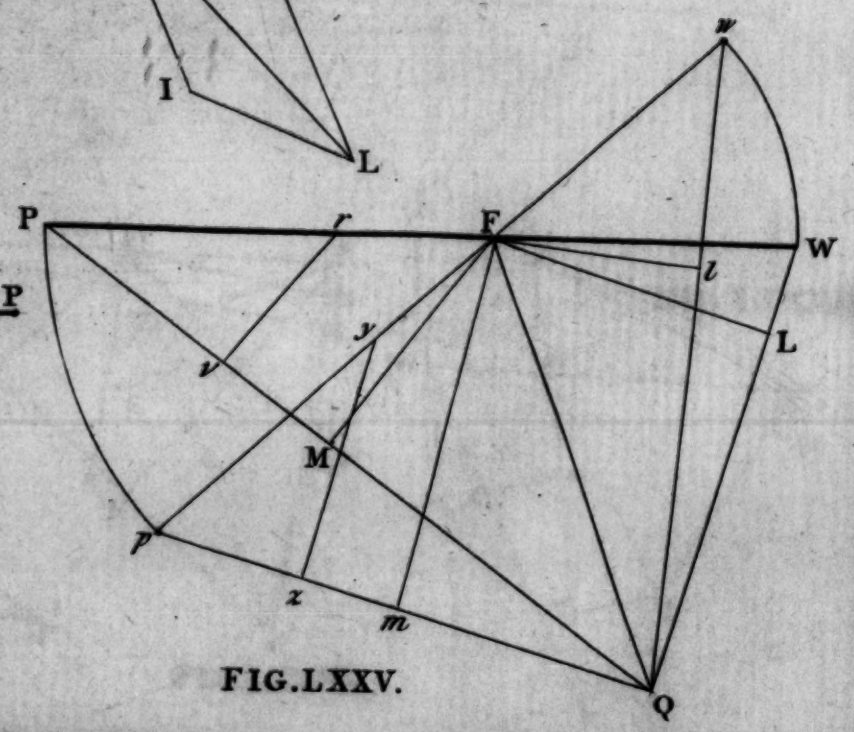


FIG. LXXV.

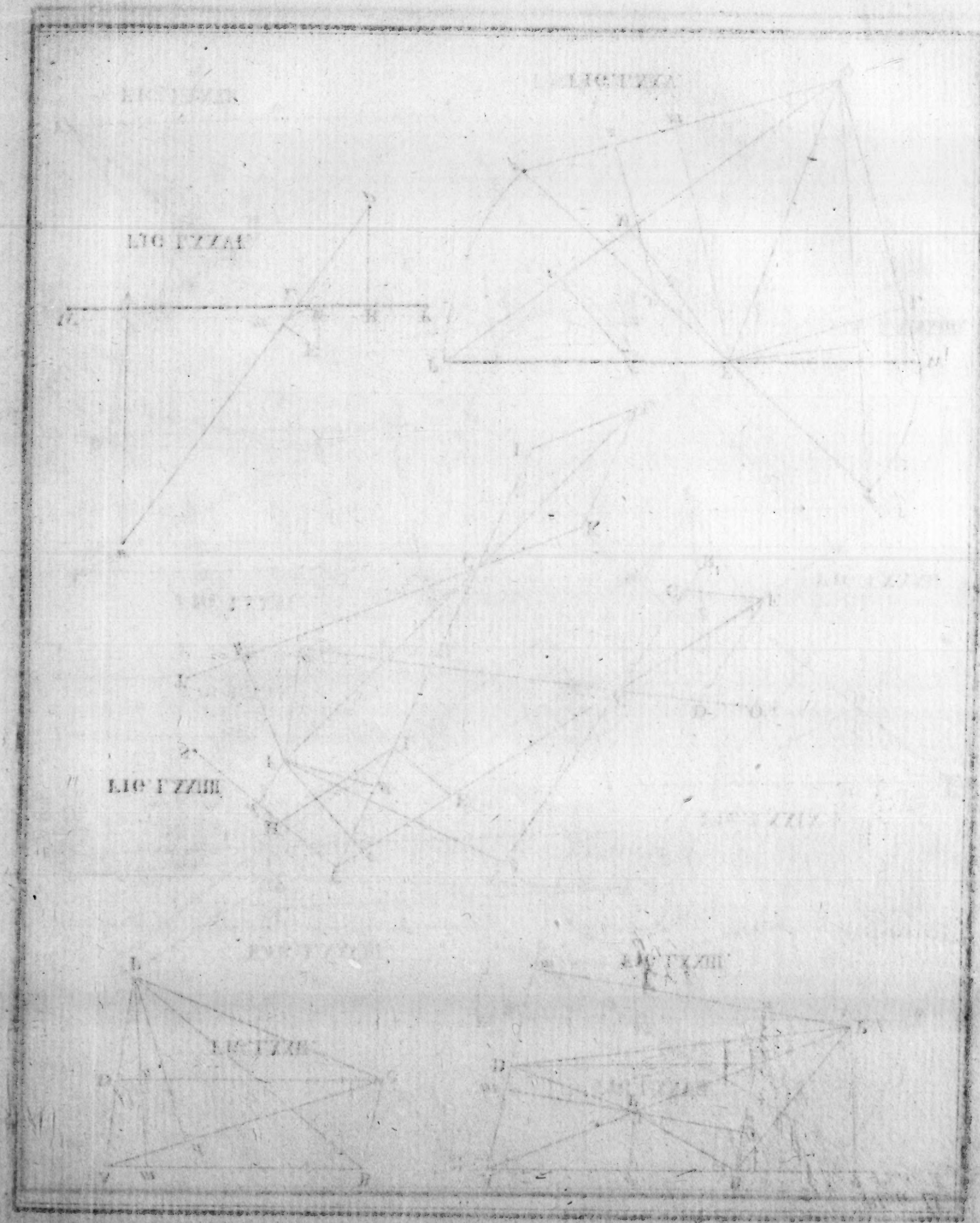


Plate X.

FIG. LXXVII.

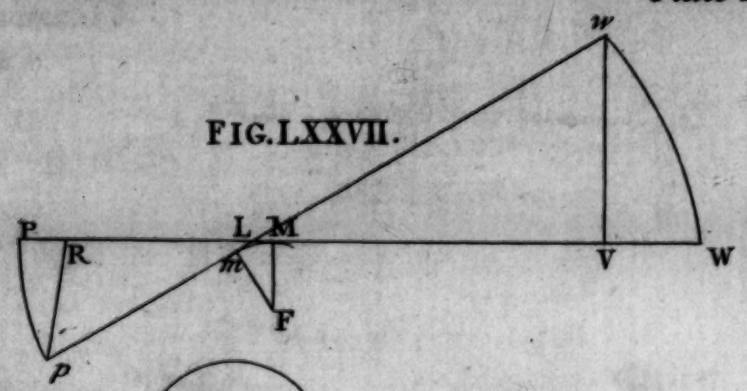


FIG. LXXVIII.

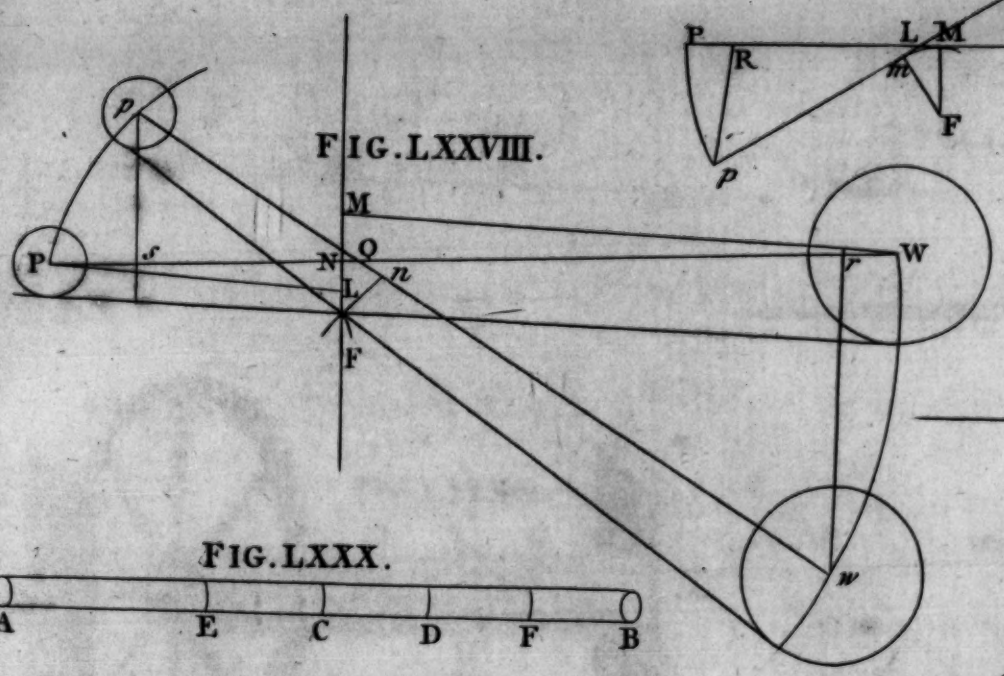


FIG. LXXIX.

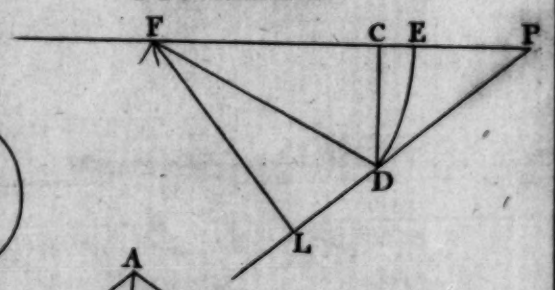


FIG. LXXX.

FIG. LXXXI.

FIG. LXXXII.

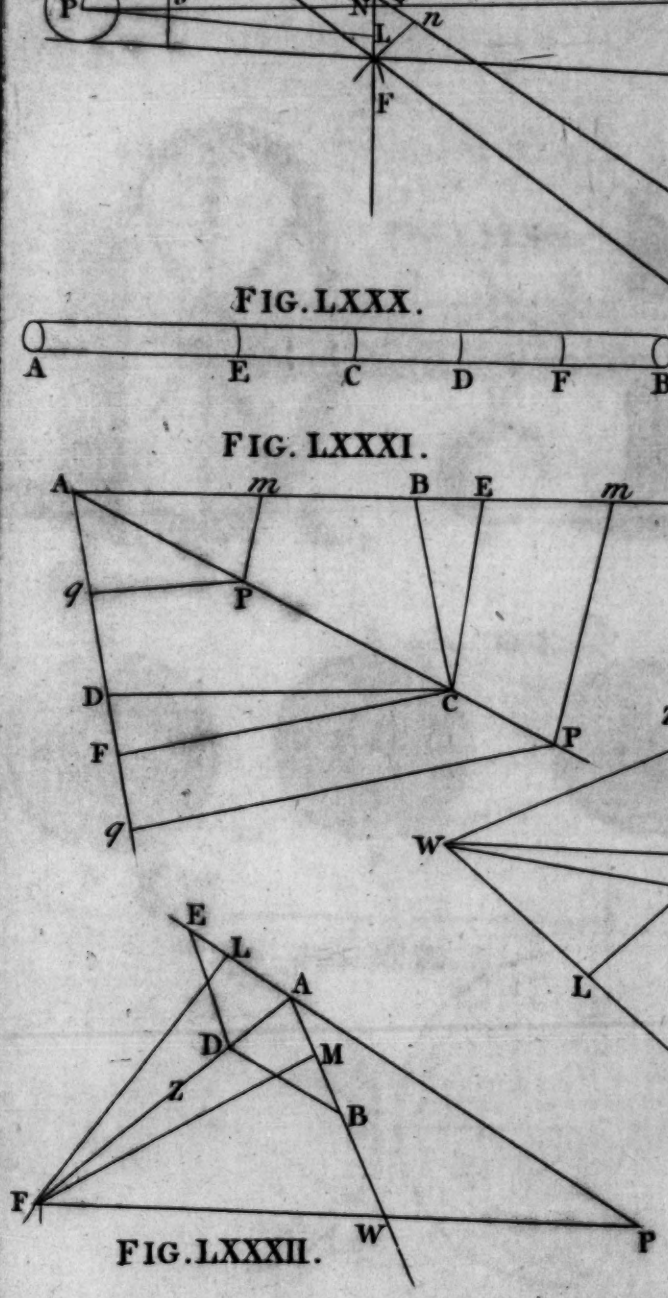


FIG. LXXXIII.

FIG. LXXXII.

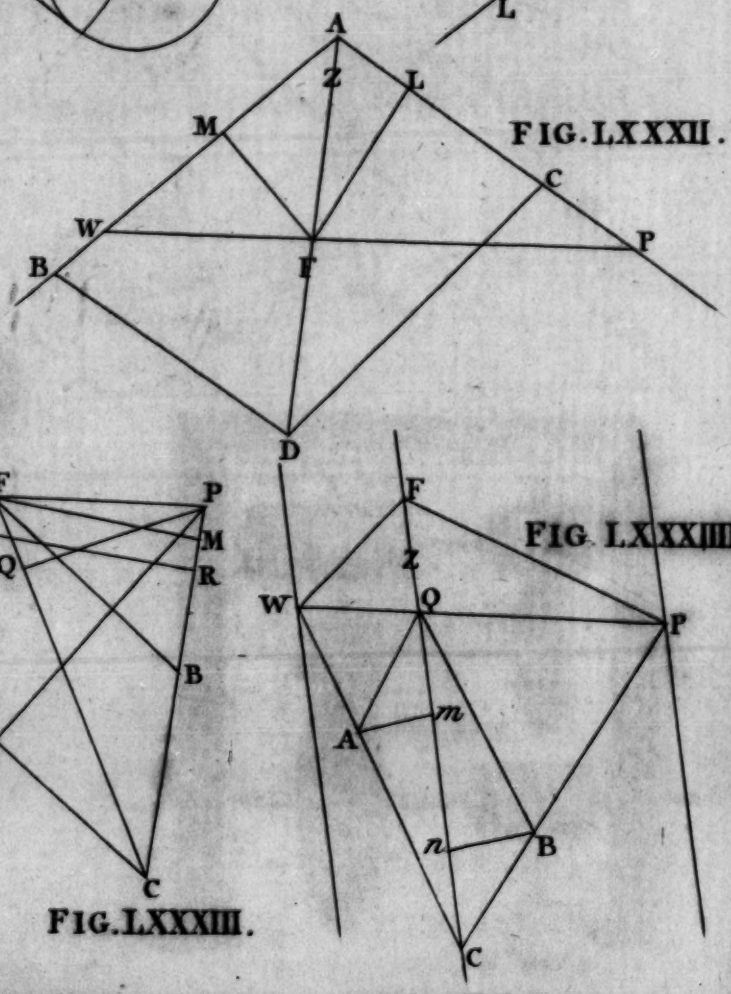


FIG. LXXXIII.

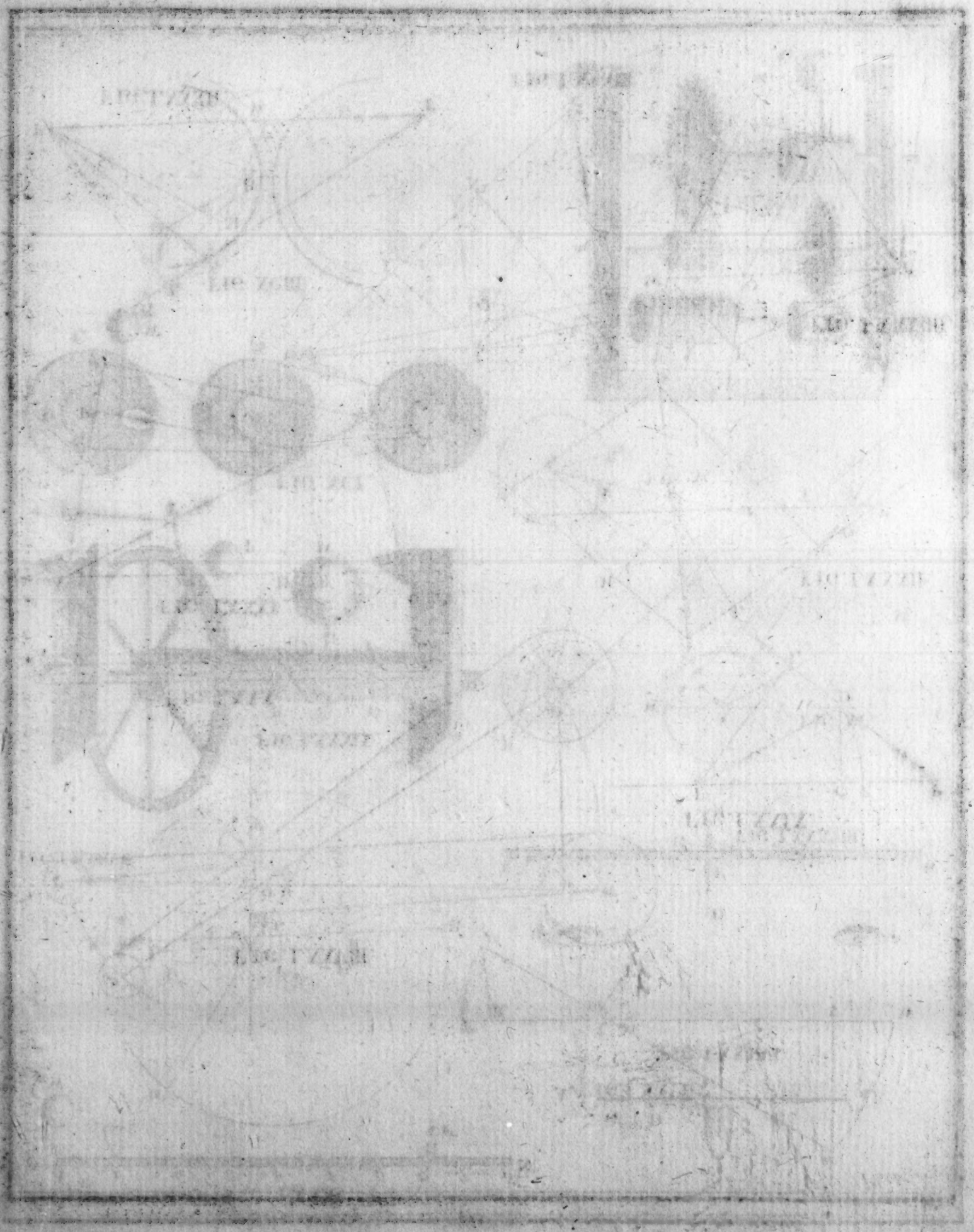


FIG. LXXXV.



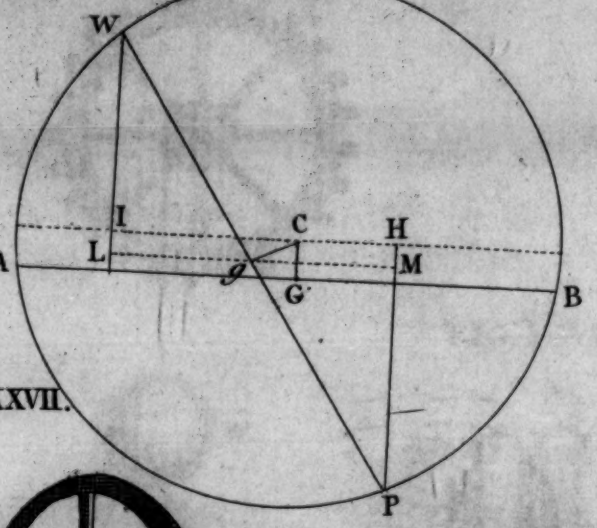


FIG. LXXXVII.

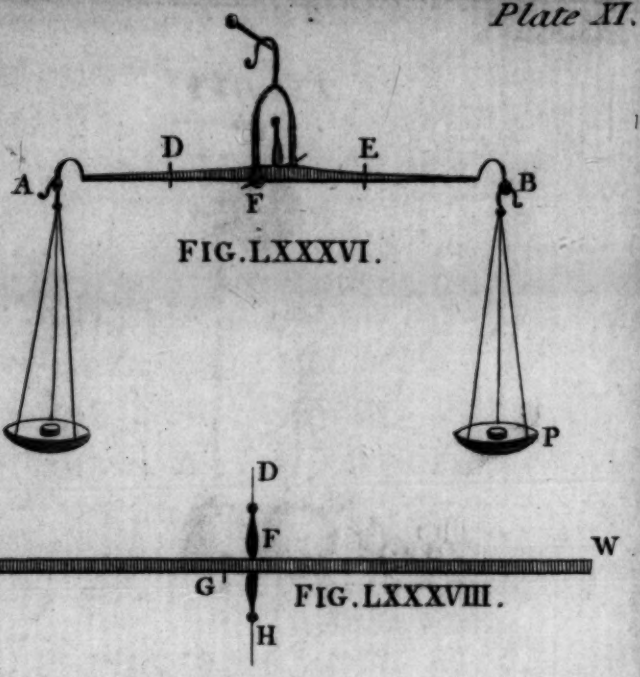
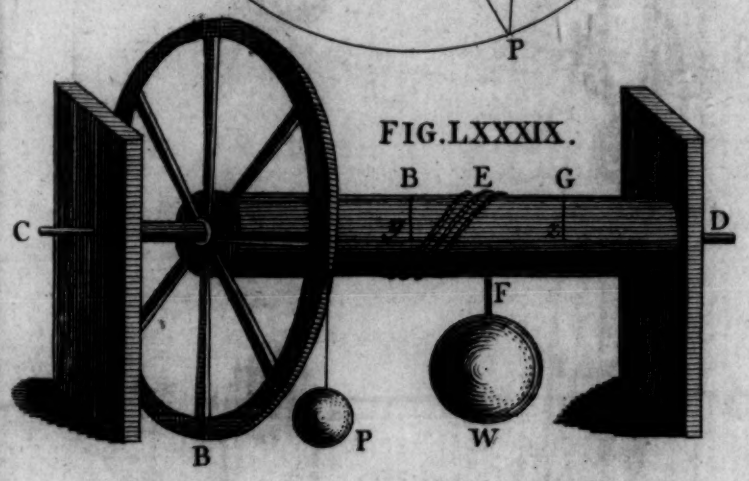


FIG. LXXXVI.

FIG. LXXXVIII.

FIG. LXXXIX.



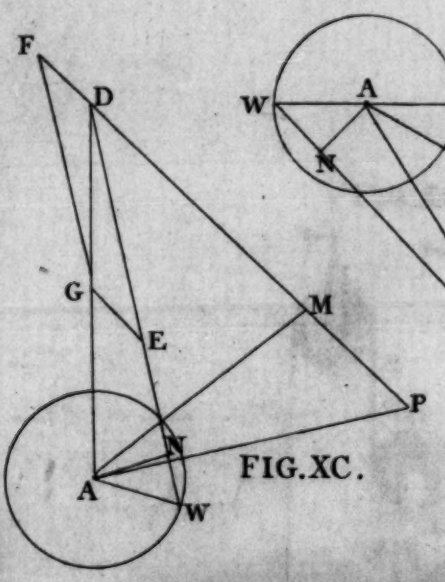


FIG. XC.

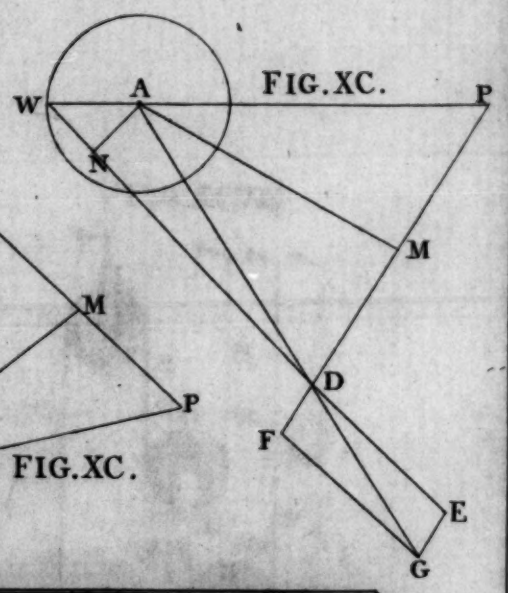


FIG. XC.

FIG. XCI.

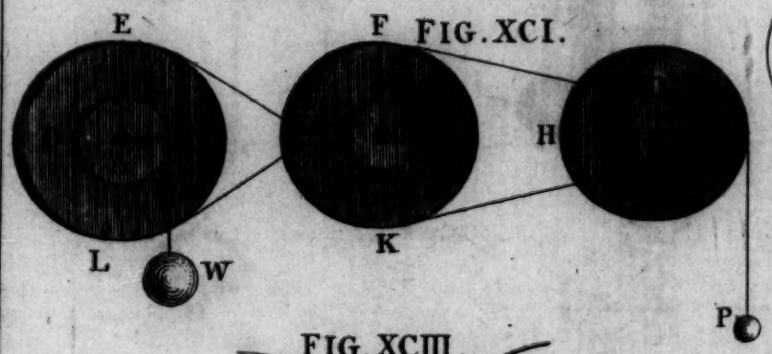
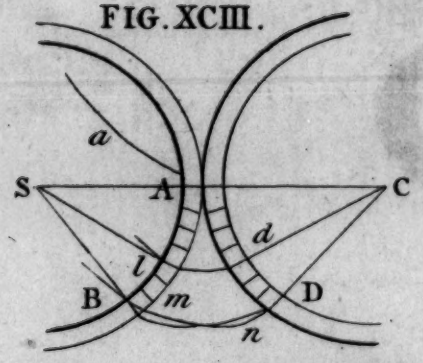


FIG. XCIII.



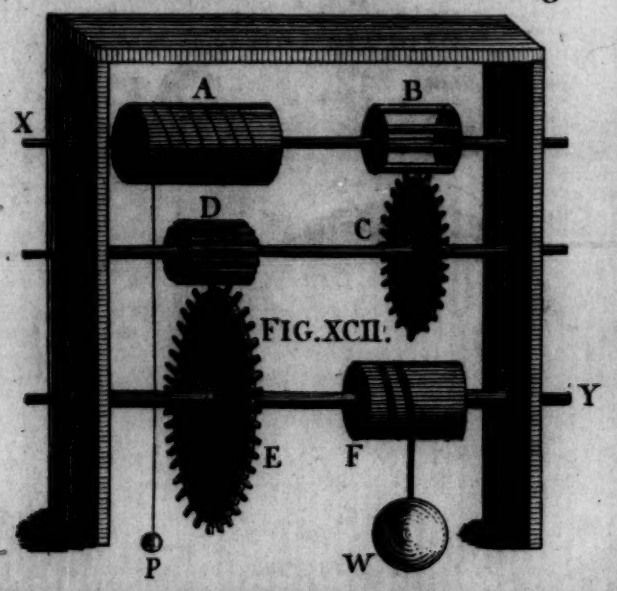


FIG. XCII.

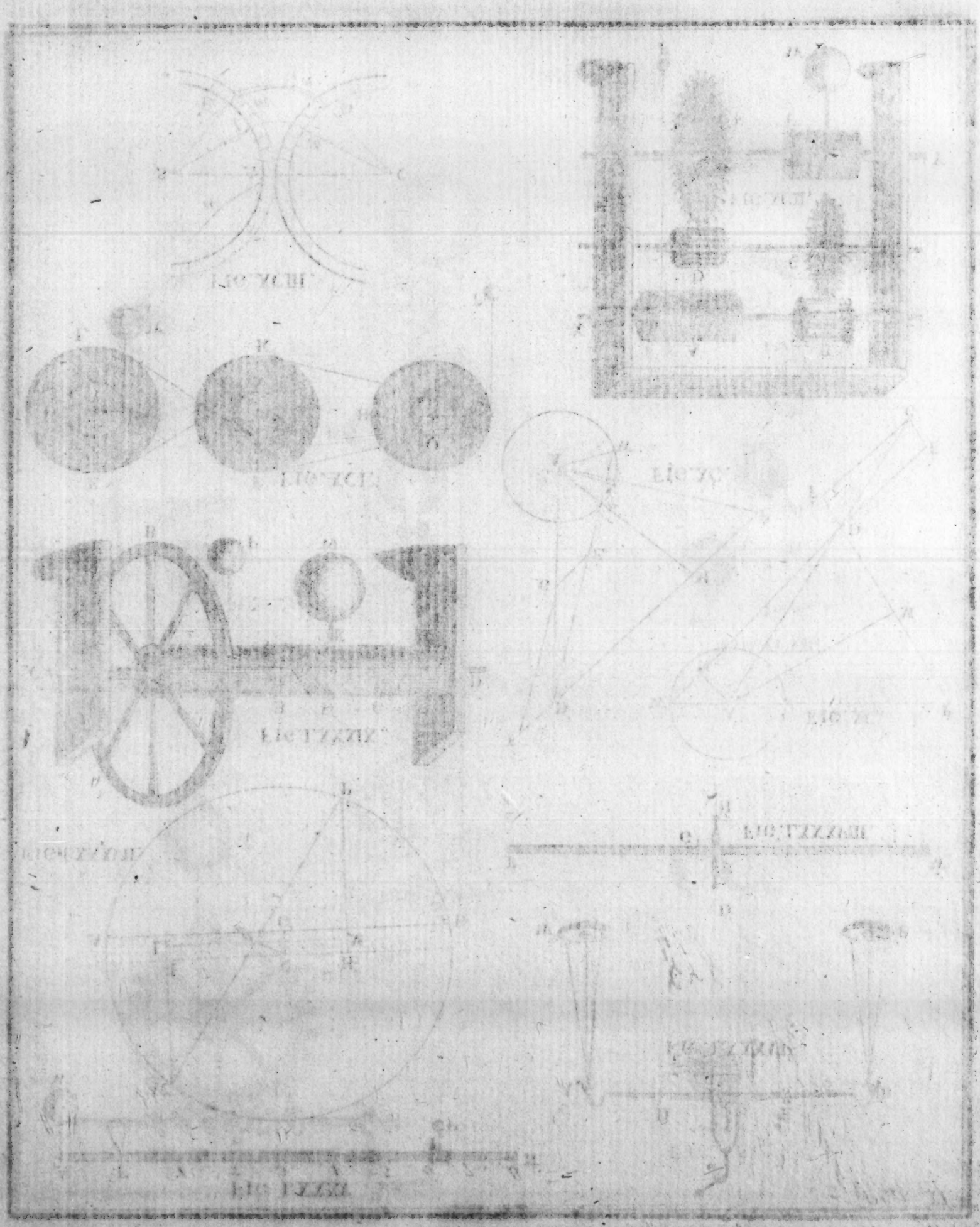


FIG. XCIV.

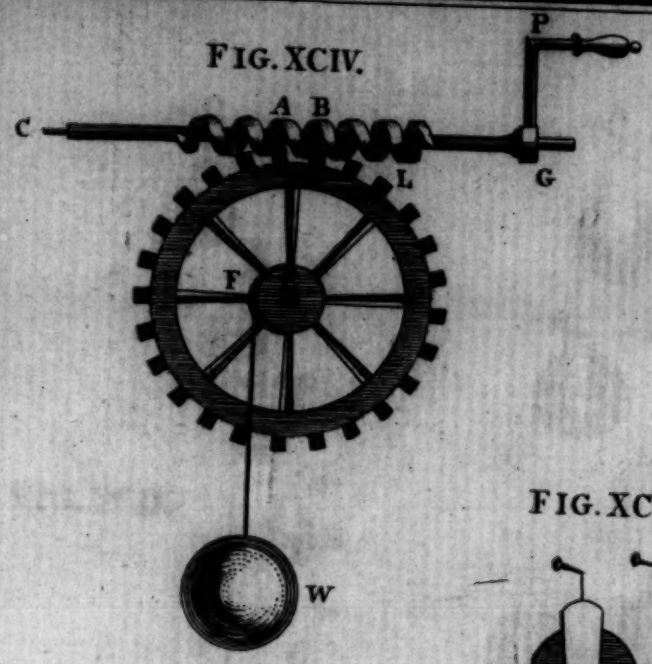


FIG. XCV.

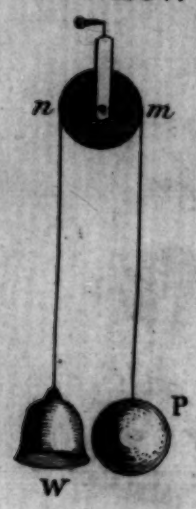


FIG. XCVI.

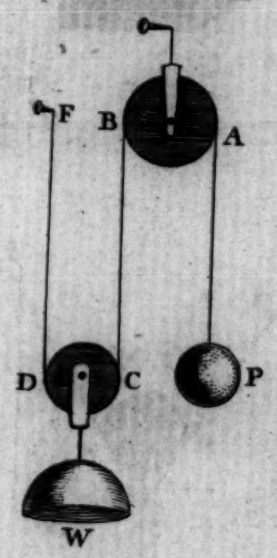
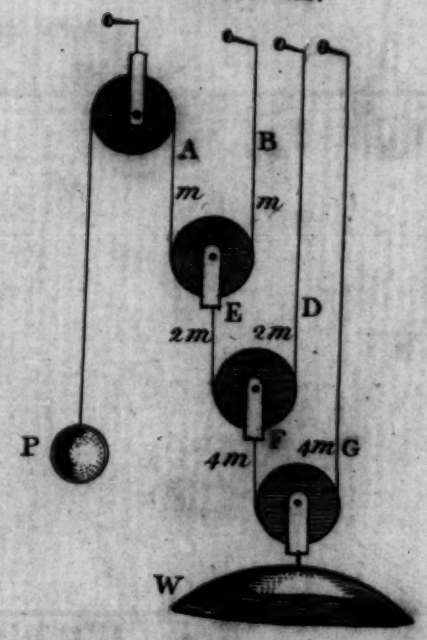
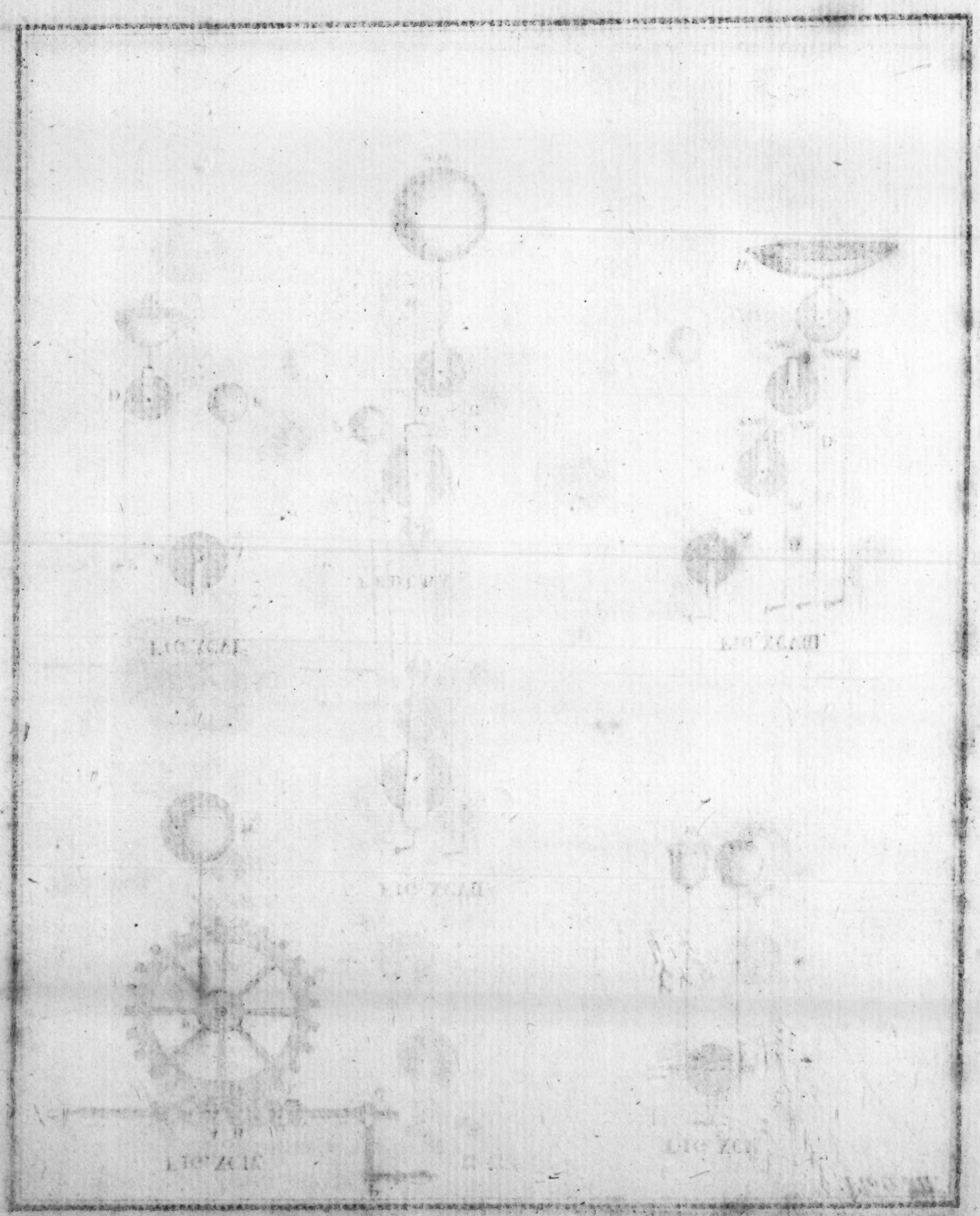


FIG. XCVII.



FIG. XCVIII.





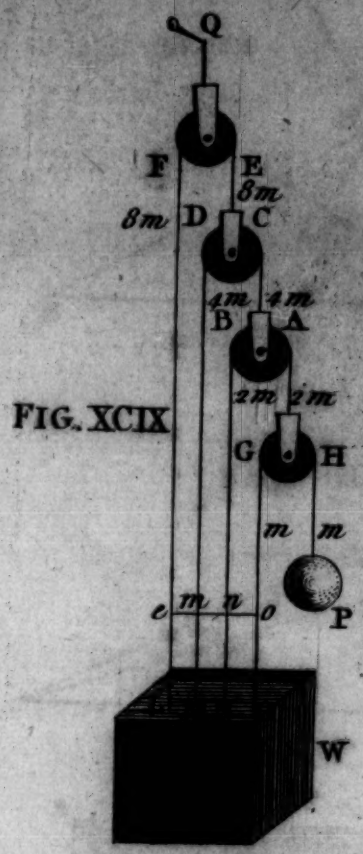


FIG. XCIX

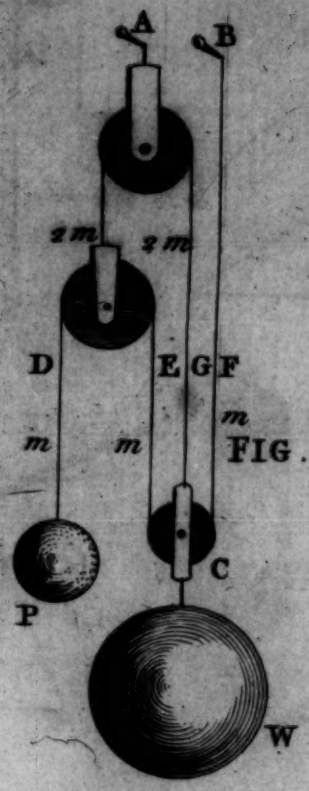


FIG. C.

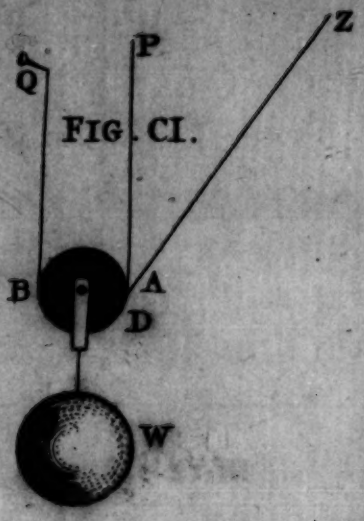


FIG. CI.

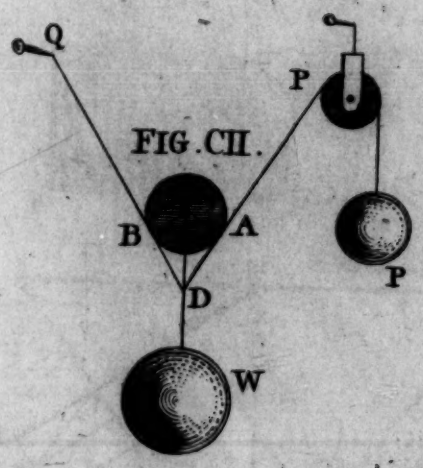
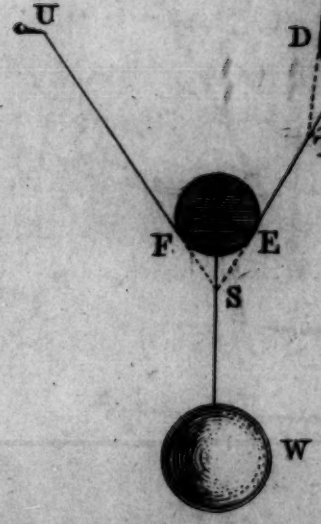


FIG. CII.



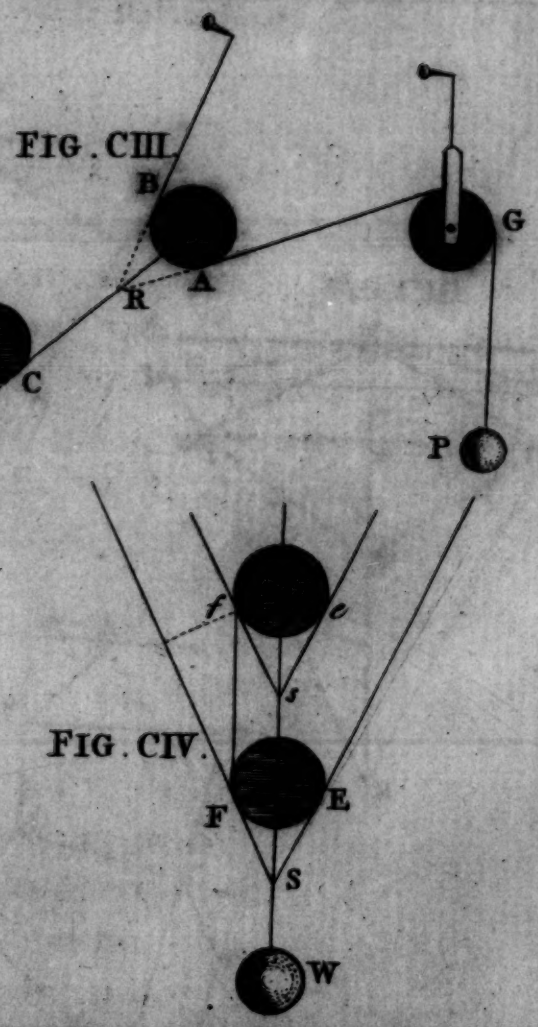


FIG. CIII.

FIG. CIV.

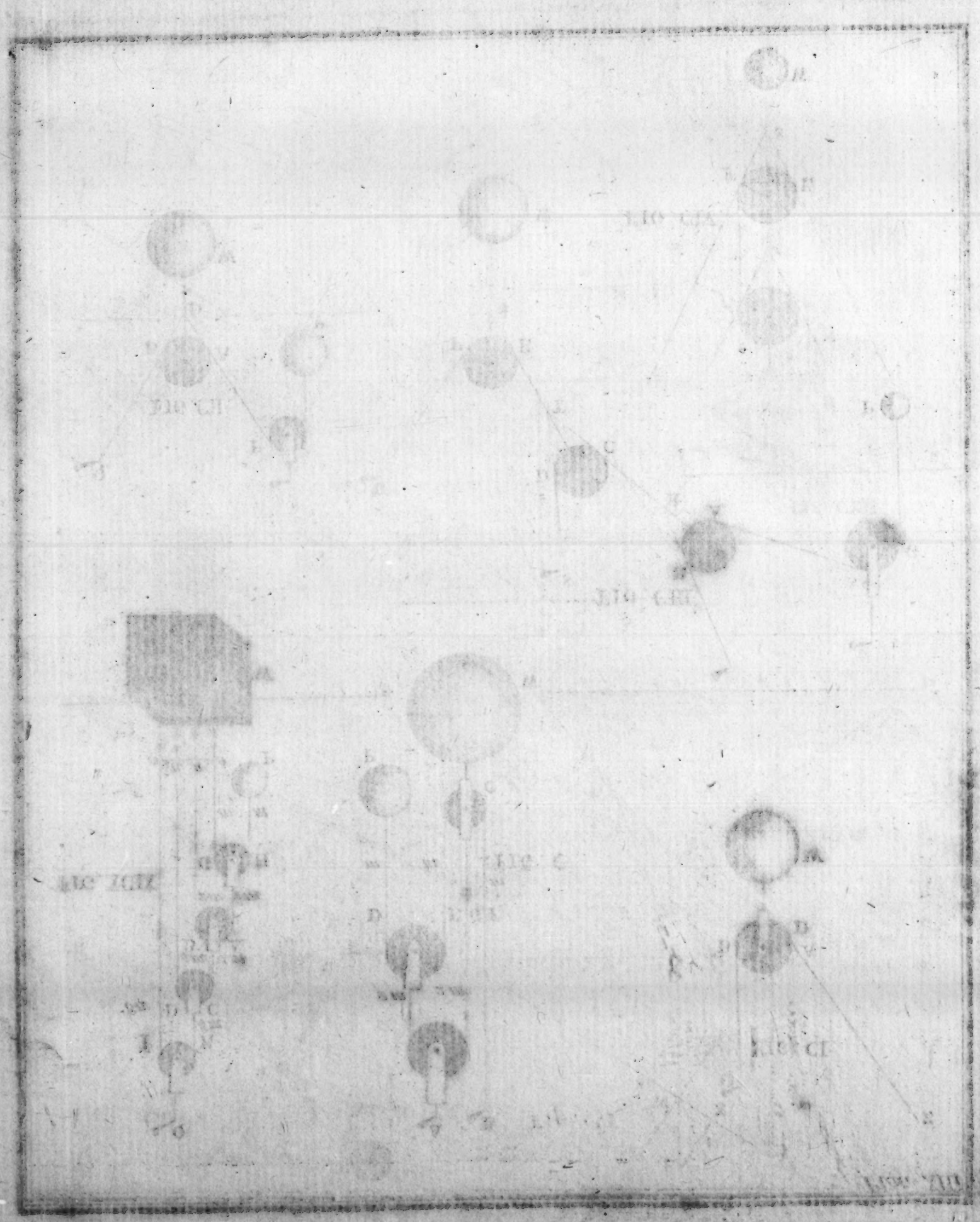


FIG. CV.

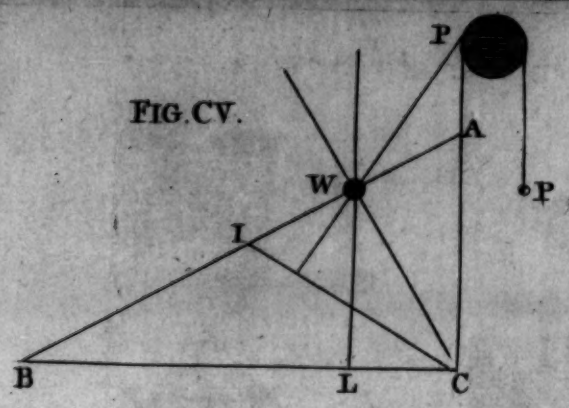


FIG. CVI.

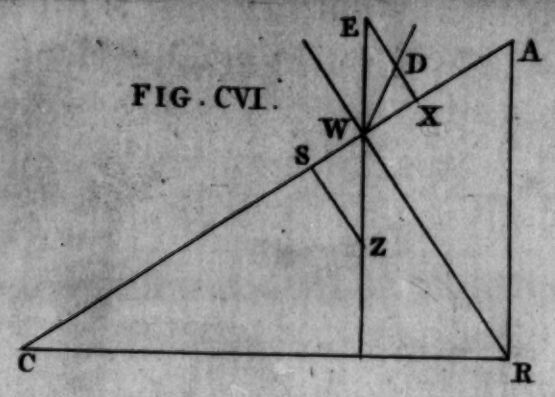


FIG. CVII.

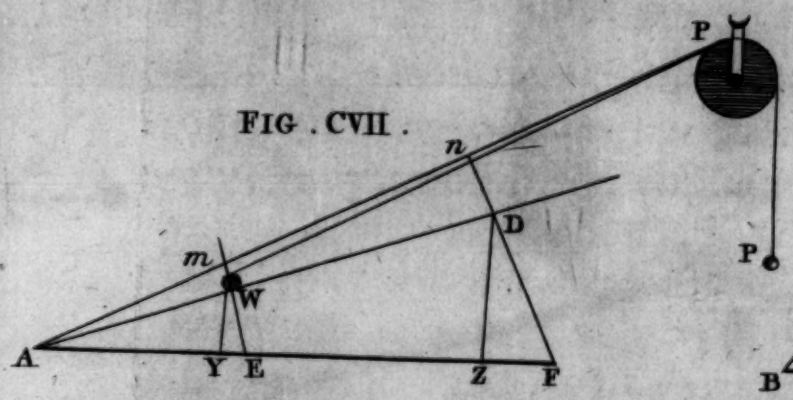


FIG. CVIII.

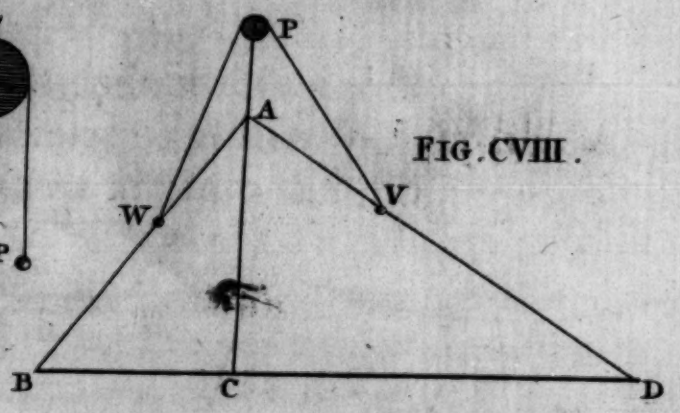


FIG. CIX.

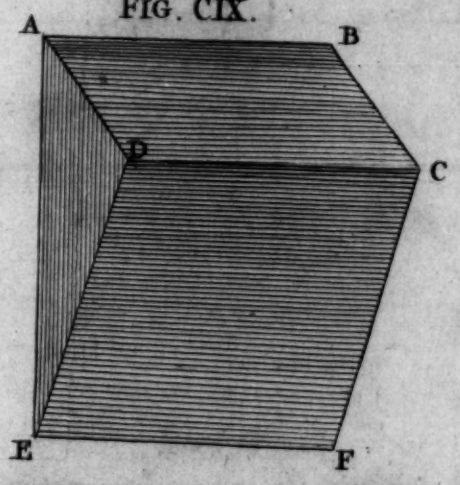


FIG. CX.

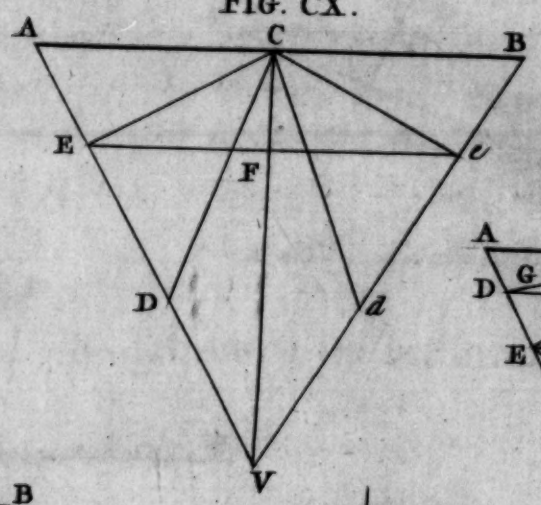


FIG. CXII.

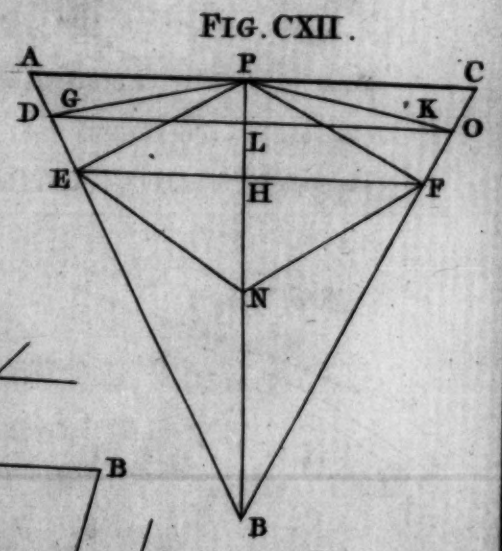


FIG. CXI.

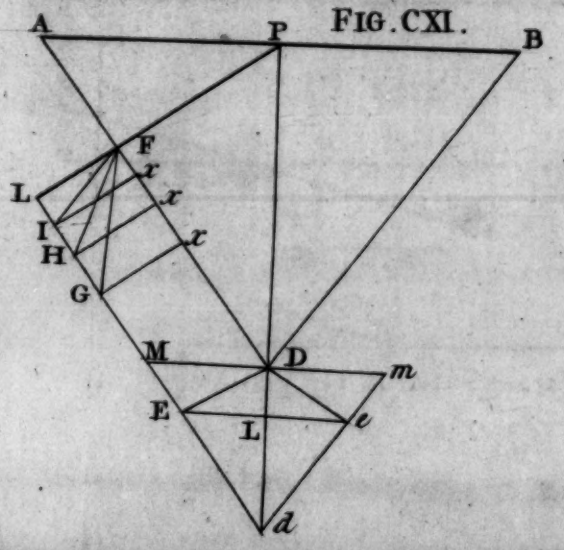
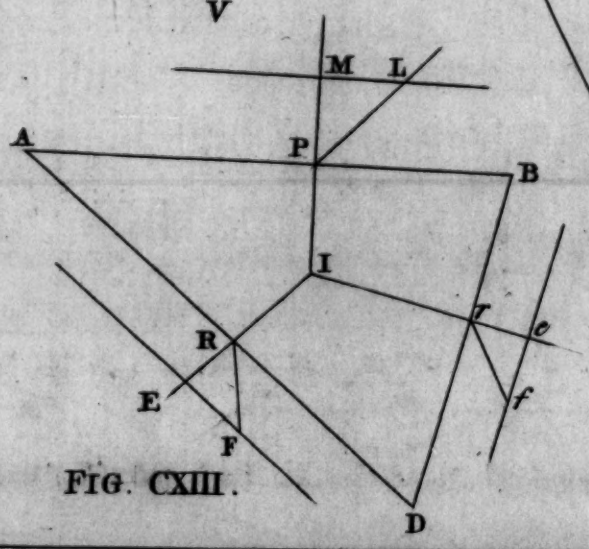


FIG. CXIII.



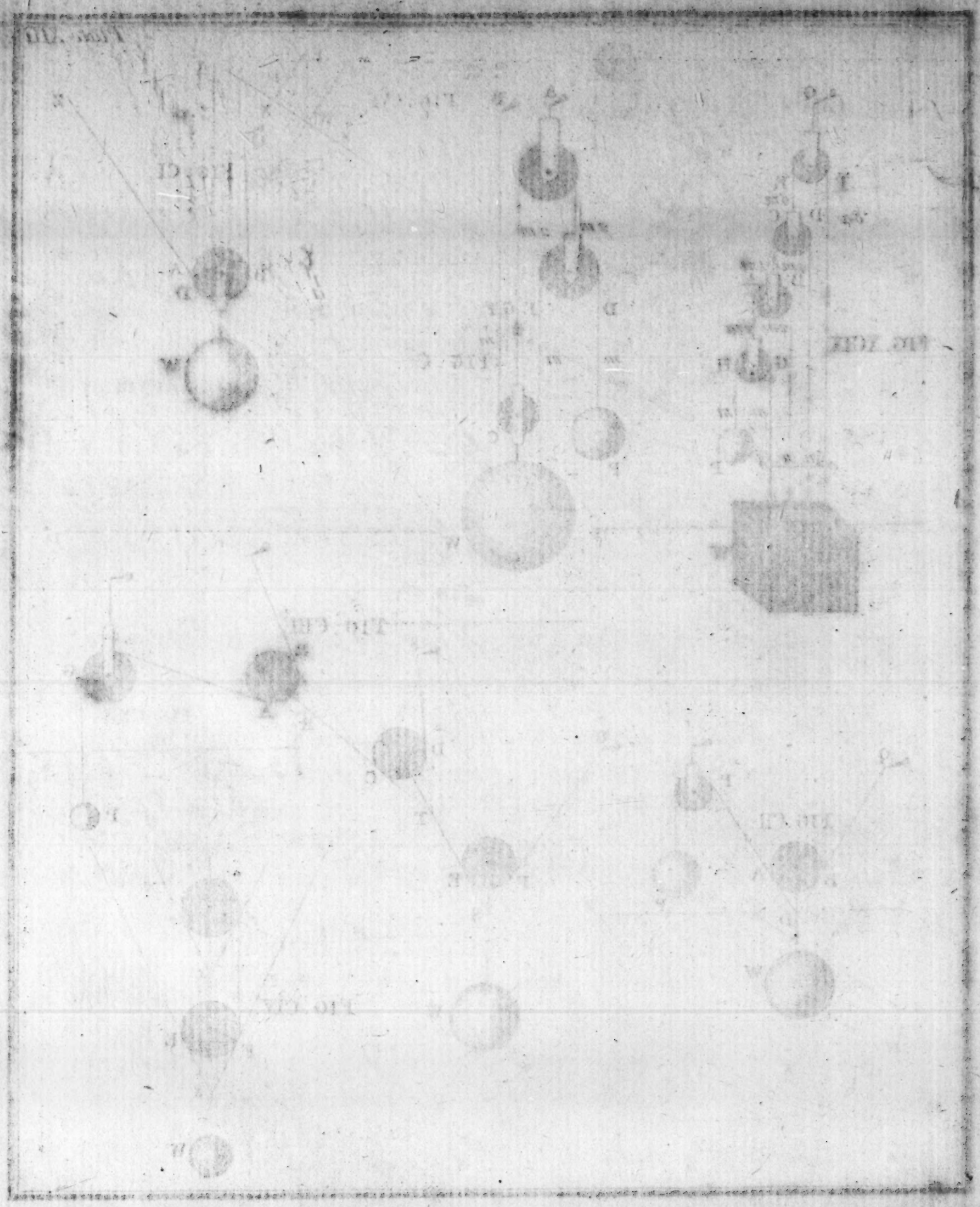


FIG. CV.

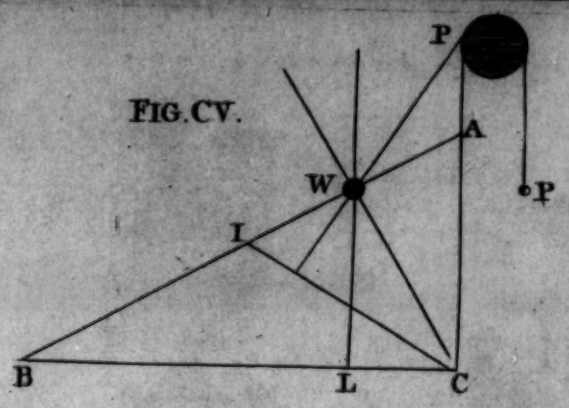


FIG. CVI.

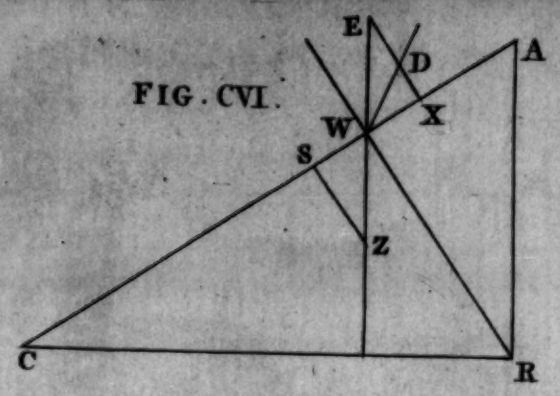


FIG. CVII.

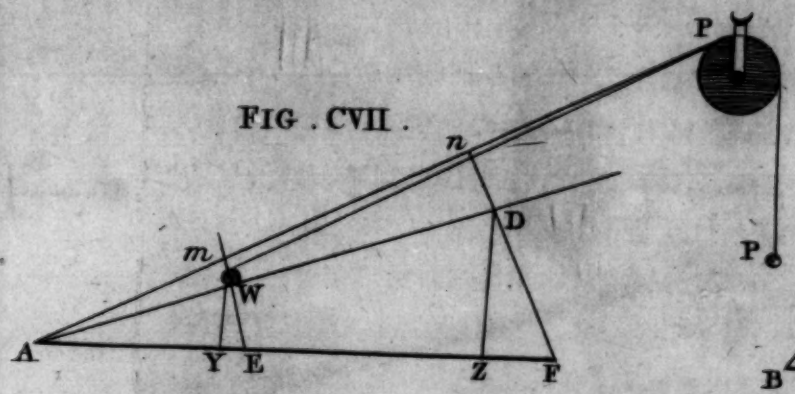


FIG. CVIII.

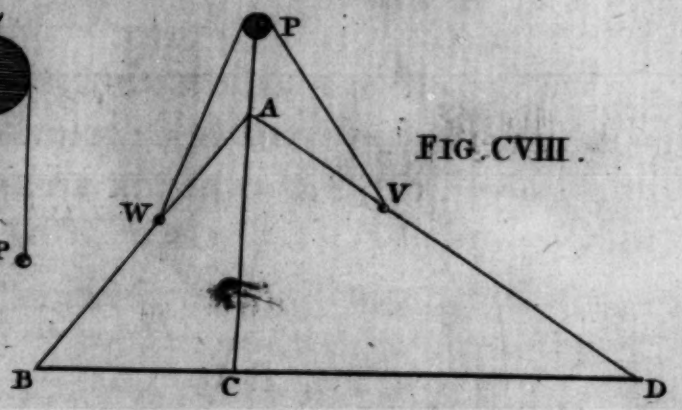


FIG. CIX.

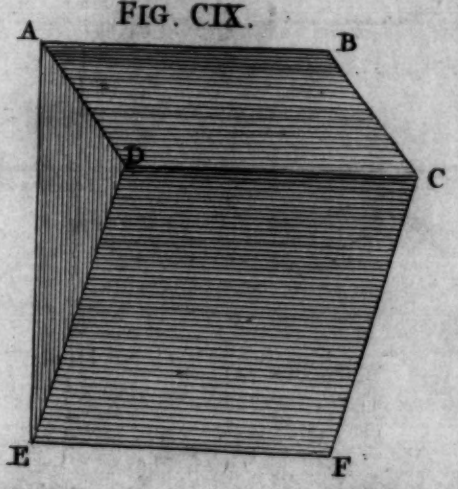


FIG. CX.

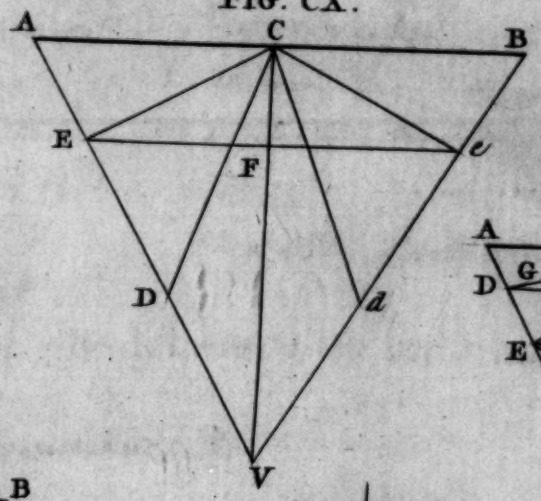


FIG. CXII.

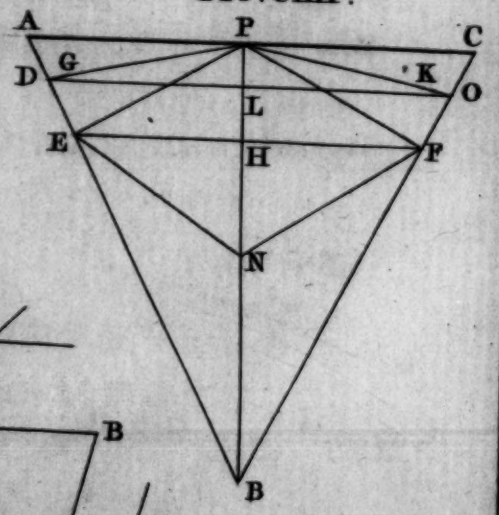


FIG. CXI.

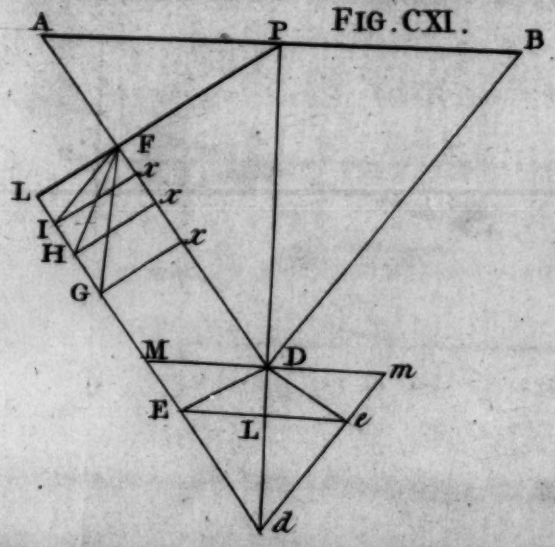
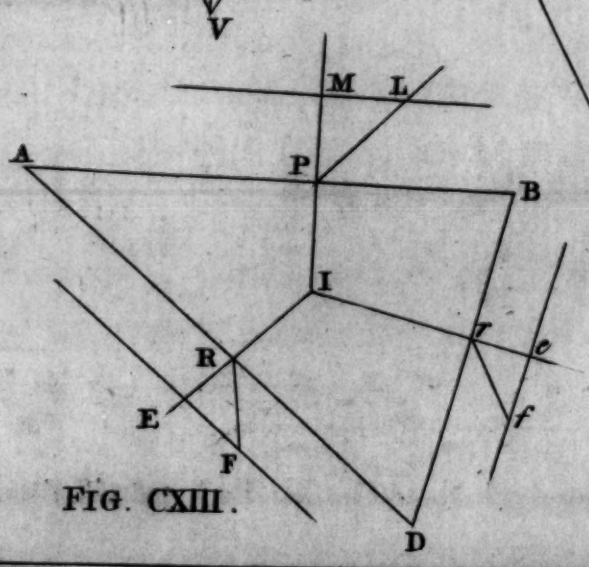


FIG. CXIII.



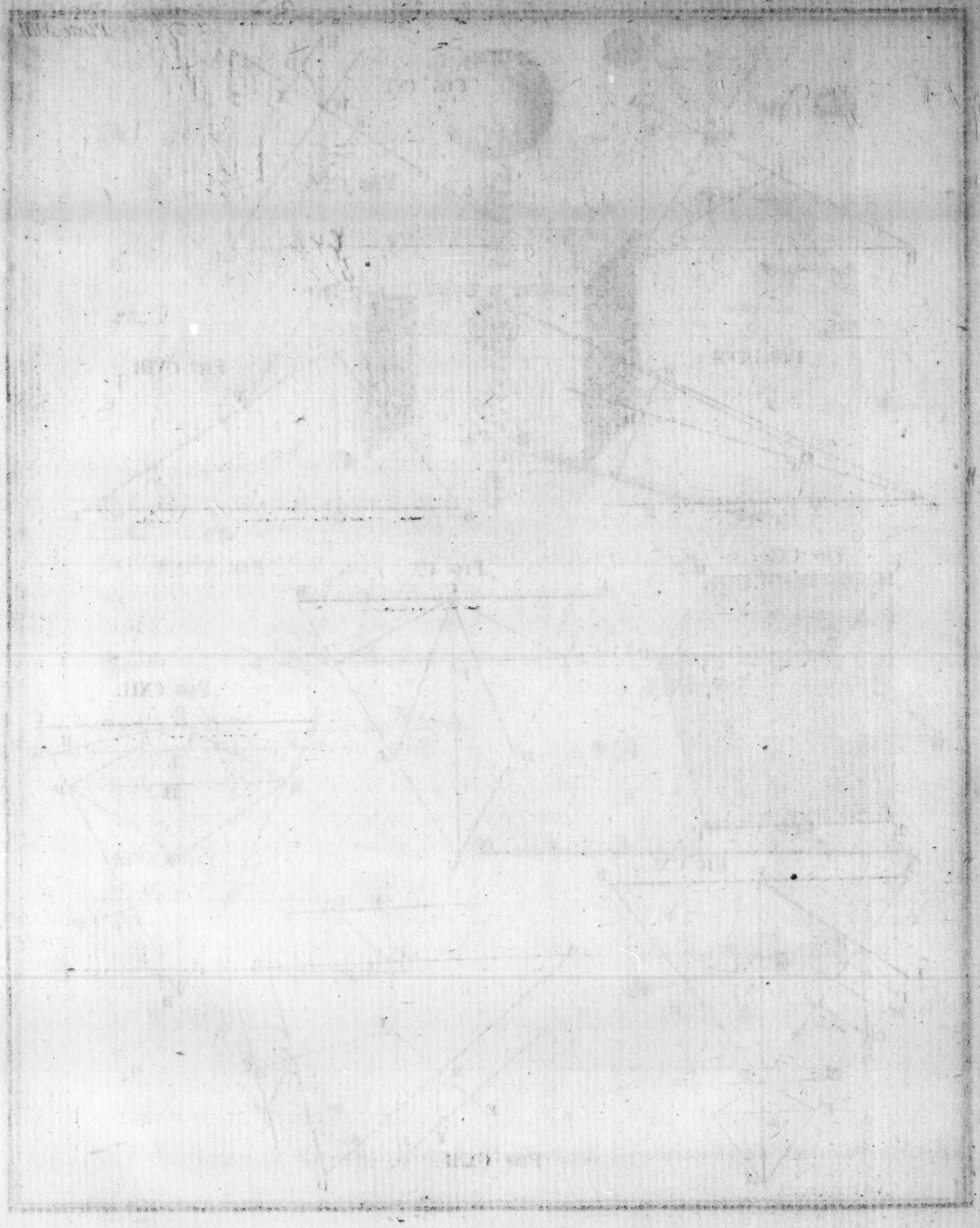
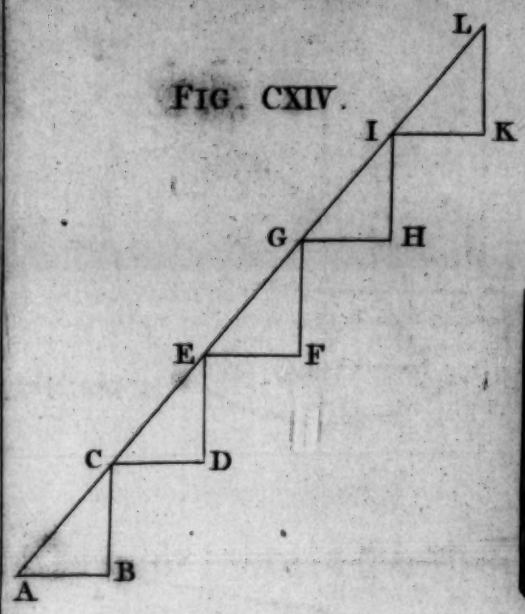


FIG. CXIV.



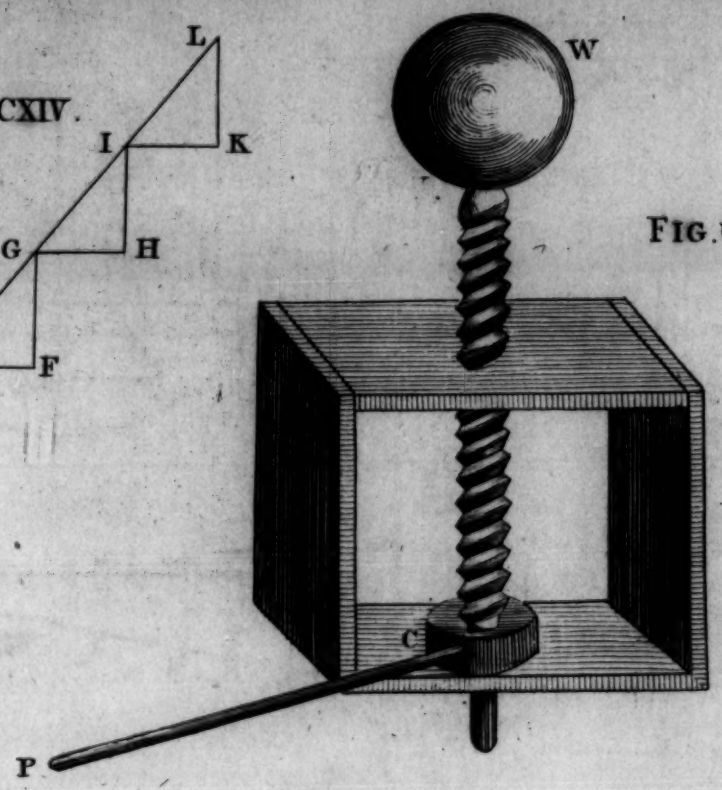


FIG. CXV.

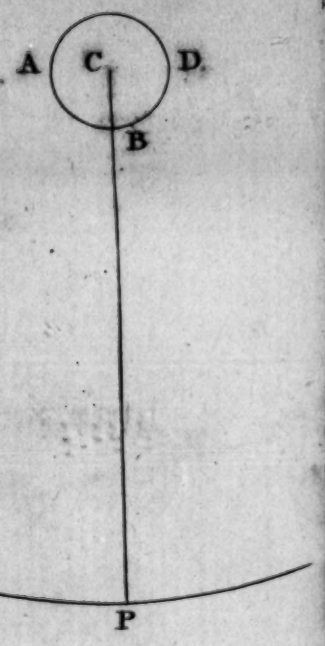


FIG. CXVI.

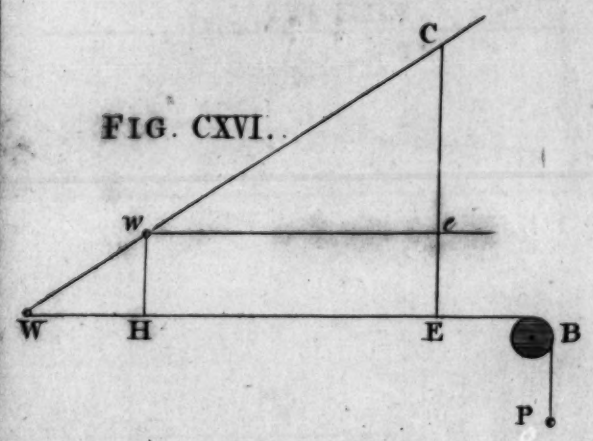


FIG. CXVII.

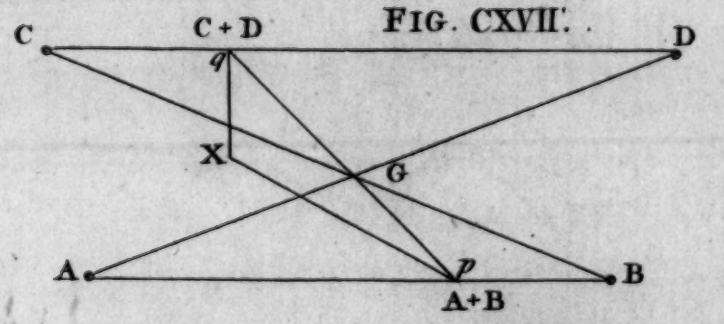


FIG. CXVIII.

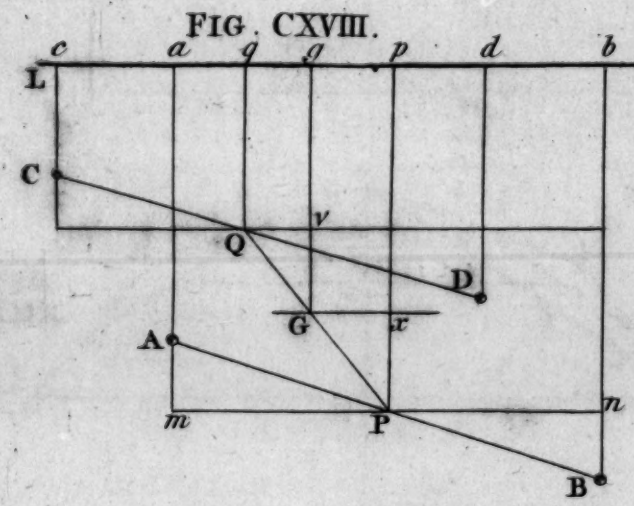
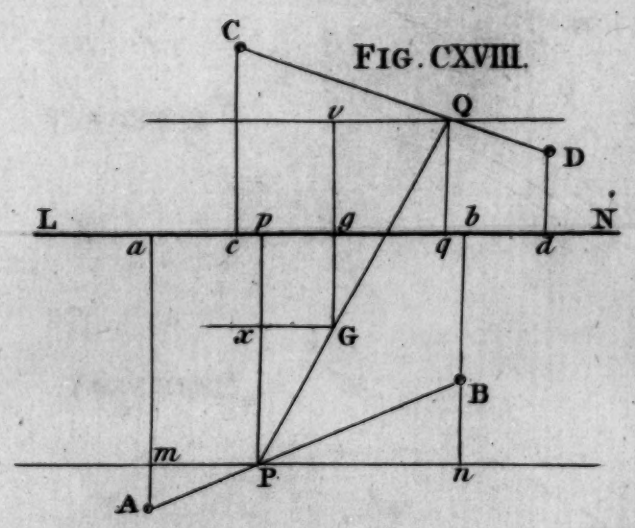


FIG. CXVIII.



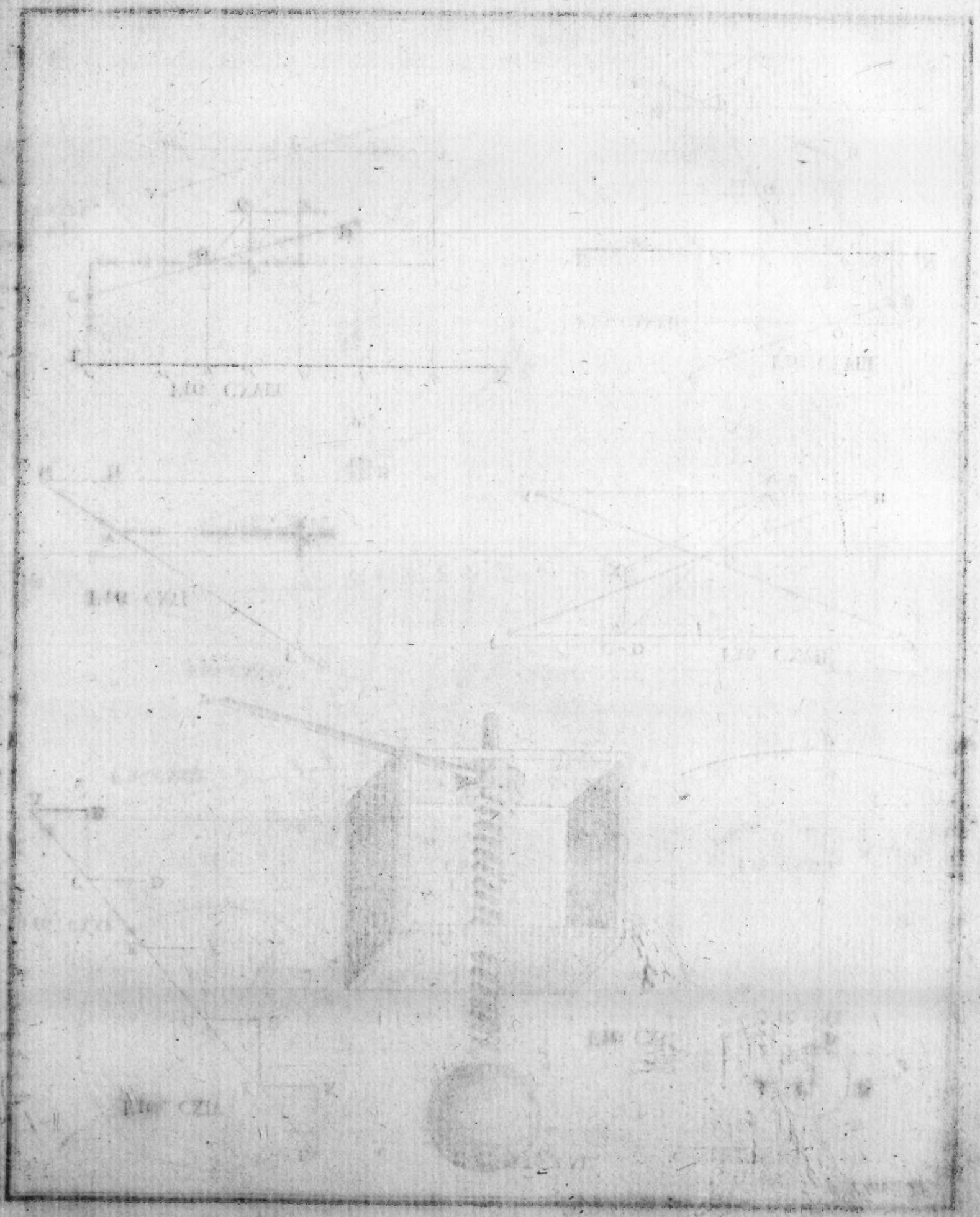


Plate XVI.

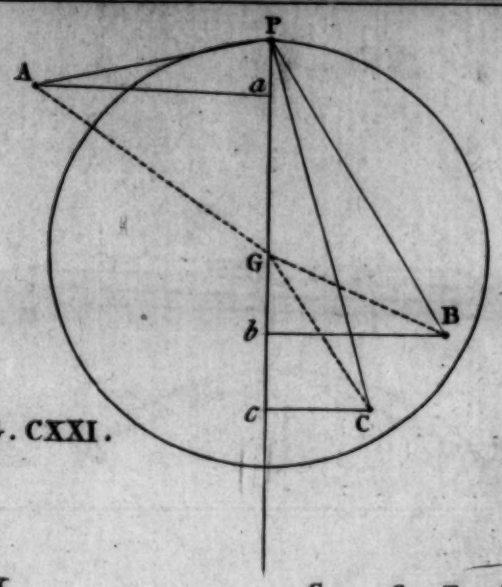


FIG. CXXI.

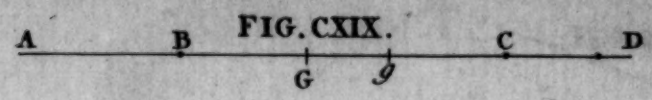


FIG. CXIX.

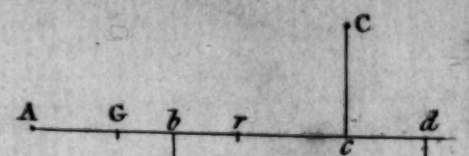


FIG. CXX.



FIG. CXXII.

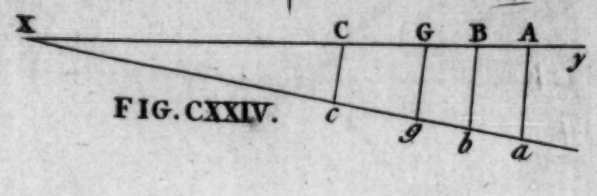


FIG. CXXIV.

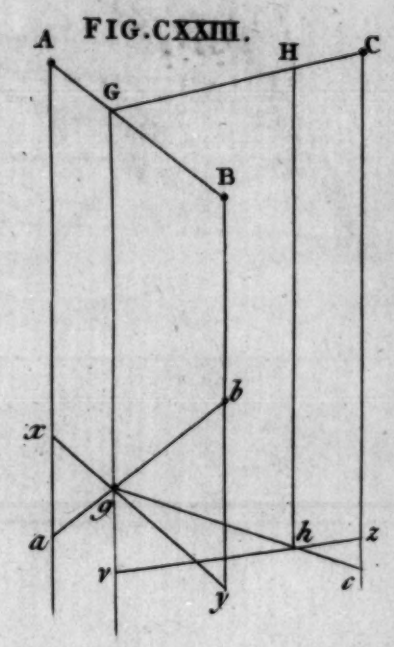


FIG. CXXIII.

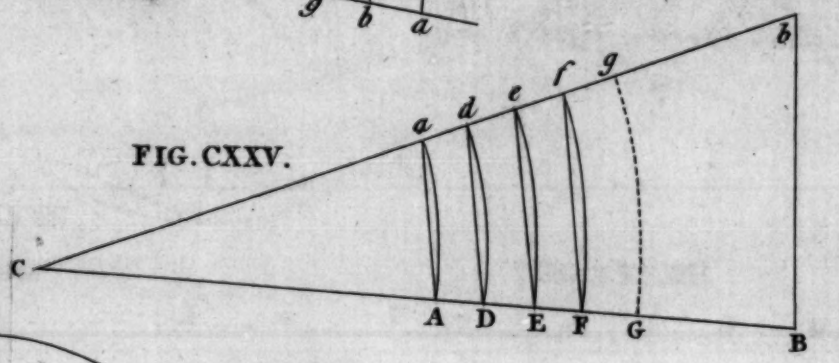


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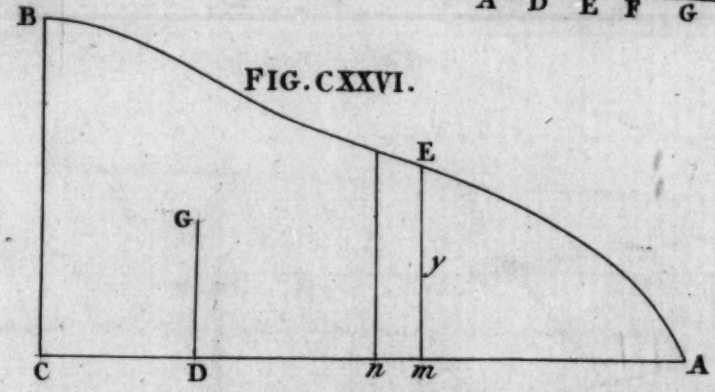


FIG. CXXVI.

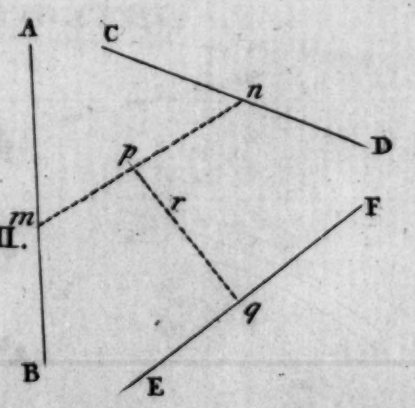


FIG. CXXVII.

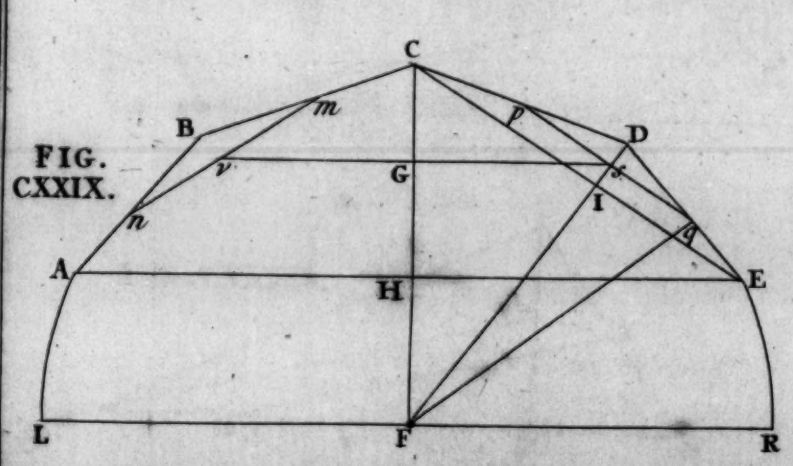


FIG. CXXIX.

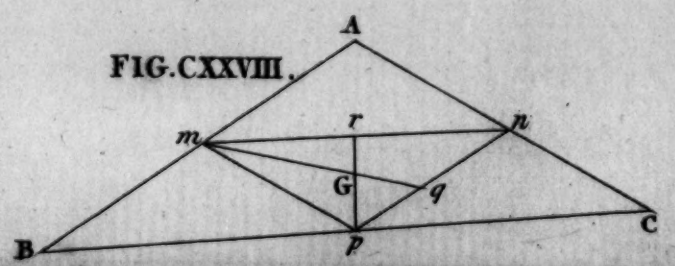


FIG. CXXVIII.

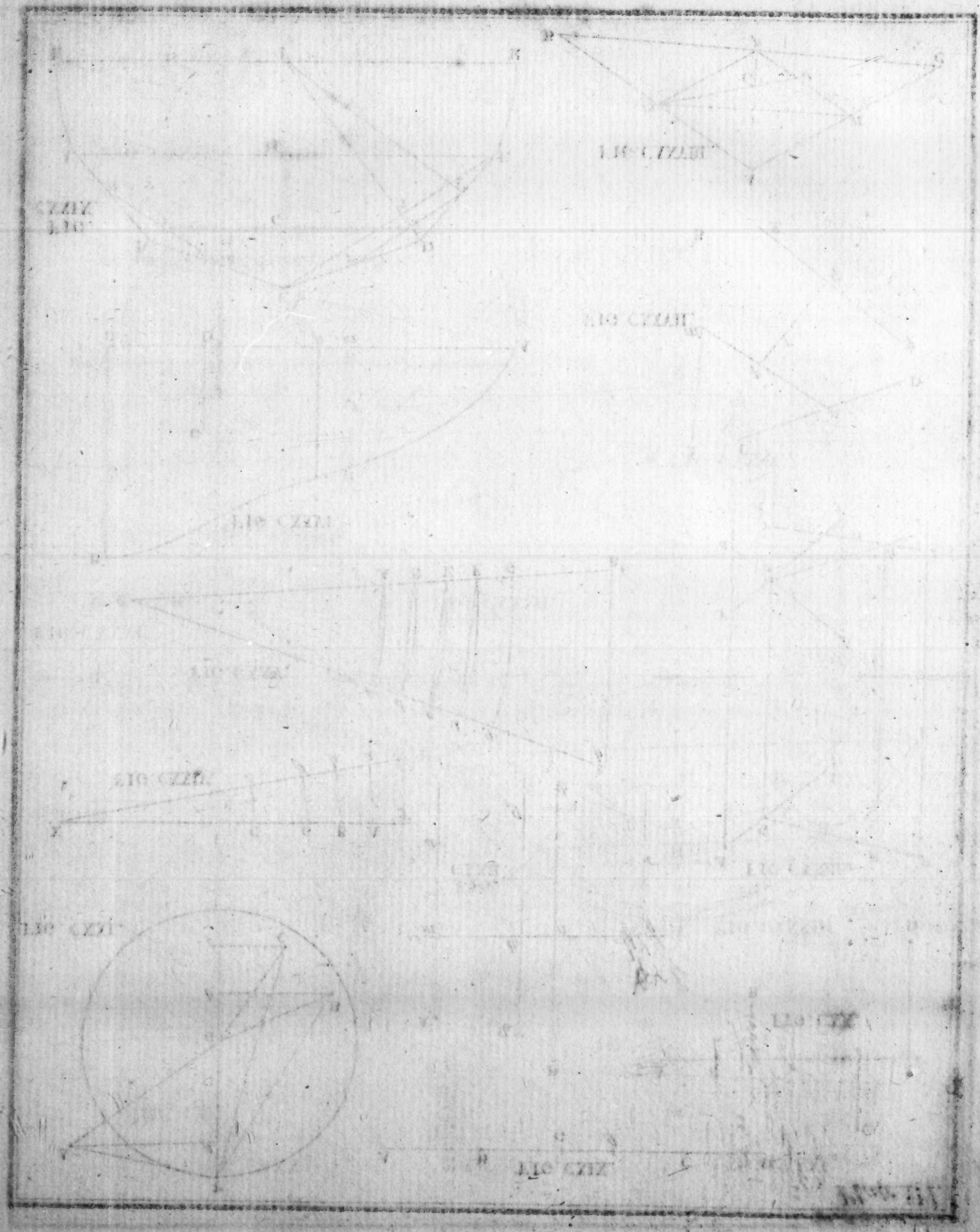


Plate XVII.

FIG. CXXX.

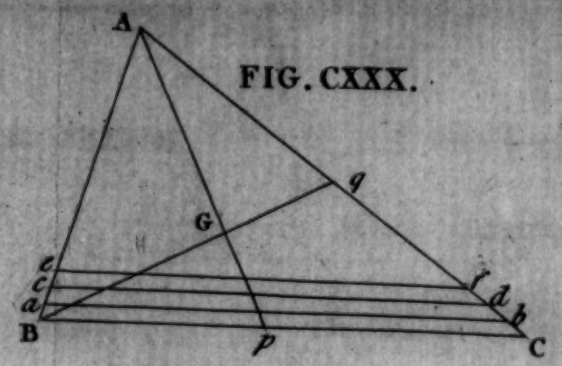
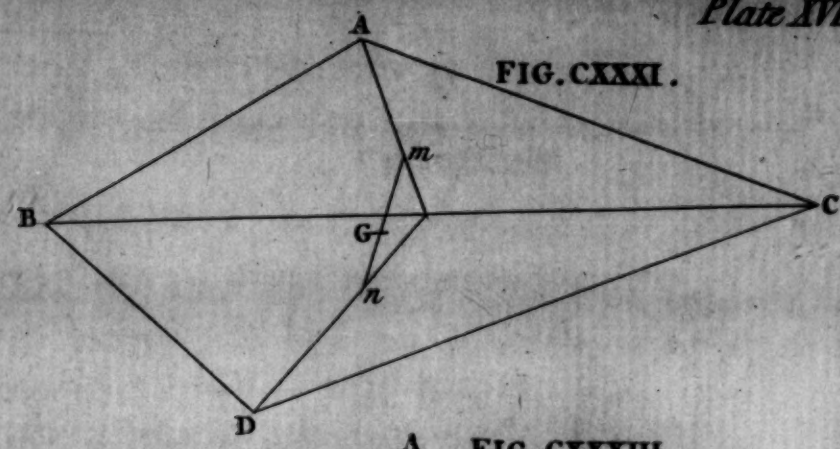


FIG. CXXXI.



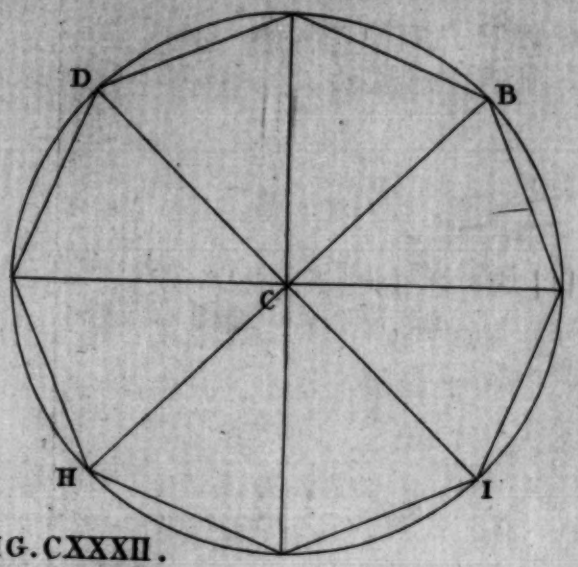


FIG. CXXXII.

FIG. CXXXIII

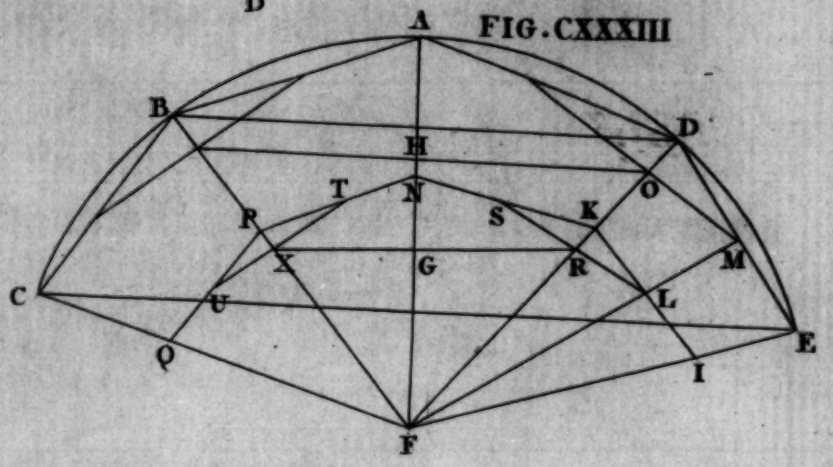


FIG. CXXXIV.

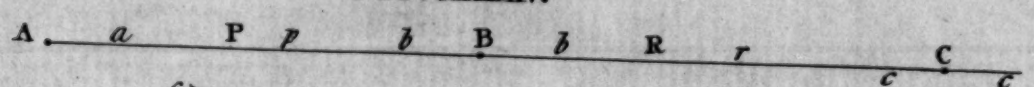


FIG. CXXXV.

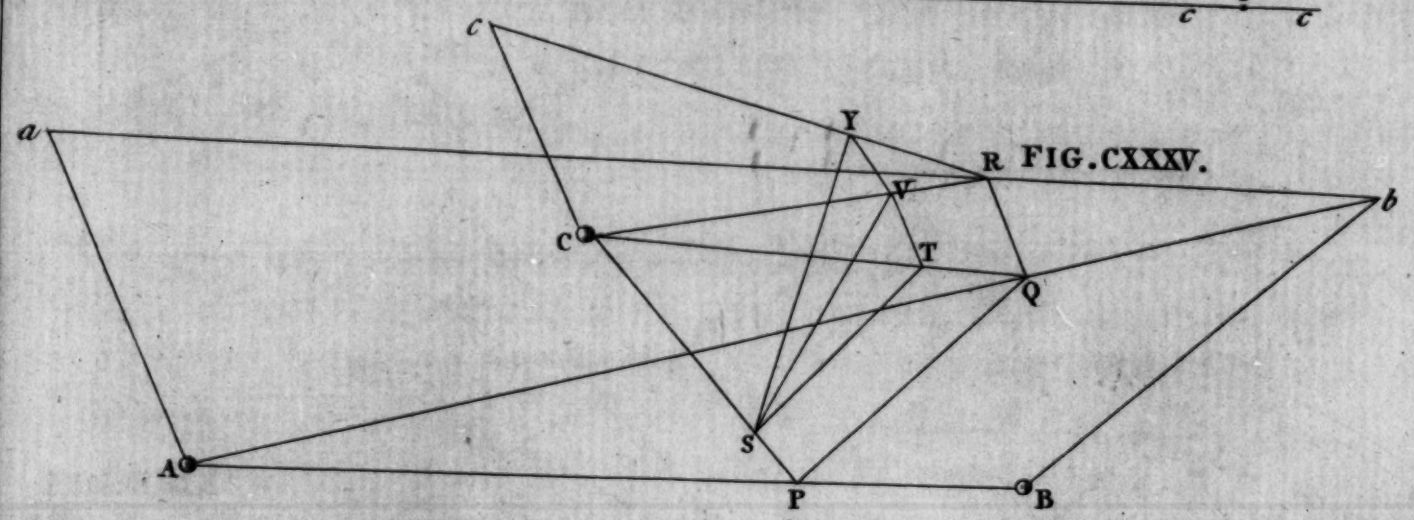
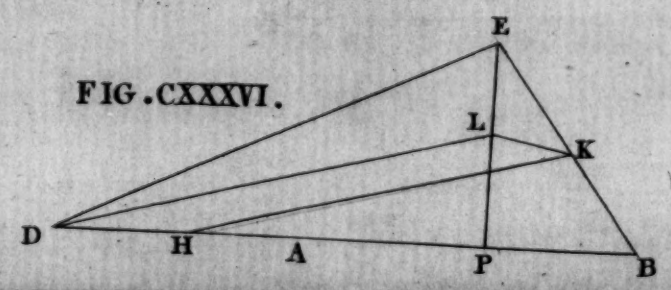


FIG. CXXXVI.



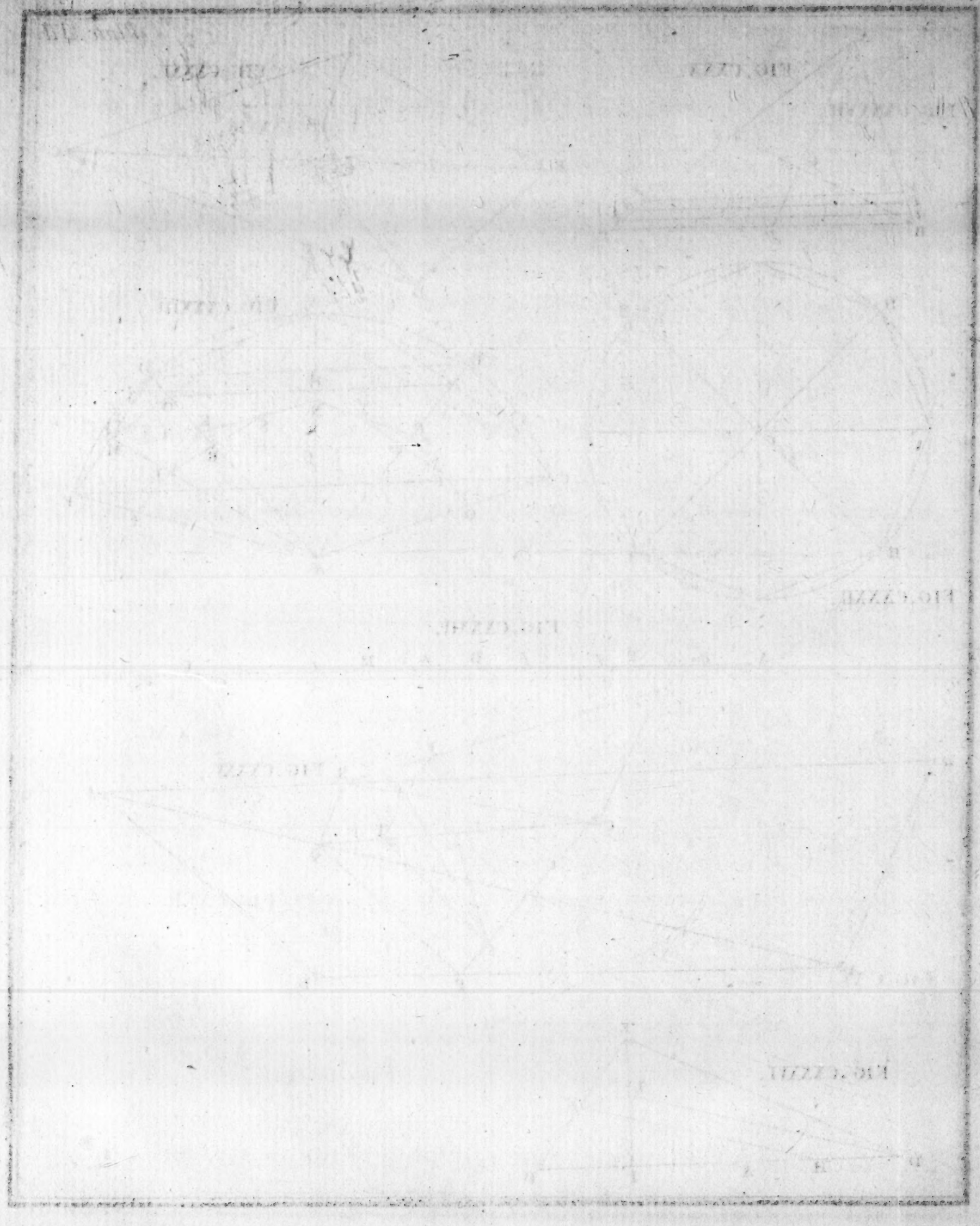


Plate XVIII.

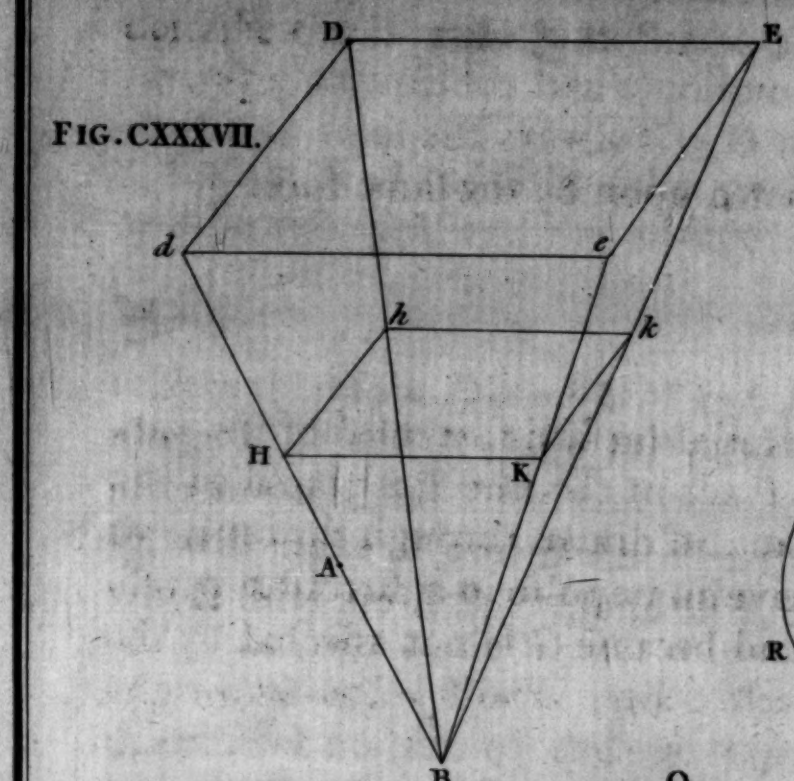


FIG. CXXXVII.

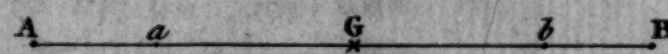


FIG. CXXXVIII.

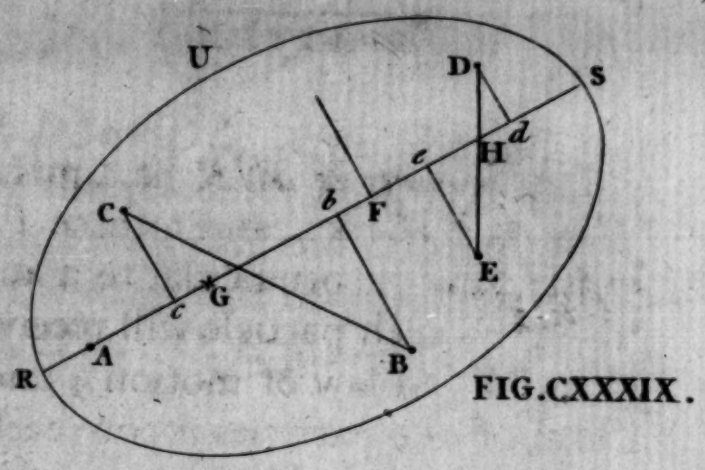


FIG. CXXXIX.

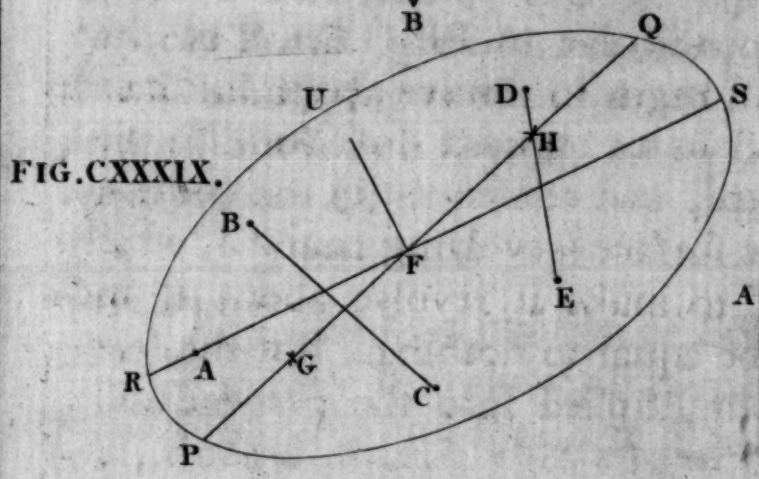


FIG. CXXXIX.

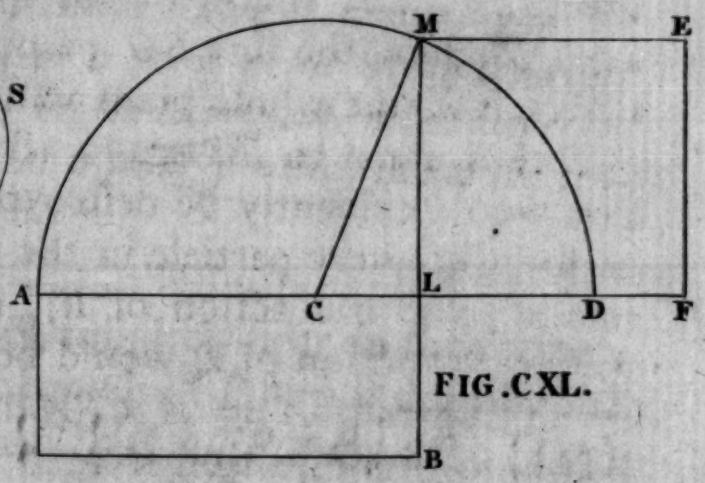


FIG. CXL.

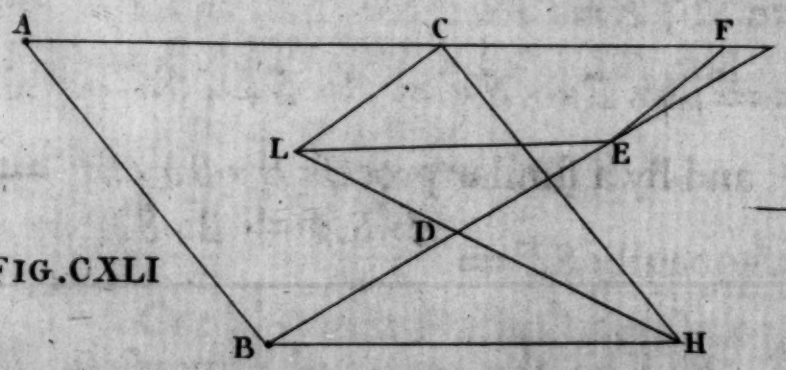


FIG. CXLI

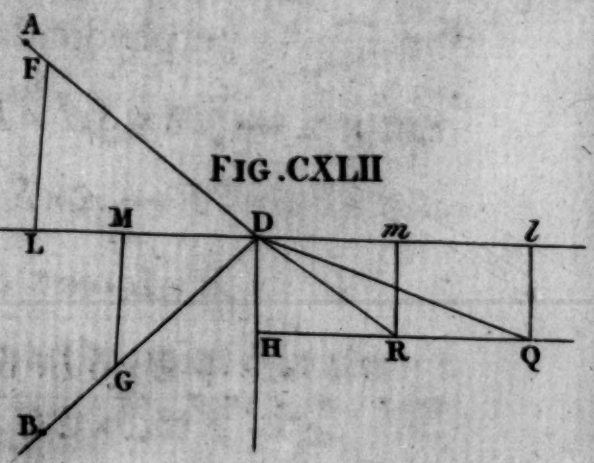


FIG. CXLII

FIG. CXLIII.

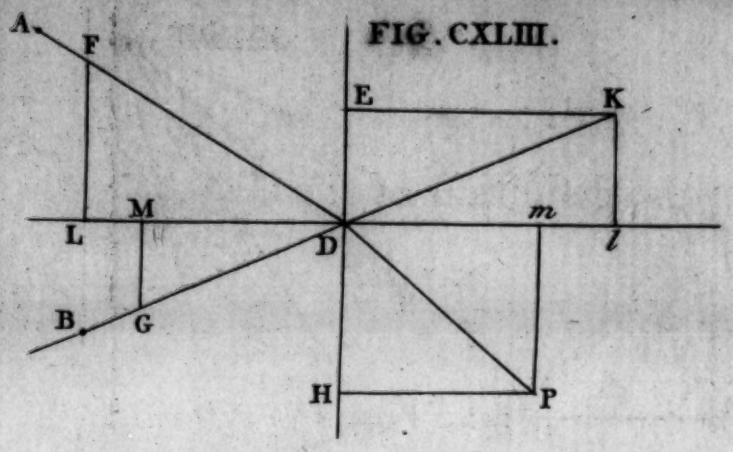


FIG. CXLIV.

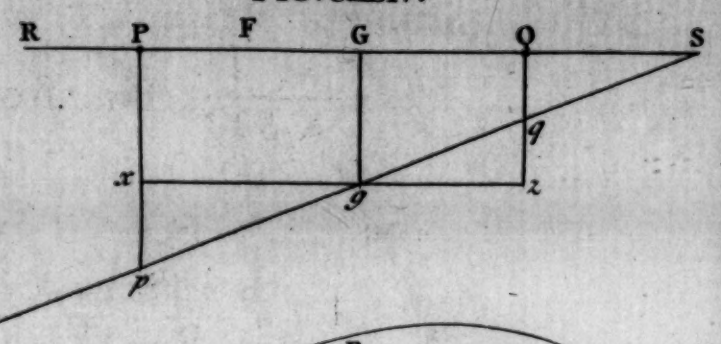
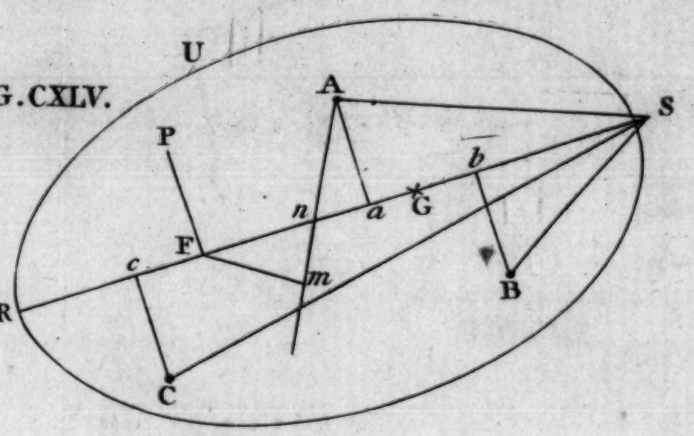


FIG. CXLV.



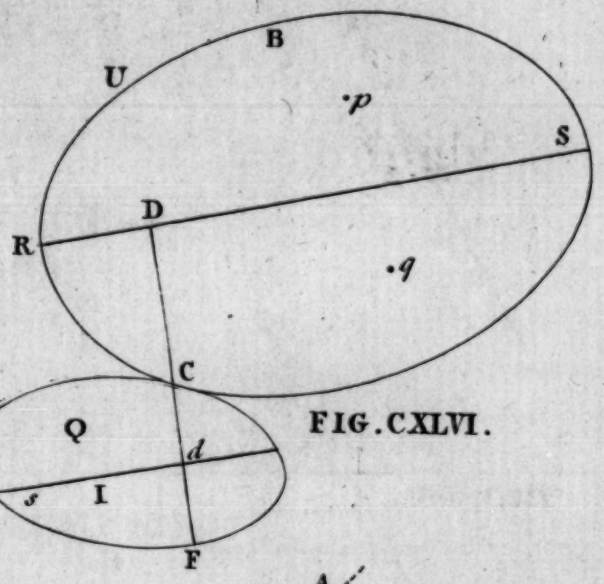
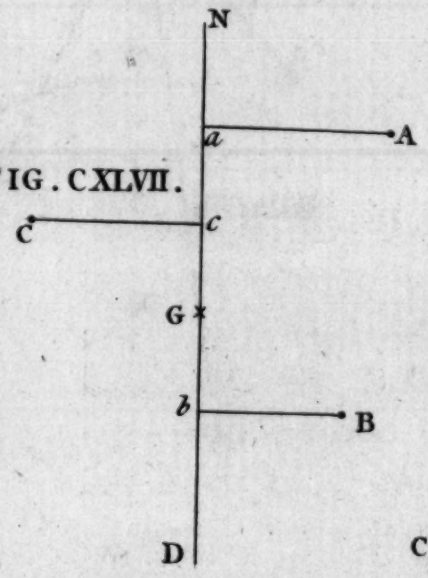


FIG. CXLVI.

FIG. CXLVII.



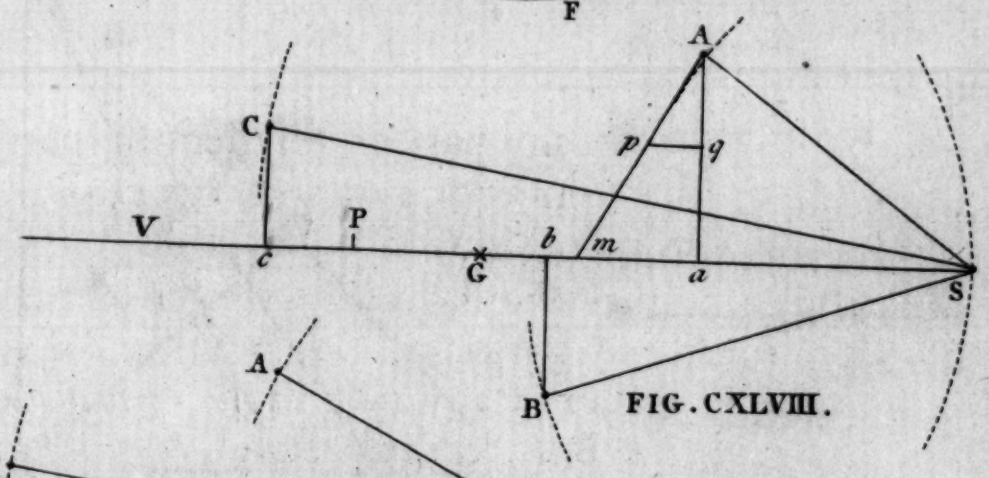


FIG. CXLVIII.

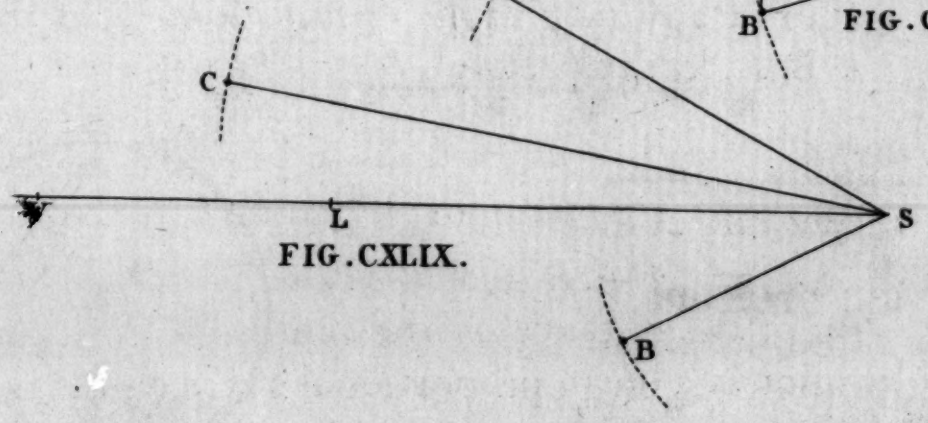


FIG. CXLIX.

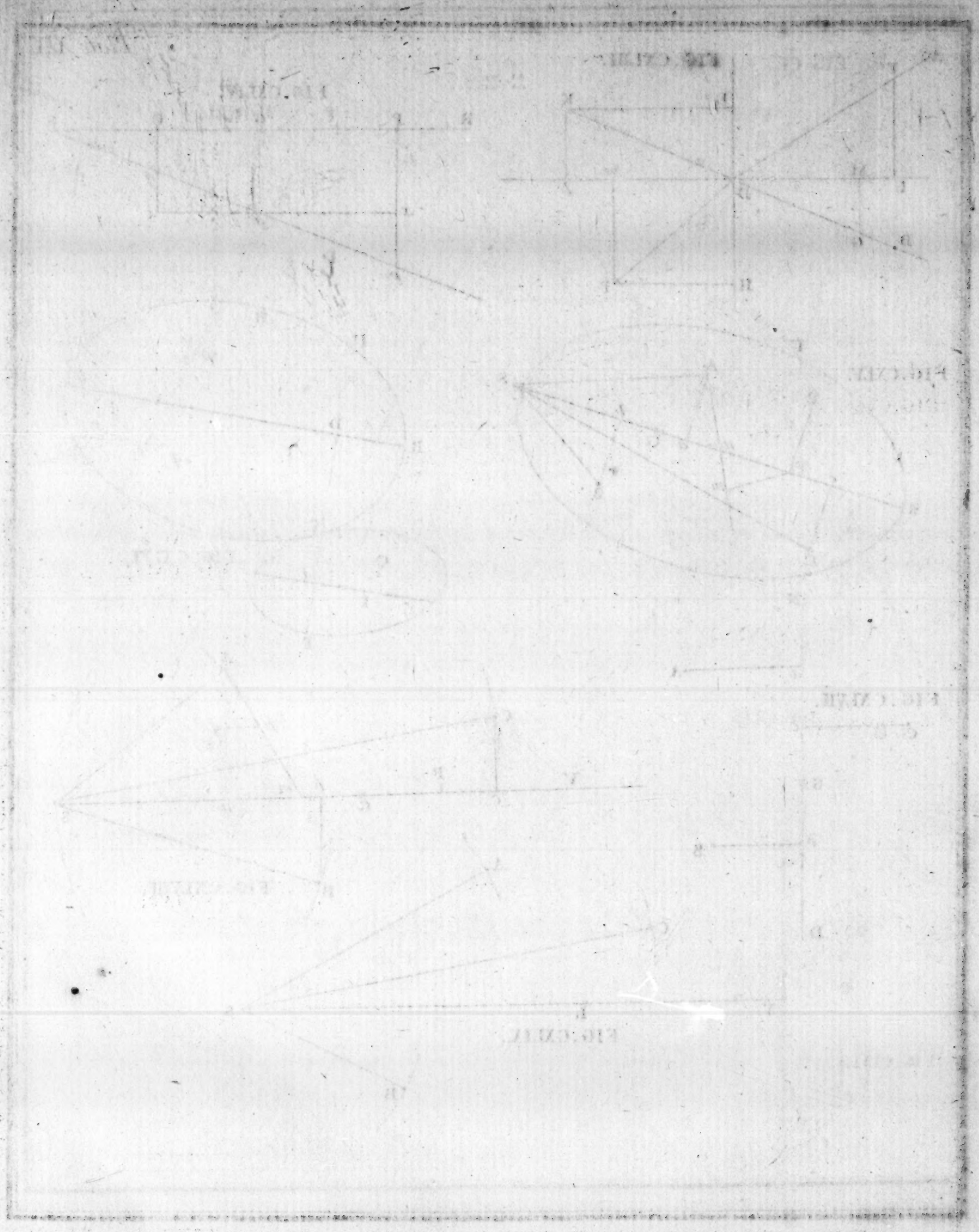


Plate XX.

FIG.CL.

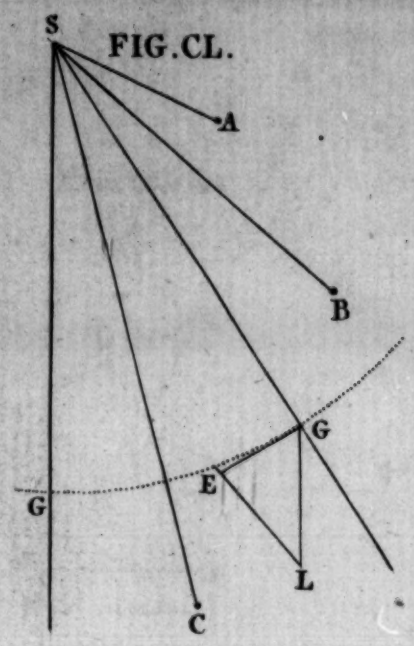
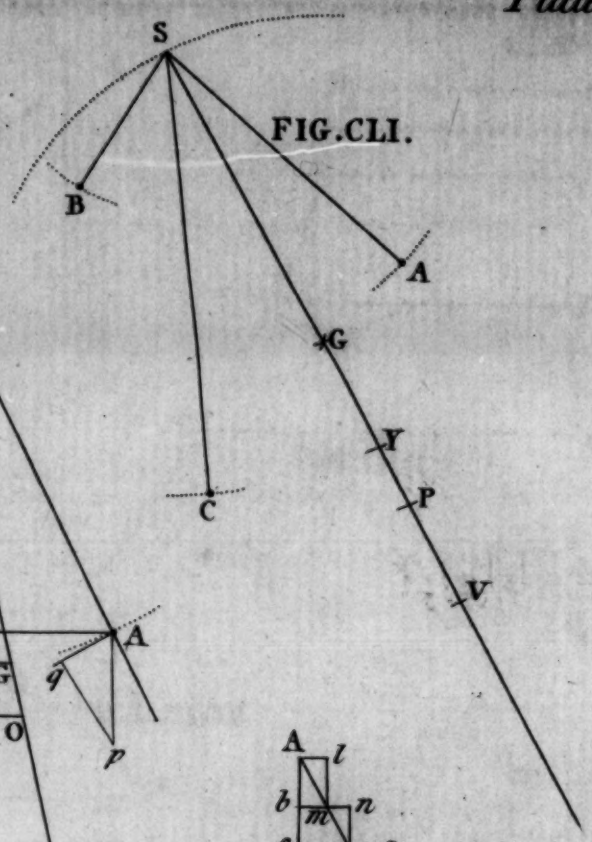


FIG.CLI.



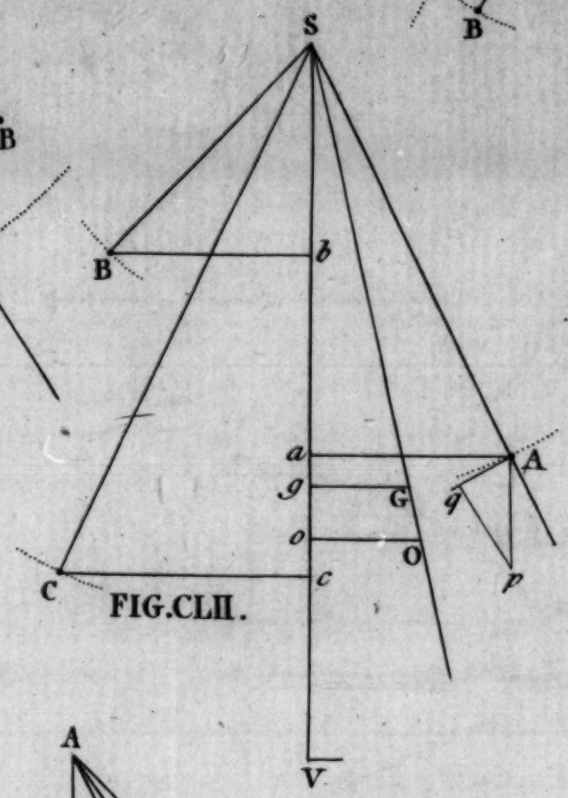


FIG.CLII.

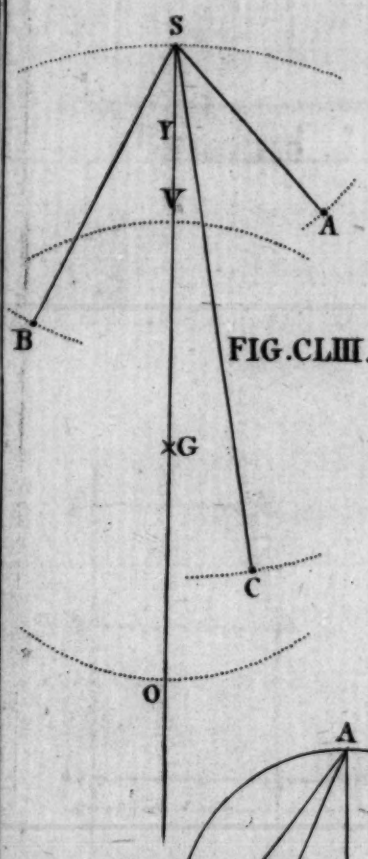


FIG.CLIII.

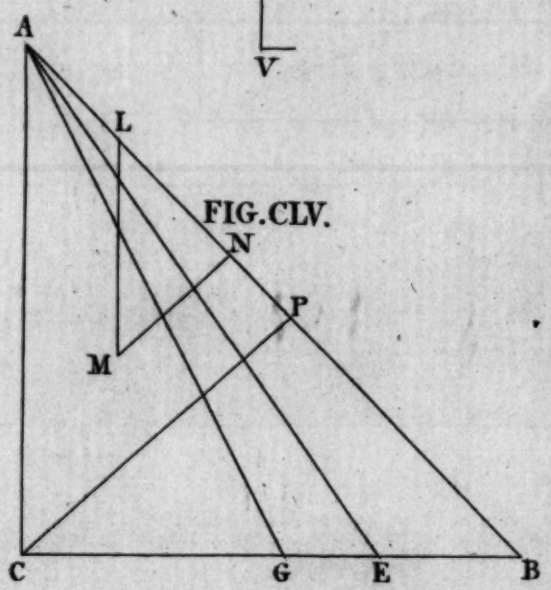


FIG.CLV.

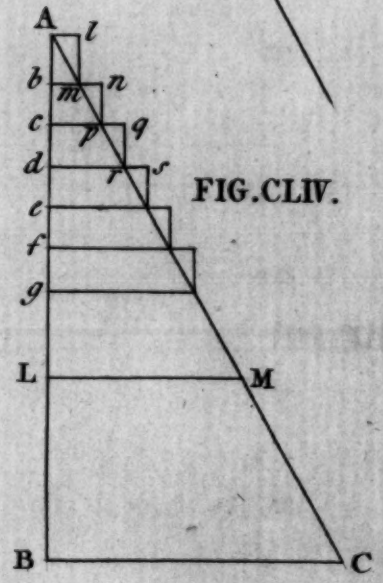


FIG.CLIV.

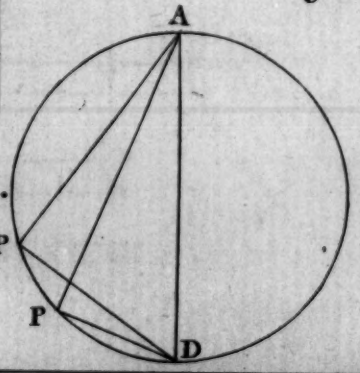


FIG.CLVI.

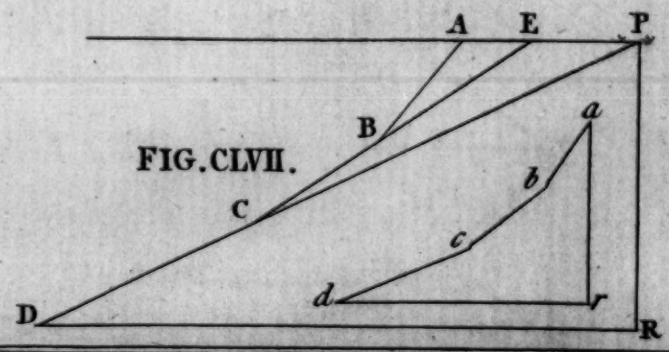


FIG.CLVII.

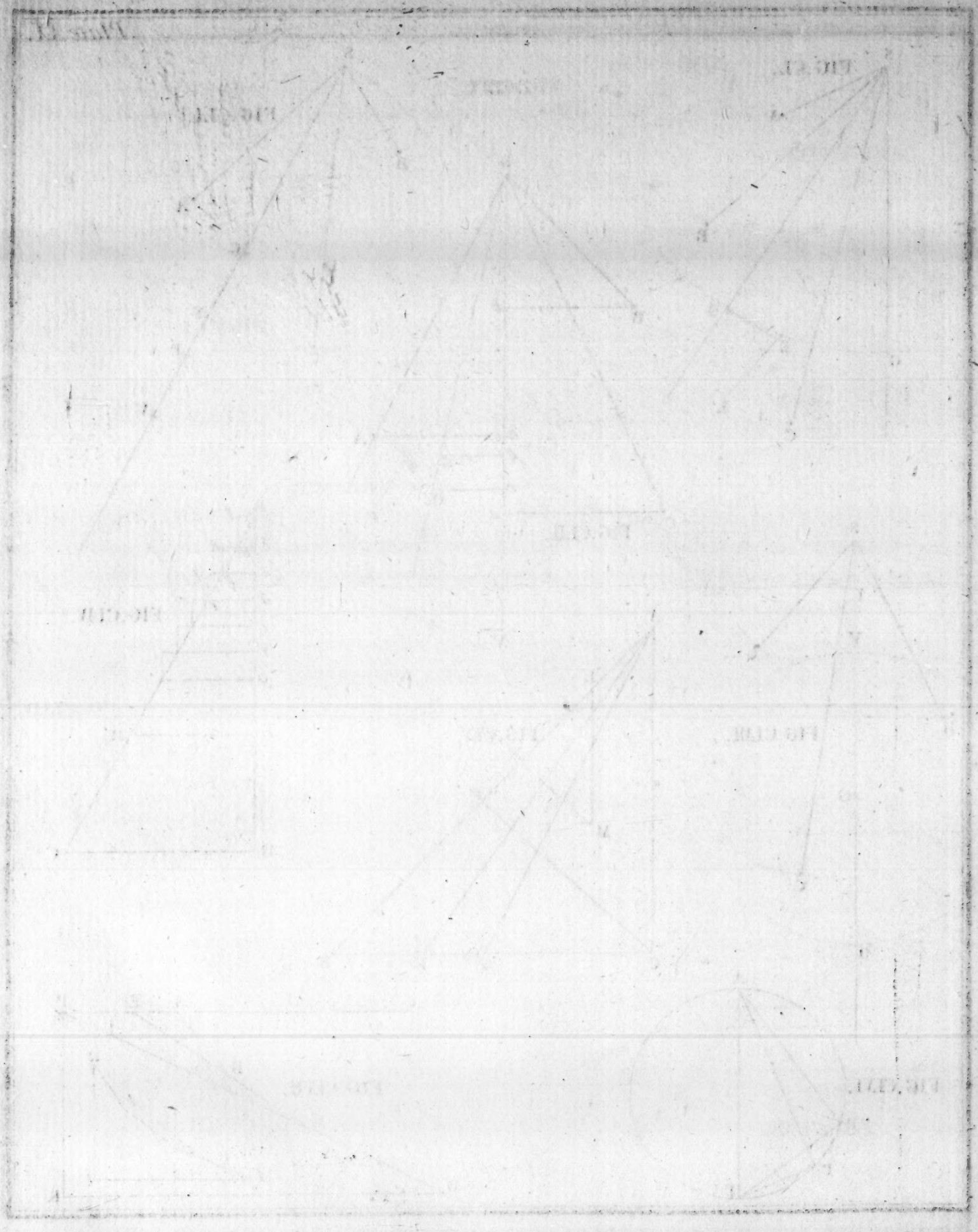


Plate XXI.

FIG. CLVIII.

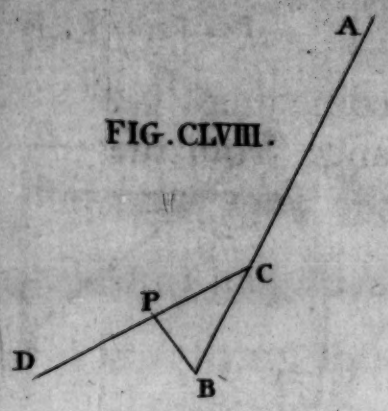
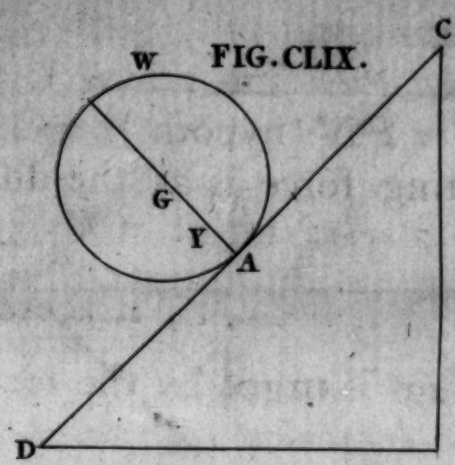


FIG. CLIX.



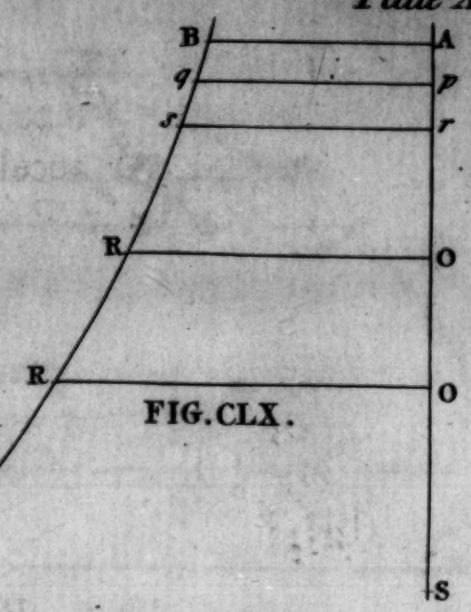


FIG. CLX.

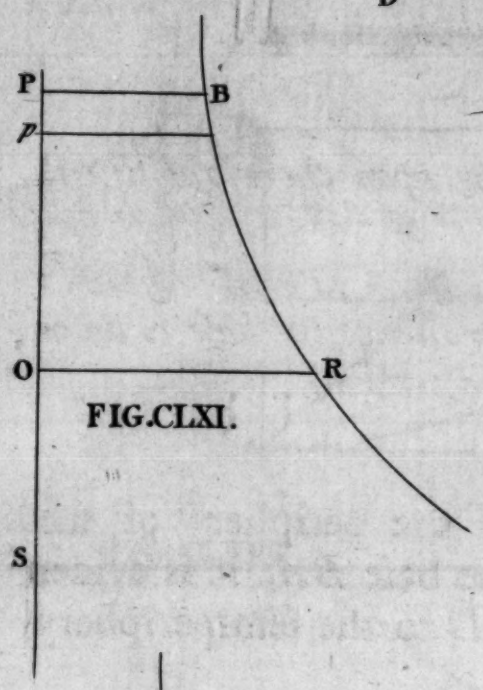


FIG. CLXI.

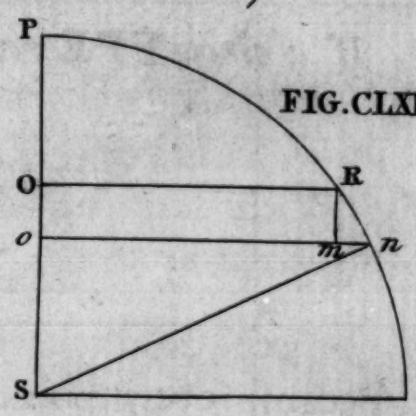


FIG. CLXII.

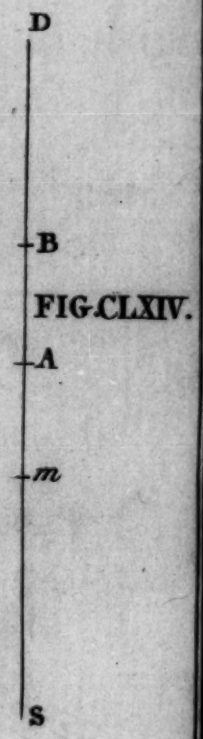


FIG. CLXIV.

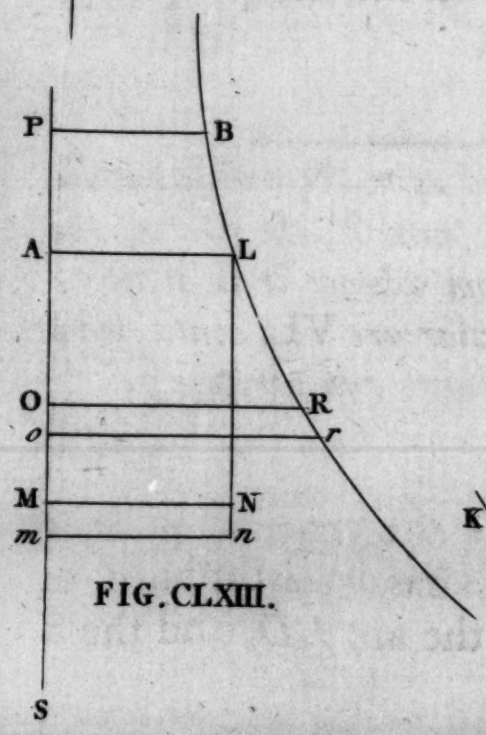


FIG. CLXIII.

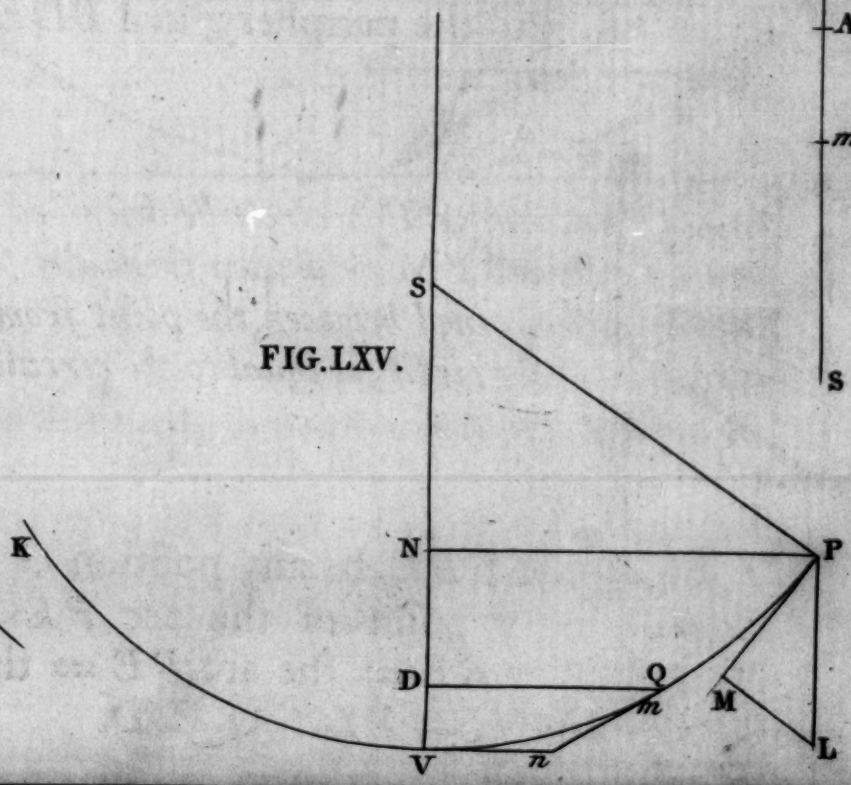


FIG. LXV.

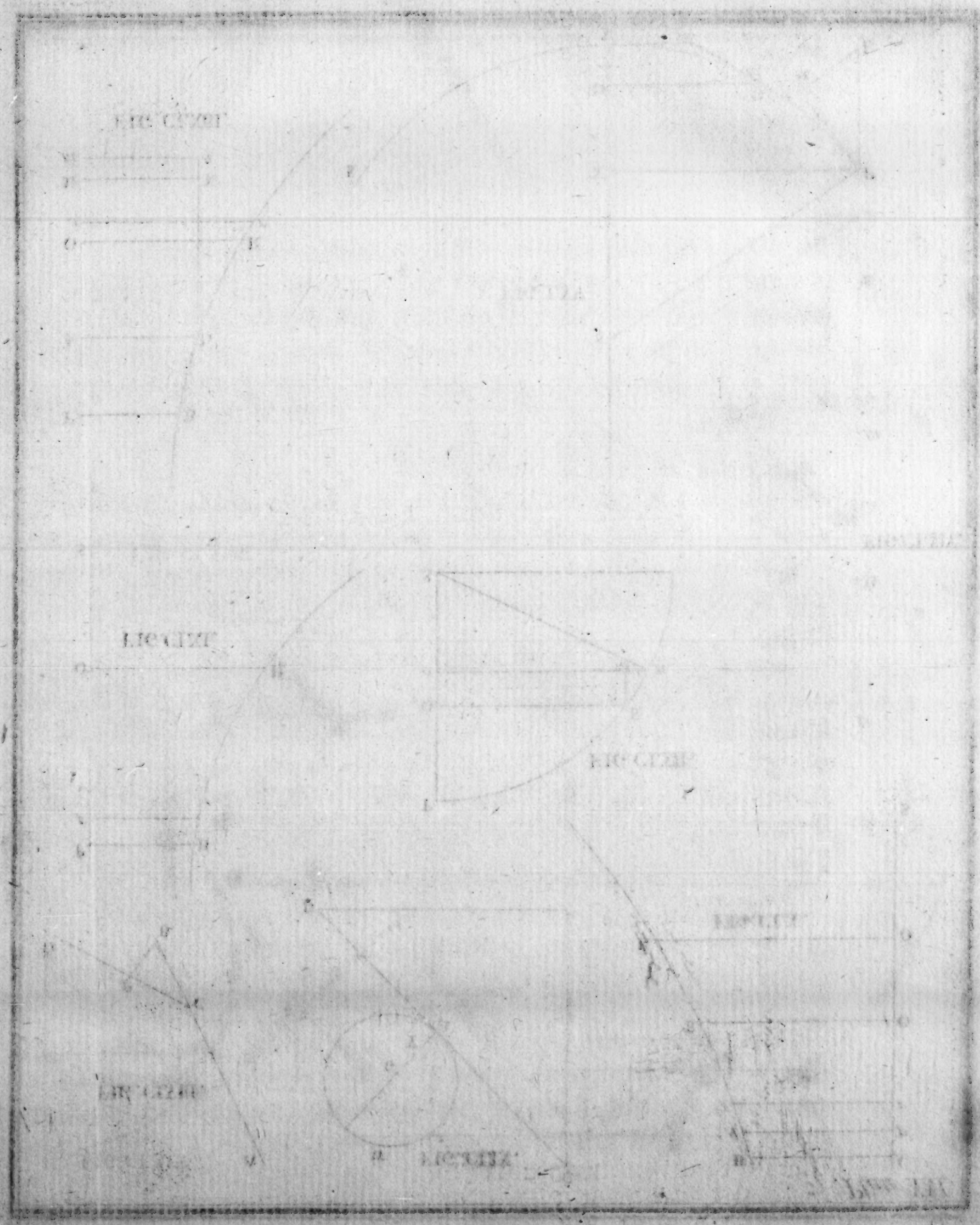


Plate XXII.

FIG. CLXVI.

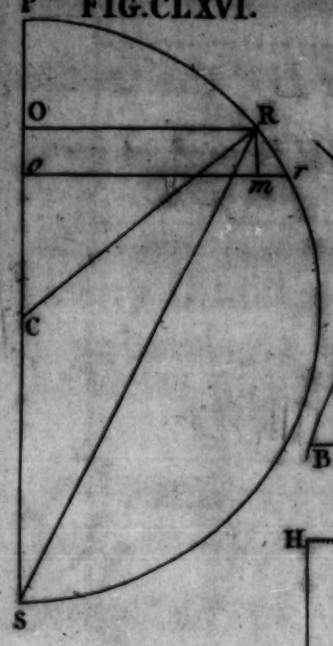


FIG. CLXVII.

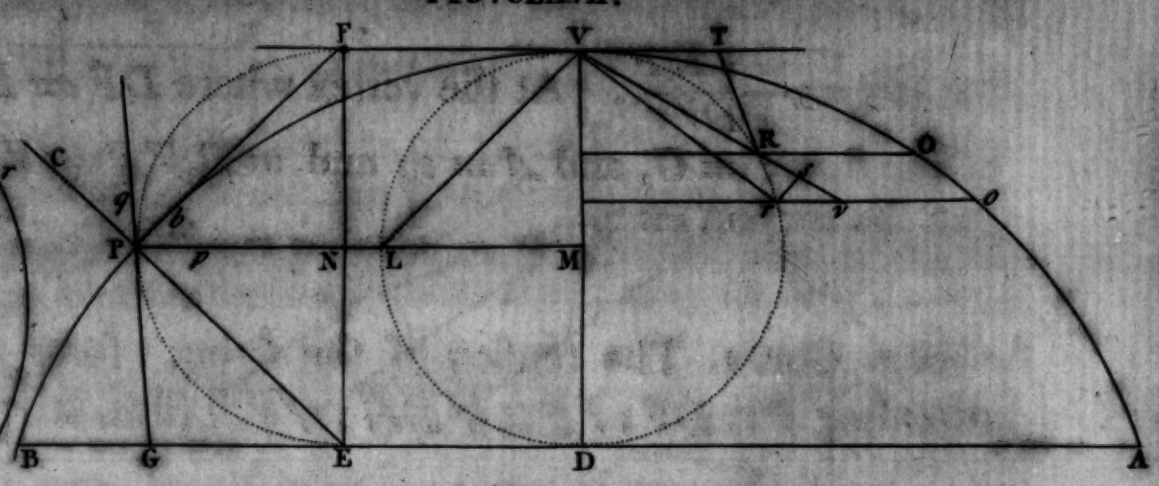
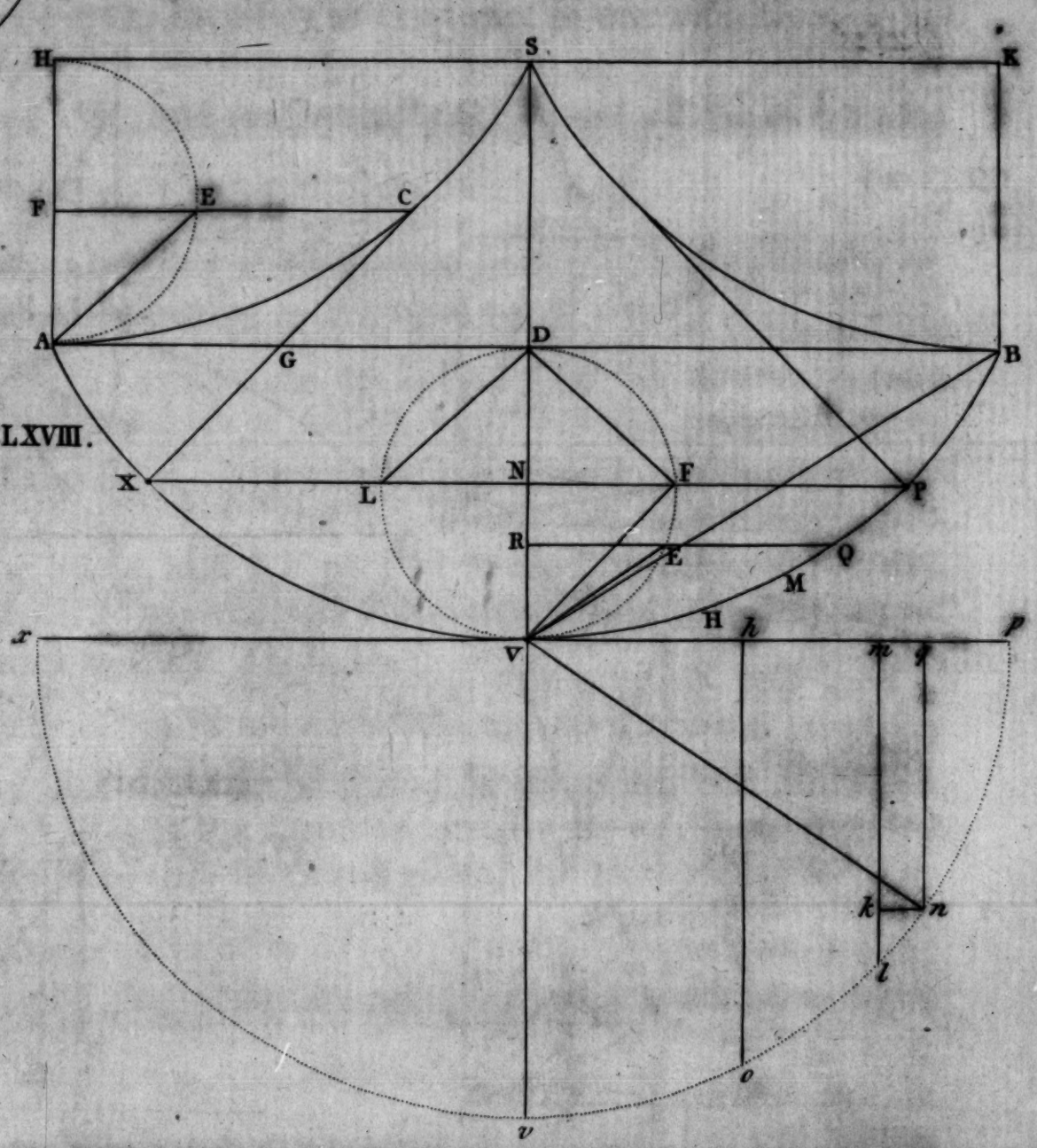


FIG. CLXVIII.



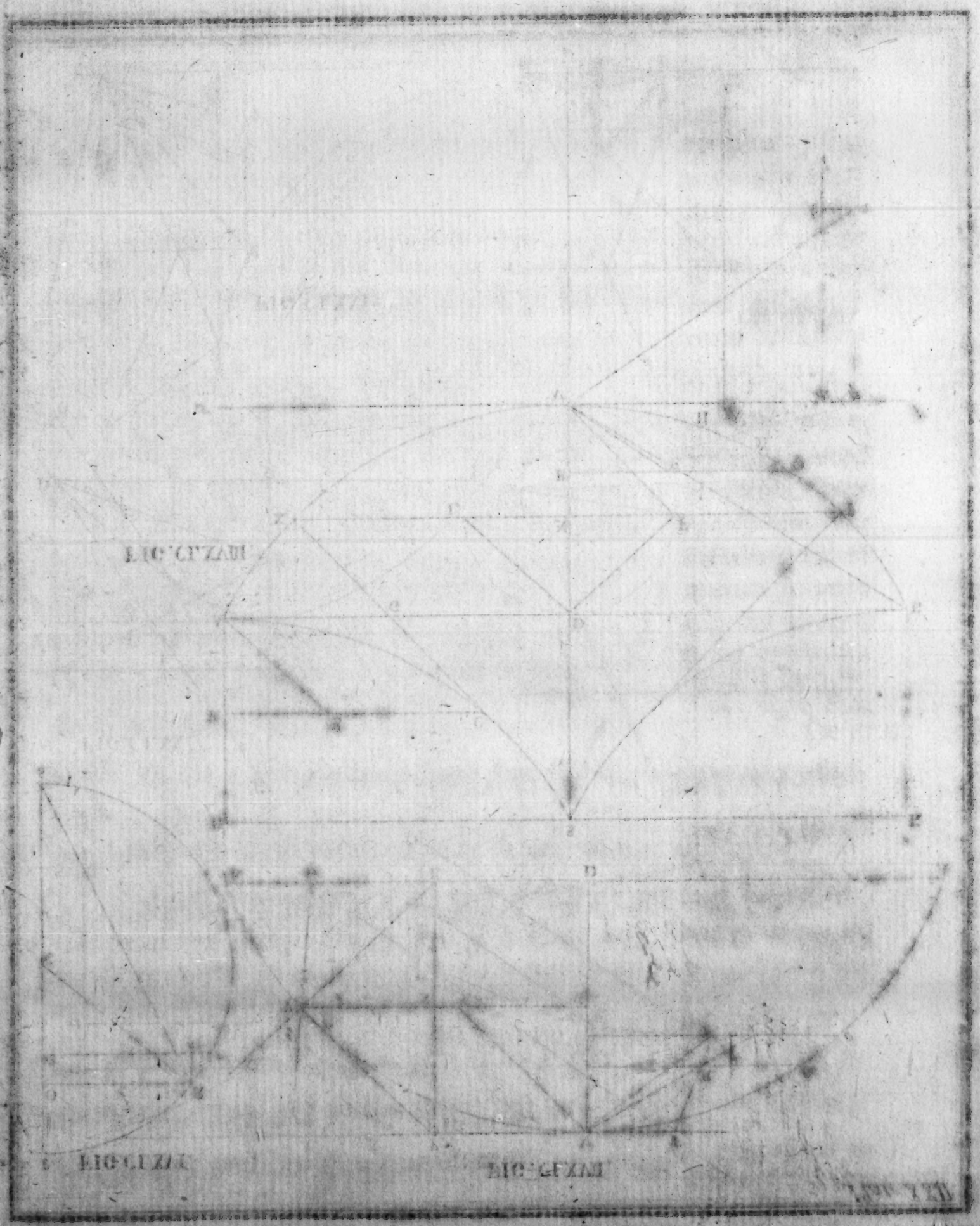
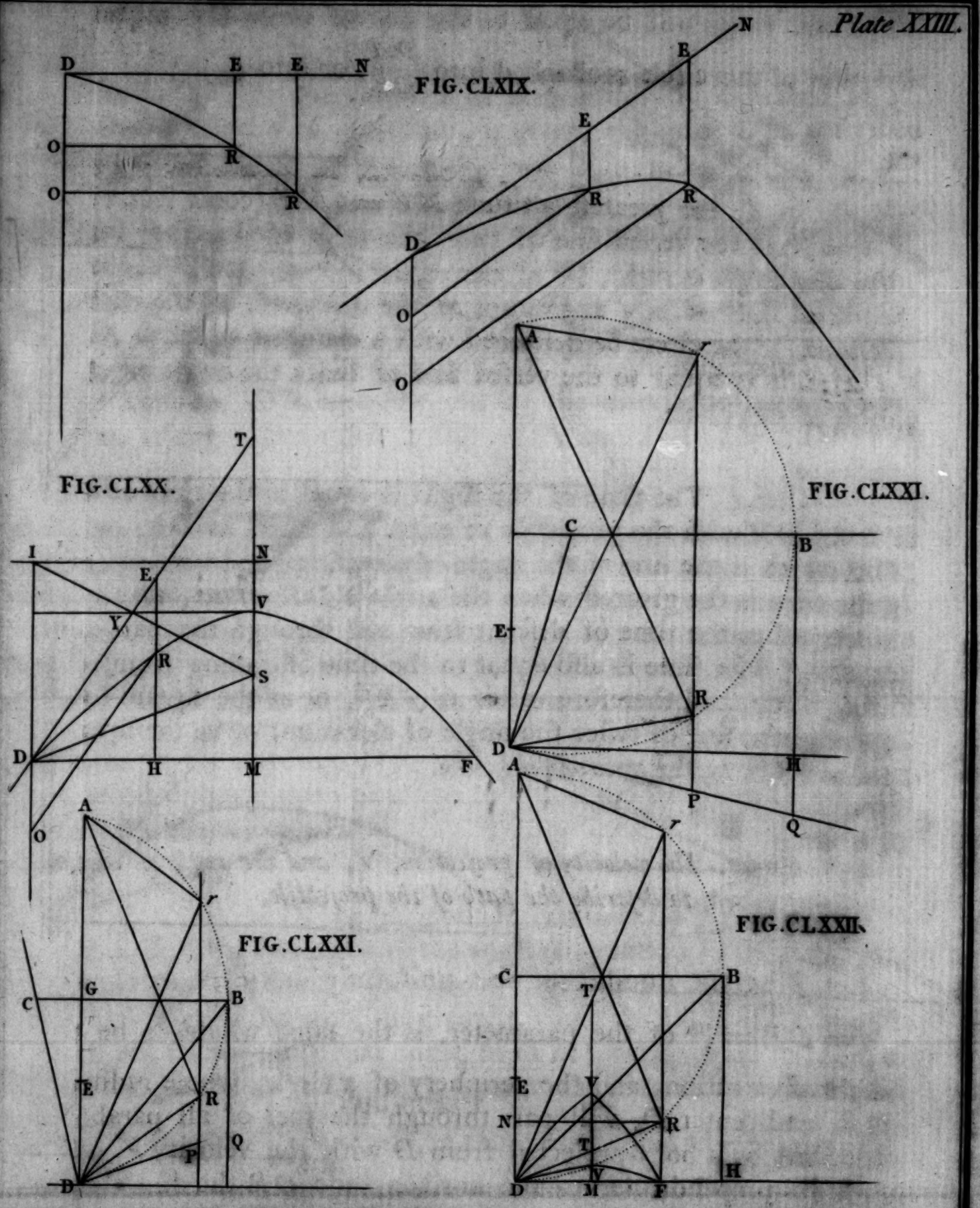
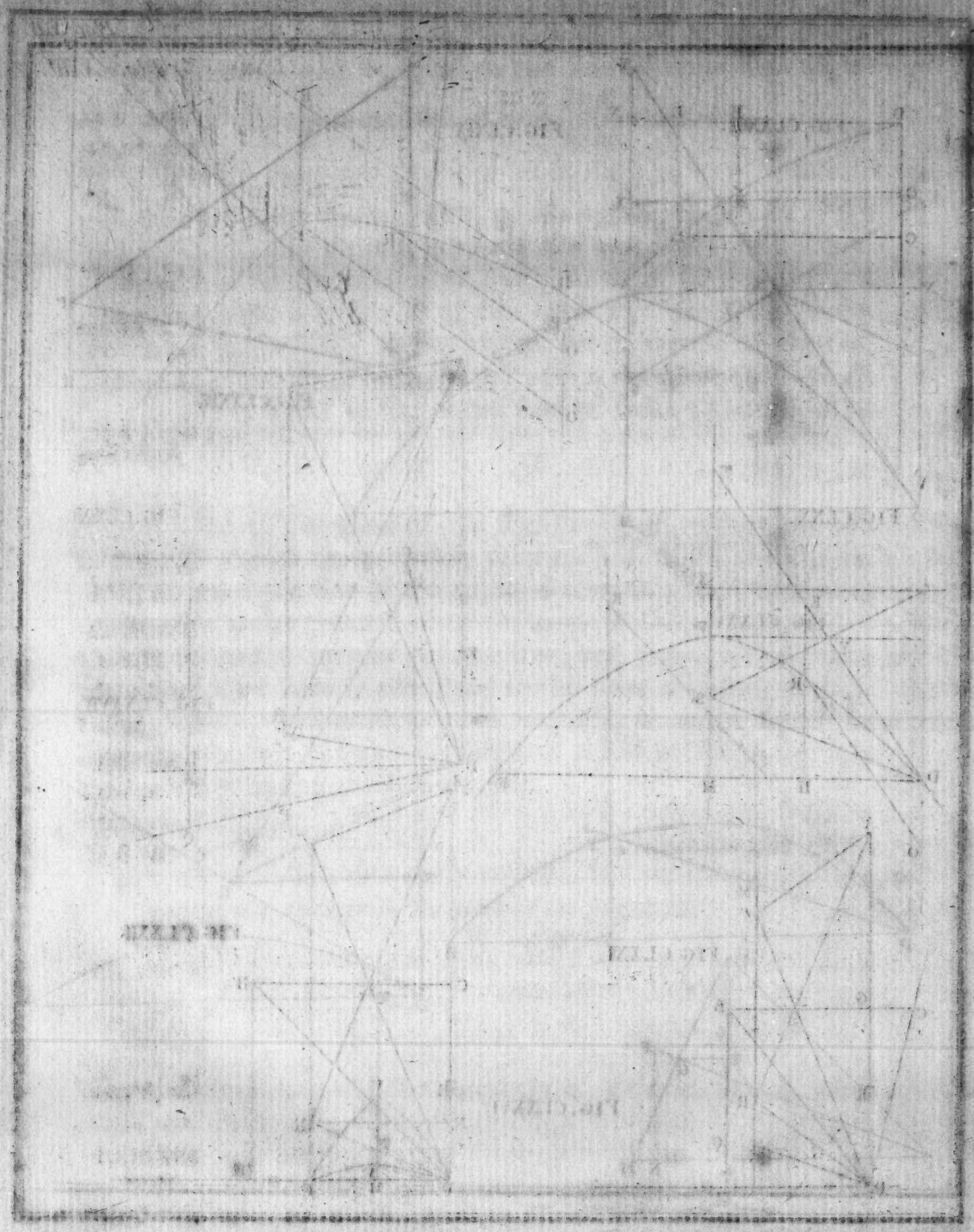


Plate XXIII.


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FIG. CLXIX.
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FIG. CLXX.
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FIG. CLXXI.
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FIG. CLXXII.
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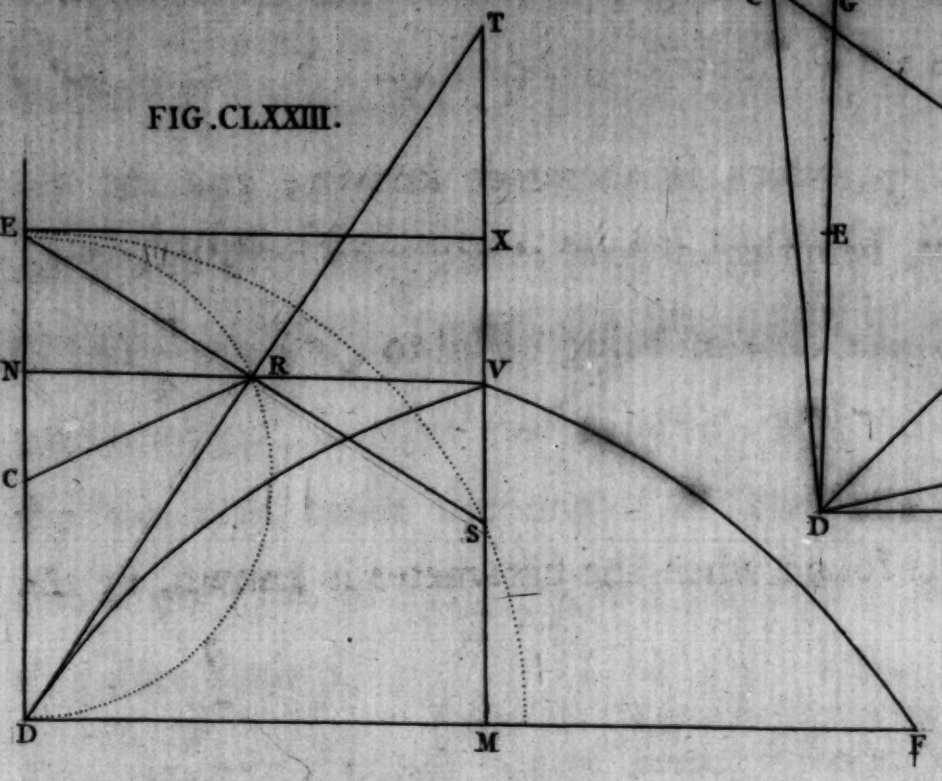


FIG. CLXXIII.

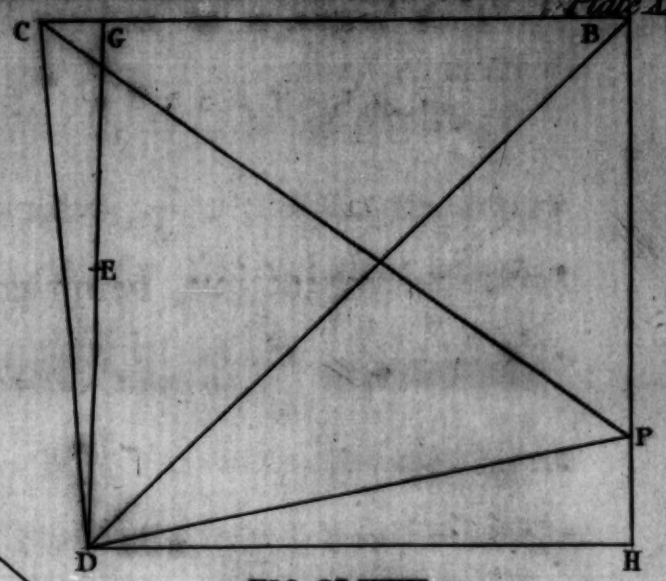


FIG. CLXXIV.

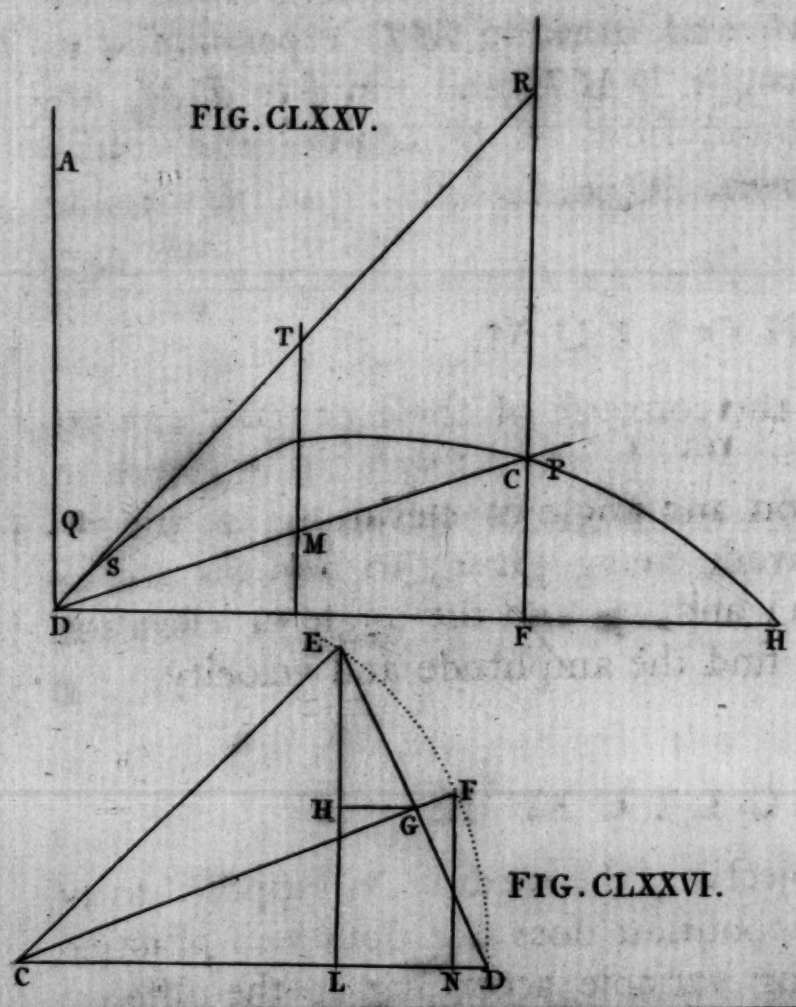


FIG. CLXXV.

FIG. CLXXVI.

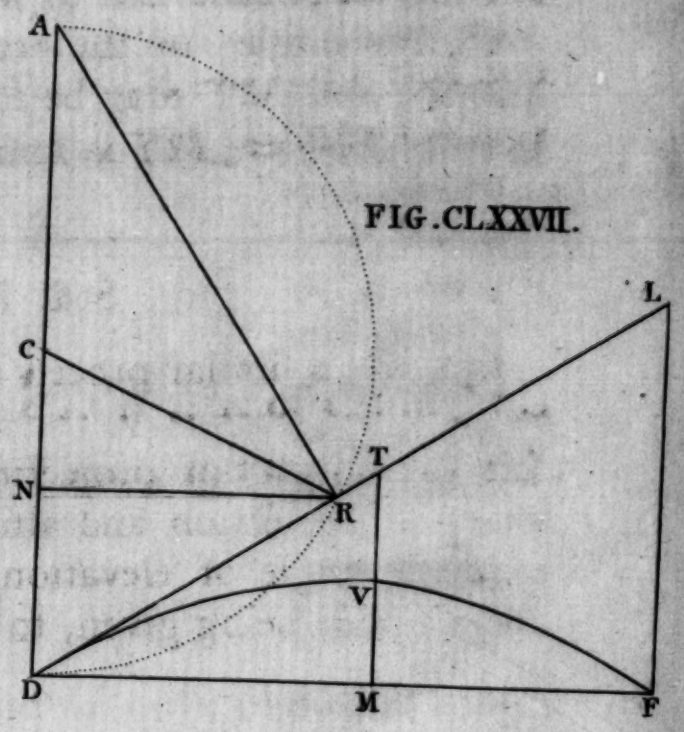


FIG. CLXXVII.

